

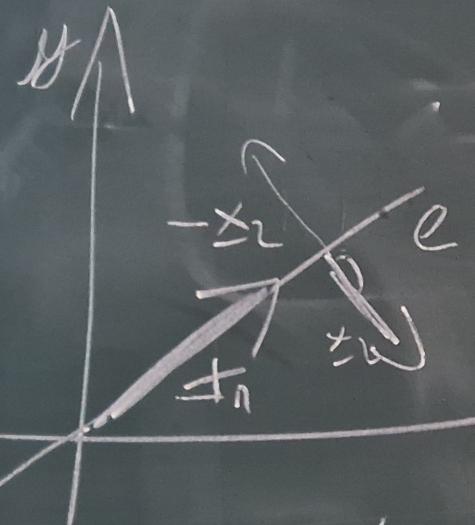
$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$+ \begin{pmatrix} 0 - a_{21}a_{31} \\ a_{21}0 - a_{32} \\ a_{31}a_{32}0 \\ 0 \end{pmatrix} = 0$$

$$\text{trace}(\Xi_4) > 4$$

8.22 Examples of linear transformations

a) Mirroring the vectors of a plan to a line



M: mirroring vectors on " ℓ " line

$$M \cdot x = f \cdot x$$

$$x_1 \parallel \ell : x \parallel \ell \text{ line}$$

$x_2 \perp \ell : x \perp \ell \text{ line}$

b) Projection of the vectors of a plan to " ℓ " line

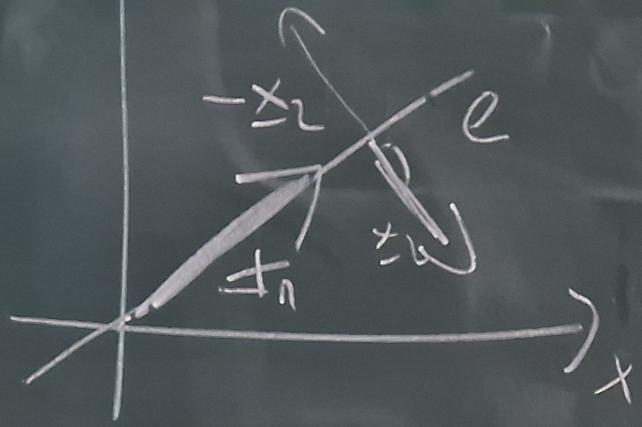


P: projection of x to " ℓ " line

$$P \cdot x = l \cdot x$$

$$x_1 \parallel \ell : x \parallel \ell \text{ line}$$

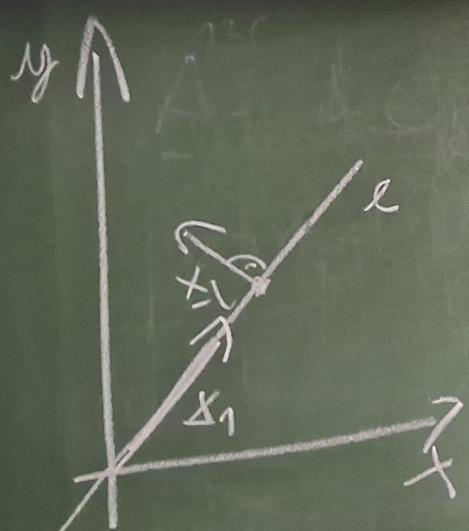
$x_2 \perp \ell : x \perp \ell \text{ line}$



$$M \cdot x = f \cdot x$$

$$x_{11} = 1 : x \parallel l \text{ like}$$

b) Projection of the vectors of a plan to "l" line



P: projection of x to "l" line

$$P_l x = l x$$

$$x_{11}, l = 1 : x \parallel l \text{ line}$$

$$x_{21}, l = 0 : x \perp l \text{ line}$$

somoak. Ezen felül tudjuk azt is, hogy fontos mátrix tulajdonságok invariánsak a hasonlóságra. E paragrafusban e tulajdonságok körét fogjuk bővíteni.

c) Rotation of the vectors of the space by α and



R: Rotation around ℓ'' line by α and

$$R \cdot x = d \pm$$

$$\sum_{i=1}^n d_i = 1 : x \parallel \ell'' \text{ line}$$

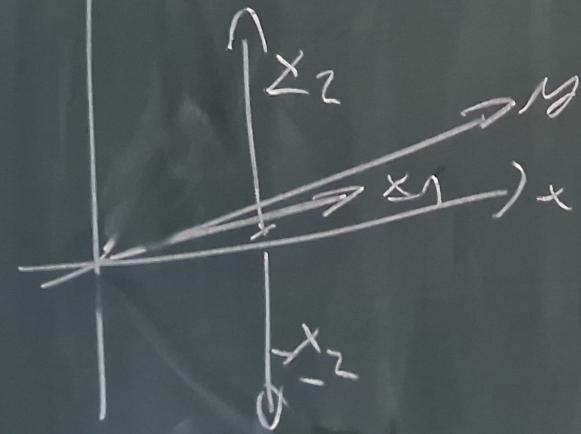
d) Position of 3D vectors to a

P. Mirroring to S_1 plane
 $x_i \rightarrow x_i \in S_1$ if $x_i \in S_1$

$$+ S(A(S)) \quad \sum_{i=1}^n d_i = 1 : S$$

e) Minimizing of 3D vectors to S^{plan}

\vec{z}



$S(x, b)$

$$M\vec{x} = \lambda\vec{x}$$

$$\vec{x}_1 | \lambda=1 : \vec{x} \in S$$

$$\vec{x}_2 | \lambda=1 \quad \vec{x} \perp S$$