# CONOR MESSER

16 Winchester St., Brookline, MA conorsmesser@gmail.com | linkedin.com/in/conormesser

#### **EDUCATION**

#### Bachelor of Science in Bioengineering, summa cum laude May 2019 Northeastern University Boston, MA

Minors: Computer Science and Vocal Performance

#### **FELLOWSHIPS**

2019 - 2020**Fulbright Fellowship** 

Awarded by U.S. Department of State to perform research and promote cultural exchange Abu Dhabi, UAE

National Science Foundation Research Experience for Undergraduates

Summer 2015 REU award to perform research at University of Colorado Boulder, CO

#### **PUBLICATIONS**

Renda F, Messer C, Rucker C, & Boyer F (2021). A Sliding-rod Variable-strain Model for Concentric Tube Robots. IEEE Robotics and Automation Letters, 6(2), 3451-3458.

Al falahi H, Renda F, Messer C, & Stefanini C (2021). Taming the Instability of Concentric Tube Robots for Distal Force Control in Minimally Invasive Cardiac Ablation. Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science, 235(23), 7212-7232.

Zareian R, Susilo M, Paten J, McLean J, Hollmann J, Karamichos D, Messer C, Tambe D, Saeidi N, Zieske J, & Ruberti J (2016). Human Corneal Fibroblast Pattern Evolution and Matrix Synthesis on Mechanically Biased Substrates. Tissue engineering. Part A, 22(19-20), 1204–1217.

#### RESEARCH EXPERIENCE

#### Associate Computational Biologist I

Sep 2020 - Present

Broad Institute of MIT and Harvard

Cambridge, MA

- · Analyze genomic and proteomic data for multiple cancer drug resistance projects using established pipelines
- · Develop and maintain state-of-the-art computational tools for identifying genomic copy number alterations and recurrent mutations

#### **Fulbright Scholar**

**Research Assistant** 

August 2019 – June 2020

Khalifa University of Science and Technology

Abu Dhabi, United Arab Emirates

- · Developed optimization and path planning algorithm in Python for the design of concentric tube surgical robot
- Integrated multiple libraries (collision-detection, dynamic KD-tree, optimization) with novel sampling-based planner and kinematic model to explore design possibilities

#### Visiting Research Intern - REU

June 2015 – August 2015

Biomaterials and Functional Tissue Engineering Lab, University of Colorado

Boulder, CO

Boston, MA

- Characterized electrospun hydrogels for tissue scaffolding with guidance from a post-doctoral mentor
- Developed multi-variable study to investigate factors contributing to fiber size and density

Extracellular Matrix Engineering Research Lab, Northeastern University

January 2015 – June 2015

· Compared growth and alignment of 200 image pairs of corneal cells to discover effects of stress on growth

Analyzed data in MATLAB to give lab decisive results and visualizations for publication in Tissue Engineering

### PROFESSIONAL EXPERIENCE

## Research Engineer Co-op

July 2018 – December 2018

Liberating Technologies Inc.

Boston, MA

- · Designed and tested prototype orthotic device using 3D printing, thermoform plastics, textiles, and hardware
- Wrote MATLAB algorithms to process and analyze gait data for balance characterization of prosthetic feet

### Hardware Engineer

January 2018 – June 2018

Robotics and Intelligent Vehicles Research Lab, Northeastern University

Boston, MA

- Developed intuitive control of a prosthetic hand through high-level human intent and ambient intelligence
- Built Arduino prototype circuit and produced data for existing motion tracking algorithm in ROS architecture

#### **Biomechanical Engineering Co-op**

July 2016 – December 2016

Stryker Trauma GmbH

Kiel, Germany

- Designed test setups using bone models in PTC Creo Parametric and constructed the test setups in the lab
- Ran mechanical fatigue tests of intramedullary nails using custom test setups and ran statistics on results

#### HONORS AND AWARDS

Distinguished Bioengineering Scholar Award	Spring 2019
Northeastern University award for top three Bioengineering students	
Sears B. Condit Award Top 100 GPA of graduating seniors at Northeastern University	Spring 2019
<b>Huntington 100</b> Top 100 undergraduate and graduate students at Northeastern University	Spring 2018
Presidential Global Scholars Program  Merit based scholarship supporting global co-op experience	Fall 2016
Northeastern University Scholar Merit based scholarship program, awarded to $\sim$ 3% of incoming class	Fall 2014
Presentations	
Developing Non-Constant Curvature Concentric Tube Robots For Use in MIS Middle East and North Africa Fulbright Enrichment Seminar	February 2020
Hand Exoskeleton to Study Motor Control in Reach to Grasp Motions Northeastern Bioengineering Capstone Presentation	April 2020
Preparation and Characterization of Electrospun Photoclickable Thiol-ene Hydro University of Colorado REU Conference	ogels August 2015
TEACHING EXPERIENCE	
ACT/SAT Test Prep Teacher	August 2017 – March 2019

ACT/SAT Test Prep Teacher	August 2017 – March 2019
Kaplan Test Prep	Boston, MA
<b>Bioengineering Tutor</b>	January 2016 – April 2018
Northeastern University	Boston, MA