

Uncertainty relations with the variance and the quantum Fisher information

Géza Tóth^{1,2,3,4} and Florian Fröwis⁵



¹Theoretical Physics and EHU Quantum Center,
University of the Basque Country (UPV/EHU), Bilbao, Spain

²Donostia International Physics Center (DIPC), San Sebastián, Spain

³IKERBASQUE, Basque Foundation for Science, Bilbao, Spain

⁴Wigner Research Centre for Physics, Budapest, Hungary

⁵Group of Applied Physics, University of Geneva, CH-1211 Geneva, Switzerland

RDM2022, 17 June 2022

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 Uncertainty relations with the variance and the QFI

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- Several variances and the QFI
- Simple observation to prove further relations
- Metrological usefulness and entanglement conditions

How can we improve uncertainty relations?

- There are many approaches to improve uncertainty relations.
- We show a method that replaces the variance with the quantum Fisher information in some well known uncertainty relations.
- We use convex/concave roofs over the decompositions of the density matrix.

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

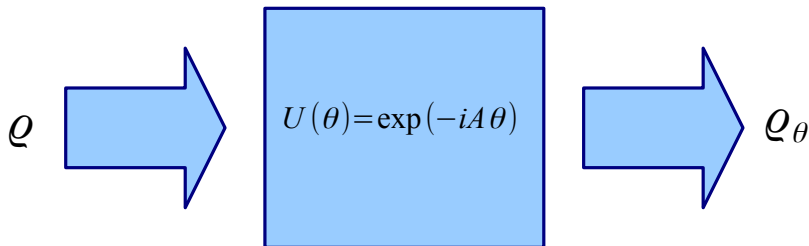
- Quantum Fisher information
- Uncertainty relations

3 Uncertainty relations with the variance and the QFI

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- Several variances and the QFI
- Simple observation to prove further relations
- Metrological usefulness and entanglement conditions

Quantum metrology

- Fundamental task in metrology



- We have to estimate θ in the dynamics

$$U = \exp(-iA\theta).$$

The quantum Fisher information

- Cramér-Rao bound on the precision of parameter estimation

$$(\Delta\theta)^2 \geq \frac{1}{mF_Q[\varrho, A]},$$

where $F_Q[\varrho, A]$ is the **quantum Fisher information**, and m is the number of independent repetitions.

- The quantum Fisher information is

$$F_Q[\varrho, A] = 2 \sum_{k,l} \frac{(\lambda_k - \lambda_l)^2}{\lambda_k + \lambda_l} |\langle k|A|l \rangle|^2,$$

where $\varrho = \sum_k \lambda_k |k\rangle\langle k|$.

Most important characteristics used for estimation

The quantum Fisher information is the convex roof of the variance

$$F_Q[\varrho, A] = 4 \min_{\{p_k, |\psi_k\rangle\}} \sum_k p_k (\Delta A)_{\psi_k}^2,$$

where

$$\varrho = \sum_k p_k |\psi_k\rangle \langle \psi_k|.$$

[GT, D. Petz, Phys. Rev. A 87, 032324 (2013); S. Yu, arXiv1302.5311 (2013);
GT, I. Apellaniz, J. Phys. A: Math. Theor. 47, 424006 (2014)]

- Convex roof over purifications.

[R. Demkowicz-Dobrzański, J. Kołodyński, M. Guţă, Nature Comm. 2012.]

Similar relation for the variance

The quantum Fisher information is the convex roof of the variance

$$(\Delta A)^2_{\varrho} = \max_{\{p_k, |\psi_k\rangle\}} \sum_k p_k (\Delta A)^2_{\psi_k},$$

where

$$\varrho = \sum_k p_k |\psi_k\rangle \langle \psi_k|.$$

[GT, D. Petz, Phys. Rev. A 87, 032324 (2013);

GT, I. Apellaniz, J. Phys. A: Math. Theor. 47, 424006 (2014)]

A single relation for the QFI and the variance

The previous statements can be concisely reformulated as follows. For any decomposition $\{p_k, |\psi_k\rangle\}$ of the density matrix ϱ we have

$$\frac{1}{4}F_Q[\varrho, A] \leq \sum_k p_k (\Delta A)^2_{\psi_k} \leq (\Delta A)^2_{\varrho},$$

where the upper and the lower bounds are both **tight**.

- Note that

$$F_Q[\varrho, A] \leq 4(\Delta A)^2_{\varrho},$$

where we have an equality for pure states.

- The QFI appears as a "pair" of variance.

The quantum Fisher information vs. entanglement

- For separable states of N spin-1/2 particles

$$F_Q[\varrho, J_l] \leq N, \quad l = x, y, z, \quad J_l = \sum_{n=1}^N j_l^{(n)}.$$

[Pezze, Smerzi, Phys. Rev. Lett. 102, 100401 (2009); Hyllus, Gühne, Smerzi, Phys. Rev. A 82, 012337 (2010)]

- For states with at most k -particle entanglement (k is divisor of N)

$$F_Q[\varrho, J_l] \leq kN.$$

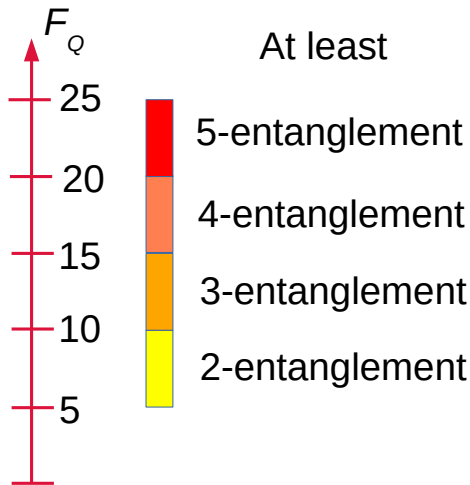
[P. Hyllus *et al.*, Phys. Rev. A 85, 022321 (2012); GT, Phys. Rev. A 85, 022322 (2012)]. → Many experiments with cold gases and photons.

- In general

$$F_Q[\varrho, J_l] \leq N^2.$$

The quantum Fisher information vs. entanglement II

5 spin-1/2 particles



Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 Uncertainty relations with the variance and the QFI

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- Several variances and the QFI
- Simple observation to prove further relations
- Metrological usefulness and entanglement conditions

Robertson-Schrödinger inequality

The Robertson-Schrödinger inequality is defined as

$$(\Delta A)_{\varrho}^2 (\Delta B)_{\varrho}^2 \geq \frac{1}{4} |L_{\varrho}|^2,$$

where the lower bound is given by

$$L_{\varrho} = \sqrt{|\langle \{A, B\} \rangle_{\varrho} - 2\langle A \rangle_{\varrho} \langle B \rangle_{\varrho}|^2 + |\langle C \rangle_{\varrho}|^2},$$

$\{A, B\} = AB + BA$ is the anticommutator, and we used the definition

$$C = i[A, B].$$

Important: L_{ϱ} is neither convex nor concave in ϱ .

Heisenberg uncertainty

The Heisenberg inequality is defined as

$$(\Delta A)^2_{\varrho}(\Delta B)^2_{\varrho} \geq \frac{1}{4}|\langle C \rangle_{\varrho}|^2,$$

where we used the definition

$$C = i[A, B].$$

The two inequalities together

We have two inequalities

$$(\Delta A)_{\varrho}^2 (\Delta B)_{\varrho}^2 \geq \frac{1}{4} |L_{\varrho}|^2 \geq \frac{1}{4} |\langle C \rangle_{\varrho}|^2.$$

The Heisenberg uncertainty can be saturated only if

$$|L_{\varrho}| = |\langle C \rangle_{\varrho}|.$$

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 **Uncertainty relations with the variance and the QFI**

- **Uncertainty relations based on a convex roof of the bound**
- Uncertainty relations based on a concave roof of the bound
- Several variances and the QFI
- Simple observation to prove further relations
- Metrological usefulness and entanglement conditions

Robertson-Schrödinger inequality for ϱ_k

- Consider a decomposition to mixed states

$$\varrho = \sum_k p_k \varrho_k.$$

- For such a decomposition, for all ϱ_k the Robertson-Schrödinger inequality holds

$$(\Delta A)^2_{\varrho_k} (\Delta B)^2_{\varrho_k} \geq \frac{1}{4} |L_{\varrho_k}|^2.$$

- Let us consider the inequality

$$\left(\sum_k p_k a_k \right) \left(\sum_k p_k b_k \right) \geq \left(\sum_k p_k \sqrt{a_k b_k} \right)^2,$$

where $a_k, b_k \geq 0$.

Uncertainty with the variance and the QFI

- Hence, we arrive at

$$\left[\sum_k p_k (\Delta A)^2_{\varrho_k} \right] \left[\sum_k p_k (\Delta B)^2_{\varrho_k} \right] \geq \frac{1}{4} \left[\sum_k p_k L_{\varrho_k} \right]^2.$$

- We can choose the decomposition such that

$$\sum_k p_k (\Delta B)^2_{\varrho_k} = F_Q[\varrho, B]/4.$$

- Due to the concavity of the variance we also know that

$$\sum_k p_k (\Delta A)^2_{\varrho_k} \leq (\Delta A)^2.$$

- Hence, it follows that

$$(\Delta A)^2_{\varrho} F_Q[\varrho, B] \geq \left(\sum_k p_k L_{\varrho_k} \right)^2.$$

- In order to use the previous inequality, we need to know the decomposition $\{p_k, \varrho_k\}$ that minimizes it.

Uncertainty with the variance and the QFI II

- We can have a inequality where we do not need to know that decomposition

$$(\Delta A)^2_{\varrho} F_Q[\varrho, B] \geq \left(\min_{\{p_k, \varrho_k\}} \sum_k p_k L_{\varrho_k} \right)^2 .$$

- On the right-hand side, the bound is defined based on a convex roof.
- It can be shown that we can move to pure state decompositions.
- We know that

$$L_{\psi_k} \geq |\langle C \rangle_{\psi_k}|$$

holds.

Uncertainty with the variance and the QFI II

- Then, we can obtain the inequality

$$(\Delta A)^2_{\varrho} F_Q[\varrho, B] \geq \left(\min_{\{p_k, |\psi_k\rangle\}} \sum_k p_k |\langle C \rangle_{\psi_k}| \right)^2,$$

- Using

$$\sum_k p_k |\langle C \rangle_{\psi_k}| \geq \left| \sum_k p_k \langle C \rangle_{\psi_k} \right| \equiv |\langle C \rangle_{\varrho}|,$$

we arrive at the improved Heisenberg-Robertson uncertainty

$$(\Delta A)^2_{\varrho} F_Q[\varrho, B] \geq |\langle C \rangle_{\varrho}|^2.$$

Uncertainty with the variance and the QFI III

- The Heisenberg uncertainty

$$(\Delta A)^2_{\varrho} (\Delta B)^2_{\varrho} \geq \frac{1}{4} |\langle i[A, B] \rangle_{\varrho}|^2.$$

- The improved Heisenberg uncertainty

$$(\Delta A)^2_{\varrho} F_Q[\varrho, B] \geq |\langle i[A, B] \rangle_{\varrho}|^2.$$

- It has been derived originally with a different method in

F. Fröwis, R. Schmied, and N. Gisin, Phys. Rev. A 92, 012102 (2015).

Conditions for saturation

- Conditions for saturating the relation with the simple bound

$$(\Delta A)^2_{\varrho} F_Q[\varrho, B] \geq \left(\min_{\{p_k, \varrho_k\}} \sum_k p_k L_{\varrho_k} \right)^2 \geq |\langle C \rangle_{\varrho}|^2.$$

- We have to have equality on the right-hand side.
- The optimal decomposition can be made with pure components ψ_k . Then, for all k, l we must have

$$\frac{1}{2} \langle \{A, B\} \rangle_{\psi_k} - \langle A \rangle_{\psi_k} \langle B \rangle_{\psi_k} = 0,$$

$$(\Delta A)^2_{\psi_k} = (\Delta A)^2_{\psi_l},$$

$$(\Delta B)^2_{\psi_k} = (\Delta B)^2_{\psi_l},$$

$$|\langle C \rangle_{\psi_k}| = |\langle C \rangle_{\varrho}|,$$

etc.

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 **Uncertainty relations with the variance and the QFI**

- Uncertainty relations based on a convex roof of the bound
- **Uncertainty relations based on a concave roof of the bound**
- Several variances and the QFI
- Simple observation to prove further relations
- Metrological usefulness and entanglement conditions

Uncertainty relation based on a concave roof

- For any decomposition $\{p_k, \varrho_k\}$ we have

$$(\Delta A)^2(\Delta B)^2 \geq \frac{1}{4} \left(\sum_k p_k L_{\varrho_k} \right)^2,$$

where

$$L_{\varrho} = \sqrt{|\langle \{A, B\} \rangle_{\varrho} - 2\langle A \rangle_{\varrho} \langle B \rangle_{\varrho}|^2 + |\langle C \rangle_{\varrho}|^2}.$$

- We can even take a concave roof on the right-hand side

$$(\Delta A)^2_{\varrho} (\Delta B)^2_{\varrho} \geq \frac{1}{4} \left(\max_{\{p_k, \varrho_k\}} \sum_k p_k L_{\varrho_k} \right)^2.$$

- We prove that for qubits the above inequality is saturated for all states.

Any decomposition leads to a valid bound

- A simple inequality that is valid

$$(\Delta A)^2_{\varrho} (\Delta B)^2_{\varrho} \geq \frac{1}{4} \left(\sum_k \lambda_k L_{|k\rangle} \right)^2.$$

if we have an eigendecomposition

$$\varrho = \sum_k \lambda_k |k\rangle \langle k|.$$

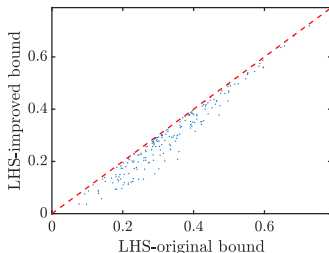
- We can even look for concave roof numerically.

Numerical example

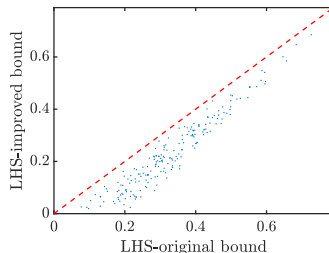
- For $d = 3$

$$(\Delta J_x)^2_{\varrho} (\Delta J_y)^2_{\varrho} \geq \frac{1}{4} \left(\max_{\{p_k, \varrho_k\}} \sum_k p_k L_{\varrho_k} \right)^2.$$

- Eigenvalues J_x and J_y are $-1, 0, +1$.



Using the eigendecomposition



Numerical search

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 **Uncertainty relations with the variance and the QFI**

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- **Several variances and the QFI**
- Simple observation to prove further relations
- Metrological usefulness and entanglement conditions

Uncertainty relations with a variance and the QFI

- Similar ideas work even for a sum of two variances. For example, for a continuous variable system

$$(\Delta x)^2 + (\Delta p)^2 \geq 1$$

holds, where x and p are the position and momentum operators.

- Hence, for any decompositions of the density matrix it follows that

$$\sum_k p_k (\Delta x)^2_{\psi_k} + \sum_k p_k (\Delta p)^2_{\psi_k} \geq 1.$$

- For p we choose the decomposition that leads to the minimal value for the average variance, i.e., the QFI over four.
- Then, since $\sum_k p_k (\Delta x)^2_{\psi_k} \leq (\Delta x)^2$ holds, it follows that

$$(\Delta x)^2 + \frac{1}{4} F_Q[\varrho, p] \geq 1.$$

Uncertainty relations with two variances and the QFI

- Let us start from the relation for pure states

$$(\Delta J_x)^2 + (\Delta J_y)^2 + (\Delta J_z)^2 \geq j,$$

where J_l are the spin components fulfilling

$$J_x^2 + J_y^2 + J_z^2 = j(j+1)\mathbb{1}.$$

- Based on similar ideas we arriving at

$$(\Delta J_x)^2 + (\Delta J_y)^2 + \frac{1}{4}F_Q[\varrho, J_z] \geq j.$$

- See parallel publication in

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 **Uncertainty relations with the variance and the QFI**

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- Several variances and the QFI
- **Simple observation to prove further relations**
- Metrological usefulness and entanglement conditions

Simple observation to prove further relations

- Let us consider a relation

$$\underbrace{(\Delta A)^2}_{\text{variance}}_{\varrho} \geq \underbrace{g(\varrho)}_{\text{convex in } \varrho},$$

which is true for pure states.

- If $g(\varrho)$ is convex in density matrices, then

$$\frac{1}{4}F_Q[\varrho, A] \geq g(\varrho)$$

holds for mixed states.

- Proof.* $\frac{1}{4}F_Q[\varrho, A]$ is given as a convex roof of the variance.
- It is the largest convex function that equals $(\Delta A)^2_{\varrho}$ for all pure states.



Repeating the proof for the two variances and the QFI

- We rewrite the relation with three variances as

$$\underbrace{(\Delta J_x)^2}_{\text{variance}} \geq j - \underbrace{(\Delta J_y)^2 - (\Delta J_z)^2}_{\text{convex in } \varrho},$$

- The right-hand side is convex in ϱ and the left-hand side is a variance.
- Hence,

$$\frac{1}{4}F_Q[\varrho, J_z] \geq j - (\Delta J_x)^2 - (\Delta J_y)^2.$$

Outline

1 Motivation

- How can we improve uncertainty relations?

2 Background

- Quantum Fisher information
- Uncertainty relations

3 **Uncertainty relations with the variance and the QFI**

- Uncertainty relations based on a convex roof of the bound
- Uncertainty relations based on a concave roof of the bound
- Several variances and the QFI
- Simple observation to prove further relations
- **Metrological usefulness and entanglement conditions**

CV systems (for spin systems, the derivation is similar, but longer)

- Consider entanglement detection in two-mode systems with uncertainty relations.
- A well-known entanglement criterion is

$$[\Delta(x_1 + x_2)]^2 + [\Delta(p_1 - p_2)]^2 \geq 2.$$

If a quantum state violates it, then it is entangled.

L.-M. Duan, G. Giedke, J. I. Cirac, and P. Zoller, Phys. Rev. Lett. 84, 2722 (2000);
R. Simon, Phys. Rev. Lett. 84, 2726 (2000).

CV systems II

- For a two-mode state, the following uncertainty relation holds

$$[\Delta(x_1 + x_2)]^2 + [\Delta(p_1 - p_2)]^2 \geq 4/F_Q[\varrho, p_1 + p_2] + 4/F_Q[\varrho, x_1 - x_2].$$

As a consequence, we know something about metrology with states violating the entanglement condition (details are in the paper).

- *Proof.* We start from the relations

$$\begin{aligned} [\Delta(x_1 + x_2)]^2 F_Q[\varrho, p_1 + p_2] &\geq 4, \\ [\Delta(p_1 - p_2)]^2 F_Q[\varrho, x_1 - x_2] &\geq 4. \end{aligned}$$

- Then, in both inequalities we divide by the term containing the QFI. Finally, we sum the two resulting inequalities. ■

Summary

- We showed how to derive new uncertainty relations with the variance and the quantum Fisher information based on simple convexity arguments.

See:

Géza Tóth and Florian Fröwis,

Uncertainty relations with the variance and the quantum Fisher information based on convex decompositions of density matrices,

,

[Phys. Rev. Research 4, 013075 \(2022\)](#).

THANK YOU FOR YOUR ATTENTION!