

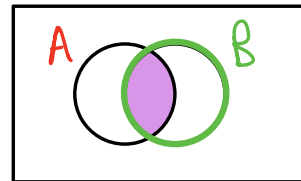
Final Review (post-midterm material)

Discrete Probability

- outcome, w
- Sample space, $\Omega = \{w_1, w_2, \dots\}$
- Event, $E \subseteq \Omega$
- Probability space: $\Omega + \frac{P(w_i)}{\text{probability}}$
- $P[E] = \frac{\sum_{w \in E} P(w)}{\sum_{w \in \Omega} P(w)}$
- Uniform Space: $P[E] = \frac{|E|}{|\Omega|}$ (counting problem!)

Conditional Probability

$$P[A|B] = \frac{P[A \cap B]}{P[B]}$$



Calculating probabilities:

Total : $P[E] = \sum P[\underbrace{E \cap C_i}_{\text{"pieces"}}] = \sum P[E|C_i] P[C_i]$
Prob. Law :

Bayes: $P[A|B] = \frac{P[B|A] P[A]}{P[B]}$

Independence :

$$P[A \cap B] = P[A] P[B]$$

$$P[A|B] = P[A]$$

$$P[B|A] = P[B]$$

Mutual \Rightarrow Pairwise Independence

Random Variables (Discrete)

$$X = \begin{cases} x_1 & \text{w.p. } p_1 \\ x_2 & \text{w.p. } p_2 \\ \vdots & \end{cases}$$

- PMF: $P[X=i]$

- $E[X] = \sum_i i \cdot P[X=i]$

Notable Distributions

- Bernoulli(p)
- Bin(n, p)
- Uniform $\{1, \dots, n\}$
- Geometric(p)
- Poisson(λ)
- Hypergeometric(N, B, n)

Estimation

MMSE / Conditional Expectation: $E[Y|X]$

LLSE: $L[Y|X] = E[Y] + \frac{\text{Cov}(X, Y)}{\text{Var}(X)} (X - E[X])$

Finding $E[X]$:

- Indicators + Linearity of Expectation

$$X = I_1 + I_2 + \dots + I_n$$

$$E[X] = E[I_1 + I_2 + \dots + I_n] = E[I_1] + \dots + E[I_n]$$

- Symmetry

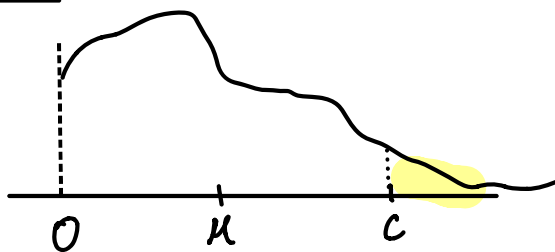
- Smoothing Rule

$$E[E[X|Y]] = E[X]$$

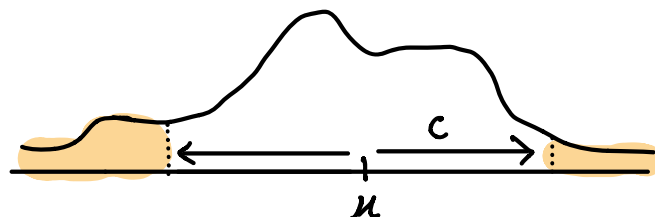
Variance: $\text{Var}(X) = E[X^2] - (E[X])^2$

Concentration Bounds

- Markov



- Chebyshev



- Law of Large Numbers

Average of i.i.d. observations $\rightarrow E[X_i]$

- Central Limit Theorem

Normalized Sum of i.i.d. observations $\rightarrow \mathcal{N}(0,1)$

Random Variables (Continuous)

p.d.f., $f_X(x)$

c.d.f., $P[X \leq x] = F[x]$

$$f_X(x) = \frac{dF}{dx}$$

$$E[X] = \int_{-\infty}^{\infty} x f_X(x) dx$$

Notable Distributions $\left\{ \begin{array}{l} \text{Uniform}[0, l] \\ \text{Exp}(\lambda) \\ \mathcal{N}(\mu, \sigma^2) \end{array} \right.$

Markov Chains

$$\pi_t = [\pi_t(1) \ \pi_t(2) \ \dots \ \pi_t(n)] = [P(X_t=1) \ P(X_t=2) \ \dots \ P(X_t=n)]$$

represents distribution at time t

π_0 = initial distribution

$$\pi_{t+1} = \pi_t P \implies \pi_t = \pi_0 P^n$$

$P_{i,j}$ = transition prob. from i to j

invariant distribution: $\pi = \pi P$

Irreducibility
(“reachability”)

Aperiodicity

Conditions of convergence (“Big Theorem”)

(calculate and check $d(i)=1$)

↑
gcd of periods of state i

Derivation of $\pi_{t+1} = \pi_t P$

$$\pi_t = [\pi_t(0) \ \pi_t(1) \ \pi_t(2)]$$

$$\pi_{t+1}(i) = \pi_t(0) \cdot P_{0,i} + \pi_t(1) \cdot P_{1,i} + \pi_t(2) \cdot P_{2,i}$$

$$[\pi_t(0) \ \pi_t(1) \ \pi_t(2)] \begin{bmatrix} P_{0,0} & P_{0,1} & P_{0,2} \\ P_{1,0} & P_{1,1} & P_{1,2} \\ P_{2,0} & P_{2,1} & P_{2,2} \end{bmatrix}$$

$$= [\pi_{t+1}(0) \ \pi_{t+1}(1) \ \pi_{t+1}(2)]$$

→ $\pi_t(0) \cdot P_{0,0} + \pi_t(1) \cdot P_{1,0} + \pi_t(2) \cdot P_{2,0}$
→ $\pi_t(0) \cdot P_{0,1} + \pi_t(1) \cdot P_{1,1} + \pi_t(2) \cdot P_{2,1}$
→ $\pi_t(0) \cdot P_{0,2} + \pi_t(1) \cdot P_{1,2} + \pi_t(2) \cdot P_{2,2}$