

# Equations of motion for Einstein-scalar system

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## 1 General setting

We study the Einstein equation with negative cosmological constant, coupled to a real massless scalar field,

$$G_{ab} - \frac{3}{L^2}g_{ab} = T_{ab}^\phi, \quad (1)$$

where

$$T_{ab}^\phi = \nabla_a \phi \nabla_b \phi - \frac{1}{2}g_{ab} \nabla^c \phi \nabla_c \phi. \quad (2)$$

Here  $L$  is the AdS radius, and we work in  $d = 4$ .

We also impose spherical symmetry, and we work in ingoing Eddington-Finkelstein coordinates,

$$ds^2 = -A(v, r)dv^2 + 2dvdr + \Sigma(v, r)^2 (d\theta^2 + \sin^2 \theta d\phi^2). \quad (3)$$

If we set

$$A(v, r) = 1 - \frac{2M}{r} + \frac{r^2}{L^2}, \quad \Sigma(v, r) = r, \quad (4)$$

this reduces to the Schwarzschild-AdS black hole. We will of course keep  $A$  and  $\Sigma$  as free functions, as they will be determined by the Einstein equation.

## 2 Equations of motion

The wave equation takes the form

$$0 = 2 \frac{\Sigma'}{\Sigma} d_+ \phi + 2 \frac{d_+ \Sigma}{\Sigma} \phi' + 2(d_+ \phi)', \quad (5)$$

while the Einstein equation is equivalent to

$$0 = -\frac{1}{2} - \frac{3\Sigma^2}{2L^2} + (d_+ \Sigma)\Sigma' + \Sigma(d_+ \Sigma)', \quad (6)$$

$$0 = \frac{2}{\Sigma^2} - 4 \frac{(d_+ \Sigma)\Sigma'}{\Sigma^2} + 2(d_+ \phi)\phi' + A'', \quad (7)$$

$$0 = d_+ d_+ \Sigma + \frac{1}{2}\Sigma(d_+ \phi)^2 - \frac{1}{2}(d_+ \Sigma)A', \quad (8)$$

$$0 = \frac{1}{2}\Sigma(\phi')^2 + \Sigma''. \quad (9)$$

Note that we expressed time derivatives in terms of

$$d_+ f = \dot{f} + \frac{1}{2} A f', \quad (10)$$

where prime and dot denote partial derivatives with respect to  $r$  and  $v$ , respectively.

Examining the above equations, we see that, given  $\phi(v = v_0, r)$ , we can integrate as follows:

1. Solve (5), (6), (7), and (9) for  $d_+ \phi$ ,  $d_+ \Sigma$ ,  $A$  and  $\Sigma$ , respectively, at time  $v = v_0$  by integrating radially.
2. Knowledge of  $A$  and  $d_+ \phi$  gives rise to the time derivative  $\partial_v \phi$  via (10). This may be integrated in time to obtain  $\phi(v = v_0 + \Delta v, x)$ .

Equation (8) is not needed.

While this basic strategy will eventually be implemented, there are several challenges that must be addressed. First, we require a finite spatial domain, so we define a new variable  $\rho = 1/r$ . There is also some gauge freedom in the equations, which must be fixed. We also require boundary data for the fields at  $r \rightarrow \infty$ , which is a regular singular point that must be treated carefully.

### 3 Compact radial coordinate $\rho = 1/r$

One difficulty with integrating the equations directly is that the spatial coordinate  $r \in [r_0, \infty)$ . Thus, we compactify the spatial coordinate by defining a new coordinate  $\rho = 1/r$ . This gives rise to a compact domain  $\rho \in [0, 1/r_0]$ . We define new functions,

$$\phi(v, r) = \varphi(v, 1/r) = \varphi(v, \rho), \quad (11)$$

$$d_+ \phi(v, r) = \Pi(v, 1/r) = \Pi(v, \rho), \quad (12)$$

$$\Sigma(v, r) = \sigma(v, 1/r) = \sigma(v, \rho), \quad (13)$$

$$d_+ \Sigma(v, r) = s(v, 1/r) = s(v, \rho), \quad (14)$$

$$A(v, r) = \alpha(v, 1/r) = \alpha(v, \rho). \quad (15)$$

After this transformation, (5), (6), (7), and (9) take the form

$$\partial_\rho \Pi = -\frac{\partial_\rho \sigma}{\sigma} \Pi - \frac{s}{\sigma} \partial_\rho \varphi, \quad (16)$$

$$\partial_\rho s = -\frac{1}{2\rho^2 \sigma} - \frac{3\sigma}{2L^2 \rho^2} - \frac{s \partial_\rho \sigma}{\sigma}, \quad (17)$$

$$\partial_\rho^2 \alpha = -\frac{2}{\sigma^2 \rho^4} - \frac{4s \partial_\rho \sigma}{\rho^2 \sigma^2} + \frac{2}{\rho^2} \Pi \partial_\rho \varphi - \frac{2}{\rho} \partial_\rho \alpha, \quad (18)$$

$$\partial_\rho^2 \sigma = -\frac{1}{2} \sigma (\partial_\rho \varphi)^2 - \frac{2}{\rho} \partial_\rho \sigma, \quad (19)$$

respectively, while the time derivative of  $\varphi$  is

$$\partial_v \varphi = \Pi + \frac{\rho^2}{2} \alpha \partial_\rho \varphi. \quad (20)$$

## 4 Boundary conditions

In order to impose boundary conditions we must first study the asymptotic solution at infinity. We expand the general solution in a power series about  $\rho = 0$ , careful to enforce that the boundary metric be the Einstein static universe  $\mathbb{R} \times S^2$  (standard for global AdS), and that the scalar field satisfy “Dirichlet” conditions. We obtain,

$$\varphi(v, \rho) = \varphi_3 \rho^3 + \left( \frac{3}{2} L^2 \lambda \varphi_3 + L^2 \dot{\varphi}_3 \right) \rho^4 + O(\rho^5), \quad (21)$$

$$\sigma(v, \rho) = \frac{1}{\rho} + \frac{1}{2} L^2 \lambda - \frac{3}{20} \varphi_3^2 \rho^5 + O(\rho^6), \quad (22)$$

$$\alpha(v, \rho) = \frac{1}{L^2 \rho^2} + \frac{\lambda}{\rho} + \left( 1 + \frac{1}{4} L^2 \lambda^2 - L^2 \dot{\lambda} \right) - 2M\rho + ML^2 \lambda \rho^2 + O(\rho^3), \quad (23)$$

where  $\varphi_3(v)$  and  $\lambda(v)$  are functions of time, and  $M$  is a constant representing the ADM mass. The function  $\lambda(v)$  represents a gauge freedom to redefine the radial coordinate  $1/\rho \rightarrow 1/\rho + \lambda(v)$ , and may be chosen arbitrarily. The ADM mass may also be chosen freely. The function  $\varphi_3(v)$ , on the other hand, will arise as a consequence of the equations of motion.

Asymptotic behavior for the “time derivative” fields may be easily determined using (10),

$$\Pi(v, \rho) = -\frac{3}{2L^2} \varphi_3 \rho^2 + O(\rho^3), \quad (24)$$

$$s(v, \rho) = \frac{1}{2L^2 \rho^2} + \frac{\lambda}{2\rho} + \left( \frac{1}{2} + \frac{L^2}{8} \lambda^2 \right) - M\rho + \frac{1}{2} M^2 L^2 \lambda \rho + O(\rho^3). \quad (25)$$

Finally, we define new (hatted) dynamical variables that have better behavior as  $\rho \rightarrow 0$ . We take

$$\hat{\varphi} = \frac{1}{\rho^2} \varphi, \quad (26)$$

$$\hat{\Pi} = \frac{1}{\rho} \Pi, \quad (27)$$

$$(28)$$

as we did in the case with no backreaction, so that both scalar field variables have linear falloff to 0 as  $\rho \rightarrow 0$ . For the metric variables, we take

$$\hat{\sigma} = \sigma - \frac{1}{\rho}, \quad (29)$$

$$\hat{s} = s - \frac{1}{2L^2} \sigma^2 - \frac{1}{2}, \quad (30)$$

$$\hat{\alpha} = \alpha - \frac{1}{L^2} \sigma^2 - 1. \quad (31)$$

These definitions differ slightly from those of Chesler and Yaffe, which worked in the Poincaré patch and thus do not have the subtraction of  $\frac{1}{2}$  and 1 in (30) and (31), respectively. We also define two new auxiliary variables,

$$\hat{\tau} \equiv \partial_\rho \hat{\sigma}, \quad (32)$$

$$\hat{\beta} \equiv \partial_\rho \hat{\alpha}, \quad (33)$$

such that the final equations of motion only contain first spatial derivatives.

The  $\rho \rightarrow 0$  behavior of the new fields is

$$\hat{\varphi} = \varphi_3 \rho + O(\rho^2) \rightarrow 0, \quad (34)$$

$$\hat{\Pi} = -\frac{3}{2L^2} \varphi_3 \rho + O(\rho^2) \rightarrow 0, \quad (35)$$

$$\hat{\sigma} = \frac{1}{2} L^2 \lambda + O(\rho^5) \rightarrow \frac{1}{2} L^2 \lambda, \quad (36)$$

$$\hat{\tau} = O(\rho^4) \rightarrow 0, \quad (37)$$

$$\hat{s} = -M\rho + \frac{1}{2} M^2 L^2 \lambda \rho^2 + O(\rho^3) \rightarrow 0, \quad (38)$$

$$\hat{\alpha} = -L^2 \dot{\lambda} - 2M\rho + O(\rho^2) \rightarrow -L^2 \dot{\lambda}, \quad (39)$$

$$\hat{\beta} = -2M + 2M^2 L^2 \lambda \rho + O(\rho^2) \rightarrow -2M. \quad (40)$$

We will impose as boundary data the right hand side limits above (for all but  $\hat{\varphi}$ , which we integrate in time rather than radially). For the gauge condition, we set  $\lambda = 0$ , so the only nontrivial boundary condition is  $\hat{\beta}(\rho = 0) = -2M$ .

## 5 Equations in final form

The equations of motion are obtained in *Mathematica* by substituting these new variables. We obtain,

$$\begin{aligned} \partial_\rho \hat{\Pi} = & -\frac{\rho \hat{\sigma}^2 \hat{\varphi}}{L^2 (\rho \hat{\sigma} + 1)} - \frac{2 \hat{\sigma} \hat{\varphi}}{L^2 (\rho \hat{\sigma} + 1)} - \frac{\hat{\varphi}}{L^2 \rho (\rho \hat{\sigma} + 1)} - \frac{\rho^2 \hat{\sigma}^2 \partial_\rho \hat{\varphi}}{2L^2 (\rho \hat{\sigma} + 1)} - \frac{\rho \hat{\sigma} \partial_\rho \hat{\varphi}}{L^2 (\rho \hat{\sigma} + 1)} \\ & - \frac{\partial_\rho \hat{\varphi}}{2L^2 (\rho \hat{\sigma} + 1)} - \frac{\hat{\Pi} \rho \hat{\tau}}{\rho \hat{\sigma} + 1} - \frac{\hat{\Pi} \hat{\sigma}}{\rho \hat{\sigma} + 1} - \frac{\rho \hat{\varphi}}{\rho \hat{\sigma} + 1} - \frac{2 \rho \hat{s} \hat{\varphi}}{\rho \hat{\sigma} + 1} - \frac{\rho^2 \hat{s} \partial_\rho \hat{\varphi}}{\rho \hat{\sigma} + 1} - \frac{\rho^2 \partial_\rho \hat{\varphi}}{2 (\rho \hat{\sigma} + 1)}, \end{aligned} \quad (41)$$

$$\begin{aligned} \partial_\rho \hat{s} = & -\frac{3 \rho \hat{\sigma}^2 \hat{\tau}}{2L^2 (\rho \hat{\sigma} + 1)} - \frac{3 \hat{\sigma} \hat{\tau}}{L^2 (\rho \hat{\sigma} + 1)} - \frac{3 \hat{\tau}}{2L^2 \rho (\rho \hat{\sigma} + 1)} - \frac{\rho \hat{\tau}}{2 (\rho \hat{\sigma} + 1)} - \frac{\rho \hat{s} \hat{\tau}}{\rho \hat{\sigma} + 1} \\ & + \frac{\hat{s}}{\rho (\rho \hat{\sigma} + 1)}, \end{aligned} \quad (42)$$

$$\partial_\rho \hat{\alpha} = \hat{\beta}, \quad (43)$$

$$\begin{aligned} \partial_\rho \hat{\beta} = & -\frac{2 \hat{\beta} \rho \hat{\sigma}^2}{(\rho \hat{\sigma} + 1)^2} - \frac{4 \hat{\beta} \hat{\sigma}}{(\rho \hat{\sigma} + 1)^2} - \frac{2 \hat{\beta}}{\rho (\rho \hat{\sigma} + 1)^2} + \frac{4 \rho^4 \hat{\sigma}^4 \hat{\varphi}^2}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{16 \rho^3 \hat{\sigma}^3 \hat{\varphi}^2}{L^2 (\rho \hat{\sigma} + 1)^2} \\ & - \frac{2 \rho^2 \hat{\sigma}^2 \hat{\tau}^2}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{2 \hat{\tau}}{L^2 \rho^2 (\rho \hat{\sigma} + 1)^2} + \frac{24 \rho^2 \hat{\sigma}^2 \hat{\varphi}^2}{L^2 (\rho \hat{\sigma} + 1)^2} - \frac{4 \rho \hat{\sigma} \hat{\tau}^2}{L^2 (\rho \hat{\sigma} + 1)^2} \\ & - \frac{2 \hat{\tau}^2}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{2 \hat{\sigma}^2 \hat{\tau}}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{4 \hat{\sigma} \hat{\tau}}{L^2 \rho (\rho \hat{\sigma} + 1)^2} + \frac{16 \rho \hat{\sigma} \hat{\varphi}^2}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{4 \hat{\varphi}^2}{L^2 (\rho \hat{\sigma} + 1)^2} \\ & + \frac{\rho^6 \hat{\sigma}^4 \partial_\rho \hat{\varphi}^2}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{4 \rho^5 \hat{\sigma}^3 \partial_\rho \hat{\varphi}^2}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{6 \rho^4 \hat{\sigma}^2 \partial_\rho \hat{\varphi}^2}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{4 \rho^3 \hat{\sigma} \partial_\rho \hat{\varphi}^2}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{\rho^2 \partial_\rho \hat{\varphi}^2}{L^2 (\rho \hat{\sigma} + 1)^2} \\ & + \frac{4 \rho^5 \hat{\sigma}^4 \partial_\rho \hat{\varphi} \hat{\varphi}}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{16 \rho^4 \hat{\sigma}^3 \partial_\rho \hat{\varphi} \hat{\varphi}}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{24 \rho^3 \hat{\sigma}^2 \partial_\rho \hat{\varphi} \hat{\varphi}}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{16 \rho^2 \hat{\sigma} \partial_\rho \hat{\varphi} \hat{\varphi}}{L^2 (\rho \hat{\sigma} + 1)^2} + \frac{4 \rho \partial_\rho \hat{\varphi} \hat{\varphi}}{L^2 (\rho \hat{\sigma} + 1)^2} \\ & + \frac{4 \hat{\Pi} \rho^2 \hat{\sigma}^2 \hat{\varphi}}{(\rho \hat{\sigma} + 1)^2} + \frac{8 \hat{\Pi} \rho \hat{\sigma} \hat{\varphi}}{(\rho \hat{\sigma} + 1)^2} + \frac{4 \hat{\Pi} \hat{\varphi}}{(\rho \hat{\sigma} + 1)^2} - \frac{2 \hat{\tau}}{(\rho \hat{\sigma} + 1)^2} + \frac{4 \hat{s}}{\rho^2 (\rho \hat{\sigma} + 1)^2} - \frac{4 \hat{s} \hat{\tau}}{(\rho \hat{\sigma} + 1)^2} \\ & + \frac{2 \hat{\Pi} \rho^3 \hat{\sigma}^2 \partial_\rho \hat{\varphi}}{(\rho \hat{\sigma} + 1)^2} + \frac{4 \hat{\Pi} \rho^2 \hat{\sigma} \partial_\rho \hat{\varphi}}{(\rho \hat{\sigma} + 1)^2} + \frac{2 \hat{\Pi} \rho \partial_\rho \hat{\varphi}}{(\rho \hat{\sigma} + 1)^2}, \end{aligned} \quad (44)$$

$$\partial_\rho \hat{\sigma} = \hat{\tau}, \quad (45)$$

$$\partial_\rho \hat{\tau} = -2 \rho^2 \hat{\sigma} \hat{\varphi}^2 - \frac{2 \hat{\tau}}{\rho} - 2 \rho \hat{\varphi}^2 - \frac{1}{2} \rho^4 \hat{\sigma} \partial_\rho \hat{\varphi}^2 - \frac{\rho^3 \partial_\rho \hat{\varphi}^2}{2} - 2 \rho^3 \hat{\sigma} \partial_\rho \hat{\varphi} \hat{\varphi} - 2 \rho^2 \partial_\rho \hat{\varphi} \hat{\varphi}, \quad (46)$$

We shall integrate these equations along radial slices, given the boundary data and  $\varphi$  on an initial time slice.

Once  $\hat{\alpha}$ ,  $\hat{\sigma}$ ,  $\hat{\varphi}$  and  $\hat{\Pi}$  are known, we integrate  $\hat{\varphi}$  forward in time, using (20), which now takes the form

$$\begin{aligned} \partial_v \hat{\varphi} = & \hat{\alpha} \rho \hat{\varphi} + \frac{\rho \hat{\sigma}^2 \hat{\varphi}}{L^2} + \frac{\hat{\varphi}}{L^2 \rho} + \frac{2 \hat{\sigma} \hat{\varphi}}{L^2} + \frac{\rho^2 \hat{\sigma}^2 \partial_\rho \hat{\varphi}}{2L^2} + \frac{\rho \hat{\sigma} \partial_\rho \hat{\varphi}}{L^2} \\ & + \frac{\partial_\rho \hat{\varphi}}{2L^2} + \frac{\hat{\Pi}}{\rho} + \rho \hat{\varphi} + \frac{1}{2} \hat{\alpha} \rho^2 \partial_\rho \hat{\varphi} + \frac{\rho^2 \partial_\rho \hat{\varphi}}{2}. \end{aligned} \quad (47)$$

These equations must be treated carefully at  $\rho = 0$ , where some terms become ill-defined. Taking limits as  $\rho \rightarrow 0$ , we obtain

$$\lim_{\rho \rightarrow 0} \partial_\rho \hat{\Pi} = -\frac{3}{2L^2} \partial_\rho \hat{\varphi}, \quad (48)$$

$$\lim_{\rho \rightarrow 0} \partial_\rho \hat{s} = -M, \quad (49)$$

$$\lim_{\rho \rightarrow 0} \partial_\rho \hat{\alpha} = -2M, \quad (50)$$

$$\lim_{\rho \rightarrow 0} \partial_\rho \hat{\beta} = 2M^2 L^2 \lambda, \quad (51)$$

$$\lim_{\rho \rightarrow 0} \partial_\rho \hat{\sigma} = 0, \quad (52)$$

$$\lim_{\rho \rightarrow 0} \partial_\rho \hat{\tau} = 0. \quad (53)$$

These results are consistent with (34)–(40), as expected.