Name	:	ID:	
1.		of BFS and DFS are $O(b^d)$ and $O(bd)$ hing factor and d is the search depth. Why is and the other not?	i
2.	• •	mong BFS, DFS, and uniform-cost search to their implementations in the generic tree ctures)	
3.	, , ,	nplexity of uniform cost search, in terms of the edges? (b) What is the key assumption that rm cost search?	

4.	search		uniform co									-	pecial case of uniform cost of A*. Under what
5.	cells so	•	resulting b		_						-	-	er tries to fill in all blank h row, each column, and
				5	3			7					
				6			1	9	5	Н		-	
				۳	9	8	Ť				6		
				8			Н	6			Ū	3	
				4			8	Ť	3	Н		1	
				7				2				6	
					6		П			2	8		
				Г			4	1	9			5	
				Г				8			7	9	
													I
										-			n. What are the state path costs?
	h	(2 points)	Agguera				inf-					<u> </u>	Main mathed would you

b. (2 points) Assume we use uninformed search. Which method would you prefer? Why?

	(2 points) Is a good heuristic possible in this case? If so, provide one. If not, why not?
wants to side to and he goose, eaten. I a. (ts) Consider the classic farmer, fox, goose, and grain problem. The farmer o move himself, the fox, the goose, and the edible grain from the west the east side of the river. Only he can row his small boat across the river, can only take one of his items with him at a time. If the fox is left with the the goose will be eaten. If the goose is left with the grain, the grain will be it turns out that you can pose this as a graph search problem. (2 points) Describe a representation of the state space for this problem. What would the start state and goal state look like in this representation?
h	(2 points) What are the possible actions at a particular state?

Э.	(2 points) Our goal is to get everything to the other side in one piece, so what are the constraints on the state space that we need for the actions in part b?
d.	(2 points) Suppose we want to use A* here. Describe a non-trivial admissible heuristic that we could use. Why admissible?