```
In [1]:
        import sympy
        from sympy import Matrix
        import numpy as np
In [2]:
        %matplotlib notebook
        import matplotlib.pyplot as plt
        from mpl toolkits.mplot3d import axes3d
       Mathematics for Machine Learning
       Session 03: solving systems of linear
       equations
       Gerhard Jäger
       October 29, 2024
       Python and SymPy
In [3]:
        import sympy
        from sympy import Matrix
        · creating a vector
In [4]:
        x = Matrix([1,2,3])
Out[4]:
        2
        3

    creating a matrix

In [5]:
        A = Matrix(
           [1,2, 3],
           [4,5,6],
           [7,8,9]
        ])
Out[5]:
          5 6
```

vector algebra

```
In [6]:
             y = Matrix([3,10,4])
 Out[6]:
             10
             \lfloor 4 \rfloor
 In [7]:
             x+y
 Out[7]:
              12
             \lfloor 7 \rfloor
 In [8]:
             3*x
 Out[8]:
              6
             [9]
 In [9]:
             2 * x - 3 * y
 Out[9]:
            applying a vector to a matrix
In [10]:
             A * x
             \lceil 14 \rceil
Out[10]:
              32
             \lfloor 50 \rfloor
            matrix transposition
In [11]:
             A.T
Out[11]:
             Γ1
                 4 \quad 7
              2 5 8
             \begin{bmatrix} 3 & 6 & 9 \end{bmatrix}
            matrix multiplication
In [12]:
             B = Matrix(
                   [4,1,0],
                   [1,0,2],
                   [4,5,6]
             ])
```

```
В
                \begin{bmatrix} 4 & 1 & 0 \end{bmatrix}
Out[12]:
                 \begin{bmatrix} 1 & 0 & 2 \end{bmatrix}
                \begin{bmatrix} 4 & 5 & 6 \end{bmatrix}
In [13]:
                A * B
Out[13]:
                \lceil 18 \quad 16 \rceil
                              22
                 45 34 46
                \begin{bmatrix} 72 & 52 & 70 \end{bmatrix}
               identity matrix
In [14]:
                sympy.eye(3)
                \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}
Out[14]:
                 0 1 0
                \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}
               diagonal matrix
In [15]:
                sympy.diag([1,2,3])
Out[15]:
                 2
                \lfloor 3 \rfloor
               matrix inverse
In [16]:
                A = Matrix(
                        [1, -4, 2],
                        [-2, 1, 3],
                       [2,6,8]
                 ])
In [17]:
                A.inv()
Out[17]:
In [18]:
                B = Matrix(
                        [1, -4, 2],
[-2, 1, 3],
                       [2,6,-10]
                ])
In [19]:
                try:
```

```
B.inv()
except ValueError:
   print("B is not invertible")
```

B is not invertible

Symbolic computation with SymPy

The real strength of Sympy is that it can calculate with variables as well as with numbers.

```
In [20]: from sympy import symbols a,b,c,d = symbols('a b c d')

In [21]: A = \text{Matrix}([ [a, b], [c,d] ])
A
Out[21]: \begin{bmatrix} a & b \\ c & d \end{bmatrix}
In [22]: A.inv()
Out[22]: \begin{bmatrix} \frac{d}{ad-bc} & -\frac{b}{ad-bc} \\ -\frac{c}{ad-bc} & \frac{a}{ad-bc} \end{bmatrix}
```

Back to solving systems of linear equations

First part: lower elimination

$$3x + 4y - z = 0$$

 $y + z = 4$
 $x - y - z = -5$

• subtracting $\frac{1}{3}$ times the first equation from the third equation:

- adding $\frac{7}{3}$ times the second equation to the third equation:

Lower elimination is completed if the left-hand side has a **upper triangular** shape.

Second part: upper elimination (a.k.a backward substitution)

In the elimination part, we transformed all coefficients below the diagonal to 0. In the substitution part, we successively transform all coefficients **above** the diagonal to 0.

• subtract $\frac{3}{5}$ times third equation from second equation.

- add $\frac{3}{5}$ times third equation to first equation.

$$3x + 4y = \frac{13}{5}$$
 $y = \frac{7}{5}$
 $\frac{5}{3}z = \frac{13}{3}$

• subtract 4 times second equation from first equation.

Third step: dividing by pivots

The diagonal coefficients are called the **pivots**. In the last step, we transform them into 1.

divide first equation by 3

$$\begin{array}{rcl}
x & & = & -1 \\
y & & = & \frac{7}{5} \\
& \frac{5}{3}z & = & \frac{13}{3}
\end{array}$$

• divide third equation by $\frac{5}{3}$

$$\begin{array}{ccc} x & & = & -1 \\ y & & = & \frac{7}{\epsilon} \end{array}$$

$$z = \frac{13}{5}$$

checking result

$$3x + 4y - z = 0$$

 $y + z = 4$
 $x - y - z = -5$

becomes

Stripping down the superfluous notation, this is a sequence of **augmented matrices**. The augmented matrix is the matrix of coefficients on the left-hand side, plus the right-hand side as additional column.

• system of equations in matrix notation

Out[25]: array([-1., 1.4, 2.6])

$$A = egin{bmatrix} 3 & 4 & -1 \ 0 & 1 & 1 \ 1 & -1 & -1 \end{bmatrix}$$

$$\mathbf{x} = egin{bmatrix} x \ y \ z \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} 4 \\ -5 \end{bmatrix}$$
$$A\mathbf{x} = \mathbf{b}$$

· augmented matrix

$$\begin{bmatrix} 3 & 4 & -1 & 0 \\ 0 & 1 & 1 & 4 \\ 1 & -1 & -1 & -5 \end{bmatrix}$$

lower elimination: transforming below-diagonal entries to 0

• subtracting $\frac{1}{3}$ times first row from third row

$$\begin{bmatrix} 3 & 4 & -1 & 0 \\ 0 & 1 & 1 & 4 \\ 0 & -\frac{7}{3} & -\frac{2}{3} & -5 \end{bmatrix}$$

• adding $\frac{7}{3}$ times second row to third row

$$\begin{bmatrix} 3 & 4 & -1 & 0 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & \frac{5}{3} & \frac{13}{3} \end{bmatrix}$$

upper elimination: transforming above-diagonal entries to 0

- subtract $\frac{3}{5}$ times third row from second row

$$\begin{bmatrix} 3 & 4 & -1 & 0 \\ 0 & 1 & 0 & \frac{7}{5} \\ 0 & 0 & \frac{5}{3} & \frac{13}{3} \end{bmatrix}$$

• add $\frac{3}{5}$ times third row to first row

$$\begin{bmatrix} 3 & 4 & 0 & \frac{13}{5} \\ 0 & 1 & 0 & \frac{7}{5} \\ 0 & 0 & \frac{5}{3} & \frac{13}{3} \end{bmatrix}$$

subtract 4 times second row from first row

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & \frac{7}{5} \\ 0 & 0 & \frac{5}{3} & \frac{13}{3} \end{bmatrix}$$

dividing by pivots

$$\begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & \frac{7}{5} \\ 0 & 0 & 1 & \frac{13}{5} \end{bmatrix}$$

All these steps can be formalized as multiplication with some matrix.

- subtracting $\frac{1}{3}$ times first row from third row

$$E_{3,1} \begin{bmatrix} 3 & 4 & -1 & 0 \\ 0 & 1 & 1 & 4 \\ 1 & -1 & -1 & -5 \end{bmatrix} = \begin{bmatrix} 3 & 4 & -1 & 0 \\ 0 & 1 & 1 & 4 \\ 0 & -\frac{7}{3} & \frac{2}{3} & -5 \end{bmatrix}$$

$$E_{3,1} = egin{bmatrix} 1 & 0 & 0 \ 0 & 1 & 0 \ -rac{1}{3} & 0 & 1 \end{bmatrix}$$

• adding $\frac{7}{3}$ times second row to third row

$$E_{3,2} egin{bmatrix} 3 & 4 & -1 & 0 \ 0 & 1 & 1 & 4 \ 0 & -rac{7}{3} & -rac{2}{3} & -5 \end{bmatrix} = egin{bmatrix} 3 & 4 & -1 & 0 \ 0 & 1 & 1 & 4 \ 0 & 0 & rac{5}{3} & rac{13}{3} \end{bmatrix}$$

$$E_{3,2} = egin{bmatrix} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & rac{7}{3} & 1 \end{bmatrix}$$

• subtract $\frac{3}{5}$ times third row from second row

$$E_{2,3} egin{bmatrix} 3 & 4 & -1 & 0 \ 0 & 1 & 1 & 4 \ 0 & 0 & rac{5}{3} & rac{13}{3} \end{bmatrix} = egin{bmatrix} 3 & 4 & -1 & 0 \ 0 & 1 & 0 & rac{7}{5} \ 0 & 0 & rac{5}{3} & rac{13}{3} \end{bmatrix}$$

$$E_{2,3} = egin{bmatrix} 1 & 0 & 0 \ 0 & 1 & -rac{3}{5} \ 0 & 0 & 1 \end{bmatrix}$$

$$E_{1,3} egin{bmatrix} 3 & 4 & -1 & 0 \ 0 & 1 & 0 & rac{7}{5} \ 0 & 0 & rac{5}{3} & rac{13}{3} \end{bmatrix} = egin{bmatrix} 3 & 4 & 0 & rac{13}{5} \ 0 & 1 & 0 & rac{7}{5} \ 0 & 0 & rac{5}{3} & rac{13}{3} \end{bmatrix}$$

$$E_{1,3} = egin{bmatrix} 1 & 0 & rac{3}{5} \ 0 & 1 & 0 \ 0 & 0 & 1 \end{bmatrix}$$

• subtract 4 times second row from first row

$$E_{1,2} egin{bmatrix} 3 & 4 & 0 & \left| egin{array}{c|ccc} rac{13}{5} \ 0 & 1 & 0 & \left| egin{array}{c|ccc} rac{7}{5} \ 0 & 0 & rac{5}{3} \end{array}
ight] = egin{bmatrix} 3 & 0 & 0 & -3 \ 0 & 1 & 0 & rac{7}{5} \ 0 & 0 & rac{5}{3} & rac{13}{3} \end{array}
ight]$$

$$E_{1,2} = egin{bmatrix} 1 & -4 & 0 \ 0 & 1 & 0 \ 0 & 0 & 1 \end{bmatrix}$$

divide each row by its pivot

$$D\begin{bmatrix} 3 & 0 & 0 & | & -3 \\ 0 & 1 & 0 & | & \frac{7}{5} \\ 0 & 0 & \frac{5}{3} & | & \frac{13}{3} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & | & -1 \\ 0 & 1 & 0 & | & \frac{7}{5} \\ 0 & 0 & 1 & | & \frac{13}{5} \end{bmatrix}$$

$$D = \begin{bmatrix} \frac{1}{3} & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & \frac{3}{5} \end{bmatrix}$$

Let us reflect what we did. Taking everyting together, we have

$$DE_{1,2}E_{1,3}E_{2,3}E_{3,2}E_{3,1}A = \mathbf{I}$$

 $DE_{1,2}E_{1,3}E_{2,3}E_{3,2}E_{3,1}\mathbf{b} = \mathbf{x}$

Therefore

$$DE_{1,2}E_{1,3}E_{2,3}E_{3,2}E_{3,1} = A^{-1}$$

Let's check this with SymPy.

```
In [26]:
          from sympy import Rational, diag
In [27]:
          A = Matrix([
               [3,4,-1],
               [0,1,1],
               [1, -1, -1]
           ])
          Α
                   -1
Out[27]:
           0
              1
                   1
              -1 -1
In [28]:
          b = Matrix([0, 4, -5])
          [ 0 ]
Out[28]:
            4
           \lfloor -5 \rfloor
In [29]:
          E31 = Matrix(
               [1, 0, 0],
               [0, 1, 0],
               [-Rational(1,3), 0, 1]
           ])
          E31
Out[29]:
            0
                1 0
In [30]:
          E32 = Matrix([
               [1,0,0],
               [0,1,0],
               [0,Rational(7,3),1]
           ])
          E32
Out[30]:
                 [0
           0
              1
                 0
                  1
In [31]:
          E23 = Matrix([
               [1,0,0],
               [0,1,-Rational(3,5)],
               [0,0,1]
          ])
          E23
Out[31]:
           0 1
```

```
In [32]:
             E13 = Matrix([
                  [1,0,Rational(3,5)],
                   [0,1,0],
                   [0,0,1]
             ])
             E13
                     \frac{3}{5}
Out[32]:
             \begin{bmatrix} 1 & 0 \end{bmatrix}
             0 \quad 1
                     0
             0 0
                     1
In [33]:
             E12 = Matrix([
                  [1, -4, 0],
                   [0,1,0],
                   [0,0,1]
             ])
             E12
Out[33]:
                 -4 \quad 0
                 1
                       0
                       1
In [34]:
             D = diag(Rational(1,3), 1, Rational(3,5))
Out[34]:
In [35]:
             D * E12 * E13 * E23 * E32 * E31 * A
             \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}
Out[35]:
             0 \quad 1 \quad 0
             \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}
In [36]:
             D * E12 * E13 * E23 * E32 * E31 * b
Out[36]:
              \frac{7}{5}
In [37]:
             D * E12 * E13 * E23 * E32 * E31
Out[37]:
In [38]:
             A.inv()
```

Γυ ο τ]

$$\begin{bmatrix} U & 1 & 1 \\ \frac{1}{5} & -\frac{2}{5} & -\frac{3}{5} \\ -\frac{1}{5} & \frac{7}{5} & \frac{3}{5} \end{bmatrix}$$

So we can compute the inverse of a square matrix by multiplying out the elimination matrices.

There is also a shorter way to the inverse matrix: augment \boldsymbol{A} with the identity matrix!

$$egin{align*} A \left[\mathbf{x}_1 \quad \mathbf{x}_2 \quad \mathbf{x}_3
ight] = \mathbf{I} \ & dots \ DE_{1,2}E_{1,3}E_{2,3}E_{3,2}E_{3,1}A \left[\mathbf{x}_1 \quad \mathbf{x}_2 \quad \mathbf{x}_3
ight] = DE_{1,2}E_{1,3}E_{2,3}E_{3,2}E_{3,1}\mathbf{I} \ A^{-1}A \left[\mathbf{x}_1 \quad \mathbf{x}_2 \quad \mathbf{x}_3
ight] = A^{-1}\mathbf{I} \ \left[\mathbf{x}_1 \quad \mathbf{x}_2 \quad \mathbf{x}_3
ight] = A^{-1} \end{split}$$

• augmented matrix:

$$\begin{bmatrix} 3 & 4 & -1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & 0 & 1 \end{bmatrix}$$

• left-multiplication with $E_{3,1}$:

$$\begin{bmatrix} 3 & 4 & -1 \\ 0 & 1 & 1 \\ 0 & -\frac{7}{3} & -\frac{2}{3} \\ \end{bmatrix} \begin{array}{c|c} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -\frac{1}{3} & 0 & 1 \\ \end{bmatrix}$$

• left-multiplication with $E_{3,2}$:

$$\begin{bmatrix} 3 & 4 & -1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & \frac{5}{3} & -\frac{1}{3} & \frac{7}{3} & 1 \end{bmatrix}$$

• left-multiplication with $E_{2,3}$:

$$\begin{bmatrix} 3 & 4 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & \frac{1}{5} & -\frac{2}{5} & -\frac{3}{5} \\ 0 & 0 & \frac{5}{3} & -\frac{1}{3} & \frac{7}{3} & 1 \end{bmatrix}$$

• left-multiplication with $E_{1,3}$:

$$\begin{bmatrix} 3 & 4 & 0 & \frac{4}{5} & \frac{7}{5} & \frac{3}{5} \\ 0 & 1 & 0 & \frac{1}{5} & -\frac{2}{5} & -\frac{3}{5} \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & \frac{5}{3} & -\frac{1}{3} & \frac{7}{3} & 1 \end{bmatrix}$$

• left-multiplication with $E_{1,2}$:

$$\begin{bmatrix} 3 & 0 & 0 & 0 & 3 & 3 \\ 0 & 1 & 0 & \frac{1}{5} & -\frac{2}{5} & -\frac{3}{5} \\ 0 & 0 & \frac{5}{3} & -\frac{1}{3} & \frac{7}{3} & 1 \end{bmatrix}$$

• left-multiplication with D:

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & \frac{1}{5} & -\frac{2}{5} & -\frac{3}{5} \\ 0 & 0 & 1 & -\frac{1}{5} & \frac{7}{5} & \frac{3}{5} \end{bmatrix}$$

$$A^{-1} = egin{bmatrix} 0 & 1 & 1 \ rac{1}{5} & -rac{2}{5} & -rac{3}{5} \ -rac{1}{5} & rac{7}{5} & rac{3}{5} \end{bmatrix}$$

Algorithm to find the inverse of a square matrix \boldsymbol{A} (preliminary)

(@ represents matrix multiplication.)

for i in n:2

```
Let n be the number of rows of A
X := A
Y := I
for i in 1:(n-1)
    for j in (i+1):n
        l := X[j,i]/X[i,i]
        Eji := I
        Eji[j,i] := -l
        X := Eji @ X
        Y := Eji @ Y
        end
end
```

```
for j in (i-1):1
          u := X[j,i]/X[i,i]
          Eji := I
          Eji[j,i] := -u
          X := Eji @ X
          Y := Eji @ Y
    end
end
D := I
for i in 1:n
    D[i,i] = 1/X[i,i]
end
Y := D @ Y
return Y
```

Permutation

The algorithm fails if a 0 occurs at the diagonal somewhere along the way. Sometimes, this is benign, sometimes not.

Here is a benign example:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix}$$

This matrix is invertible, according to SymPy:

Out[39]:
$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix}$$



Out[40]:
$$\begin{bmatrix} 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & 0 & -\frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & 0 \end{bmatrix}$$



Still, elimination fails:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 1 & 1 & -1 & 0 & 1 & 0 \\ 1 & -1 & 1 & 0 & 0 & 1 \end{bmatrix}$$

• subtracting first row from second:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & -2 & -1 & 1 & 0 \\ 1 & -1 & 1 & 0 & 0 & 1 \end{bmatrix}$$

· subtracting first row from third:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & -2 & -1 & 1 & 0 \\ 0 & -2 & 0 & -1 & 0 & 1 \end{bmatrix}$$

Now, according to the algorithm, we have to subtract l times the second row from the third, with

$$l = \frac{-2}{0}$$

This is not possible. We can recover from this though, by swapping the second and third row:

$$egin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 \ 0 & -2 & 0 & -1 & 0 & 1 \ 0 & 0 & -2 & -1 & 1 & 0 \ \end{bmatrix}$$

The rest is straightforward:

• add $\frac{1}{2}$ times third row to first row:

$$\begin{bmatrix} 1 & 1 & 0 & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & -2 & 0 & -1 & 0 & 1 \\ 0 & 0 & 2 & 1 & 1 & 0 \end{bmatrix}$$

• add $\frac{1}{2}$ times second row to first row:

$$\begin{bmatrix} 1 & 0 & 0 & 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & -2 & 0 & -1 & 0 & 1 \\ 0 & 0 & -2 & -1 & 1 & 0 \end{bmatrix}$$

· divide each row by its pivot

$$\begin{bmatrix} 1 & 0 & 0 & 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & 1 & 0 & \frac{1}{2} & 0 & -\frac{1}{2} \\ 0 & 0 & 1 & \frac{1}{2} & -\frac{1}{2} & 0 \end{bmatrix}$$

The step of exchanging the second and third row can also be done via matrix multiplication:

$$P_{2,3} = egin{bmatrix} 1 & 0 & 0 \ 0 & 0 & 1 \ 0 & 1 & 0 \end{bmatrix}$$

Here we had a configuration where, during lower elimination, a 0 was in $X_{i,i}$ and a non-zero entry $X_{j,i}$ was below it.

In such a configuration, we can save the day by multiplying everything with $P_{i,j}$ from the left.

If both $X_{i,i}=0$ and $X_{j,i}=0$, we just do nothing and proceed to the next row.

This cannot happen during upper elimination, because it does not affect the diagonal.

Algorithm to find the inverse of a square matrix \boldsymbol{A} (final version)

(@ represents matrix multiplication.)

```
X := P1] @ X
                Y := Pij @ Y
            end
            l := X[j,i]/X[i,i]
            Eji := I
            Eji[j,i] := -l
            X := Eji @ X
            Y := Eji @ Y
        end
     end
end
for i in n:2
    for j in (i-1):1
          u := X[j,i]/X[i,i]
          Eji := I
          Eji[j,i] := -u
          X := Eji @ X
          Y := Eji @ Y
    end
end
D := I
for i in 1:n
    D[i,i] = 1/X[i,i]
end
Y := D @ Y
return Y
```

Systems of linear equation without solution

$$A = egin{bmatrix} 3 & 4 & -1 \ 0 & 1 & 1 \ 0 & -1 & -1 \end{bmatrix}$$

$$\begin{bmatrix} 0 \end{bmatrix}_{4}$$

elimination step

$$\begin{bmatrix} 3 & 4 & -1 & 0 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 0 & 9 \end{bmatrix}$$

Here we already see that this system cannot have a solution, because the third row has no solution.

Systems of linear equation with infinitely many solution

$$A = egin{bmatrix} 3 & 4 & -1 \ 0 & 1 & 1 \ 0 & -1 & -1 \end{bmatrix}$$

$$\mathbf{b} = egin{bmatrix} 0 \ 4 \ -4 \end{bmatrix}$$

augmented matrix

$$\begin{bmatrix} 3 & 4 & -1 & 0 \\ 0 & 1 & 1 & 4 \\ 0 & -1 & -1 & -4 \end{bmatrix}$$

elimination step

$$\begin{bmatrix} 3 & 0 & -5 & | & -16 \\ 0 & 1 & 1 & | & 4 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

dividing by the pivots

$$\begin{bmatrix} 1 & 0 & -\frac{5}{3} & -\frac{16}{3} \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The set of solutions obtained this way is

$$x = \frac{5}{z} - \frac{16}{z}$$

$$egin{array}{ccc} 3 & 3 \ y=4-z \ z\in\mathbb{R} \end{array}$$

Permutations during elimination

Consider the following matrix:

Out[41]:
$$\begin{bmatrix} 1 & 4 & 5 \\ 4 & 16 & 6 \\ 5 & 6 & 3 \end{bmatrix}$$

We want to find the inverse.

$$\begin{bmatrix} 1 & 4 & 5 & 1 & 0 & 0 \\ 4 & 16 & 6 & 0 & 1 & 0 \\ 5 & 6 & 3 & 0 & 0 & 1 \end{bmatrix}$$

$$E_1 = egin{bmatrix} 1 & 0 & 0 \ -4 & 1 & 0 \ 0 & 0 & 1 \end{bmatrix} \qquad egin{bmatrix} 1 & 4 & 5 & 1 & 0 & 0 \ 0 & 0 & -14 & -4 & 1 & 0 \ 5 & 6 & 3 & 0 & 0 & 1 \end{bmatrix}$$

Since we have a 0 above a non-0, we have to exchange rows.

$$P_1 = egin{bmatrix} 1 & 0 & 0 \ 0 & 0 & 1 \ 0 & 1 & 0 \end{bmatrix} \qquad egin{bmatrix} 1 & 4 & 5 & 1 & 0 & 0 \ 5 & 6 & 3 & 0 & 0 & 1 \ 0 & 0 & -14 & -4 & 1 & 0 \end{bmatrix}$$

Now we can continue with elimination.

$$E_2 = egin{bmatrix} 1 & 0 & 0 \ -5 & 1 & 0 \ 0 & 0 & 1 \end{bmatrix} \hspace{1cm} egin{bmatrix} 1 & 4 & 5 & 1 & 0 & 0 \ 0 & -14 & -22 & -5 & 0 & 1 \ 0 & 0 & -14 & -4 & 1 & 0 \end{bmatrix}$$

$$E_3 = egin{bmatrix} 1 & 0 & 0 \ 0 & 1 & -rac{11}{7} \ 0 & 0 & 1 \end{bmatrix} \qquad egin{bmatrix} 1 & 4 & 5 & 1 & 0 & 0 \ 0 & -14 & 0 & rac{9}{7} & -rac{11}{7} & 1 \ 0 & 0 & -14 & -4 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & \frac{5}{14} \end{bmatrix} \qquad \begin{bmatrix} 1 & 4 & 0 & -\frac{3}{7} & \frac{5}{14} & 0 \end{bmatrix}$$

$$E_4 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \qquad \begin{bmatrix} 0 & -14 & 0 & \frac{3}{7} & -\frac{11}{7} & 1 \\ 0 & 0 & -14 & -4 & 1 & 0 \end{bmatrix}$$

Alltogether we have