

Uncertainty relations with the variance and the quantum Fisher information

Géza Tóth^{1,2,3,4} and Florian Fröwis⁵



¹Theoretical Physics and EHU Quantum Center,
University of the Basque Country (UPV/EHU), Bilbao, Spain

²Donostia International Physics Center (DIPC), San Sebastián, Spain

³IKERBASQUE, Basque Foundation for Science, Bilbao, Spain

⁴Wigner Research Centre for Physics, Budapest, Hungary

⁵Group of Applied Physics, University of Geneva, CH-1211 Geneva, Switzerland

DPG Tagung, Regensburg,
9 September 2022

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 Uncertainty relations with the variance and the QFI

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- Simple observation to prove further relations
- Further applications

How can we improve uncertainty relations?

- There are many approaches to improve uncertainty relations.
- We show a method that replaces the variance with the quantum Fisher information in some well known uncertainty relations.
- We use convex/concave roofs over the decompositions of the density matrix.

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

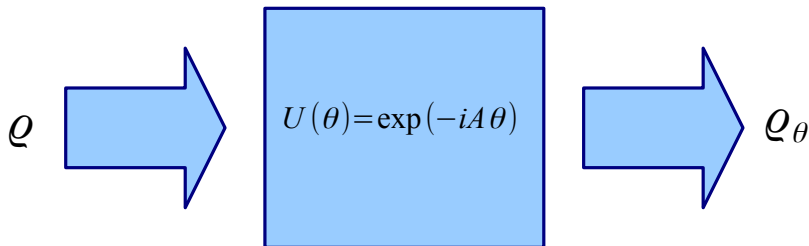
- Quantum Fisher information
- Uncertainty relations

3 Uncertainty relations with the variance and the QFI

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- Simple observation to prove further relations
- Further applications

Quantum metrology

- Fundamental task in metrology



- We have to estimate θ in the dynamics

$$U = \exp(-iA\theta).$$

The quantum Fisher information

- Cramér-Rao bound on the precision of parameter estimation

$$(\Delta\theta)^2 \geq \frac{1}{mF_Q[\varrho, A]},$$

where $F_Q[\varrho, A]$ is the **quantum Fisher information**, and m is the number of independent repetitions.

- The quantum Fisher information is

$$F_Q[\varrho, A] = 2 \sum_{k,l} \frac{(\lambda_k - \lambda_l)^2}{\lambda_k + \lambda_l} |\langle k|A|l \rangle|^2,$$

where $\varrho = \sum_k \lambda_k |k\rangle\langle k|$.

Most important characteristics used for estimation

The quantum Fisher information is the convex roof of the variance

$$F_Q[\varrho, A] = 4 \min_{\{p_k, |\psi_k\rangle\}} \sum_k p_k (\Delta A)_{\psi_k}^2,$$

where

$$\varrho = \sum_k p_k |\psi_k\rangle \langle \psi_k|.$$

[GT, D. Petz, Phys. Rev. A 87, 032324 (2013); S. Yu, arXiv1302.5311 (2013);
GT, I. Apellaniz, J. Phys. A: Math. Theor. 47, 424006 (2014)]

Similar relation for the variance

The quantum Fisher information is the convex roof of the variance

$$(\Delta A)^2_{\varrho} = \max_{\{p_k, |\psi_k\rangle\}} \sum_k p_k (\Delta A)^2_{\psi_k},$$

where

$$\varrho = \sum_k p_k |\psi_k\rangle \langle \psi_k|.$$

[GT, D. Petz, Phys. Rev. A 87, 032324 (2013);

GT, I. Apellaniz, J. Phys. A: Math. Theor. 47, 424006 (2014)]

A single relation for the QFI and the variance

The previous statements can be concisely reformulated as follows. For any decomposition $\{p_k, |\psi_k\rangle\}$ of the density matrix ϱ we have

$$\frac{1}{4}F_Q[\varrho, A] \leq \sum_k p_k (\Delta A)_{\psi_k}^2 \leq (\Delta A)_{\varrho}^2,$$

where the upper and the lower bounds are both **tight**.

- Note that

$$F_Q[\varrho, A] \leq 4(\Delta A)_{\varrho}^2,$$

where we have an equality for pure states.

- The QFI appears as a "pair" of variance.

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 Uncertainty relations with the variance and the QFI

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- Simple observation to prove further relations
- Further applications

Robertson-Schrödinger inequality

The Robertson-Schrödinger inequality is defined as

$$(\Delta A)_{\varrho}^2 (\Delta B)_{\varrho}^2 \geq \frac{1}{4} |L_{\varrho}|^2,$$

where the lower bound is given by

$$L_{\varrho} = \sqrt{|\langle \{A, B\} \rangle_{\varrho} - 2\langle A \rangle_{\varrho} \langle B \rangle_{\varrho}|^2 + |\langle C \rangle_{\varrho}|^2},$$

$\{A, B\} = AB + BA$ is the anticommutator, and we used the definition

$$C = i[A, B].$$

Important: L_{ϱ} is neither convex nor concave in ϱ .

Heisenberg uncertainty

The Heisenberg inequality is defined as

$$(\Delta A)^2_{\varrho}(\Delta B)^2_{\varrho} \geq \frac{1}{4}|\langle C \rangle_{\varrho}|^2,$$

where we used the definition

$$C = i[A, B].$$

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 **Uncertainty relations with the variance and the QFI**

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- Simple observation to prove further relations
- Further applications

Robertson-Schrödinger inequality for ϱ_k

- Consider a decomposition to mixed states

$$\varrho = \sum_k p_k \varrho_k.$$

- For such a decomposition, for all ϱ_k the Robertson-Schrödinger inequality holds

$$(\Delta A)^2_{\varrho_k} (\Delta B)^2_{\varrho_k} \geq \frac{1}{4} |L_{\varrho_k}|^2.$$

- Let us consider the inequality

$$\left(\sum_k p_k a_k \right) \left(\sum_k p_k b_k \right) \geq \left(\sum_k p_k \sqrt{a_k b_k} \right)^2,$$

where $a_k, b_k \geq 0$.

Uncertainty with the variance and the QFI

- Hence, we arrive at

$$\left[\sum_k p_k (\Delta A)^2_{\varrho_k} \right] \left[\sum_k p_k (\Delta B)^2_{\varrho_k} \right] \geq \frac{1}{4} \left[\sum_k p_k L_{\varrho_k} \right]^2.$$

- We can choose the decomposition such that

$$\sum_k p_k (\Delta B)^2_{\varrho_k} = F_Q[\varrho, B]/4.$$

- Due to the concavity of the variance we also know that

$$\sum_k p_k (\Delta A)^2_{\varrho_k} \leq (\Delta A)^2.$$

- Hence, it follows that

$$(\Delta A)^2_{\varrho} F_Q[\varrho, B] \geq \left(\sum_k p_k L_{\varrho_k} \right)^2.$$

- In order to use the previous inequality, we need to know the decomposition $\{p_k, \varrho_k\}$ that minimizes $\sum_k p_k (\Delta B)^2_{\varrho_k}$.

Uncertainty with the variance and the QFI II

- Then, we can obtain the inequality

$$(\Delta A)^2_{\varrho} F_Q[\varrho, B] \geq \left(\min_{\{p_k, \varrho_k\}} \sum_k p_k L_{\varrho_k} \right)^2.$$

where there is a convex roof on the right-hand side.

- After simple algebra, we arrive at the improved Heisenberg-Robertson uncertainty

$$(\Delta A)^2_{\varrho} F_Q[\varrho, B] \geq |\langle C \rangle_{\varrho}|^2.$$

Uncertainty with the variance and the QFI IV

- The Heisenberg uncertainty

$$(\Delta A)^2_{\varrho} (\Delta B)^2_{\varrho} \geq \frac{1}{4} |\langle i[A, B] \rangle_{\varrho}|^2.$$

- The improved Heisenberg uncertainty

$$(\Delta A)^2_{\varrho} F_Q[\varrho, B] \geq |\langle i[A, B] \rangle_{\varrho}|^2.$$

- It has been derived originally with a different method in

F. Fröwis, R. Schmied, and N. Gisin, Phys. Rev. A 92, 012102 (2015).

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 **Uncertainty relations with the variance and the QFI**

- Uncertainty relations based on a convex roof of the bound
- **Uncertainty relations based on a concave roof of the bound**
- Simple observation to prove further relations
- Further applications

Uncertainty relation based on a concave roof

- For any decomposition $\{p_k, \varrho_k\}$ we have

$$(\Delta A)^2(\Delta B)^2 \geq \frac{1}{4} \left(\sum_k p_k L_{\varrho_k} \right)^2,$$

where

$$L_{\varrho} = \sqrt{|\langle \{A, B\} \rangle_{\varrho} - 2\langle A \rangle_{\varrho} \langle B \rangle_{\varrho}|^2 + |\langle C \rangle_{\varrho}|^2}.$$

- We can even take a concave roof on the right-hand side

$$(\Delta A)^2_{\varrho} (\Delta B)^2_{\varrho} \geq \frac{1}{4} \left(\max_{\{p_k, \varrho_k\}} \sum_k p_k L_{\varrho_k} \right)^2.$$

- We prove that for qubits the above inequality is saturated for all states.

Uncertainty relations with two variances and the QFI

- Let us start from the relation for pure states

$$(\Delta J_x)^2 + (\Delta J_y)^2 + (\Delta J_z)^2 \geq j,$$

where J_l are the spin components fulfilling

$$J_x^2 + J_y^2 + J_z^2 = j(j+1)\mathbb{1}.$$

- Based on similar ideas we arriving at

$$(\Delta J_x)^2 + (\Delta J_y)^2 + \frac{1}{4}F_Q[\varrho, J_z] \geq j.$$

- See parallel publication in

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 **Uncertainty relations with the variance and the QFI**

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- **Simple observation to prove further relations**
- Further applications

Simple observation to prove further relations

- Let us consider a relation

$$\underbrace{(\Delta A)^2}_{\text{variance}}_{\varrho} \geq \underbrace{g(\varrho)}_{\text{convex in } \varrho},$$

which is true for pure states.

- If $g(\varrho)$ is convex in density matrices, then

$$\frac{1}{4}F_Q[\varrho, A] \geq g(\varrho)$$

holds for mixed states.

- Proof.* $\frac{1}{4}F_Q[\varrho, A]$ is given as a convex roof of the variance.
- It is the largest convex function that equals $(\Delta A)^2_{\varrho}$ for all pure states.



Extreme spin squeezing

- For a particle with spin- j

$$\underbrace{(\Delta J_x)^2}_{\text{variance}} \geq \underbrace{j F_j(\langle J_z \rangle / j)}_{\text{convex in } \varrho}$$

holds, where $F_j(X)$ is a convex function defined as

$$F_j(X) = \min_{\varrho: \langle J_z \rangle = Xj} \frac{(\Delta J_x)^2}{j}.$$

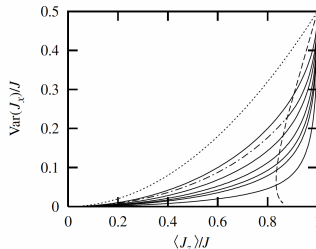


FIG. 1. Maximal squeezing for different values of J . The curves starting at the origin represent the minimum obtainable variance as a function of the mean spin. Starting from above, the curves represent $J = 1/2, 1, 3/2, 2, 3, 4, 5$, and 10 . The dotted curve for $J = 1/2$ is the limit identified in Ref. [11]. The solid

Application for extreme spin squeezing

- The metrological usefulness of a state is bounded with the spin-length as

$$F_Q[\varrho, J_x] \geq 4jF_j(\langle J_z \rangle / j).$$

- *Proof.* For the components of the angular momentum

$$(\Delta J_x)^2 \geq jF_j(\langle J_z \rangle / j)$$

holds. Then, it follows

$$\frac{1}{4}F_Q[\varrho, J_x] \geq jF_j(\langle J_z \rangle / j).$$



Can also be seen based on I. Apellaniz, M. Kleinmann, O. Gühne, and G. Tóth, Phys. Rev. A 95, 032330 (2017).

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 **Uncertainty relations with the variance and the QFI**

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- Simple observation to prove further relations
- **Further applications**

Further applications

- Metrological usefulness based on the violation of entanglement conditions.
- Cramér-Rao bound as a convex roof.
- Conditions on the saturation of the improved Heisenberg uncertainty.

Summary

- We showed how to derive new uncertainty relations with the variance and the quantum Fisher information based on simple convexity arguments.

See:

Géza Tóth and Florian Fröwis,

Uncertainty relations with the variance and the quantum Fisher information based on convex decompositions of density matrices,

[Phys. Rev. Research 4, 013075 \(2022\).](#)

THANK YOU FOR YOUR ATTENTION!