

## PHYS 615 – Activity 7.2: Lagrangian for two Particles

Let's consider two particles, at  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$ , respectively. The kinetic energy is then the sum of the kinetic energies for each particle, and we've seen before that we can get the forces from a single potential  $U(x_1, y_1, z_1, x_2, y_2, z_2)$ .

The Lagrangian is defined just as before, but now depends on 6 coordinates (and, possibly, time):

$$\mathcal{L} = T - U = \frac{1}{2}m_1(\dot{x}_1^2 + \dot{y}_1^2 + \dot{z}_1^2) + \frac{1}{2}m_2(\dot{x}_2^2 + \dot{y}_2^2 + \dot{z}_2^2) - U(x_1, y_1, z_1, x_2, y_2, z_2) \quad (1)$$

As before, a change to generalized coordinates  $q_1, q_2, \dots, q_n$ , may be advantageous, but the Euler-Lagrange equation will hold either with the original Cartesian coordinates or the new generalized coordinates:

$$\frac{\partial \mathcal{L}}{\partial q_i} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} \quad (2)$$

### 1. *Two masses and a spring*

- (a) Write down the Lagrangian  $\mathcal{L}(x_1, x_2, \dot{x}_1, \dot{x}_2)$  for particles of equal mass  $m$  that move along the  $x$ -axis (only). The two particles are connected by a spring with potential energy  $\frac{1}{2}kx^2$ , where  $x$  is the extension of the spring  $x = x_1 - x_2 - l$ ,  $l$  being the equilibrium length of the spring.

- (b) Rewrite  $\mathcal{L}$  in terms of the new variables  $X = \frac{1}{2}(x_1 + x_2)$  and  $x$ .

(c) Write down the two Euler-Lagrange equations.

(d) Solve for  $X(t)$  and  $x(t)$  and describe the motion. Is there a connection to what we saw about the center of mass earlier in this class?