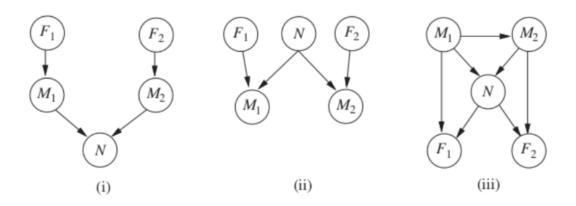
| Name: | ID: |
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1. (14 points) Two astronomers are making measurements M₁ and M₂ of the number of stars N in a small region of sky using telescopes. The measurements are noisy, so there is a probability of e that the measurements are off by ±1. Besides this, the telescope might be out of focus with probability f (F_i = true means the i-th astronomers telescope is out of focus, i = 1,2). If it is out of focus, then the measurement will undercount N by at least 3 (or if N < 3, then M_i will just be 0). Consider the following.



a. (2 points) Which is the best network? Explain. (Hint: Accuracy and efficiency)

| Best network: Reason: | | | |
|--------------------------|--|--|--|
| | | | |
| | | | |

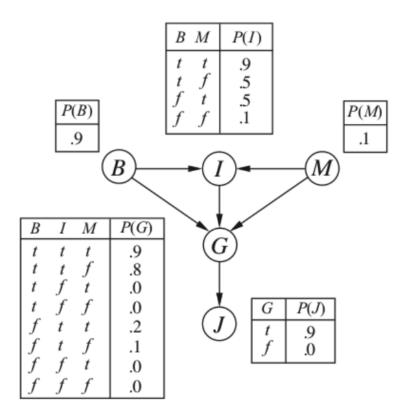
b. (9 points) Assuming using network (ii), and $N \in \{1,2,3\}$ and $M_1 \in \{0,1,2,3,4\}$, write out the conditional distribution for $P(M_1|N)$ in terms of e and f. (Fill the blanks and equation)

| $P(M_1 N)$ | $= P(M_1 N, F_1)P($ |) + P(| $)P(\neg F_1 N)$ |
|------------|--------------------------|---------------|------------------|
| = P(| $)P(F_{1}) + P(M_{1} N)$ | $\neg F_1)P($ |) |

| $P(M_1 N)$ | N = 1 | N = 2 | N = 3 |
|-------------|-------|-------|-------|
| $M_1 = 0$ | | | |
| $M_1 = 1$ | | | |
| $M_{1} = 2$ | | | |
| $M_{1} = 3$ | | | |
| $M_1 = 4$ | | | |

| C. | (3 points) Suppose $M_1 = 1$ and $M_2 = 3$, and assume no prior constraint on N. What are |
|----|--|
| | the possible numbers that N can be? Why? (Hint: fix M1 = 1, M2 = 3, try each possibility |
| | of F1, F2 and get all possible values of N.) |

2. (6 points) Consider this figure for the next problem.



a. (3 points) Which of the following (if any) are asserted by the network structure (ignoring the conditional probability tables)? (Hint: Write "Yes" or "No" following each equation)

$$P(B, I, M) = P(B)P(I)P(M);$$

 $P(J, G) = P(J|G, I);$
 $P(M|G, B, I) = P(M|G, B, I, J);$

b. (3 points) Calculate the value of $P(b, i, m, \neg g, j)$. (Fill the blanks and compute the result)

$$P(b, i, m, \neg g, j) = P()P(m)P(i|b, m)P()P(j|\neg g) =$$