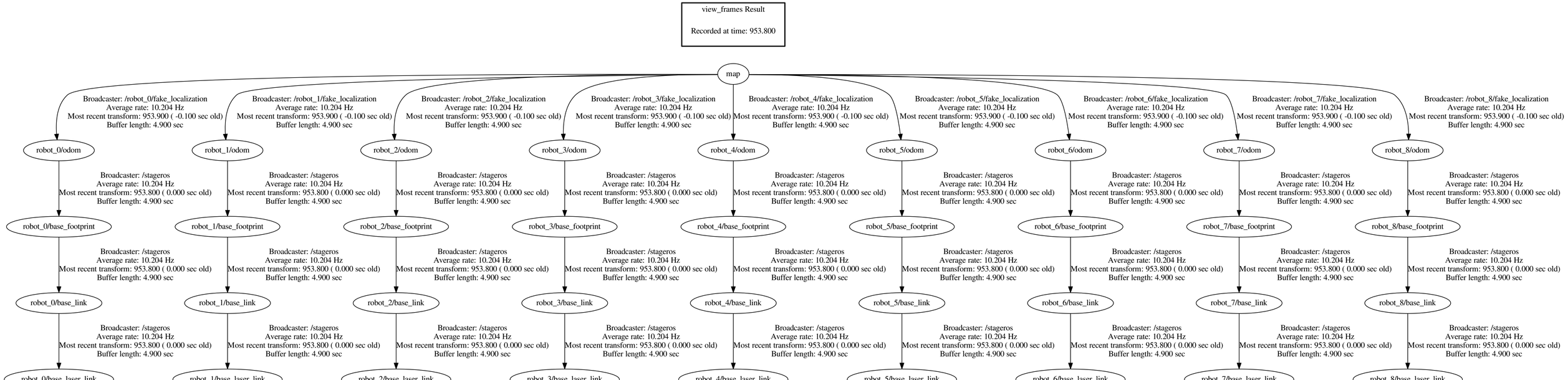
view_frames Result
Recorded at time: 953.800
map
Broadcaster: /robot_0/fake_localization
Average rate: 10.204 Hz
Most recent transform: 953.900 (-0.100 sec old)
Buffer length: 4.900 sec
Broadcaster: /robot_1/fake_localization
Average rate: 10.204 Hz
Most recent transform: 953.900 (-0.100 sec old)
Buffer length: 4.900 sec
Broadcaster: /robot_2/fake_localization
Average rate: 10.204 Hz
Most recent transform: 953.900 (-0.100 sec old)
Buffer length: 4.900 sec
Broadcaster: /robot_3/fake_localization
Average rate: 10.204 Hz
Most recent transform: 953.900 (-0.100 sec old)
Buffer length: 4.900 sec
Broadcaster: /robot_4/fake_localization
Average rate: 10.204 Hz
Most recent transform: 953.900 (-0.100 sec old)
Buffer length: 4.900 sec
Broadcaster: /robot_5/fake_localization
Average rate: 10.204 Hz
Most recent transform: 953.900 (-0.100 sec old)
Buffer length: 4.900 sec
Broadcaster: /robot_6/fake_localization
Average rate: 10.204 Hz
Most recent transform: 953.900 (-0.100 sec old)
Buffer length: 4.900 sec
Broadcaster: /robot_7/fake_localization
Average rate: 10.204 Hz
Most recent transform: 953.900 (-0.100 sec old)
Buffer length: 4.900 sec
Broadcaster: /robot_8/fake_localization
Average rate: 10.204 Hz
Most recent transform: 953.900 (-0.100 sec old)
Buffer length: 4.900 sec
robot_0/odom
robot_1/odom
robot_2/odom
robot_3/odom
robot_4/odom
robot_5/odom
robot_6/odom
robot_7/odom
robot_8/odom
Broadcaster: /stageros
Average rate: 10.204 Hz
Most recent transform: 953.800 (0.000 sec old)
Buffer length: 4.900 sec
robot_0/base_footprint
robot_1/base_footprint
robot_2/base_footprint
robot_3/base_footprint
robot_4/base_footprint
robot_5/base_footprint
robot_6/base_footprint
robot_7/base_footprint
robot_8/base_footprint
robot_0/base_link
robot_1/base_link
robot_2/base_link
robot_3/base_link
robot_4/base_link
robot_5/base_link
robot_6/base_link
robot_7/base_link
robot_8/base_link
robot_0/base_laser_link
robot_1/base_laser_link
robot_2/base_laser_link
robot_3/base_laser_link
robot_4/base_laser_link
robot_5/base_laser_link
robot_6/base_laser_link
robot_7/base_laser_link
robot_8/base_laser_link