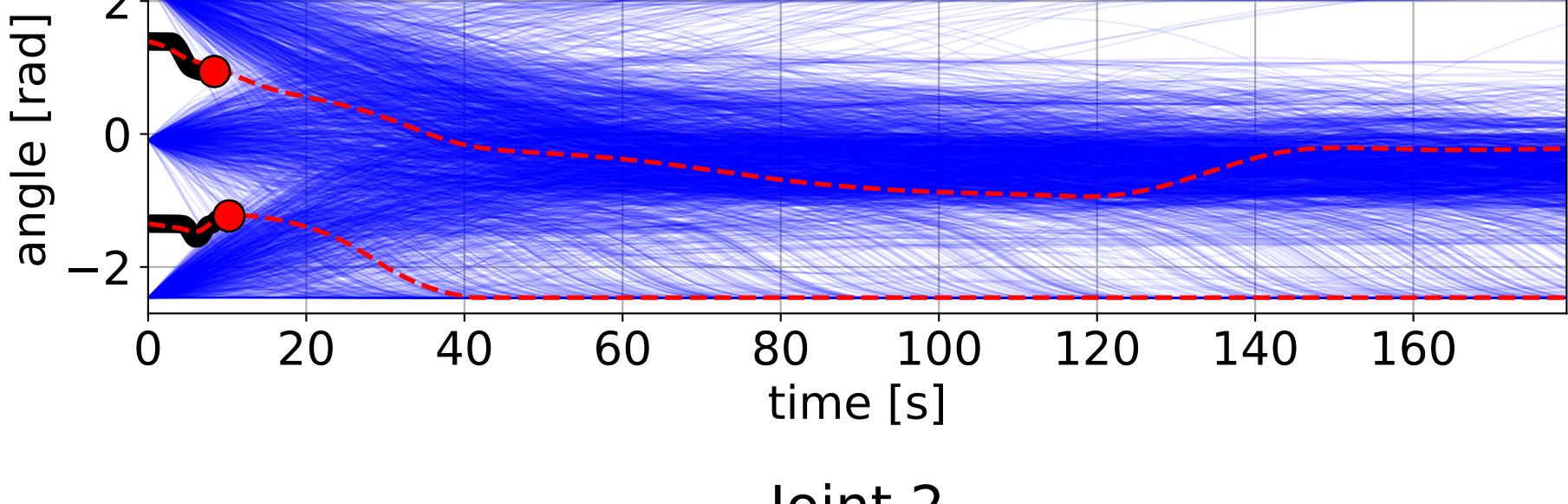
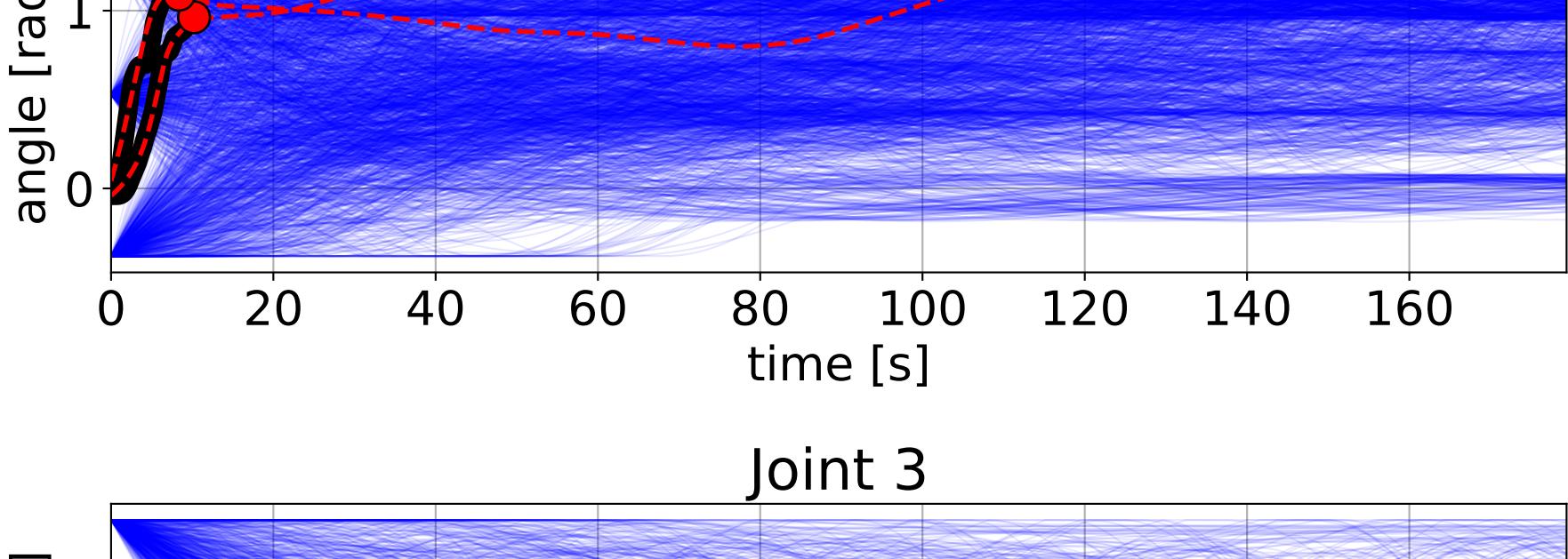


Dynamical System

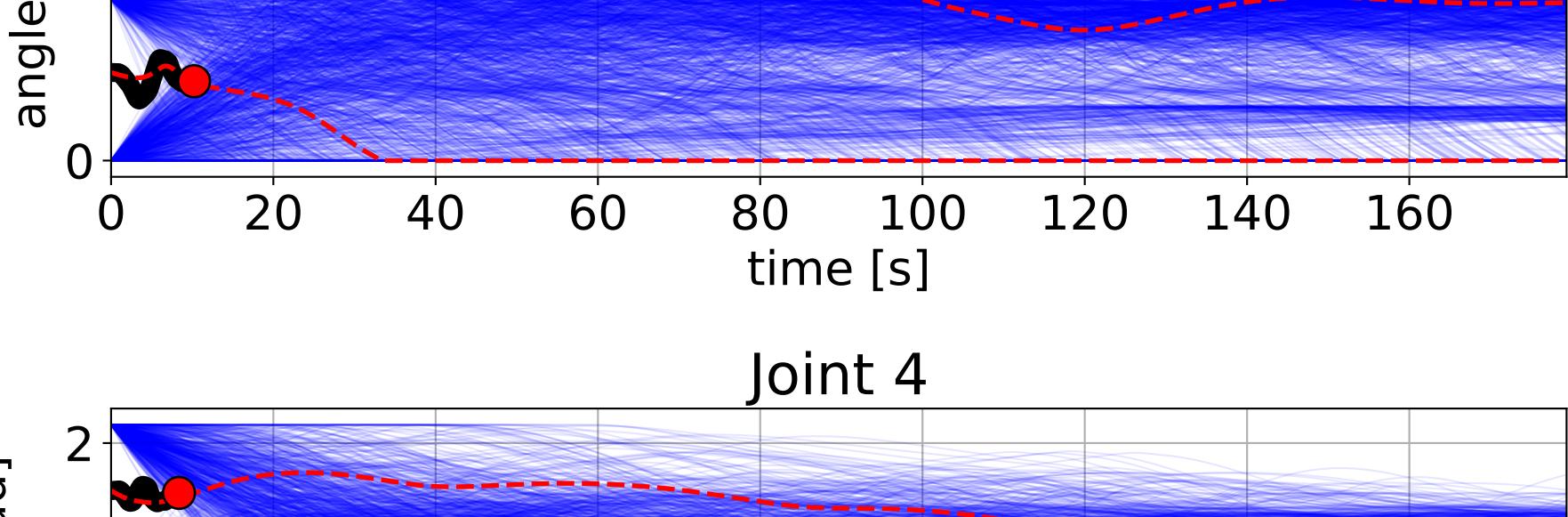
Joint 1



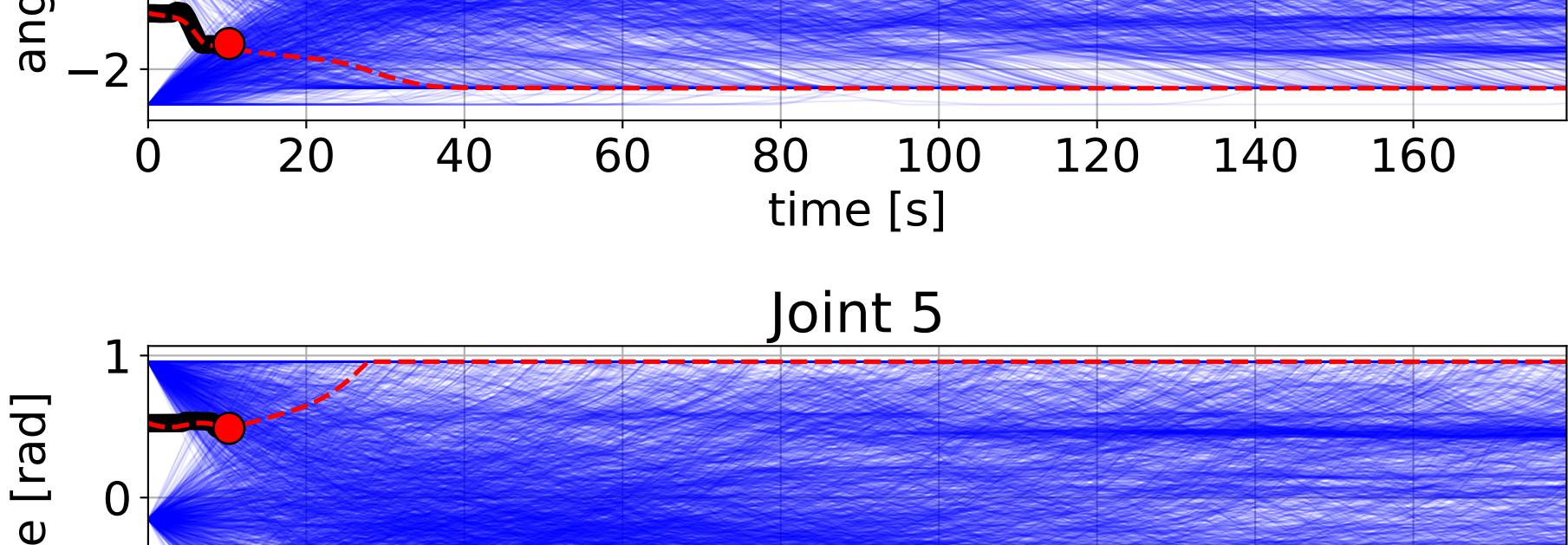
Joint 2



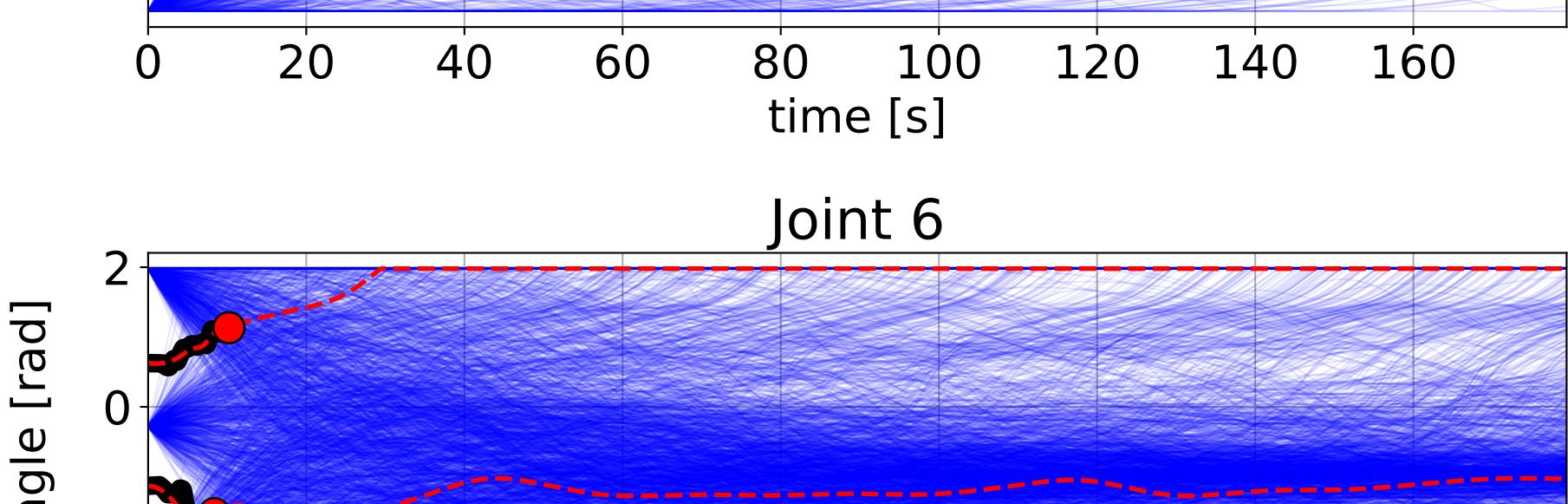
Joint 3



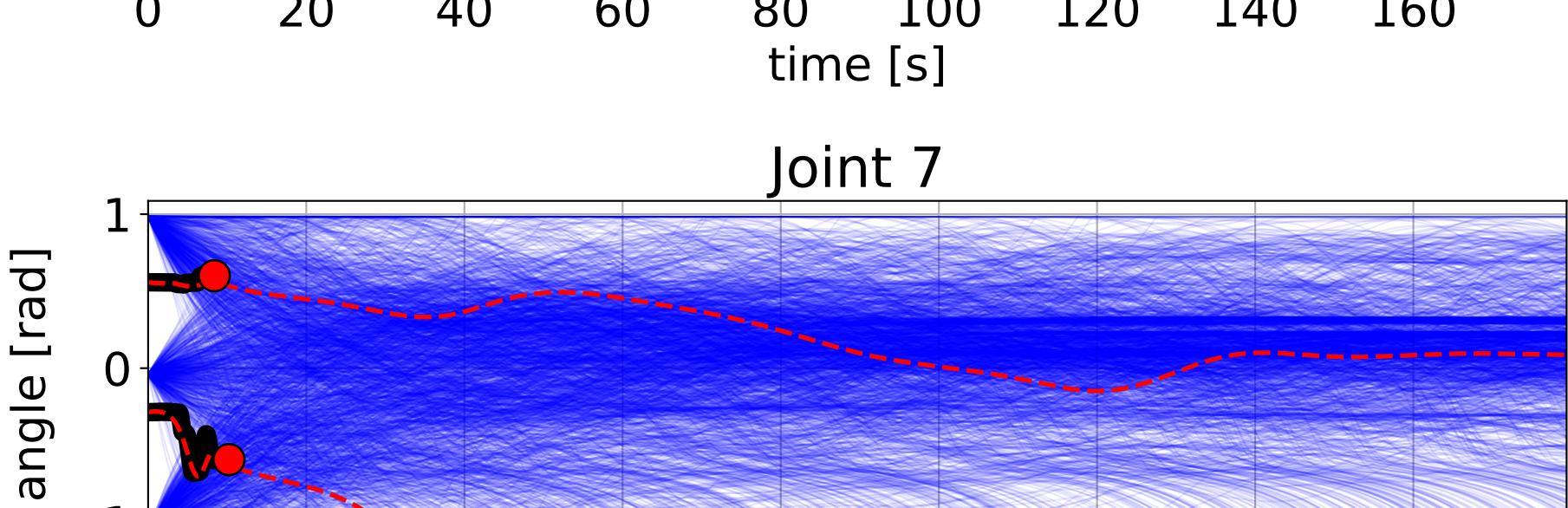
Joint 4



Joint 5



Joint 6



Joint 7