



(PTIA0301) Elementary Linear Algebra

Dr. Gabor FACSKO, PhD

Senior Research Fellow

facskog@gamma.ttk.pte.hu

University of Pécs, Faculty of Sciences, Institute of Mathematics and Informatics, 7624 Pécs, Ifjuság útja 6.
Wigner Research Centre for Physics, Department of Space Physics and Space Technology, 1121 Budapest, Konkoly-Thege Miklós ut 29-33.
<https://facsko.ttk.pte.hu>

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Unitvector

- ▶ Definition: The unit vectors are vectors with unit (1) length. The canonic basis of \mathbb{R}^3 is

$$\mathbf{i} = \mathbf{e}_1 = (1, 0, 0), \mathbf{j} = \mathbf{e}_2 = (0, 1, 0), \mathbf{k} = \mathbf{e}_3 = (0, 0, 1).$$

- ▶ Thesis: For all $\mathbf{v} (v_1, v_2, v_3)$ 3D vector:

$$\mathbf{v} = v_1 \mathbf{e}_1 + v_2 \mathbf{e}_2 + v_3 \mathbf{e}_3.$$

Definition: The normal of the $|\mathbf{v}| \neq 0$ vector is $\frac{\mathbf{v}}{|\mathbf{v}|}$.

Distance of points, equation of sphere I

- ▶ The M bisecting point of the segment between the $P_1(x_1, y_1, z_1)$ and the $P_2(x_2, y_2, z_2)$ points is

$$M\left(\frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}, \frac{z_1 + z_2}{2}\right).$$

- ▶ The distance of the $P_1(x_1, y_1, z_1)$ and the $P_2(x_2, y_2, z_2)$ points is the length of the \mathbf{a} , \mathbf{b} vectors with ending point of P_1 and P_2 : $|\mathbf{a} - \mathbf{b}|$.
- ▶ Definition: The distance of the $P_1(x_1, y_1, z_1)$ and the $P_2(x_2, y_2, z_2)$ points is

$$|P_1P_2| = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2}.$$

Distance of points, equation of sphere II

- Definition: The equation of the sphere with a radius and (x_0, y_0, z_0) centre is

$$(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = a^2.$$

Scalar multiplication of vectors I

- Definition. The scalar (or inner) multiplication of two vectors is

$$\mathbf{ab} = |\mathbf{a}| \cdot |\mathbf{b}| \cos \theta$$

where $\theta = (\mathbf{a}, \mathbf{b}) \angle$ és $(\mathbf{a}, \mathbf{b} \in V^3)$.

- Note that $\mathbf{aa} = |\mathbf{a}|^2$.
- Thesis: (the features of scalar multiplication):
 - commutative: $\mathbf{ab} = \mathbf{ba}$ és $(\mathbf{a}, \mathbf{b} \in V^3)$.
 - additive: $(\mathbf{a} + \mathbf{b})\mathbf{c} = \mathbf{ac} + \mathbf{bc}$ és $(\mathbf{a}, \mathbf{b}, \mathbf{c} \in V^3)$.
 - homogenous: $(\lambda\mathbf{a})\mathbf{b} = \lambda(\mathbf{ab})$, where $\lambda \in \mathbb{R}$ és $(\mathbf{ab} \in V^3)$.
 - positive definit: $\mathbf{aa} \geq 0$, ahol $(\mathbf{a} \in V^3)$ és $\mathbf{aa} = 0 \Leftrightarrow \mathbf{a} = \mathbf{0}$.

Scalar multiplication of vectors II

- Thesis: The scalar multiplication of $\mathbf{a} = (a_1, a_2, a_3)$ and $\mathbf{b} = (b_1, b_2, b_3)$ vectors is

$$\mathbf{ab} = a_1b_1 + a_2b_2 + a_3b_3.$$

- Thesis: The angle of two non-zero vectors ($\mathbf{a} = (a_1, a_2, a_3)$ and $\mathbf{b} = (b_1, b_2, b_3)$) is

$$\cos \theta = \frac{\mathbf{ab}}{|\mathbf{a}| \cdot |\mathbf{b}|}$$

- Definition: The \mathbf{a} and \mathbf{b} vectors are orthogonal (perpendicular) if $\mathbf{ab} = 0$.
- Definition: The perpendicular projection ($proj_{\mathbf{b}}\mathbf{a}$) of \mathbf{a} vector to \mathbf{b} vector is that \mathbf{b} directed vector that ends in the point that is determined by a perpendicular line to \mathbf{b} vector.

Scalar multiplication of vectors III

- Thesis: If $(\mathbf{a}\mathbf{b} \in V^3)$, then

$$\text{proj}_{\mathbf{b}} \mathbf{a} = \frac{\mathbf{a}\mathbf{b}}{|\mathbf{b}|^2} \cdot \mathbf{b}.$$

- If \mathbf{b} unit vector has unit length, then the formula is simple:

$$\text{proj}_{\mathbf{b}} \mathbf{a} = (\mathbf{a}\mathbf{b}) \mathbf{b}.$$

The End

Thank you for your attention!