

Notas de aula

Introdução à Física Computacional

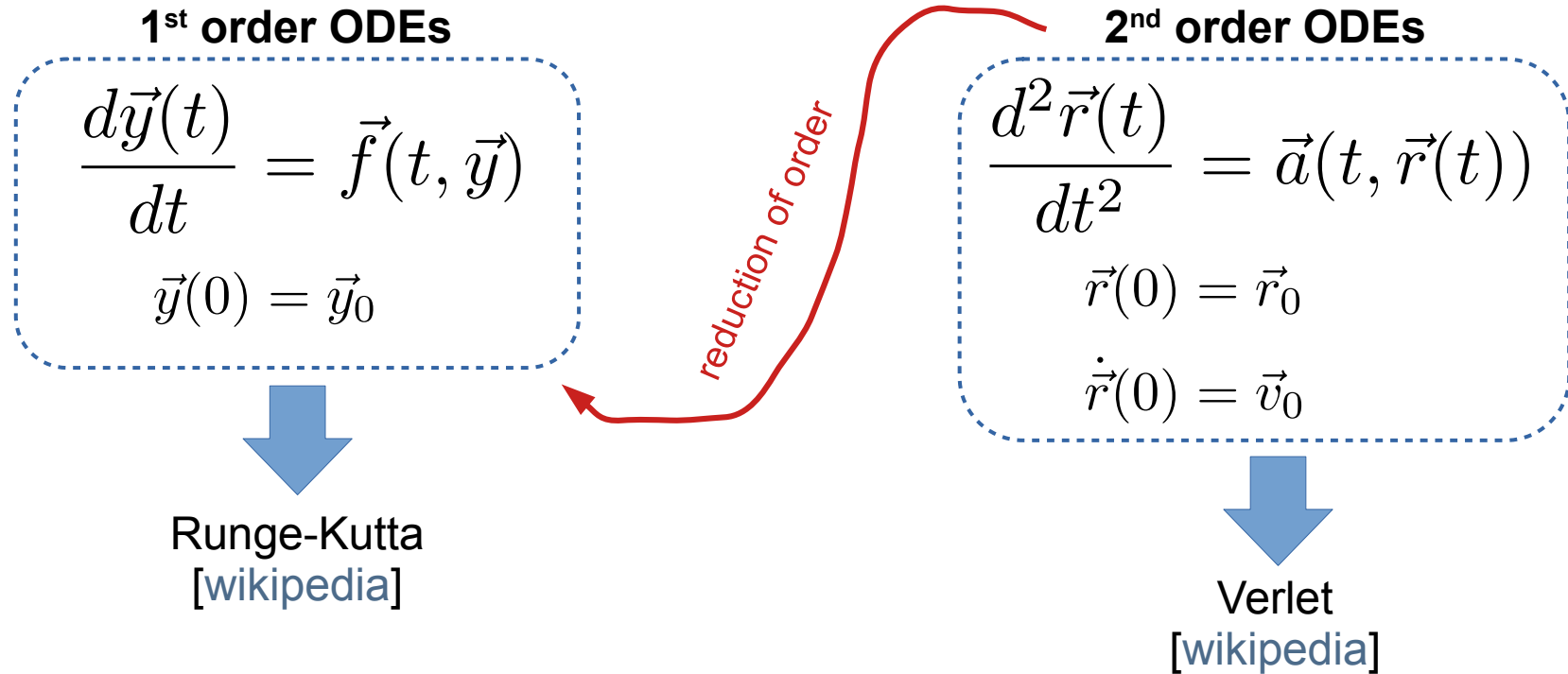
Prof. Gerson – UFU – 2019

Atendimento:

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- Horário: sextas-feiras 16:00 – 16:50

1st and 2nd order differential equations

→ While Euler and Runge-Kutta solve 1st order ODEs,
in physics we often deal with 2nd order ODEs → Newton's law



Verlet integration → We want to solve: $\frac{d^2 \vec{r}(t)}{dt^2} = \vec{a}(t, \vec{r}(t))$

How to discretize the second order derivative?

... Taylor ...

$$\text{forward: } r(t + \Delta t) \approx r(t) + \Delta t r'(t) + \frac{\Delta t^2}{2} r''(t) + \frac{\Delta t^3}{3!} r'''(t) + \mathcal{O}(\Delta t^4)$$

$$\text{backward: } r(t - \Delta t) \approx r(t) - \Delta t r'(t) + \frac{\Delta t^2}{2} r''(t) - \frac{\Delta t^3}{3!} r'''(t) + \mathcal{O}(\Delta t^4)$$

Sum both to get...

$$r''(t) = \frac{r(t - \Delta t) - 2r(t) + r(t + \Delta t)}{\Delta t^2} + \mathcal{O}(\Delta t^2)$$

$$t \rightarrow t_n = n\Delta t$$

$$r''_n = \frac{r_{n-1} - 2r_n + r_{n+1}}{\Delta t^2}$$

Time-reversal invariant!!!

$$\Delta t \rightarrow -\Delta t$$

Noether: conservation of energy!

Verlet integration

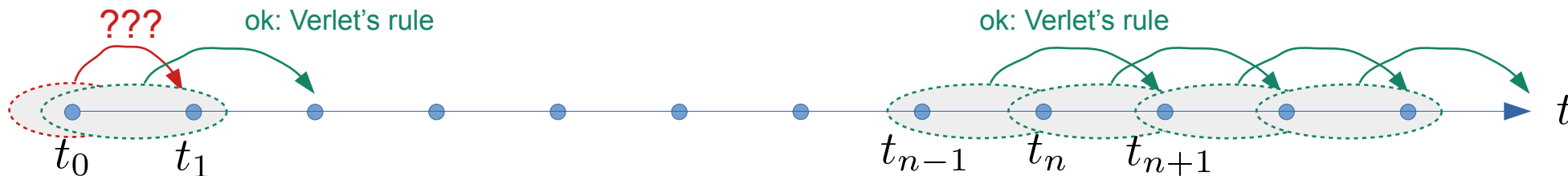
$$\frac{d^2 \vec{r}(t)}{dt^2} = \vec{a}(t, \vec{r}(t))$$

$$r_n'' = \frac{r_{n-1} - 2r_n + r_{n+1}}{\Delta t^2}$$

a simple recursion, just as complex as Euler's

$$\vec{r}_{n+1} = 2\vec{r}_n - \vec{r}_{n-1} + \vec{a}(t_n, \vec{r}_n) \Delta t^2$$

is it sufficient?



How to do the first step from $n=0$ to $n=1$?

We know \mathbf{r}_0 , \mathbf{v}_0 , and $\mathbf{a}(t_0, \mathbf{r}_0) \rightarrow$

$$\vec{r}_1 = \vec{r}_0 + \vec{v}_0 \Delta t + \frac{1}{2} \vec{a}(t_0, \vec{r}_0) \Delta t^2$$

small initialization error

Velocity-dependent forces

What if $\vec{a} \equiv \vec{a}(t, \vec{r}(t), \vec{v}(t))$?

answer 1:

forget Verlet...
use **Runge-Kutta**
+ reduction of order

answer 2:

→ use Euler to calculate the velocity

$$\vec{v}_1 = \vec{v}_0 + \vec{a}(t_0, \vec{r}_0, \vec{v}_0)\Delta t \quad \text{and} \quad \vec{v}_{n+1} = \vec{v}_{n-1} + \vec{a}(t_n, \vec{r}_n, \vec{v}_n)2\Delta t$$

Summary: the **full Verlet** recursion is:

Prototype

$$\frac{d^2\vec{r}(t)}{dt^2} = \vec{a}(t, \vec{r}(t), \vec{v}(t))$$

Initial conditions

$$\begin{aligned}\vec{r}(0) &= \vec{r}_0 \\ \dot{\vec{r}}(0) &= \vec{v}_0\end{aligned}$$

First step: $0 \rightarrow 1$

$$\begin{aligned}\vec{r}_1 &= \vec{r}_0 + \vec{v}_0\Delta t + \frac{1}{2}\vec{a}(t_0, \vec{r}_0, \vec{v}_0)\Delta t^2 \\ \vec{v}_1 &= \vec{v}_0 + \vec{a}(t_0, \vec{r}_0, \vec{v}_0)\Delta t\end{aligned}$$

Other steps: $n \rightarrow n+1$

$$\begin{aligned}\vec{r}_{n+1} &= 2\vec{r}_n - \vec{r}_{n-1} + \vec{a}(t_n, \vec{r}_n)\Delta t^2 \\ \vec{v}_{n+1} &= \vec{v}_{n-1} + \vec{a}(t_n, \vec{r}_n, \vec{v}_n)2\Delta t\end{aligned}$$