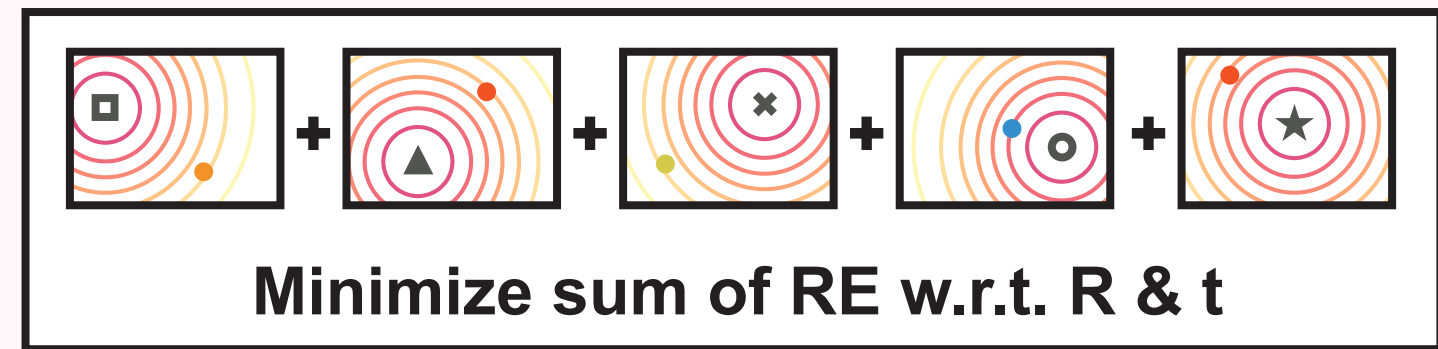
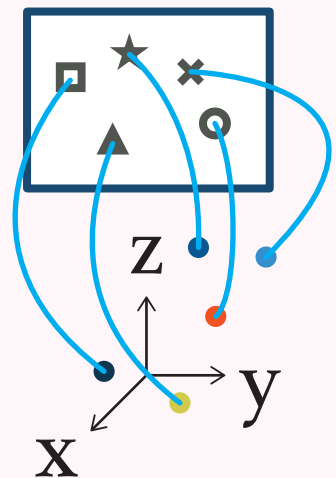


RE-based pose estimation



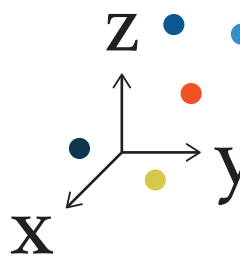
Putative matches



Query image



3D Points
& Descriptors



NRE-based pose estimation

