

# 01. FUNCTIONS & LIMITS

## Rules of Limits

- $\lim_{x \rightarrow a} (f \pm g)(x) = L \pm L'$
- $\lim_{x \rightarrow a} (fg)(x) = LL'$
- $\lim_{x \rightarrow a} \frac{f}{g}(x) = \frac{L}{L'}$ , provided  $L' \neq 0$
- $\lim_{x \rightarrow a} kf(x) = kL$  for any real number  $k$ .

# 02. DIFFERENTIATION

extreme values:

- $f'(x) = 0$
- $f'(x)$  does not exist
- end points of the domain of  $f$

parametric differentiaton:  $\frac{d^2y}{dx^2} = \frac{d}{dx} \left( \frac{dy}{dx} \right) = \frac{\frac{d}{dt} \left( \frac{dy}{dx} \right)}{\frac{dx}{dt}}$

## Differentiation Techniques

$f(x)$	$f'(x)$
$\tan x$	$\sec^2 x$
$\csc x$	$-\csc x \cot x$
$\sec x$	$\sec x \tan x$
$\cot x$	$-\csc^2 x$
$a^f(x)$	$\ln a \cdot f'(x) a^f(x)$
$\log_a f(x)$	$\log_a e \cdot \frac{f'(x)}{f(x)}$
$\sin^{-1} f(x)$	$\frac{f'(x)}{\sqrt{1-[f(x)]^2}},  f(x)  < 1$
$\cos^{-1} f(x)$	$-\frac{f'(x)}{\sqrt{1-[f(x)]^2}},  f(x)  < 1$
$\tan^{-1} f(x)$	$\frac{f'(x)}{1+[f(x)]^2}$
$\cot^{-1} f(x)$	$-\frac{f'(x)}{1+[f(x)]^2}$
$\sec^{-1} f(x)$	$\frac{f'(x)}{ f(x) \sqrt{[f(x)]^2-1}}$
$\csc^{-1} f(x)$	$-\frac{f'(x)}{ f(x) \sqrt{[f(x)]^2-1}}$

## L'Hopital's Rule

$$\lim_{x \rightarrow x_0} \frac{f(x)}{g(x)} = \lim_{x \rightarrow x_0} \frac{f'(x)}{g'(x)}$$

- for indeterminate forms ( $\frac{0}{0}$  or  $\frac{\infty}{\infty}$ ), cannot directly substitute  $x = a$ .
- for other forms: convert to ( $\frac{0}{0}$  or  $\frac{\infty}{\infty}$ ) then apply L'Hopital's rule
- for exponents: use  $\ln$ , then sub into  $e^{f(x)}$

# 03. INTEGRATION

## Integration Techniques

$f(x)$	$\int f(x)$
$\tan x$	$\ln(\sec x),  x  < \frac{\pi}{2}$
$\cot x$	$\ln(\sin x), 0 < x < \pi$
$\csc x$	$-\ln(\csc x + \cot x), 0 < x < \pi$
$\sec x$	$\ln(\sec x + \tan x),  x  < \frac{\pi}{2}$
$\frac{1}{x^2+a^2}$	$\frac{1}{a} \tan^{-1} \left( \frac{x}{a} \right)$
$\frac{1}{\sqrt{a^2-x^2}}$	$\sin^{-1} \left( \frac{x}{a} \right),  x  < a$
$\frac{1}{x^2-a^2}$	$\frac{1}{2a} \ln \left( \frac{x-a}{x+a} \right), x > a$
$\frac{1}{a^2-x^2}$	$\frac{1}{2a} \ln \left( \frac{x+a}{x-a} \right), x < a$
$a^x$	$\frac{a^x}{\ln a}$

$$19. \int \frac{1}{\sqrt{(x+b)^2+a^2}} dx = \ln \left| (x+b) + \sqrt{(x+b)^2+a^2} \right| + C$$

$$20. \int \frac{1}{\sqrt{(x+b)^2-a^2}} dx = \ln \left| (x+b) + \sqrt{(x+b)^2-a^2} \right| + C$$

$$21. \int \sqrt{a^2-x^2} dx = \frac{x}{2} \sqrt{a^2-x^2} + \frac{a^2}{2} \sin^{-1} \frac{x}{a} + C$$

$$22. \int \sqrt{x^2-a^2} dx = \frac{x}{2} \sqrt{x^2-a^2} - \frac{a^2}{2} \ln |x + \sqrt{x^2-a^2}| + C$$

$$\frac{d}{dx} \int_a^x f(t) dt = f(x)$$

substitution:  $\int_a^b f(g(x))g'(x)dx = \int_{g(a)}^{g(b)} f(u)du$

by parts:  $\int uv' dx = uv - \int u'v dx$

## Volume of Revolution

about x-axis:

• (with hollow area)  $V = \pi \int_a^b [f(x)]^2 - [g(x)]^2 dx$

• (about line  $y = k$ )  $V = \pi \int_a^b [f(x) - k]^2 dx$

# 04. SERIES

## Geometric Series

sum (divergent)	sum (convergent)
$\frac{a(1-r^n)}{1-r}$	$\frac{a}{1-r}$

## Power Series

power series about  $x = 0$

$$\sum_{n=0}^{\infty} c_n x^n = c_0 + c_1 x + c_2 x^2 + \dots$$

power series about  $x = a$  ( $a$  is the centre of the power

series)  $\sum_{n=0}^{\infty} c_n x^n = c_0 + c_1(x-a) + c_2(x-a)^2 + \dots$

## Taylor series

$$\sum_{k=0}^{\infty} \frac{f^{(k)}(a)}{k!} (x-a)^k$$

MacLaurin series:

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n$$

Taylor polynomial of  $f$  at  $a$ :

$$P_n(x) = \sum_{k=0}^n \frac{f^{(k)}(a)}{k!} (x-a)^k$$

## Radius of Convergence

power series converges where  $\lim_{n \rightarrow \infty} \left| \frac{u_{n+1}}{u_n} \right| < 1$

converge at	$R$	$\lim_{n \rightarrow \infty} \left  \frac{u_{n+1}}{u_n} \right $
$x = a$	0	$\infty$
$(x-h, x+h)$	$h, \frac{1}{N}$	$N \cdot  x-a $
all $x$	$\infty$	0

## MacLaurin Series

For  $-\infty < x < \infty$

$$\sin x = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n+1}}{(2n+1)!}$$

$$\cos x = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n}}{(2n)!}$$

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}$$

For  $-1 < x < 1$

$$\frac{1}{1-x} = \sum_{n=0}^{\infty} x^n$$

$$\frac{1}{1+x} = \sum_{n=0}^{\infty} (-1)^n x^n$$

$$\frac{1}{1+x^2} = \sum_{n=0}^{\infty} (-1)^n x^{2n}$$

$$\ln(1+x) = \sum_{n=1}^{\infty} \frac{(-1)^{n-1} x^n}{n}$$

$$\tan^{-1} x = \sum_{n=0}^{\infty} \frac{(-1)^n}{2n+1} x^{2n+1}$$

$$\frac{1}{(1+x)^2} = \sum_{n=1}^{\infty} (-1)^{n-1} n x^{n-1}$$

$$\frac{1}{(1-x)^2} = \sum_{n=1}^{\infty} n x^{n-1}$$

$$\frac{1}{(1-x)^3} = \frac{1}{2} \sum_{n=2}^{\infty} n(n-1) x^{n-2}$$

$$(1+x)^k = \sum_{n=0}^{\infty} \binom{k}{n} x^n = 1 + kx + \frac{k(k-1)}{2!} x^2 + \dots$$

## Differentiation/Integration

For  $f(x) = \sum_{n=0}^{\infty} c_n (x-a)^n$  and  $a-h < x < a+h$ ,

**differentiation** of power series:

$$f'(x) = \sum_{n=0}^{\infty} n c_n (x-a)^{n-1}$$

**integration** of power series:

$$\int f(x) dx = \sum_{n=0}^{\infty} c_n \frac{(x-a)^{n+1}}{n+1} + c$$

if  $R = \infty$ ,  $f(x)$  can be integrated to  $\int_0^1 f(x) dx$

# 05. VECTORS

## Dot (Scalar) product

$$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta$$

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \cdot \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = a_1 b_1 + a_2 b_2 + a_3 b_3$$

$\mathbf{a} \perp \mathbf{b} \Rightarrow \mathbf{a} \cdot \mathbf{b} = 0$	$\mathbf{a} \cdot \mathbf{b} > 0 : \mathbf{a}$ is acute
$\mathbf{a} \parallel \mathbf{b} \Rightarrow \mathbf{a} \cdot \mathbf{b} =  \mathbf{a}   \mathbf{b} $	$\mathbf{a} \cdot \mathbf{b} < 0 : \mathbf{a}$ is obtuse

## Cross (Vector) product

$$\mathbf{a} \times \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \sin \theta \hat{n}$$

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \times \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = \begin{pmatrix} a_2 b_3 - a_3 b_2 \\ -(a_1 b_3 - a_3 b_1) \\ a_1 b_2 - a_2 b_1 \end{pmatrix}$$

$\mathbf{a} \perp \mathbf{b} \Rightarrow \mathbf{a} \times \mathbf{b} =  \mathbf{a}   \mathbf{b} $	$\mathbf{a} \times \mathbf{b} = -(\mathbf{b} \times \mathbf{a})$
$\mathbf{a} \parallel \mathbf{b} \Rightarrow \mathbf{a} \times \mathbf{b} = 0$	$\lambda \mathbf{a} \times \mu \mathbf{b} = \lambda \mu (\mathbf{a} \times \mathbf{b})$

## Projection

$$|\vec{ON}| = |\mathbf{a} \cdot \hat{\mathbf{b}}| = \frac{|\mathbf{a} \cdot \mathbf{b}|}{|\mathbf{b}|}$$

$$\vec{ON} = (\mathbf{a} \cdot \hat{\mathbf{b}}) \hat{\mathbf{b}} = \frac{|\mathbf{a} \cdot \mathbf{b}|}{|\mathbf{b}|^2} \mathbf{b}$$

$$\Delta ANO = \frac{1}{2} |\vec{OA} \times \vec{ON}|$$

**Sphere:** Normal Vector: Passes through centre of sphere

## Planes

### Equation of a Plane

$\mathbf{n}$  is a perpendicular to the plane;  $A$  is a point on the plane.

- parametric:  $\mathbf{r} = \mathbf{a} + \lambda \mathbf{b} + \mu \mathbf{c}$
- scalar product:  $\mathbf{r} \cdot \mathbf{n} = \mathbf{a} \cdot \mathbf{n}$
- standard form:  $\mathbf{r} \cdot \hat{\mathbf{n}} = d$
- cartesian:  $\mathbf{ax} + \mathbf{by} + \mathbf{cz} = p$

Length of projection of  $\mathbf{a}$  on  $\mathbf{n} = |\mathbf{a} \cdot \hat{\mathbf{n}}| = \perp$  from  $O$  to  $\pi$

## Distance from a point to a plane

Shortest distance from a point  $S(x_0, y_0, z_0)$  to a plane

$\Pi : ax + by + c = d$  is given by:

$$\frac{|ax_0 + by_0 + cz_0 - d|}{\sqrt{a^2 + b^2 + c^2}}$$

# 06. PARTIAL DIFFERENTIATION

## Partial Derivatives

For  $f(x, y)$ , (some function of 2 variables)

first-order partial derivatives:	
$f_x = \frac{d}{dx} f(x, y)$	$f_y = \frac{d}{dy} f(x, y)$
second-order partial derivatives:	
$f_{xx} = (f_x)_x = \frac{d}{dx} f_x$	$f_{xy} = (f_x)_y = \frac{d}{dy} f_x$
$f_{yy} = (f_y)_y = \frac{d}{dy} f_y$	$f_{yx} = (f_y)_x = \frac{d}{dx} f_y$

## Chain Rule

For  $z(t) = f(x(t), y(t))$ ,

$$\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$$

For  $z(s, t) = f(x(s, t), y(s, t))$ ,

$$\frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t}$$

$$\frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s}$$

Directional Derivatives

The directional derivative of  $f$  at  $(a, b)$  in the direction of unit vector  $\hat{u} = u_1\hat{i} + u_2\hat{j}$  is

$D_u f(a, b) = f_x(a, b) \cdot u_1 + f_y(a, b) \cdot u_2$   
 $D_u f(a, b) = \nabla f(a, b) \cdot \hat{u}$   
(gradient vector . unit direction)

- geometric meaning:**  $D_u f(a, b)$  is the gradient of the tangent at  $(a, b)$  to curve  $C$  on a surface  $z = f(x, y)$ 
  - rate of change of  $f(x, y)$  at  $(a, b)$  in the direction of  $\mathbf{u}$

Gradient Vector

The **gradient** at  $f(x, y)$  is the vector  $\nabla f = f_x\hat{i} + f_y\hat{j} = (f_x, f_y)$

In Direction of  $\mathbf{u}$ :

$D_u f(a, b) = \nabla f(a, b) \cdot \hat{u}$   
 $= |\nabla f(a, b)| \cos \theta$

- $f$  increases most rapidly in the direction  $\nabla f(a, b)$
- $f$  decreases most rapidly in the direction  $-\nabla f(a, b)$
- largest possible value of  $D_u f(a, b) = |\nabla f(a, b)|$
- (occurs in the same direction as  $(f_x, f_y)$ )

Maximum & Minimum Values

$f(x, y)$  has a **local maximum** at  $(a, b)$  if  $f(x, y) \leq f(a, b)$  for all points  $(x, y)$  near  $(a, b)$ .  
 $f(x, y)$  has a **local minimum** at  $(a, b)$  if  $f(x, y) \geq f(a, b)$  for all points  $(x, y)$  near  $(a, b)$ .

Critical Points

- $f_x(a, b)$  or  $f_y(a, b)$  does not exist; OR
- $f_x(a, b) = 0$  and  $f_y(a, b) = 0$ 
  - $f_x(0, b) \leq 0$  - maximum point *along the x axis*
  - $f_y(a, 0) \geq 0$  - minimum point *along the y axis*

Saddle Points

- $f_x(a, b) = 0, f_y(a, b) = 0$
- neither a local minimum nor a local maximum

Second Derivative Test

Where  $f_x(a, b) = 0$  and  $f_y(a, b) = 0$ .

Discriminant D:

$D = f_{xx}(a, b)f_{yy}(a, b) - f_{xy}(a, b)^2$

$D$	$f_{xx}(a, b)$	local
+	+	min
+	-	max
-	any	saddle point
0	any	no conclusion

07. DOUBLE INTEGRALS

Let  $\Delta A_i$  be the area of  $R_i$  and  $(x_i, y_i)$  be a point on  $R_i$ .  
Let  $f(x, y)$  be a function of two variables. The **double integral** of  $f$  over  $R$  is

$$\iint_R f(x, y) dA = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i, y_i) \Delta A_i$$

Properties of Double Integrals

- $\iint_R (f(x, y) + g(x, y)) dA = \iint_R f(x, y) dA + \iint_R g(x, y) dA$
- $\iint_R cf(x, y) dA = c \iint_R f(x, y) dA$ , where  $c$  is a constant
- If  $f(x, y) \geq g(x, y)$  for all  $(x, y) \in \mathbb{R}$ , then  $\iint_R f(x, y) dA \geq \iint_R g(x, y) dA$
- If  $R = R_1 \cup R_2$ ,  $R_1$  and  $R_2$  do not overlap, then  $\iint_R f(x, y) dA = \iint_{R_1} f(x, y) dA + \iint_{R_2} f(x, y) dA$
- The area of  $R$ ,  $A(R) = \iint_R dA = \iint_R 1 dA$
- If  $m \leq f(x, y) \leq M$  for all  $(x, y) \in R$ , then  $m A(R) \leq \iint_R f(x, y) dA \leq M A(R)$

Rectangular Regions

For a rectangular region  $R$  in the  $xy$ -plane,  
 $a \leq x \leq b, \quad c \leq y \leq d$

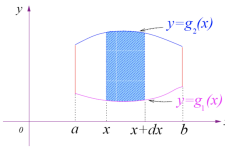
$$\iint_R f(x, y) dA = \int_c^d \left[ \int_a^b f(x, y) dx \right] dy$$
$$= \int_a^b \left[ \int_c^d f(x, y) dy \right] dx$$

If  $f(x, y) = g(x)h(y)$ , then

$$\iint_R g(x)h(y) dA = \left( \int_a^b g(x) dx \right) \left( \int_c^d h(y) dy \right)$$

General Regions

Type I: Integrate against complicated y first

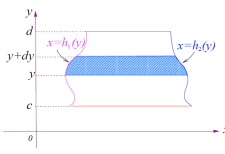


lower/upper bounds:  
 $g_1(x) \leq y \leq g_2(x)$   
  
left/right bounds:  
 $a \leq x \leq b$

The region  $R$  is given by

$$\iint_R f(x, y) dA = \int_a^b \left[ \int_{g_1(x)}^{g_2(x)} f(x, y) dy \right] dx$$

Type II: Integrate against complicated x first

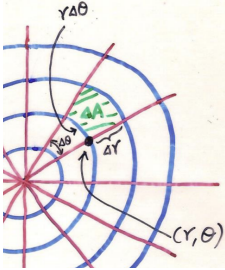


lower/upper bounds:  
 $c \leq y \leq d$   
  
left/right bounds:  
 $h_1(y) \leq x \leq h_2(y)$

The region  $R$  is given by

$$\iint_R f(x, y) dA = \int_c^d \left[ \int_{h_1(y)}^{h_2(y)} f(x, y) dx \right] dy$$

Polar Coordinates



$x = r \cos \theta$   
 $y = r \sin \theta$   
Hence,  $x^2 + y^2 = r^2$   
 $dx dy \Rightarrow r dr d\theta$

$$\Delta A \approx (r \Delta \theta)(\Delta r)$$
$$= r \Delta r \Delta \theta$$

$$dA = r dr d\theta$$

The region  $R$  is given by

$R : a \leq r \leq b, \alpha \leq \theta \leq \beta$

$$\iint_R f(x, y) dA = \int_\alpha^\beta \int_a^b f(r \cos \theta, r \sin \theta) r dr d\theta$$

Where,  $D = \{(r, \theta) \mid 0 \leq \theta \leq \dots, 0 \leq r \leq \dots\}$

Applications

Volume

Suppose  $D$  is a solid under the surface of  $z = f(x, y)$  over a plane region  $R$

Volume of  $D = \iint_R f(x, y) dA$

Surface Area

For area  $S$  of that portion of the surface  $z = f(x, y)$  that projects onto  $R$ ,

$$S = \iint_R \sqrt{\left(\frac{\partial z}{\partial x}\right)^2 + \left(\frac{\partial z}{\partial y}\right)^2 + 1} dA$$

08. ORDINARY DIFFERENTIAL EQUATIONS

- general solution:** solution containing arbitrary constants
- particular solution:** gives specific values to arbitrary constants
- the general solution of the  $n$ -th order DE will have  $n$  arbitrary constants

Separable Equations (dx/dy separable)

A first-order DE is **separable** if it can be written in the form  
 $M(x) - N(y)y' = 0$  or  $M(x)dx = N(y)dy$

Reductions to Separable Form

form	rec change of variable
$y' = g\left(\frac{y}{x}\right)$	set $v = \frac{y}{x}$ $\Rightarrow y' = v + xv'$
$y' = f(ax + by + c)$ $\Rightarrow y' = \frac{ax+by+c}{\alpha x + \beta y + \gamma}$	set $v = ax + by$ get eqn in terms of $v$ & $v'$
<b>Standard Form:</b> $y' + P(x)y = Q(x)$	$R = e^{\int P dx}$ $\Rightarrow y = \frac{1}{R} \int RQ dx$
<b>Bernoulli Equation:</b> $y' + P(x)y = Q(x)y^n$	set $z = y^{1-n}$ sub $z$ and $z'$ obtain eqn $\Rightarrow y' = \frac{y^n}{1-n} z'$ $R = e^{\int P dx}$ $\Rightarrow z = \frac{1}{R} \int RQ dx$

Population Models

$N$ - number; $B$ - birth rate; $t$ - time; $D$ - death rate	
<b>Logistic Model</b> $N = \frac{N_{t=\infty}}{1 + (\frac{N_{t=\infty}}{N_{t=0}} - 1)e^{-Bt}}$	<b>Malthus Model</b> $N(t) = N_0 e^{kt}$ where $k = B - D$

Common Scenarios: Uranium decays into Thorium

amount of uranium, $U(t) = U_0 e^{-k_U t}$ $\frac{dU}{dt} = -k_U U$	amount of thorium, $T(t) = \frac{k_U U_0}{k_T - k_U} (e^{-k_U t} - e^{-k_T t})$ $\frac{dT}{dt} = k_U U - k_T T$
decay rate constant, $k = \frac{\ln 2}{t_{1/2}}$	ratio of thorium to uranium, $\frac{T}{U} = \frac{k_U}{k_T - k_U} (1 - e^{-(k_T - k_U)t})$

<b>Radioactive decay</b> $Q(t) = Q_0 e^{-kt}$ $k = \frac{\ln 2}{t_{1/2}}$	<b>Cooling/Heating</b> $\frac{dT}{dt} = k(T - T_{env})$ $\frac{1}{T - T_{env}} dT = k dt$
<b>Falling objects (N2L)</b> Resistance = $bv^2$ $m \frac{dv}{dt} = mg - bv^2$ Let $k = \sqrt{\frac{mg}{b}}$ $\Rightarrow \frac{1}{v^2 - k^2} dv = -\frac{b}{m} dt$	<b>Resistive medium</b> Resistance = $kv$ $m \frac{dv}{dt} = mg - kv$ $v' + \frac{k}{m} v = g$ (linear)
<b>Concentration of salt in liquid</b> Let $R$ = rate of flow (in and out), $Q$ = total amount of salt, $V$ = total volume, $C_{in}$ = concentration of inflow Rate of flow, $\frac{dQ}{dt} = RC_{in} - \frac{R}{V} Q$ $\Rightarrow Q' + \frac{R}{V} Q = RC_{in}$	