Not Applicable If: The incident points alternate on the curve and plane mirror, there is no consecutive incidents of light on the either curve or x axis, Number of iterations limited in case of back tracing

Applicable Cases: No information of source point of light, there can be multiple incidents on the same point, light can retrace its path back

Incident points input and their plot

```
intersecpts = {{5.166010488516726`,5.166010488516724`},{6.003831069285709`,0},{6.7462485659745}
intersecplot = ListPlot[Labeled[#,#] &/@ intersecpts, PlotRange→Full,PlotStyle→{Green}]

Out[*]= {{5.16601, 5.16601}, {6.00383, 0}, {6.74625, 4.57775}, {3.35734, 0},
{-1.05854, 5.96498}, {-4.35714, 0}, {-6.86151, 4.52874}, {0, 0}}

-6.86151, 4.52874}

Solution = 1.05854, 5.96498

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```

Separate the points into x -axis (plane mirror points) and unknown reflecting curve incident points

```
curvepts = \{\{-6.86151, 4.52874\}, \{-1.05854, 5.96498\}, \{5.16601, 5.16601\}, \{6.74625, 4.57775\}\}
      xaxispts = \{\{-4.35714, 0\}, \{0, 0\}, \{3.35734, 0\}, \{6.00383, 0\}\}
                                     6
                                     5
Out[ • ]=
                                     3
```

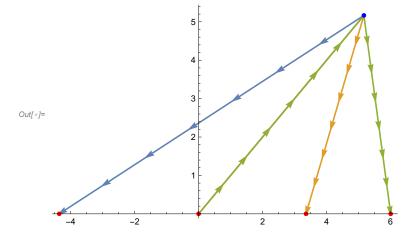
Function for initial 3 point tuple permutations

```
pttuplefunc[domainls_, codomainls_]:=
In[ • ]:=
            Module[{tupleset={}},
                     For[k=0, k<Length[domainls], k++;</pre>
                         tupleset = AppendTo[tupleset, {domainls[2],codomainls[3], If[domainls[k]] # {0,6
                         ];
            Return[tupleset, Module]];
```

Path permutations till the first plane mirror reflection

```
In[ • ]:=
       tuple3point = pttuplefunc[xaxispts, curvepts]
       Print["No of tuples = ", Length[tuple3point]]
 Out[\circ] = \{ \{ \{0, 0\}, \{5.16601, 5.16601\}, \{-4.35714, 0\} \}, 
       \{\{0,0\},\{5.16601,5.16601\},\{3.35734,0\}\},\{\{0,0\},\{5.16601,5.16601\},\{6.00383,0\}\}\}
      No of tuples = 3
       For[tupleset1 ={};k =0, k<Length[xaxispts], k++;</pre>
            For[i=0, i<Length[curvepts], i++;</pre>
                For[slope1=0, slope2 = 0;j=0, j<Length[curvepts], j++;</pre>
                     If[curvepts[i]]=curvepts[j], Continue[]];
                     slope1 = (curvepts[i][2]-xaxispts[k][2])/(curvepts[i][1]-xaxispts[k][1]);
                     slope2 = (curvepts[j][2] -xaxispts[k][2])/(curvepts[j][1] -xaxispts[k][1]);
                     Print[slope1];
                     If[slope1 == -slope2, tupleset1 = AppendTo[tupleset1, {curvepts[i], xaxispts[k], 
                    ]]]];
       For[tuple1 = {}, k=0, k<Length[xaxispts], k++</pre>
```

```
point3path = ListLinePlot[tuple3point, Axes→True, AxesOrigin→{0,0}, MeshFunctions → {#2 &}, N
In[ • ]:=
          MeshShading \rightarrow {Arrowheads[Small]}, DataRange \rightarrow {0, 4 Pi}] /. Line \rightarrow Arrow;
        Show[point3path, intersecplot2]
```



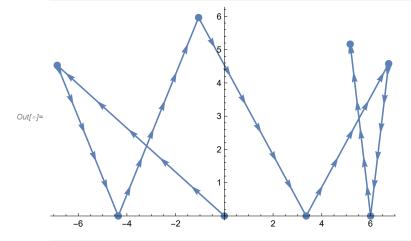
Next we check check reflections and eliminate paths based on it

```
(*Function to check for the curve points lying on the reflected ray *)
reflecdrop[domainls_] :=
    Module[{tupleset = {}},
        For[i=0, i<Length[domainls], i++;</pre>
             For[(eqn = y == -(Last[List @@ Reduce[y - InterpolatingPolynomial[{Part[domainls[
                 j=0, j<Length[curvepts], j++;</pre>
                 If [ (eqn /. \{x\rightarrow curvepts[j,1], y\rightarrow curvepts[j,2]\}) == True,
                      tupleset = AppendTo[tupleset,Join[domainls[i], {curvepts[j]}]]]]];
    Return[tupleset, Module]];
```

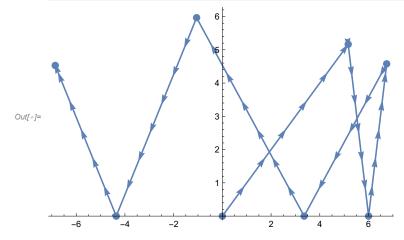
Out of 64 paths, after elimination we have 24 paths after the 1st reflection on plane mirror

```
In[*]:= a = reflecdrop[tuple3point];
 Out[\circ] = \{\{\{0, 0\}, \{5.16601, 5.16601\}, \{6.00383, 0\}, \{6.74625, 4.57775\}\}\}
        path2func[path ]:=
In[ • ]:=
            Module[{tupleset={}},
                For[tupleset={};i=0, i<Length[path], i++;</pre>
                     For[j=0, j<Length[xaxispts], j++;</pre>
                         tupleset = Append[tupleset, Join[path[i]], {xaxispts[j]]}]]]; Print[tupleset]]
                Return[tupleset, Module]];
        merge[list_]:=Module[{a= reflecdrop[list]}, Return[path2func[a], Module]];
In[ • ]:=
        function[list_]:= Module[{a, new={}},
            If[EvenQ[Length[intersecpts]] == True, a = reflecdrop[Nest[merge, list, (Length[intersecpts]
            For[i=0, i<Length[a], i++;</pre>
            If[CountDistinct[a[i]] == Length[intersecpts], new = AppendTo[new, a[i]]]];
            Return[new, Module]];
        finalpath = function[tuple3point]
In[ • ]:=
```

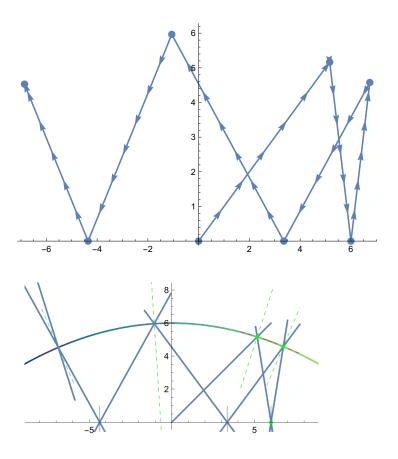
ListLinePlot[finalpath[1]], PlotMarkers→{Automatic, 8}, Axes→True, AxesOrigin→{0,0}, MeshFunct
MeshShading → {Arrowheads[Small]}, DataRange → {0, 4 Pi}] /. Line → Arrow



In[*]:= ListLinePlot[finalpath[2], PlotMarkers→{Automatic, 8}, Axes→True, AxesOrigin→{0,0}, MeshFunct
 MeshShading → {Arrowheads[Small]}, DataRange → {0, 4 Pi}] /. Line → Arrow



Comparison



Trying large number of iterations for back tracing

```
In[ • ]:=
         (* function2[list_]:= Module[{a, new={}}},
             If[EvenQ[Length[intersecpts]] == True, a = reflecdrop[Nest[merge, list, 3*(Length[intersecpt
             For[i=0, i<Length[a], i++;</pre>
             If[CountDistinct[a[i]] == Length[intersecpts], new = AppendTo[new, a[i]]]];
             Return[new, Module]]; *)
In[ • ]:=
         (* b = function2[tuple3point]*)
         (* Length[b]
In[ = ]:=
        ListLinePlot[b, PlotMarkers→{Automatic, 8}, Axes→True, AxesOrigin→{0,0}, MeshFunctions → {#2
           MeshShading \rightarrow \{Arrowheads[Small]\}, \ DataRange \rightarrow \{\emptyset, \ 4 \ Pi\}] \ \ \textit{/.} \ Line \rightarrow Arrow \ \star)
```