

50.007

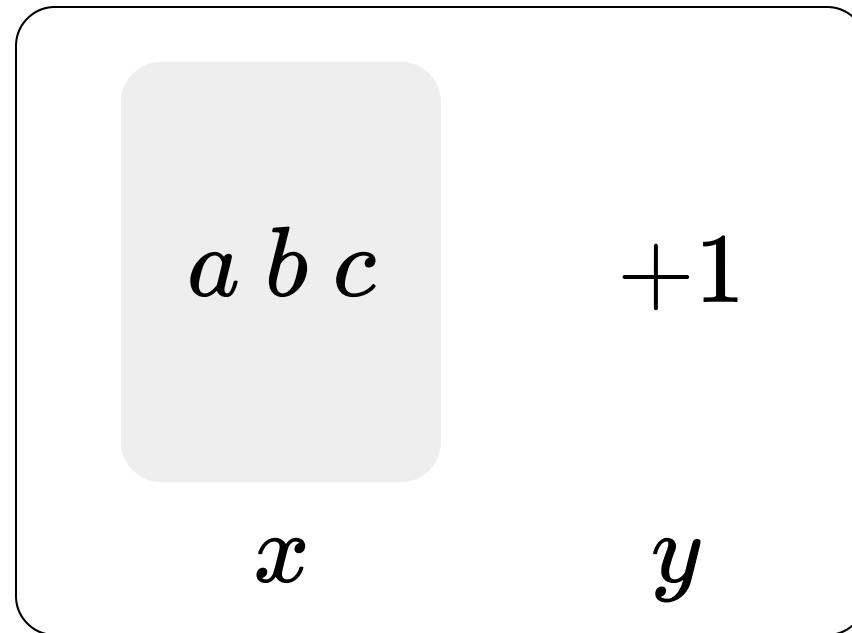
Machine Learning

Lu, Wei

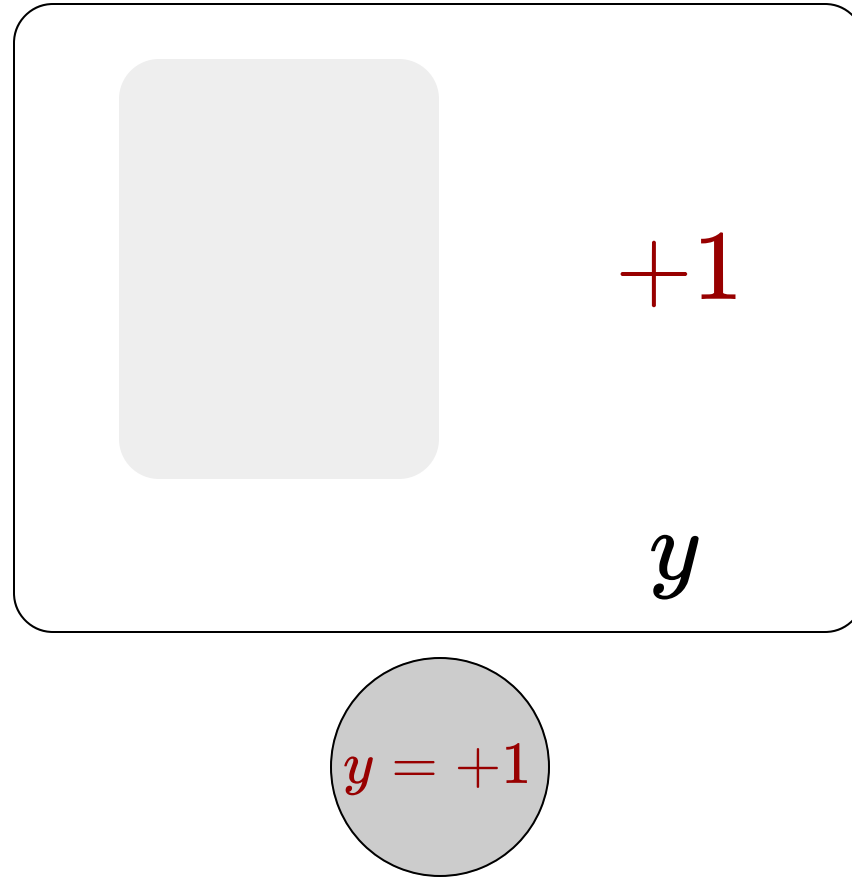


Hidden Markov Model (I)

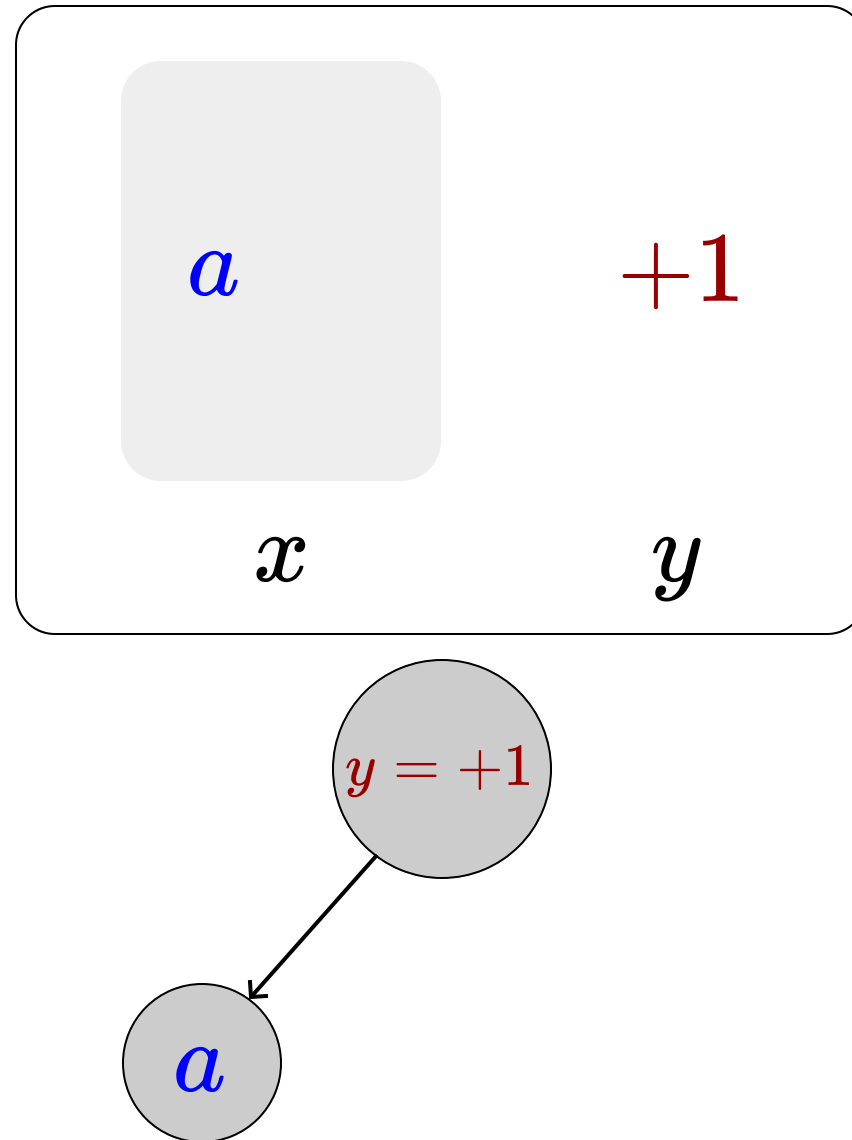
Generative Models



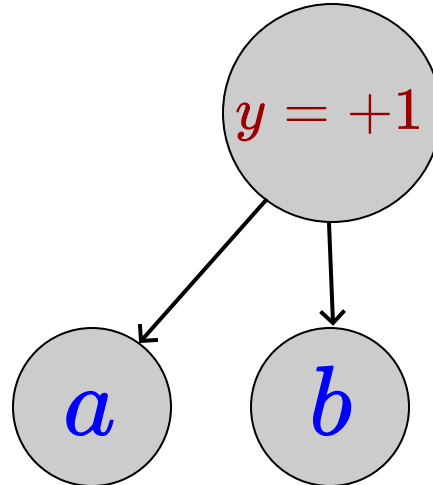
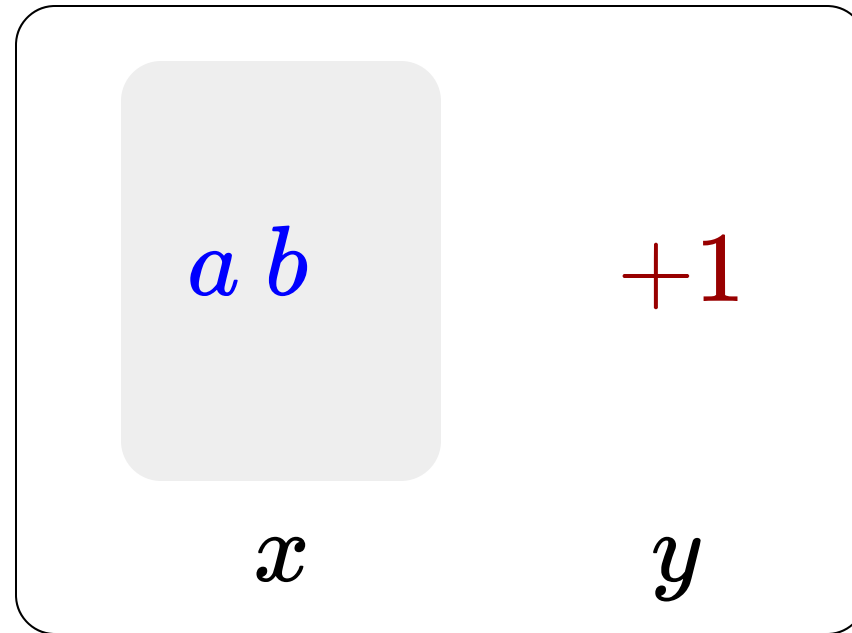
Generative Models



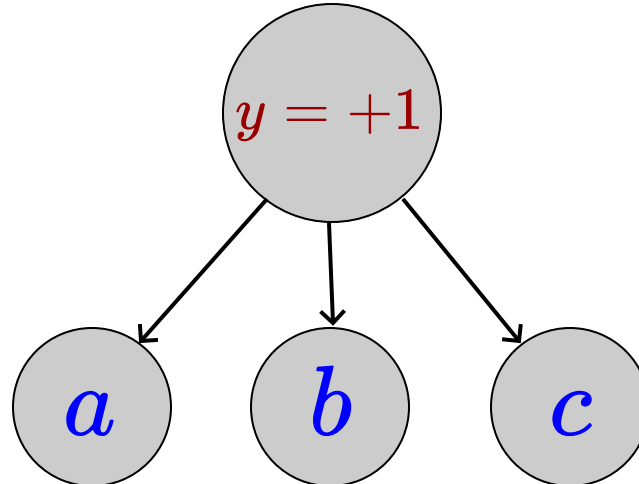
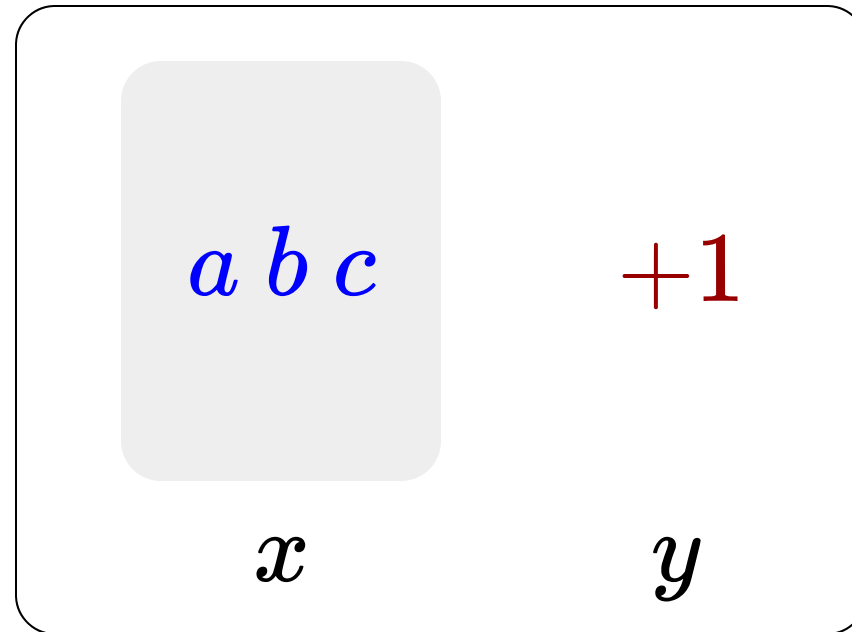
Generative Models



Generative Models



Generative Models



Sequence Labeling

Faith is a fine invention

Sequence Labeling

Noun

Verb

Determiner

Adjective

Noun

N

V

D

A

N

Faith

is

a

fine

invention



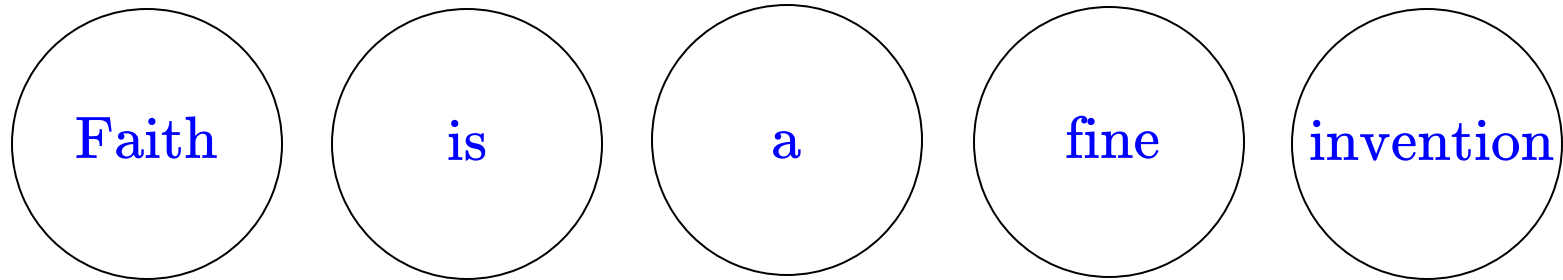
Sequence Labeling



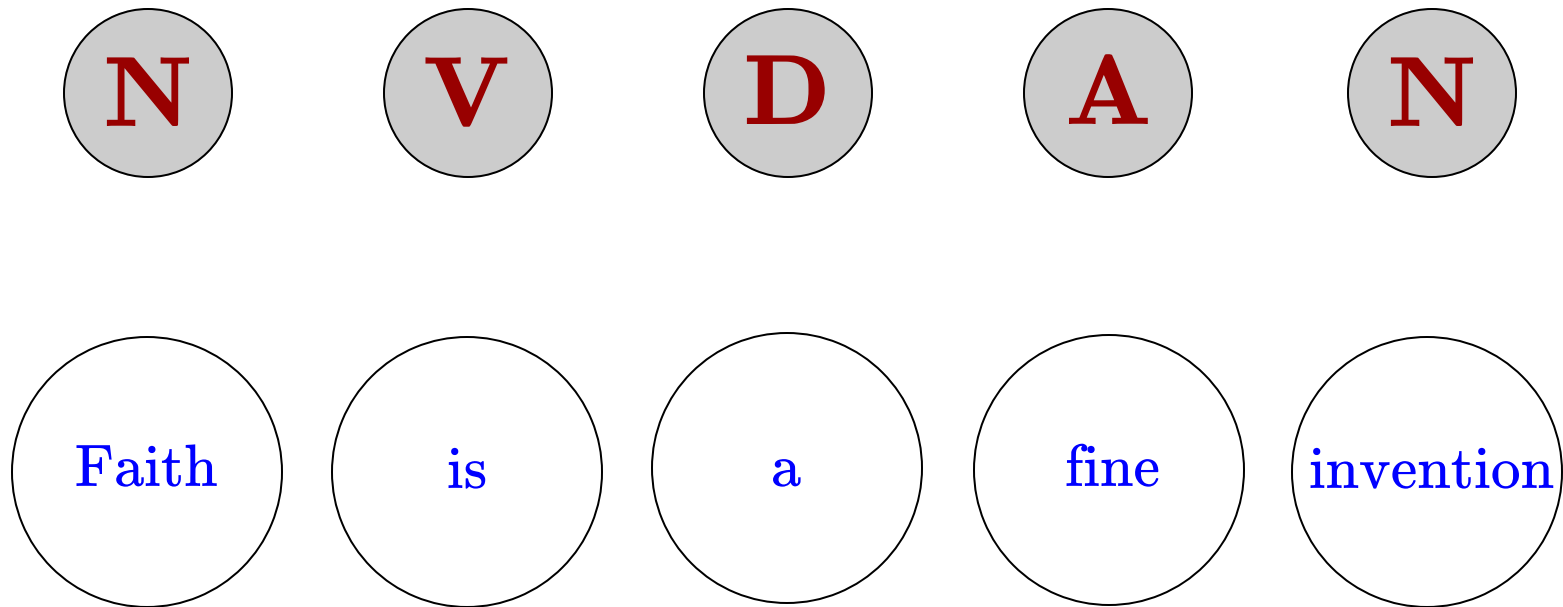
Sequence Labeling



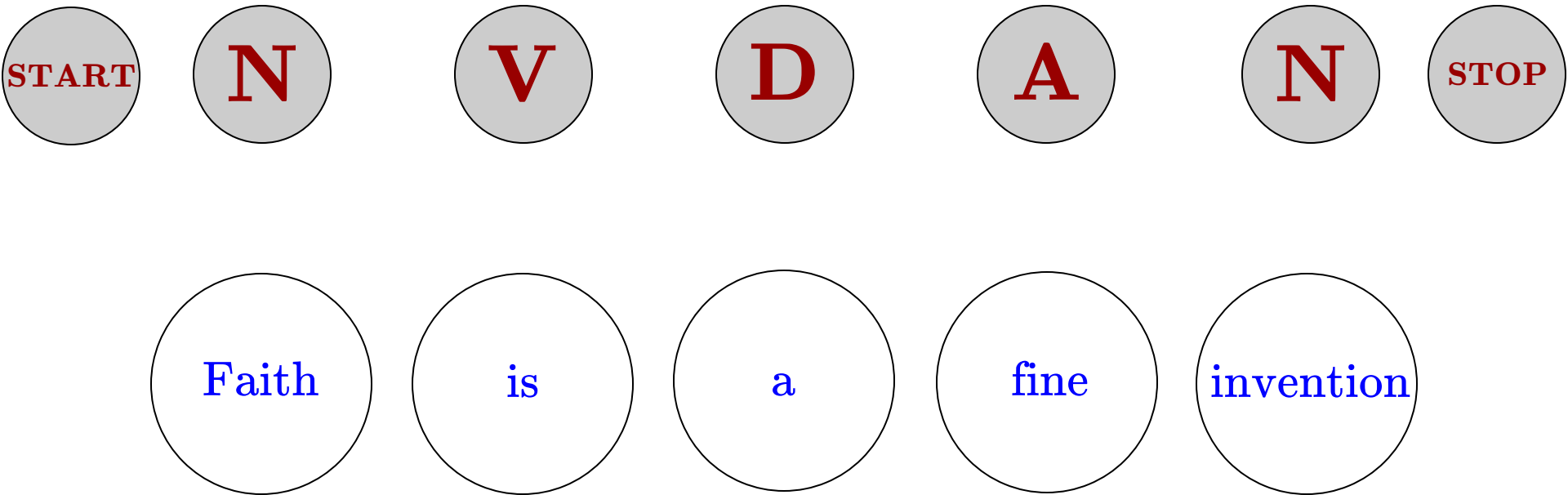
Sequence Labeling



Sequence Labeling



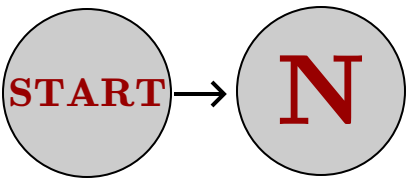
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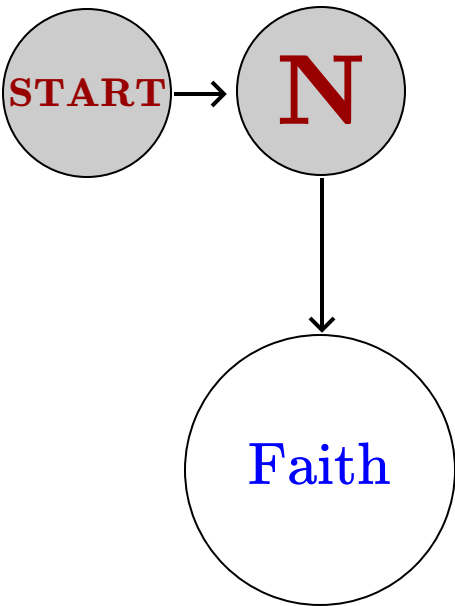
Sequence Labeling



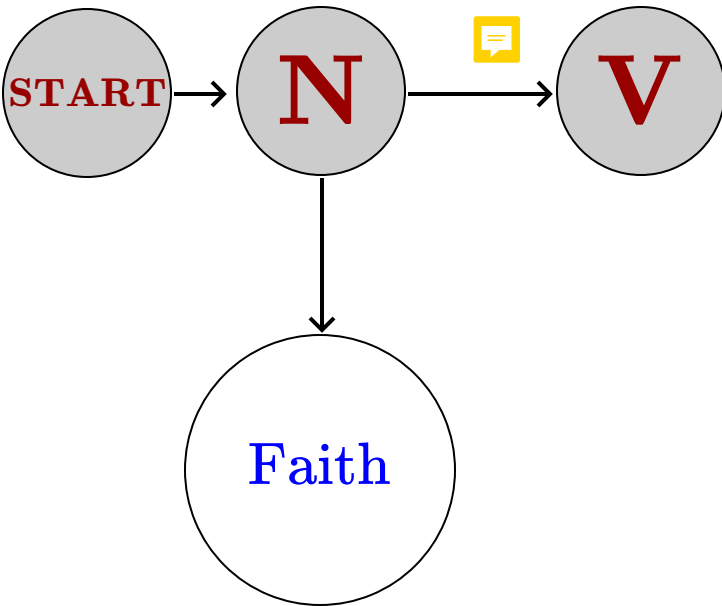
Sequence Labeling



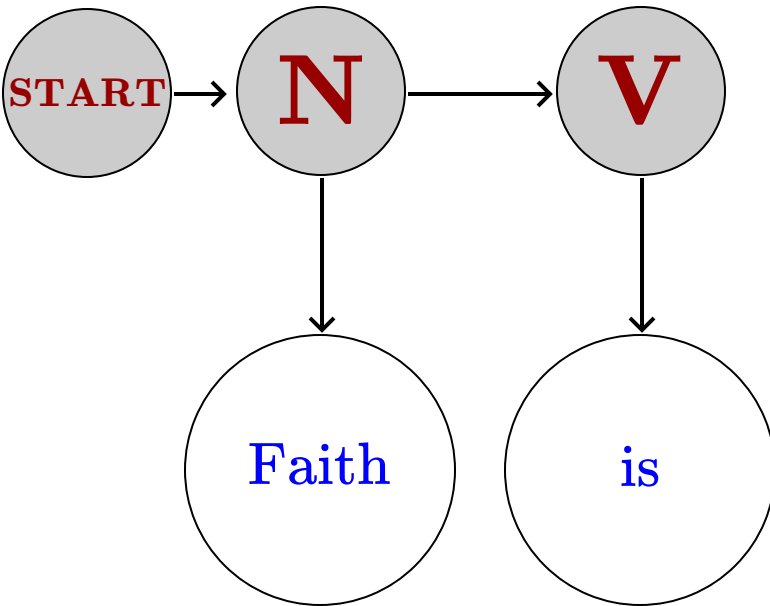
Sequence Labeling



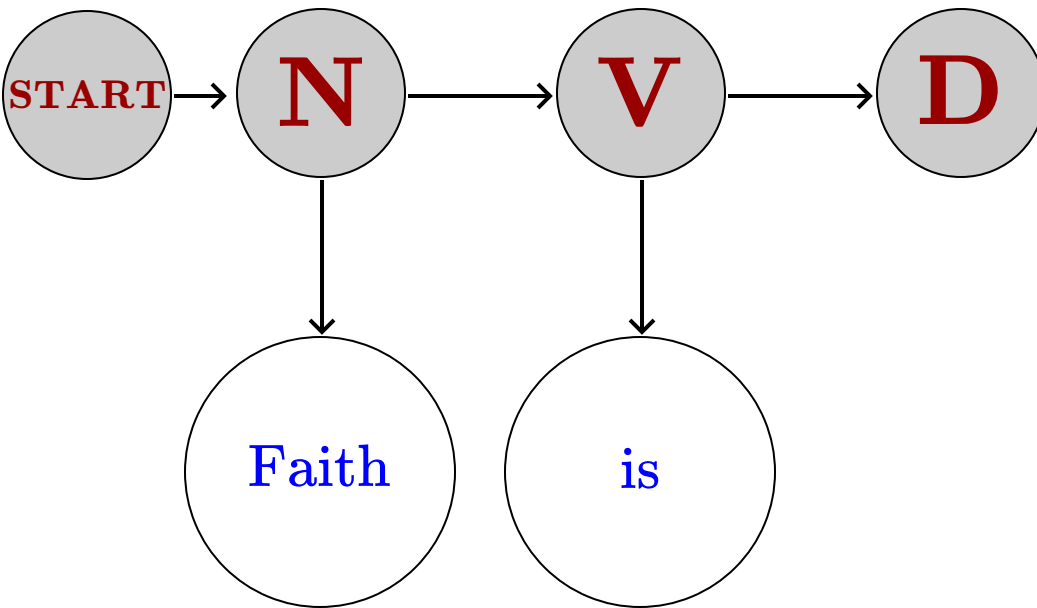
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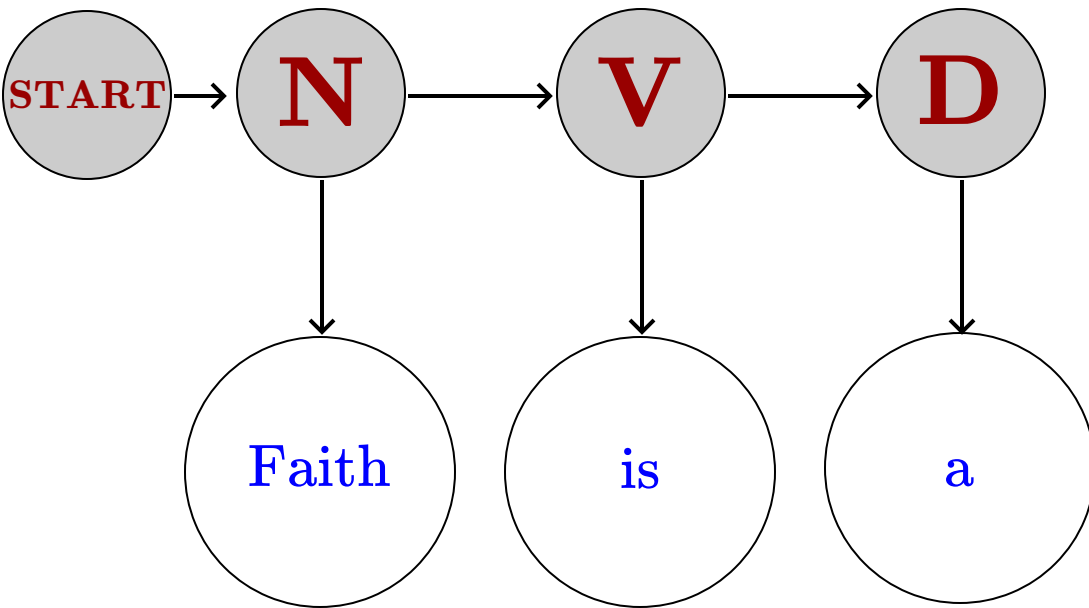
Sequence Labeling



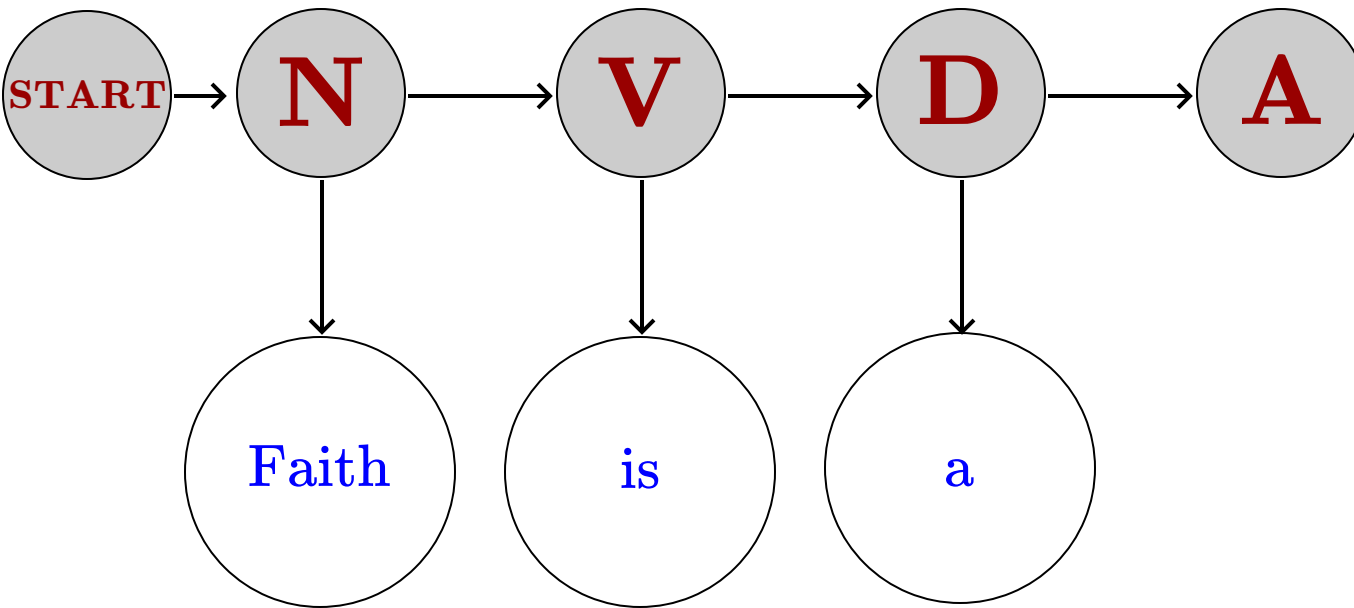
Sequence Labeling



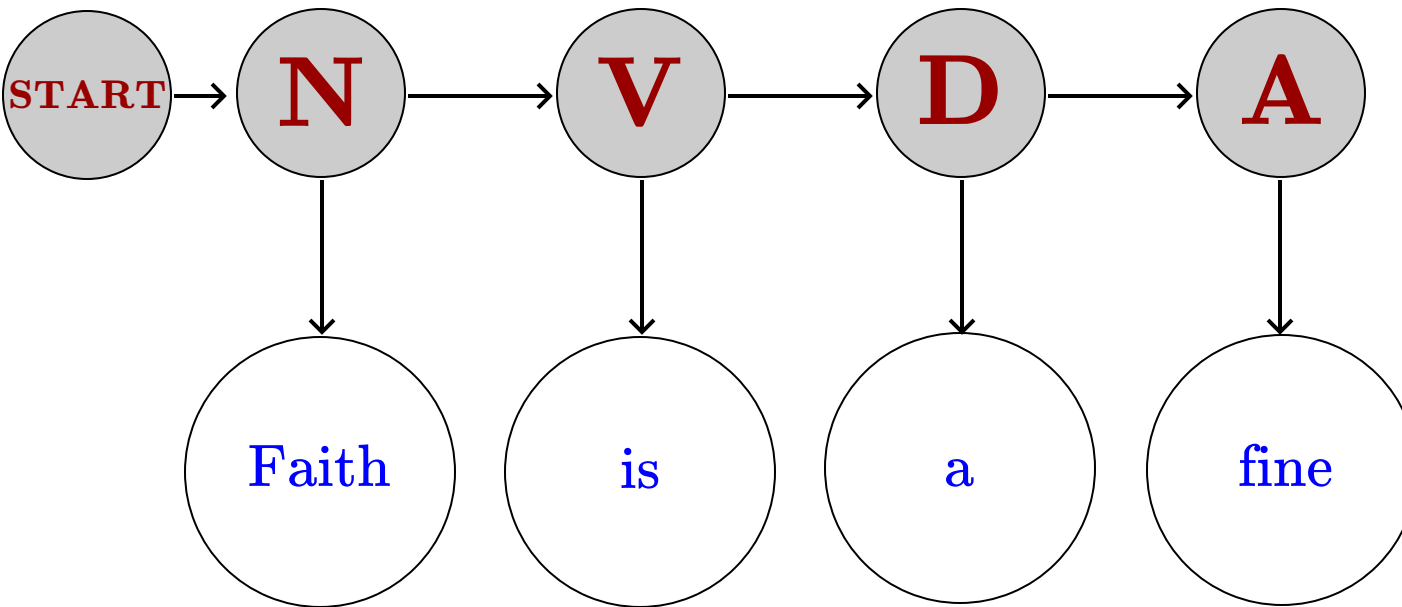
Sequence Labeling



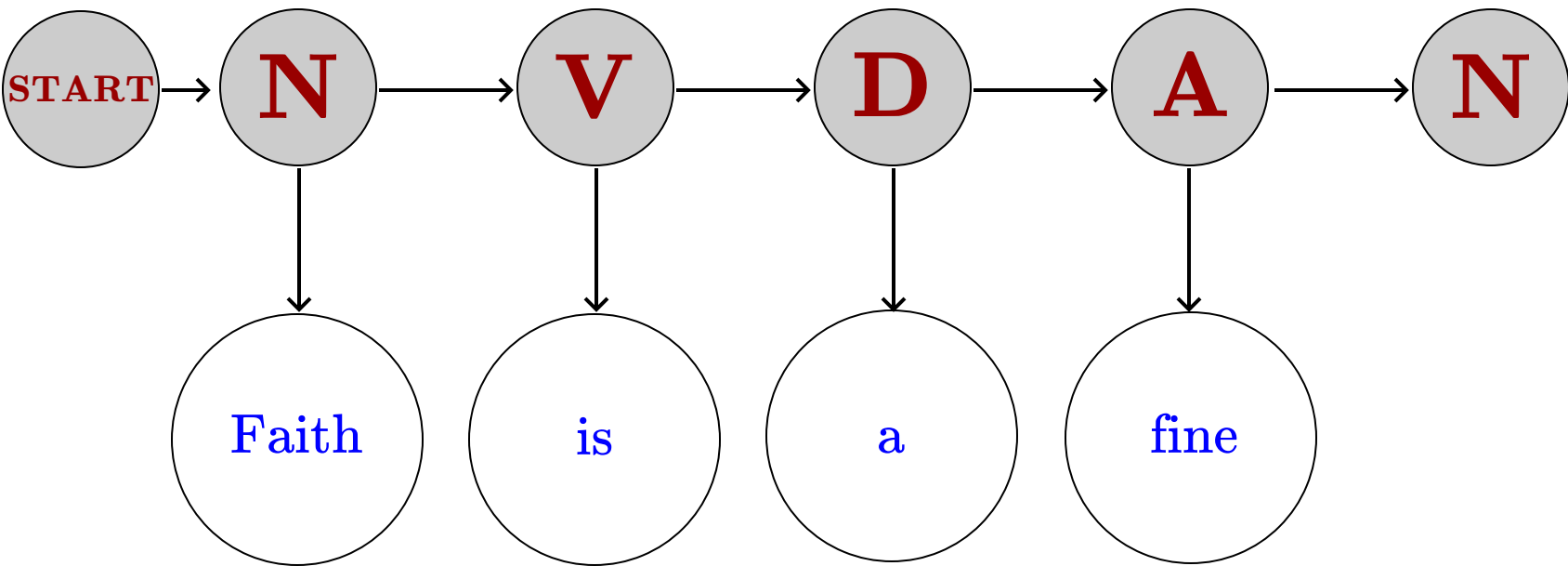
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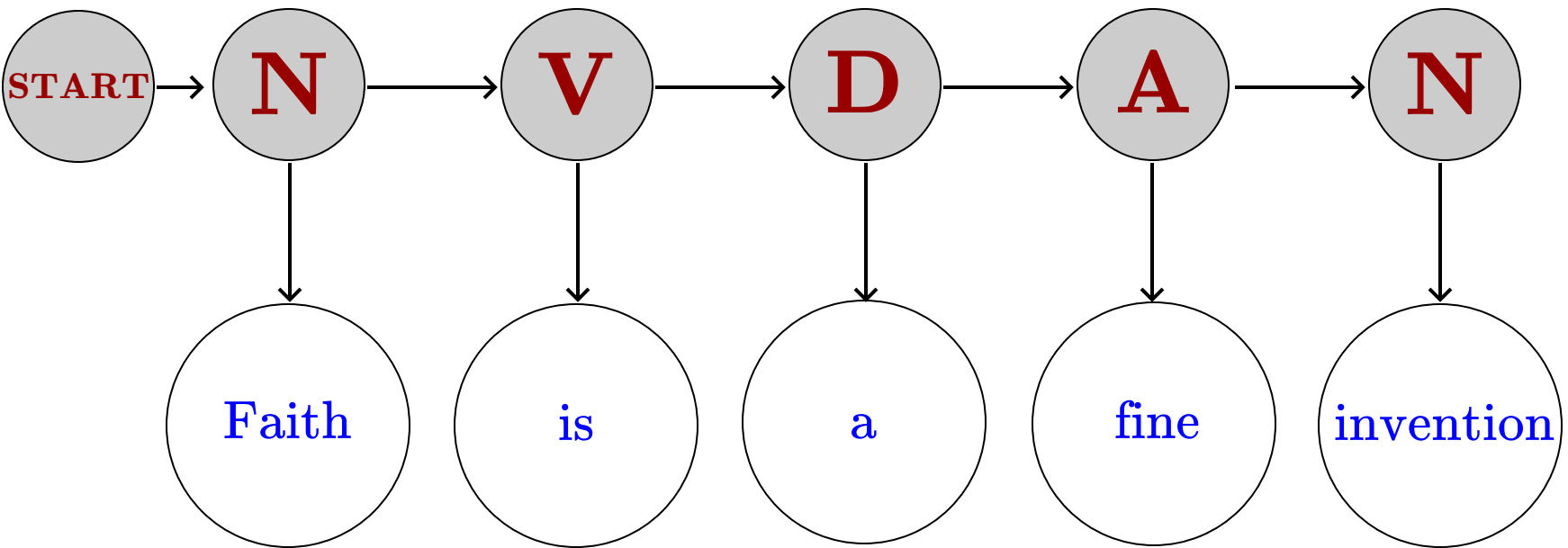
Sequence Labeling



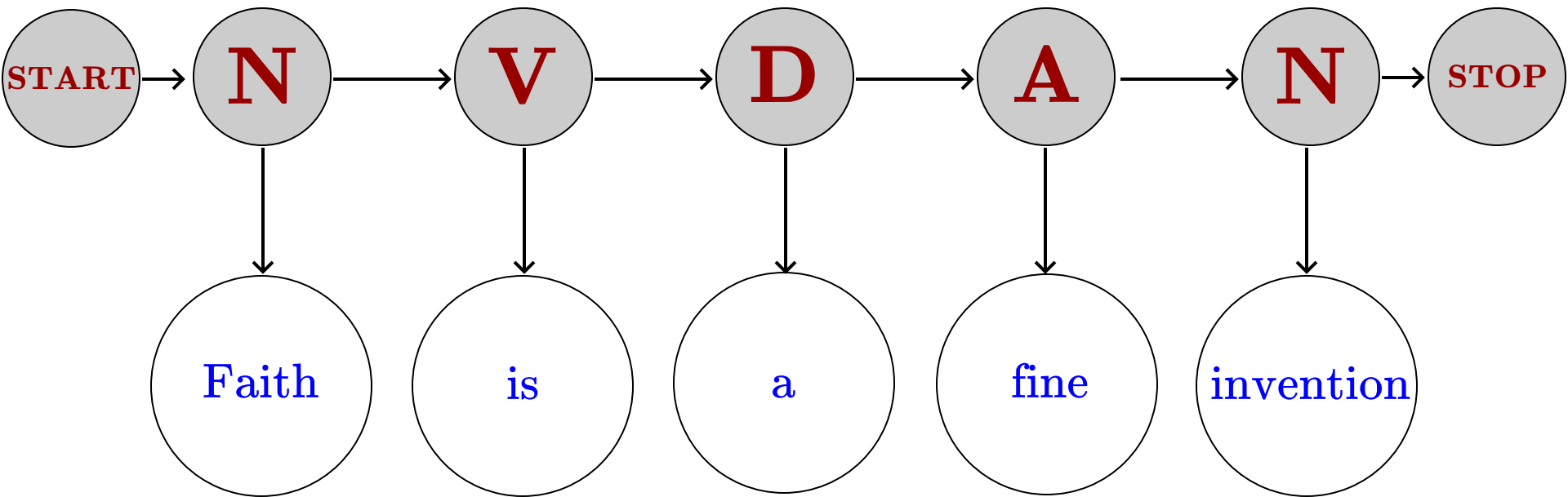
Sequence Labeling



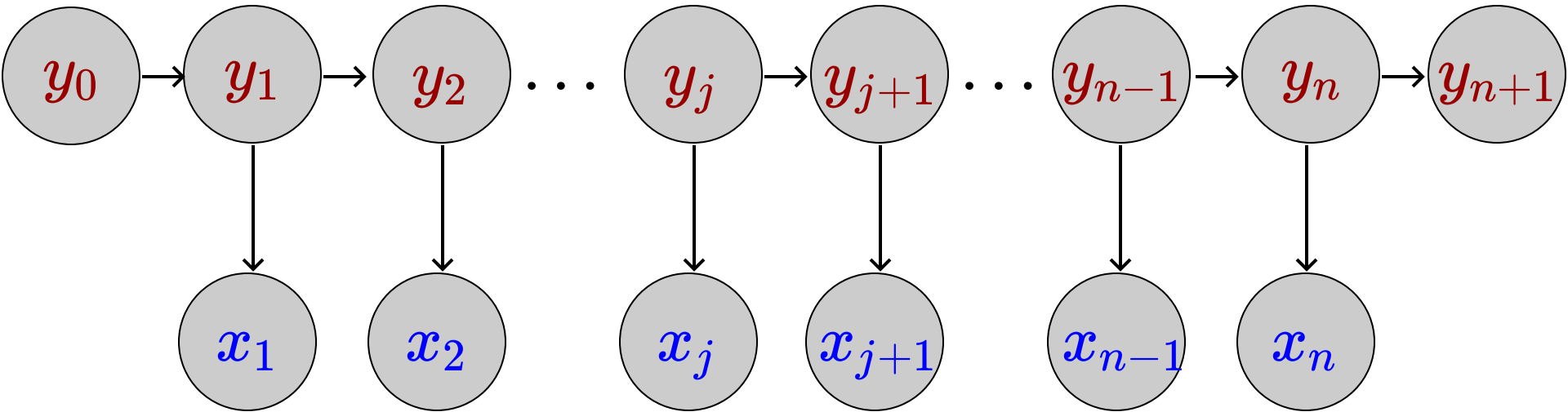
Sequence Labeling



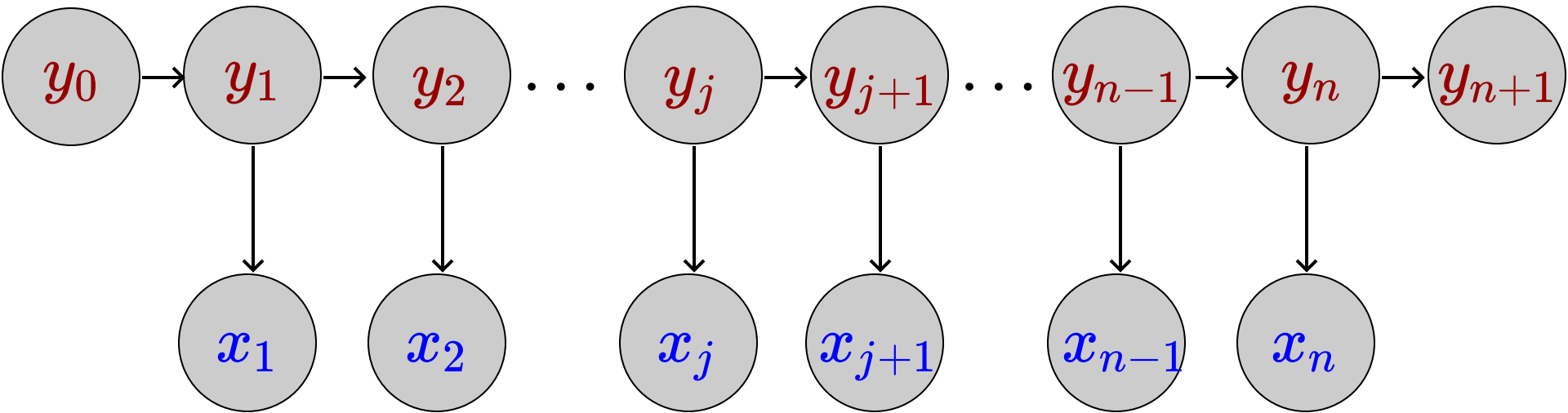
Sequence Labeling



Sequence Labeling



Sequence Labeling

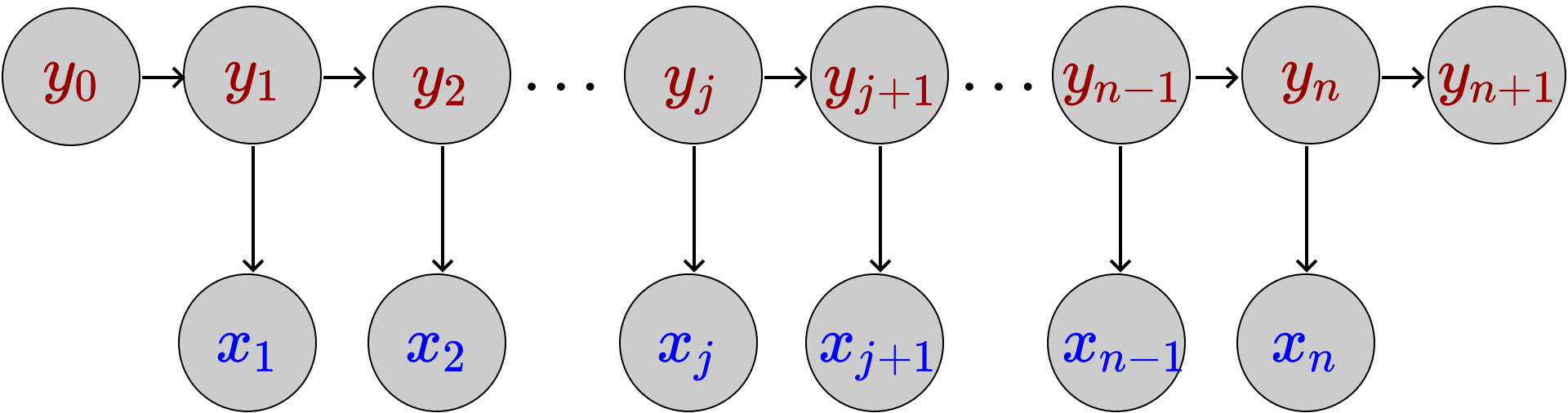


$$p(x_1, x_2, \dots, x_{n-1}, x_n, y_0, y_1, y_2, \dots, y_{n-1}, y_n, y_{n+1})$$

↑
START

↑
STOP

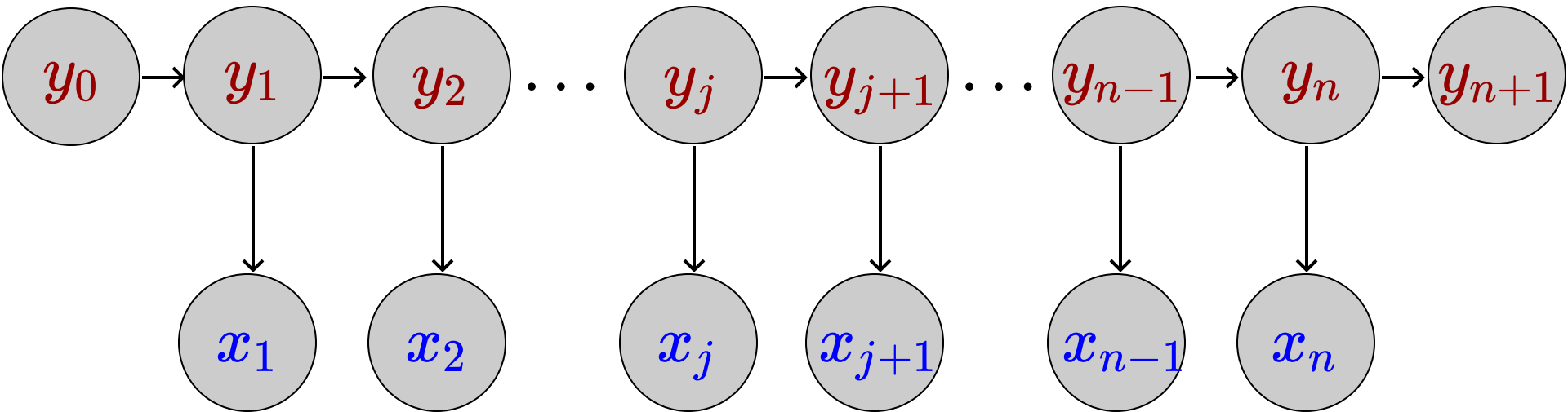
Sequence Labeling



$$p(x_1, x_2, \dots, x_{n-1}, x_n, y_0, y_1, y_2, \dots, y_{n-1}, y_n, y_{n+1})$$

$$\prod_{j=0}^n p(y_{j+1}|y_j) \times \prod_{j=1}^n p(x_j|y_j)$$

Hidden Markov Model



$$p(x_1, x_2, \dots, x_{n-1}, x_n, y_0, y_1, y_2, \dots, y_{n-1}, y_n, y_{n+1})$$

$$\underbrace{\prod_{j=0}^n a_{y_j, y_{j+1}}}_{\text{Transition probabilities}} \times \underbrace{\prod_{j=1}^n b_{y_j}(x_j)}_{\text{Emission probabilities}}$$

Transition probabilities

Emission probabilities

Hidden Markov Model

An HMM is defined by a tuple $\langle \mathcal{T}, \mathcal{O}, \theta \rangle$, where

\mathcal{T}

a set of states including START and STOP states.

\mathcal{O}

a set of observation symbols

θ

Transition and emission parameters $a_{u,v}$ and $b_u(o)$.

Hidden Markov Model

An Example

$$\mathcal{T} = \{\text{START}, A, B, \text{STOP}\}$$

$$\mathcal{O} = \{\text{“the”}, \text{“dog”}\}$$

$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

$$a_{u,v}$$

$u \backslash o$	“the”	“dog”
A	0.9	0.1
B	0.1	0.9

$$b_u(o)$$

Hidden Markov Model

An Example

 $a_{u,v}$

$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

 $b_u(o)$

$u \backslash o$	“the”	“dog”
A	0.9	0.1
B	0.1	0.9

$(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$



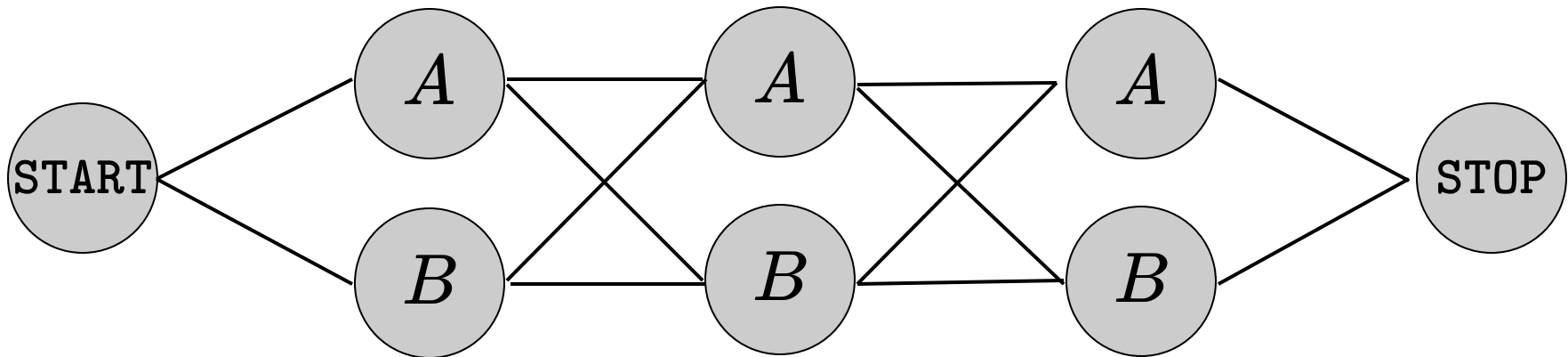
What is $p(\mathbf{x}, \mathbf{y})$?

Hidden Markov Model

$a_{u,v}$ $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$ $b_u(o)$

$u \setminus v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

$u \setminus o$	“the”	“dog”
A	0.9	0.1
B	0.1	0.9



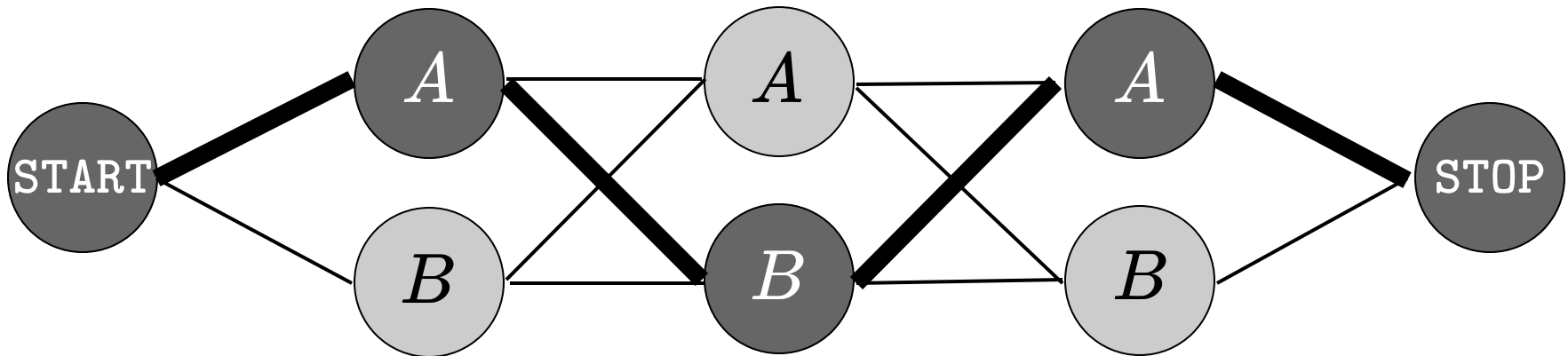
One path corresponds to one label sequence.

Hidden Markov Model

$a_{u,v}$ $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$ $b_u(o)$

$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

$u \backslash o$	“the”	“dog”
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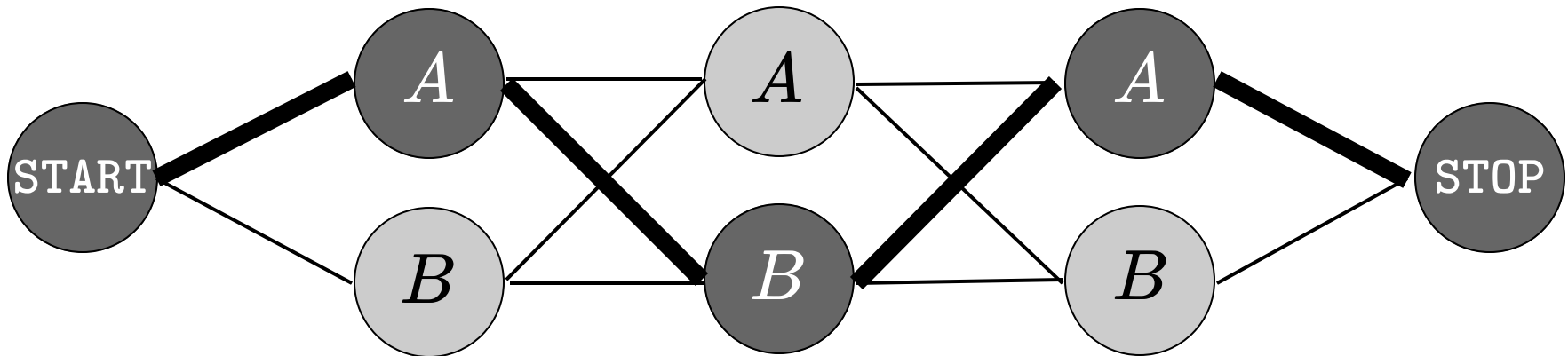
$a_{\text{START},A}$

Hidden Markov Model

$a_{u,v}$ $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$ $b_u(o)$

$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

$u \backslash o$	“the”	“dog”
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B	0.1	0.9



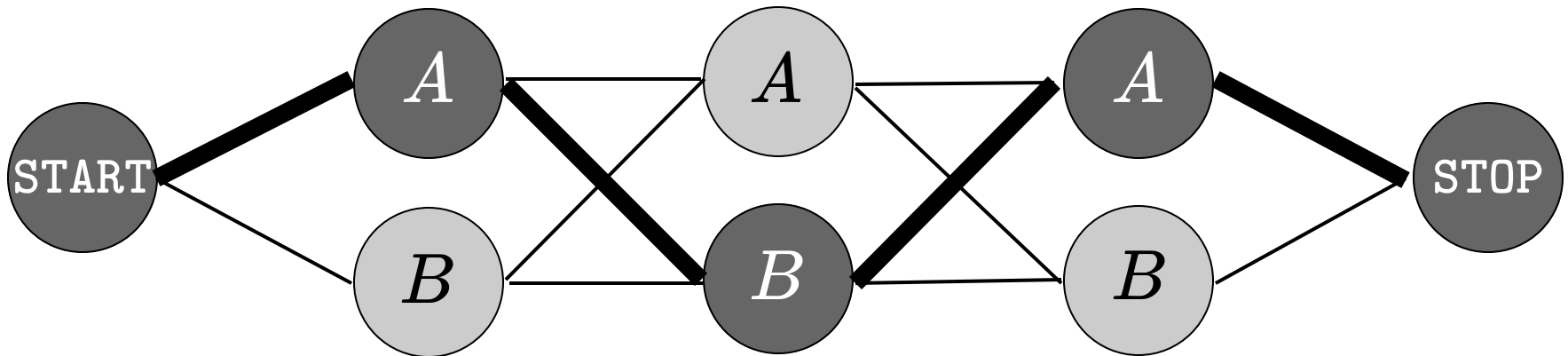
$$a_{\text{START},A} \times b_A(\text{“The”})$$

Hidden Markov Model

$a_{u,v}$ $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$ $b_u(o)$

$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

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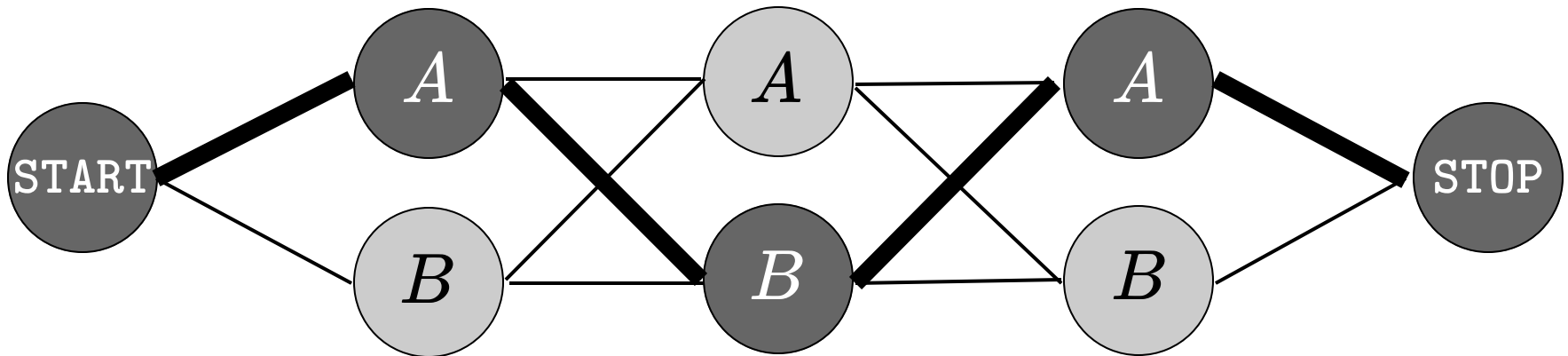
$$a_{\text{START},A} \times b_A(\text{“The”}) \times a_{A,B}$$

Hidden Markov Model

$a_{u,v}$ $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$ $b_u(o)$

$u \backslash v$	A	B	STOP
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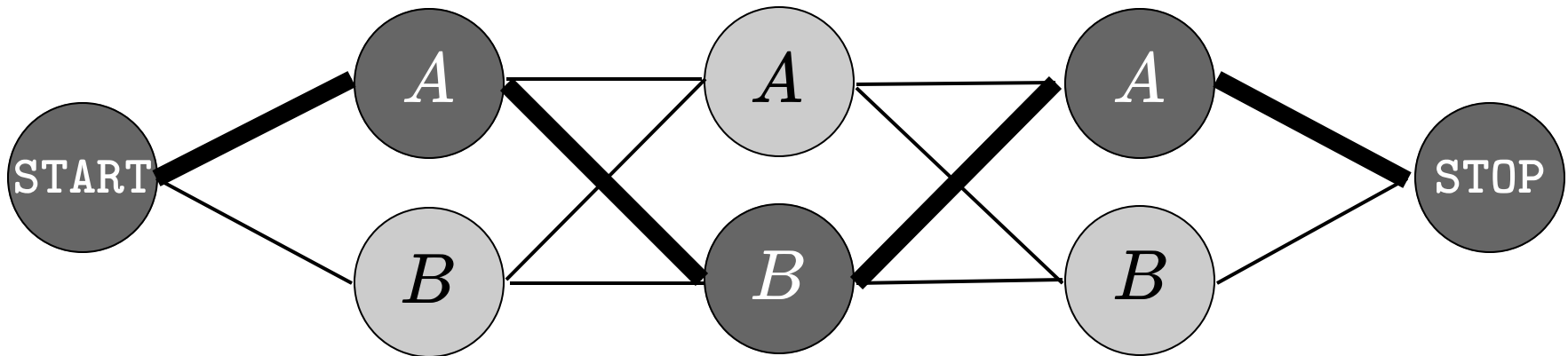
$$a_{\text{START},A} \times b_A(\text{“The”}) \times a_{A,B} \times b_B(\text{“dog”})$$

Hidden Markov Model

$a_{u,v}$ $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$ $b_u(o)$

$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
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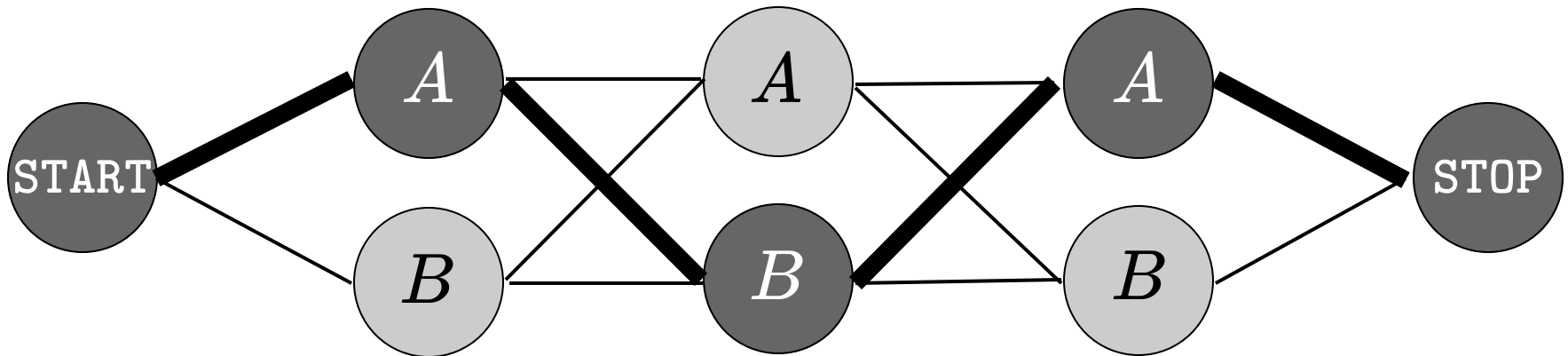
$$a_{\text{START},A} \times b_A(\text{“The”}) \times a_{A,B} \times b_B(\text{“dog”}) \times a_{B,A}$$

Hidden Markov Model

$a_{u,v}$ $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$ $b_u(o)$

$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

$u \backslash o$	“the”	“dog”
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B	0.1	0.9



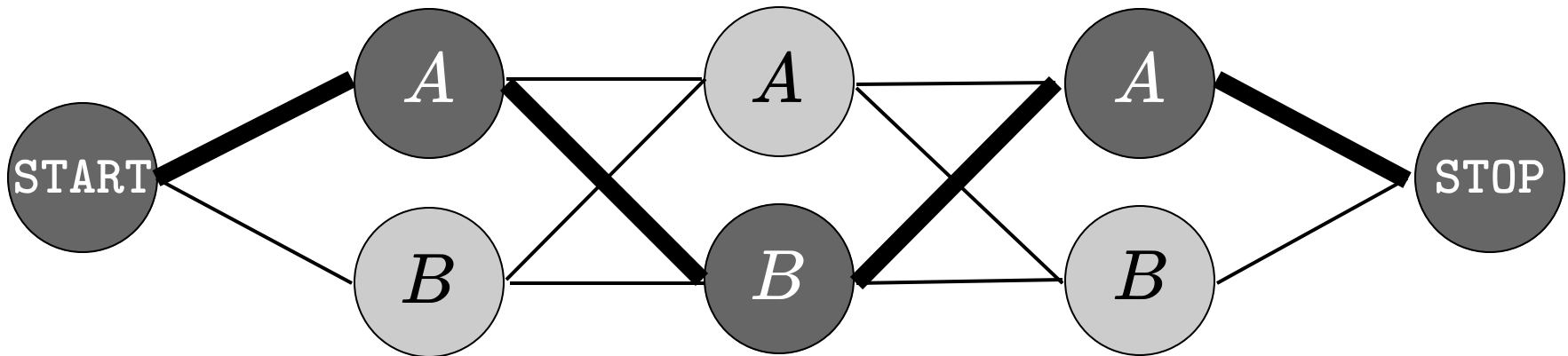
$$a_{\text{START},A} \times b_A(\text{“The”}) \times a_{A,B} \times b_B(\text{“dog”}) \times a_{B,A} \times b_A(\text{“the”})$$

Hidden Markov Model

$a_{u,v}$ $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$ $b_u(o)$

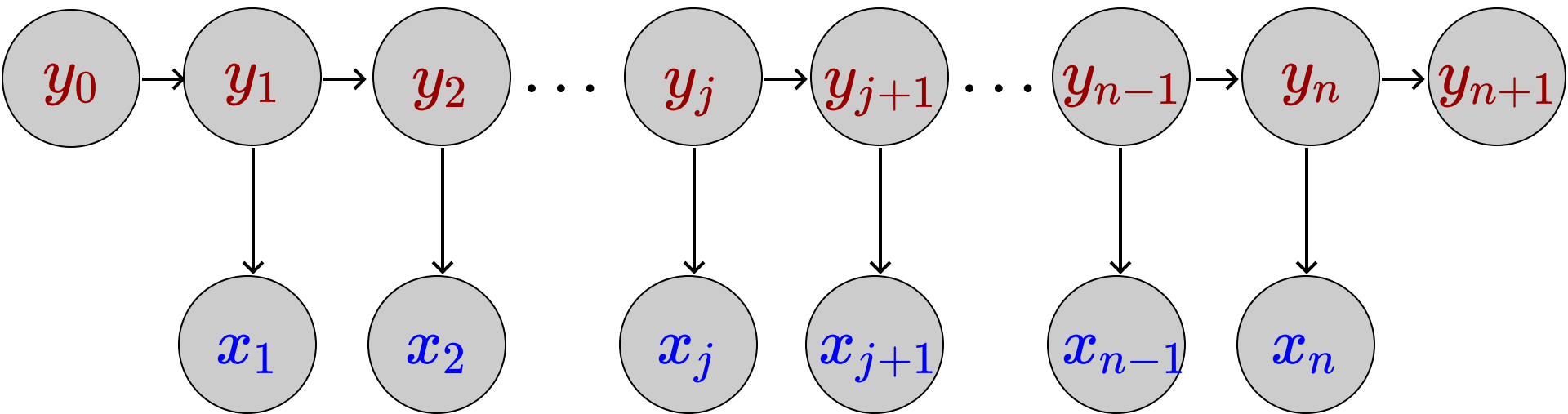
$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
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B	0.0	0.8	0.2

$u \backslash o$	“the”	“dog”
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B	0.1	0.9



$$a_{\text{START},A} \times b_A(\text{“The”}) \times a_{A,B} \times b_B(\text{“dog”}) \times a_{B,A} \times b_A(\text{“the”}) \times a_{A,\text{STOP}}$$

Hidden Markov Model

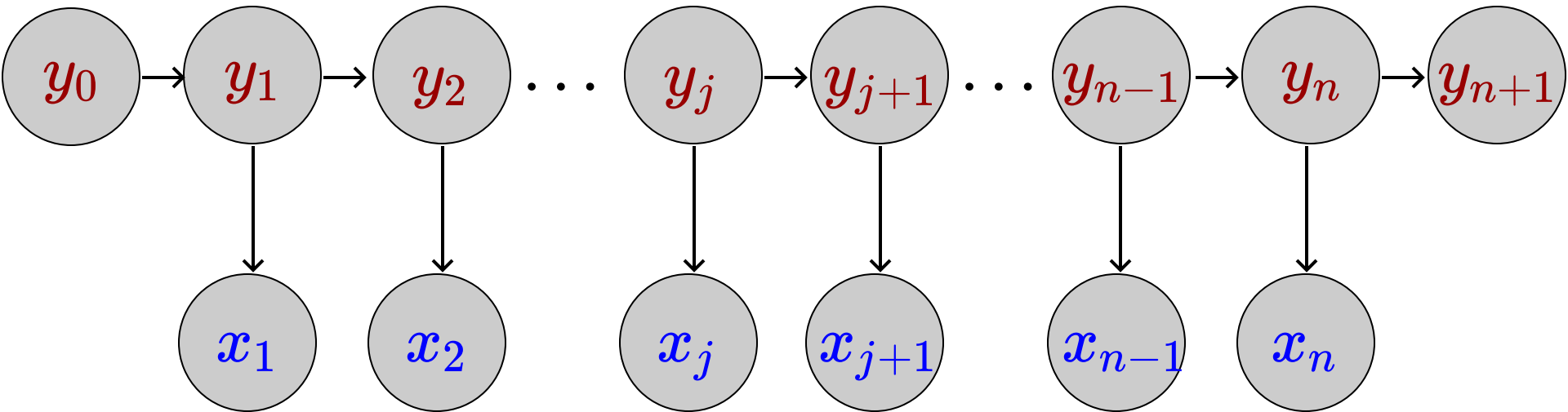


$$p(\mathbf{x}, \mathbf{y}) = \underbrace{\prod_{j=0}^n a_{y_j, y_{j+1}}}_{\text{Transition probabilities}} \times \underbrace{\prod_{j=1}^n b_{y_j}(x_j)}_{\text{Emission probabilities}}$$




Now that we know what are the model parameters, how do we estimate them? In other words, how to do learning?

Hidden Markov Model



Number of times we see a transition from u to v

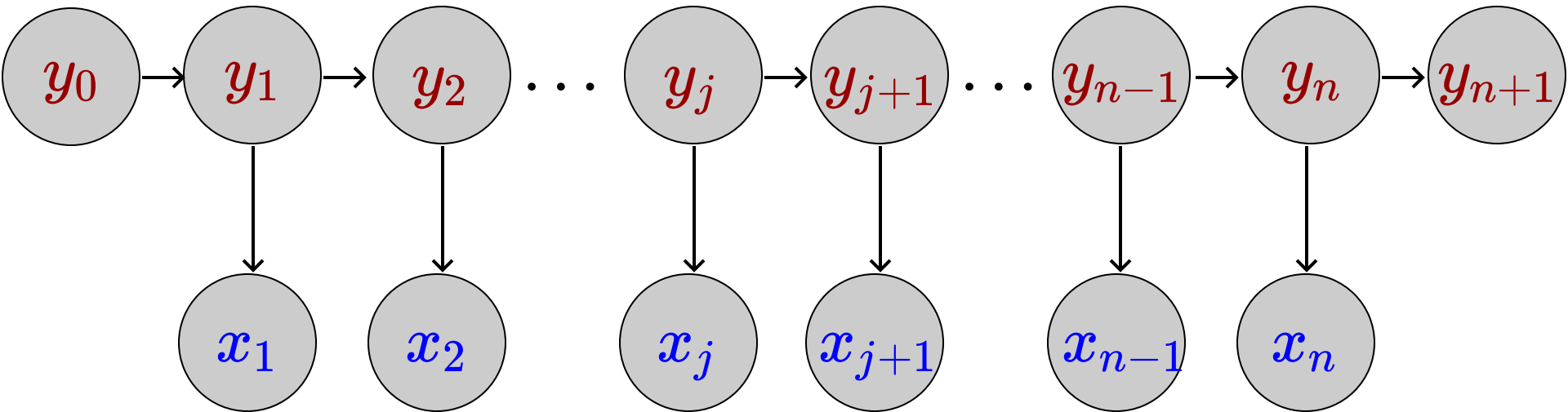


$$a_{u,v} = \frac{\text{count}(u,v)}{\text{count}(u)}$$

$$b_u(o) = \frac{\text{count}(u \rightarrow o)}{\text{count}(u)}$$

Number of times we see the state u in the training set

Hidden Markov Model



Number of times we see observation o generated from u



$$a_{u,v} = \frac{\text{count}(u,v)}{\text{count}(u)}$$

$$b_u(o) = \frac{\text{count}(u \rightarrow o)}{\text{count}(u)}$$



Number of times we see the state u in the training set

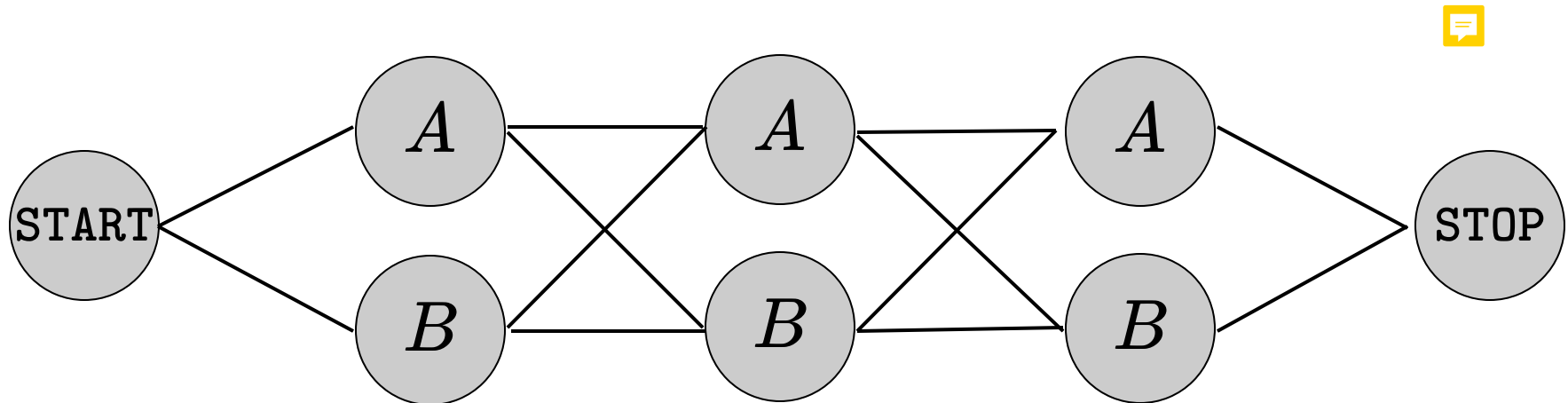
Hidden Markov Model

$a_{u,v}$ $b_u(o)$

$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

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A	0.9	0.1
B	0.1	0.9

$\mathbf{x} = \text{the dog the}$



Which label sequence \mathbf{y} is the most probable given the word sequence \mathbf{x} ?

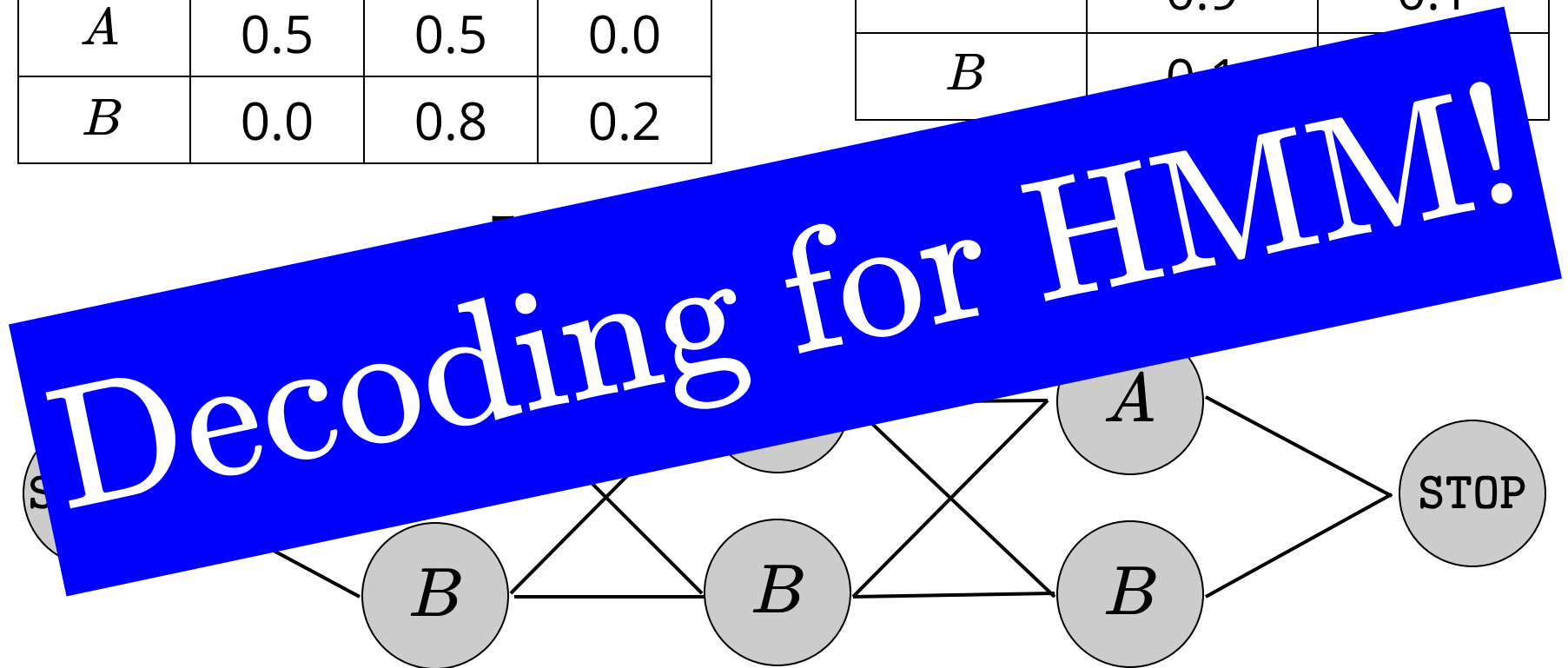
Hidden Markov Model

 $a_{u,v}$

$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

 $b_u(o)$

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