

ARISTOTLE UNIVERSITY OF THESSALONIKI

SLAM for Autonomous Planetary Exploration using Global Map Matching

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*A thesis submitted to the Faculty of Engineering in
partial fulfillment of the requirements for the degree of*

Diploma
in
Electrical and Computer Engineering

February 3, 2018
Thessaloniki, Greece

Abstract

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Contents

Abstract	iii
Contents	v
List of Figures	vii
List of Tables	ix
1 Introduction	1
1.1 Motivation	1
1.2 Problem Statement	1
1.2.1 Presumptions	1
1.3 Literature Review	1
1.3.1 Planetary Absolute Localization	1
1.3.2 SLAM	1
1.4 Thesis Objectives and Organization	1
1.4.1 Research Objectives	1
1.4.2 Organization	1
2 Algorithm Design	3
2.1 Algorithm Overview	3
2.2 Data Registration	3
2.2.1 Point Cloud Processing	3
2.2.2 Map Prediction and Update	3
2.3 Data Fusion	3
2.3.1 Sensor Fusion	3
2.3.2 Neighborhood Fusion	3
2.4 Pose Estimation	3
2.4.1 Initialization	3
2.4.2 Prediction	3
2.4.3 Update	3
2.4.4 Resampling	3
2.4.5 Estimation	3
2.5 Pose Correction	3
2.5.1 Global to Local Map Matching	3
2.5.2 Criteria Checking	3

	Elevation Features Checking	3
	Traversed Distance Checking	3
3	System Implementation	5
3.1	Library	5
3.1.1	Concurrency	5
3.1.2	Robotic Software Framework	5
3.1.3	Orbiter Data Preprocessing	5
3.2	System Architecture	5
3.3	Planetary Rover Testbed	5
4	Experimental Validation	7
4.1	Scope of Experiments	7
4.1.1	Environment	7
4.1.2	Metrics	7
4.2	Experiments on Pose Estimation	7
4.2.1	Relative Localization Results	7
4.3	Experiments on Global Map Matching	7
4.3.1	Absolute Localization Results	7
4.3.2	Map Resolution Viability	7
5	Conclusion	9
5.1	Thesis Summary	9
5.2	Contributions	9
5.3	Directions for Future Extensions	9
5.4	Applications	9

List of Figures

List of Tables

Chapter 1

Introduction

1.1 Motivation

1.2 Problem Statement

1.2.1 Presumptions

1.3 Literature Review

1.3.1 Planetary Absolute Localization

1.3.2 SLAM

1.4 Thesis Objectives and Organization

1.4.1 Research Objectives

1.4.2 Organization

Chapter 2

Algorithm Design

2.1 Algorithm Overview

2.2 Data Registration

2.2.1 Point Cloud Processing

2.2.2 Map Prediction and Update

2.3 Data Fusion

2.3.1 Sensor Fusion

2.3.2 Neighborhood Fusion

2.4 Pose Estimation

2.4.1 Initialization

2.4.2 Prediction

2.4.3 Update

2.4.4 Resampling

2.4.5 Estimation

2.5 Pose Correction

2.5.1 Global to Local Map Matching

2.5.2 Criteria Checking

Elevation Features Checking

Traversed Distance Checking

Chapter 3

System Implementation

3.1 Library

3.1.1 Concurrency

3.1.2 Robotic Software Framework

3.1.3 Orbiter Data Preprocessing

3.2 System Architecture

3.3 Planetary Rover Testbed

Chapter 4

Experimental Validation

4.1 Scope of Experiments

4.1.1 Environment

4.1.2 Metrics

4.2 Experiments on Pose Estimation

4.2.1 Relative Localization Results

4.3 Experiments on Global Map Matching

4.3.1 Absolute Localization Results

4.3.2 Map Resolution Viability

Chapter 5

Conclusion

5.1 Thesis Summary

5.2 Contributions

5.3 Directions for Future Extensions

5.4 Applications