## MA1521

AY22/23 Sem 2

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## 01. FUNCTIONS & LIMITS

## **Rules of Limits**

- 1.  $\lim_{x \to a} (f \pm g)(x) = L \pm L'$
- $2. \lim_{n \to \infty} (fg)(x) = LL'$
- 3.  $\lim_{x \to a} \frac{f}{g}(x) = \frac{L}{L'}$ , provided  $L' \neq 0$
- 4.  $\lim_{x \to \infty} kf(x) = kL$  for any real number k.

## 02. DIFFERENTIATION

extreme values:

- f'(x) = 0
- f'(x) does not exist
- end points of the domain of f

parametric differentiaton:  $\frac{d^2y}{dx^2} = \frac{d}{dx}(\frac{dy}{dx}) = \frac{\frac{d}{dt}(\frac{dy}{dx})}{\frac{dx}{dx}}$ 

## Differentiation Techniques

f(x)	f'(x)
$\tan x$	$\sec^2 x$
$\csc x$	$-\csc x \cot x$
$\sec x$	$\sec x \tan x$
$\cot x$	$-\csc^2 x$
$a^{f(x)}$	$\ln a \cdot f'(x) a^{f(x)}$
$\log_a f(x)$	$\log_a e \cdot \frac{f'(x)}{f(x)}$
$\sin^{-1} f(x)$	$\frac{f'(x)}{\sqrt{1 - [f(x)]^2}},  f(x)  < 1$
$\cos^{-1} f(x)$	$-\frac{f'(x)}{\sqrt{1-[f(x)]^2}},  f(x)  < 1$
$\tan^{-1} f(x)$	$\frac{f'(x)}{1+[f(x)]^2}$
$\cot^{-1} f(x)$	$-\frac{f'(x)}{1+[f(x)]^2}$
$\sec^{-1} f(x)$	$\frac{f'(x)}{ f(x) \sqrt{[f(x)]^2 - 1}}$
$\csc^{-1} f(x)$	$-\frac{f'(x)}{ f(x) \sqrt{[f(x)]^2-1}}$

## L'Hopital's Rule

$$\lim_{x \to x_0} \frac{f(x)}{g(x)} = \lim_{x \to x_0} \frac{f'(x)}{g'(x)}$$

- for indeterminate forms  $(\frac{0}{0} \text{ or } \frac{\infty}{\infty})$ , cannot directly substitute x = a.
- for other forms: convert to  $(\frac{0}{0} \text{ or } \frac{\infty}{\infty})$  then apply L'Hopital's
- for exponents: use  $\ln$ , then sub into  $e^{f(x)}$

### 03. INTEGRATION

## **Integration Techniques**

f(x)	$\int f(x)$
$\tan x$	$\ln(\sec x),  x  < \frac{\pi}{2}$
$\cot x$	$\ln(\sin x), {\scriptscriptstyle 0} < {\scriptscriptstyle x} < {\scriptscriptstyle \pi}$
$\csc x$	$-\ln(\csc x + \cot x),  0 < x < \pi$
$\sec x$	$\ln(\sec x + \tan x),  x  < \frac{\pi}{2}$
$ \begin{array}{c} \frac{1}{x^2 + a^2} \\ 1 \end{array} $	$\frac{1}{a} \tan^{-1} \left( \frac{x}{a} \right)$ $\sin^{-1} \left( \frac{x}{a} \right),  x  < a$
$\frac{\sqrt{a^2 - x^2}}{\frac{1}{x^2 - a^2}}$	$\frac{1}{2a}\ln(\frac{x-a}{x+a}), x>a$
$\frac{1}{a^2 - x^2}$	$\frac{1}{2a}\ln(\frac{x+a}{x-a}), x < a$
$a^x$	$\frac{a^x}{\ln a}$

$$\frac{d}{dx} \int_a^x f(t) dt = f(x)$$

- indefinite integral the integral of the function without any limits
- antiderivative any function whose derivative will be the same as the original function

substitution:  $\int_a^b f(g(x))g'(x)dx = \int_{g(a)}^{g(b)} f(u)du$ by parts:  $\int uv' dx = uv - \int u'v dx$ 

## Volume of Revolution

about x-axis:

- (with hollow area)  $V = \pi \int_a^b [f(x)]^2 [g(x)]^2 dx$
- (about line y = k)  $V = \pi \int_{a}^{b} [f(x) k]^{2} dx$

## 04. SERIES

### **Geometric Series**

sum (divergent)		
$a(1-r^n)$		
1-r		

sum (convergent)

### **Power Series**

power series about x = 0

$$\sum_{n=0}^{\infty} c_n x^n = c_0 + c_1 x + c_2 x^2 + \dots$$

power series about x = a (a is the centre of the power series)  $\sum_{n=0}^{\infty} c_n x^n = c_0 + c_1(x-a) + c_2(x-a)^2 + \dots$ 

## Taylor series

$$\sum_{k=0}^{\infty} \frac{f^k(a)}{k!} (x-a)^k$$

 $f(x) = \sum_{n=0}^{\infty} \frac{f^n(0)}{n!} x^n$ 

Taylor polynomial of f at a:

$$P_n(x) = \sum_{k=0}^{n} \frac{f^k(a)}{k!} (x-a)^k$$

### **Radius of Convergence**

power series converges where  $\lim_{n\to\infty} \left|\frac{u_{n+1}}{u_n}\right| < 1$ 

converge at	R	$\lim_{n \to \infty} \left  \frac{u_{n+1}}{u_n} \right $
x = a	0	$\infty$
(x-h,x+h)	$h, \frac{1}{N}$	$N \cdot  x-a $
all $x$	$\infty$	0

#### MacLaurin Series

For 
$$-\infty < x < \infty$$

$$\sin x = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n+1}}{(2n+1)!}$$

$$\cos x = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n}}{(2n)!}$$

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}$$
For  $-1 < x < 1$ 

$$\frac{1}{1-x} = \sum_{n=0}^{\infty} x^n$$

$$\frac{1}{1+x} = \sum_{n=0}^{\infty} (-1)^n x^n$$

$$\frac{1}{1+x^2} = \sum_{n=0}^{\infty} (-1)^n x^{2n}$$

$$\ln(1+x) = \sum_{n=1}^{\infty} \frac{(-1)^{n-1} x^n}{n}$$

$$\tan^{-1} x = \sum_{n=0}^{\infty} \frac{(-1)^n}{2n+1} x^{2n+1}$$

$$\frac{1}{(1+x)^2} = \sum_{n=1}^{\infty} (-1)^{n-1} n x^{n-1}$$

$$\frac{1}{(1-x)^2} = \sum_{n=1}^{\infty} n x^{n-1}$$

$$\frac{1}{(1-x)^3} = \frac{1}{2} \sum_{n=2}^{\infty} n (n-1) x^{n-2}$$

$$(1+x)^k = \sum_{n=0}^{\infty} \binom{k}{n} x^n$$

$$= 1 + kx + \frac{k(k-1)}{2!} x^2 + \dots$$

## Differentiation/Integration

For 
$$f(x) = \sum\limits_{n=0}^{\infty} c_n (x-a)^n$$
 and  $a-h < x < a+h$ , differentiation of power series:

$$f'(x) = \sum_{n=0}^{\infty} nc_n (x-a)^{n-1}$$

$$\int f(x)dx = \sum_{0}^{\infty} c_n \frac{(x-1)^{n+1}}{n+1} + c$$

if  $R = \infty$ , f(x) can be integrated to  $\int_0^1 f(x)dx$ 

## 05. VECTORS

unit vector,  $\hat{\boldsymbol{p}} = \frac{\boldsymbol{p}}{|\boldsymbol{p}|}$ 



ratio theorem  $p = \frac{\mu a + \lambda b}{\lambda + \mu}$ 

midpoint theorem

### Dot (Scalar) product

$$\begin{aligned} & \boldsymbol{a} \cdot \boldsymbol{b} = |\boldsymbol{a}||\boldsymbol{b}|\cos\theta \\ & \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \cdot \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = a_1b_1 + a_2b_2 + a_3b_3 \\ & \boldsymbol{a} \perp \boldsymbol{b} \Rightarrow \boldsymbol{a} \cdot \boldsymbol{b} = 0 \\ & \boldsymbol{a} \parallel \boldsymbol{b} \Rightarrow \boldsymbol{a} \cdot \boldsymbol{b} = |\boldsymbol{a}||\boldsymbol{b}| \\ & \boldsymbol{a} \cdot \boldsymbol{b} < 0 : \boldsymbol{a} \text{ is acute} \end{aligned}$$

## Cross (Vector) product

$$\begin{aligned} \boldsymbol{a} \times \boldsymbol{b} &= |\boldsymbol{a}| |\boldsymbol{b}| \sin \theta \hat{\boldsymbol{n}} \\ \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \times \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} &= \begin{pmatrix} a_2b_3 - a_3b_2 \\ -(a_1b_3 - a_3b_1) \\ a_1b_2 - a_2b_1 \end{pmatrix} \\ \boldsymbol{a} \perp \boldsymbol{b} &\Rightarrow \boldsymbol{a} \times \boldsymbol{b} &= |\boldsymbol{a}| |\boldsymbol{b}| \\ \boldsymbol{a} \parallel \boldsymbol{b} &\Rightarrow \boldsymbol{a} \times \boldsymbol{b} &= 0 \\ & \lambda \boldsymbol{a} \times \mu \boldsymbol{b} &= \lambda \mu (\boldsymbol{a} \times \boldsymbol{b}) \end{aligned}$$

### Projection



Sphere: Normal Vector: Passes through centre of sphere

#### **Planes**

### **Equation of a Plane**

n is a perpendicular to the plane; A is a point on the plane.

- parametric:  $r = a + \lambda b + \mu c$
- scalar product:  $r \cdot n = a \cdot n$
- standard form:  $\mathbf{r} \cdot \hat{\mathbf{n}} = d$
- cartesian: ax + by + cz = p

Length of projection of  $\boldsymbol{a}$  on  $\boldsymbol{n} = |\boldsymbol{a} \cdot \hat{\boldsymbol{n}}| = \perp$  from O to  $\pi$ 

## Distance from a point to a plane

Shortest distance from a point  $S(x_0, y_0, z_0)$  to a plane  $\Pi: ax + by + c = d$  is given by:  $\frac{|ax_0 + by_0 + cz_0 - d|}{\sqrt{a^2 + b^2 + c^2}}$ 

## 06. PARTIAL DIFFERENTIATION

## **Partial Derivatives**

For f(x, y), (some function of 2 variables)

$$\begin{array}{c|c} \text{first-order partial derivatives:} \\ f_x = \frac{d}{dx} f(x,y) & f_y = \frac{d}{dy} f(x,y) \\ \text{second-order partial derivatives:} \end{array}$$

$$f_{xx} = (f_x)_x = \frac{d}{dx} f_x$$

$$f_{yy} = (f_y)_y = \frac{d}{dy} f_y$$

$$f_{yx} = (f_y)_x = \frac{d}{dy} f_x$$

$$f_{yx} = (f_y)_x = \frac{d}{dy} f_x$$

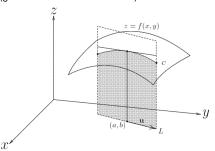
### Chain Rule

$$\begin{aligned} & \text{For } z(t) = f(x(t),y(t)), \\ & \frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt} \\ & \text{For } z(s,t) = f\left(x(s,t),y(s,t)\right), \\ & \frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t} \\ & \frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s} \end{aligned}$$

## **Directional Derivatives**

The directional derivative of f at (a, b) in the direction of unit vector  $\hat{\boldsymbol{u}} = u_1 \boldsymbol{i} + u_2 \boldsymbol{j}$  is

$$\begin{aligned} D_u f(a,b) &= f_x(a,b) \cdot u_1 + f_y(a,b) \cdot u_2 \\ D_u f(a,b) &= \nabla f(a,b) \cdot \hat{\boldsymbol{u}} \\ \text{(gradient vector . unit direction)} \end{aligned}$$



- geometric meaning:  $D_u f(a, b)$  is the gradient of the tangent at (a, b) to curve C on a surface z = f(x, y)
  - rate of change of f(x, y) at (a, b) in the direction of u

#### **Gradient Vector**

The **gradient** at f(x, y) is the vector  $\nabla f = f_x \mathbf{i} + f_y \mathbf{j} = (f_x, f_y)$ 

#### In Direction of u:

$$D_u f(a, b) = \nabla f(a, b) \cdot \hat{\boldsymbol{u}}$$
  
=  $|\nabla f(a, b)| \cos \theta$ 

- f increases most rapidly in the direction  $\nabla f(a,b)$
- f decreases most rapidly in the direction  $-\nabla f(a,b)$
- largest possible value of  $D_u f(a,b) = |\nabla f(a,b)|$
- (occurs in the same direction as  $(f_x, f_y)$ )

#### **Physical Meaning**

Suppose a point p moves a small distance  $\Delta t$  along a unit vector  $\hat{\boldsymbol{u}}$  to a new point  $\boldsymbol{q}$ .



increment in f,  $\Delta f \approx D_u f(\mathbf{p})(\Delta t)$ 

## Maximum & Minimum Values

f(x,y) has a **local maximum** at (a,b) if  $f(x,y) \leq f(a,b)$ for all points (x, y) near (a, b). f(x,y) has a **local minimum** at (a,b) if f(x,y) > f(a,b)for all points (x, y) near (a, b).

#### **Critical Points**

- $f_x(a,b)$  or  $f_y(a,b)$  does not exist; OR
- $f_x(a,b) = 0$  and  $f_y(a,b) = 0$ 
  - $f_x(0,b) \le 0$  maximum point along the x axis
- $f_u(a,0) > 0$  minimum point along the y axis

#### **Saddle Points**

•  $f_x(a,b) = 0, f_y(a,b) = 0$ 

· neither a local minimum nor a local maximum

#### **Second Derivative Test**

Where  $f_x(a,b) = 0$  and  $f_y(a,b) = 0$ .

Discriminant D:

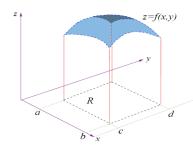
### 07. DOUBLE INTEGRALS

Let  $\Delta A_i$  be the area of  $R_i$  and  $(x_i, y_i)$  be a point on  $R_i$ . Let f(x, y) be a function of two variables. The **double** integral of f over R is

$$\iint_{R} f(x,y)dA = \lim_{n \to \infty} \sum_{i=1}^{n} f(x_{i}, y_{i}) \Delta A_{i}$$

## **Geometric Meaning**

 $\iint_{B} f(x,y)dA$  is the volume under the surface z=f(x,y) and above the xy-plane over the region R.



## **Properties of Double Integrals**

- 1.  $\iint_{\mathcal{B}} (f(x,y) + g(x,y)) dA$  $=\iint_R f(x,y)dA + \iint_R g(x,y)dA$
- 2.  $\iint_R cf(x,y)dA = c\iint_R f(x,y)dA$ , where c is a
- 3. If  $f(x,y) \geq g(x,y)$  for all  $(x,y) \in \mathbb{R}$ , then
- $\iint_R f(x,y)dA \geq \iint_R g(x,y)dA$  4. If  $R=R1\cup R2,\,R1$  and R2 do not overlap, then  $\iint_{B} f(x,y)dA = \iint_{B_1} f(x,y)dA + \iint_{B_2} f(x,y)dA$
- 5. The area of R,
- $A(R)=\iint_R dA=\iint_R 1dA$  6. If  $m\leq f(x,y)\leq M$  for all  $(x,y)\in R$  , then
- $mA(R) \le \iint_R f(x,y) dA \le MA(R)$

## **Rectangular Regions**

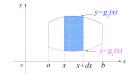
For a rectangular region R in the xy-plane, a < x < b, c < y < d

$$\iint_{R} f(x,y)dA = \int_{c}^{d} \left[ \int_{a}^{b} f(x,y)dx \right] dy$$
$$= \int_{a}^{b} \left[ \int_{c}^{d} f(x,y)dy \right] dx$$

If 
$$f(x,y) = g(x)h(y)$$
, then 
$$\iint_{\mathcal{B}} g(x)h(y)dA = \left(\int_{-a}^{b} g(x)dx\right)\left(\int_{-a}^{d} h(y)dy\right)$$

### **General Regions**

### Type I: Integrate against complicated y first



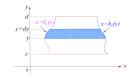
lower/upper bounds:  $g_1(x) \le y \le g_2(x)$ 

> left/right bounds:  $a \le x \le b$

The region R is given by

$$\iint_{R} f(x,y)dA = \int_{a}^{b} \left[ \int_{g_{1}(x)}^{g_{2}(x)} f(x,y)dy \right] dx$$

### Type II: Integrate against complicated x first

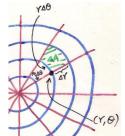


lower/upper bounds:  $c \le y \le d$ 

left/right bounds:  $h_1(y) \le x \le h_2(y)$ 

The region R is given by  $\iint_{R} f(x,y)dA = \int_{0}^{d} \left[ \int_{h_{1}(x)}^{h_{2}(y)} f(x,y)dx \right] dy$ 

### **Polar Coordinates**



 $x = r \cos \theta$  $y = r \sin \theta$ Hence,  $x^2 + y^2 = r^2$  $dxdy \Rightarrow rdrd\theta$ 

$$\Delta A \approx (r\Delta\theta)(\Delta r)$$
$$= r\Delta r\Delta\theta$$
$$dA = rdrd\theta$$

The region R is given by

$$R: a \leq r \leq b, \ \alpha \leq \theta \leq \beta$$
 
$$\iint_{R} f(x,y) dA = \int_{\alpha}^{\beta} \int_{a}^{b} f(r\cos\theta, r\sin\theta) r \ dr d\theta$$

Where, 
$$D = \{(r, \theta) \mid 0 \le \theta \le ..., 0 \le r \le ...\}$$

## **Applications**

#### Volume

Suppose D is a solid under the surface of z = f(x, y)over a plane region R

Volume of 
$$D = \iint_R f(x, y) dA$$

#### Surface Area

For area S of that portion of the surface z = f(x, y)that projects onto R,

$$S = \iint_{R} \sqrt{\left(\frac{\partial z}{\partial x}\right)^{2} + \left(\frac{\partial z}{\partial y}\right)^{2} + 1} dA$$

## 08. ORDINARY DIFFERENTIAL **EQUATIONS**

- general solution: solution containing arbitrary constants
- · particular solution: gives specific values to arbitrary
- the general solution of the n-th order DE will have narbitrary constants

## Separable Equations (dx/dy separable)

A first-order DE is separable if it can be written in the form M(x) - N(y)y' = 0 or M(x)dx = N(y)dy

### **Reductions to Separable Form**

form	rec change of variable
$y' = g(\frac{y}{x})$	$ set v = \frac{y}{x} \\ \Rightarrow y' = v + xv' $
y' = f(ax + by + c) $\Rightarrow y' = \frac{ax + by + c}{\alpha x + \beta y + \gamma}$	
Standard Form: $y' + P(x)y = Q(x)$	$R = e^{\int P dx}$ $\Rightarrow y = \frac{1}{R} \int RQ dx$
Bernoulli Equation: $y' + P(x)y = Q(x)y^n$	set $z = y^{1-n}$ sub $z$ and $z'$ obtain eqn $\Rightarrow y' = \frac{y^n}{1-n}z'$ $R = e^{\int P dz}$
	$\Rightarrow z = \frac{1}{R} \int RQdx$

## **Population Models**

N - number; B - birth rate; t - time; D - death rate

Logistic Model
$$N = \frac{N_{t=\infty}}{1 + (N_{t=\infty} - 1) - Bt}$$

**Malthus Model**  $N(t) = N_0 e^{kt}$ where k = B - D

## Common Scenarios: Uranium decays into Thorium

amount of uranium,  $U(t) = U_0 e^{-k_U t}$ 

$$\frac{dU}{dt} = -k_U U$$
amount of thorium,

 $T(t) = \frac{k_U U_0}{k_T - k_U} (e^{-k_U t} - e^{-k_T t})$  $\frac{d\vec{T}}{dt} = k_U U - k_T T$ 

decay rate constant,  $k = \frac{\ln 2}{t_{1/2}}$ 

ratio of thorium to uranium,  $\frac{k_U}{t}$   $(1 - e^{-(k_T - k_U)t})$ 

Cooling/Heating

# Radioactive decay

 $Q(t) = Q_0 e^{-kt}$ 

Falling objects (N2L)

Resistance =  $bv^2$  $m\frac{dv}{dt} = mg - bv^2$ Let  $k = \sqrt{\frac{mg}{h}}$ 

 $\Rightarrow \frac{1}{v^2 - k^2} dv = -\frac{b}{m} dt$ 

Resistive medium Resistance = kv

 $m\frac{dv}{dt} = mg - kv$  $v' + \frac{k}{m}v = g$  (linear)

 $\frac{dT}{dt} = k(T - T_{env})$ 

 $\frac{1}{T - T_{env}} dT = kdt$ 

### Concentration of salt in liquid

Let R = rate of flow (in and out), Q = total amount of salt, V = total volume,  $C_{in}$  = concentration of inflow

Rate of flow, 
$$\frac{dQ}{dt} = RC_{in} - \frac{R}{V}Q$$
  
 $\Rightarrow Q' + \frac{R}{V}Q = RC_{in}$