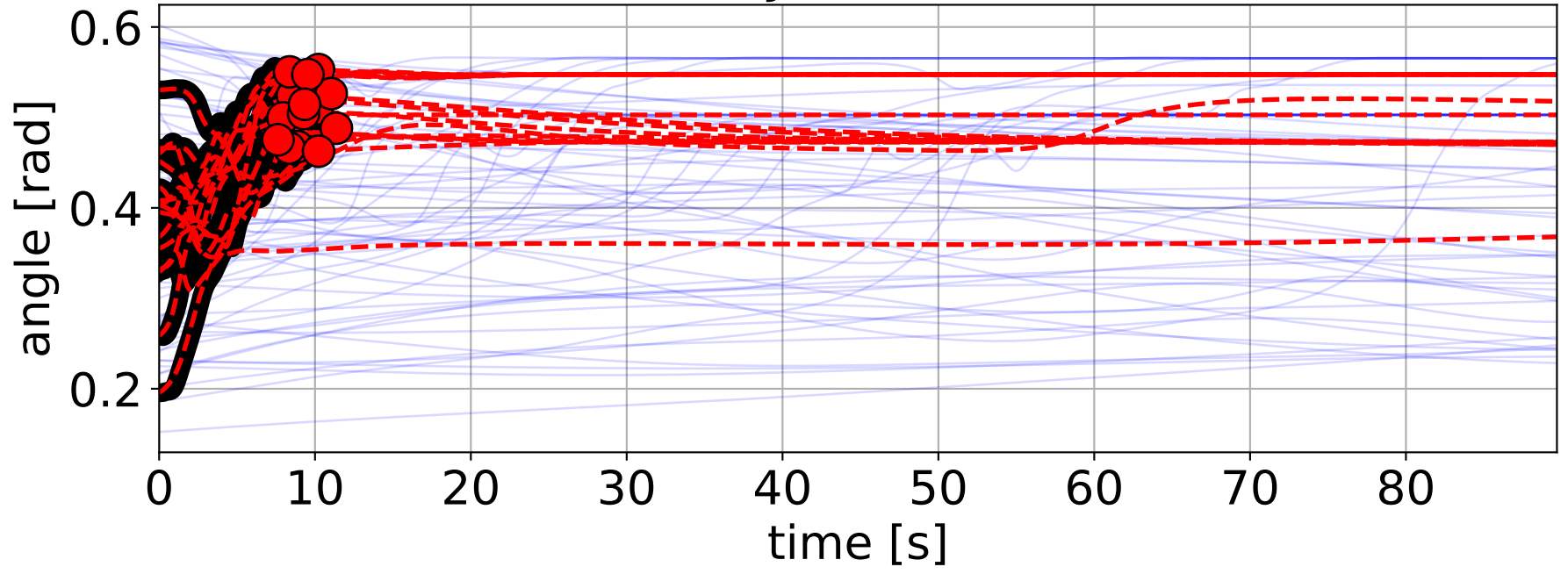
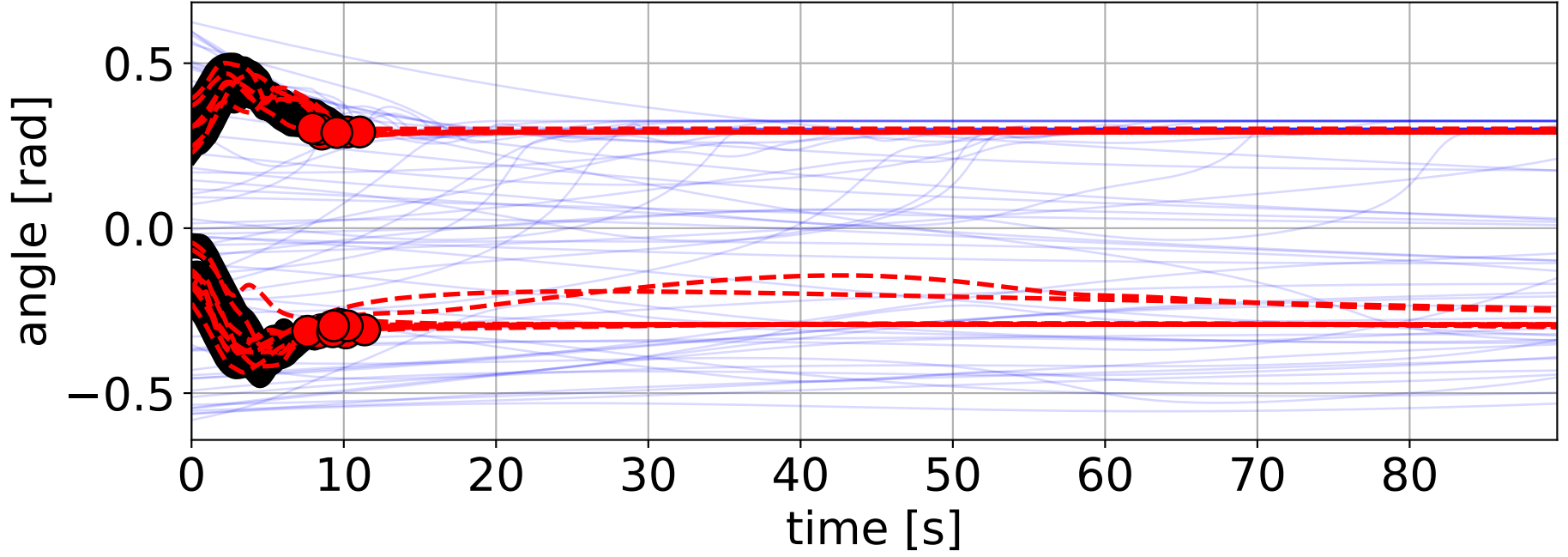


# Dynamical System

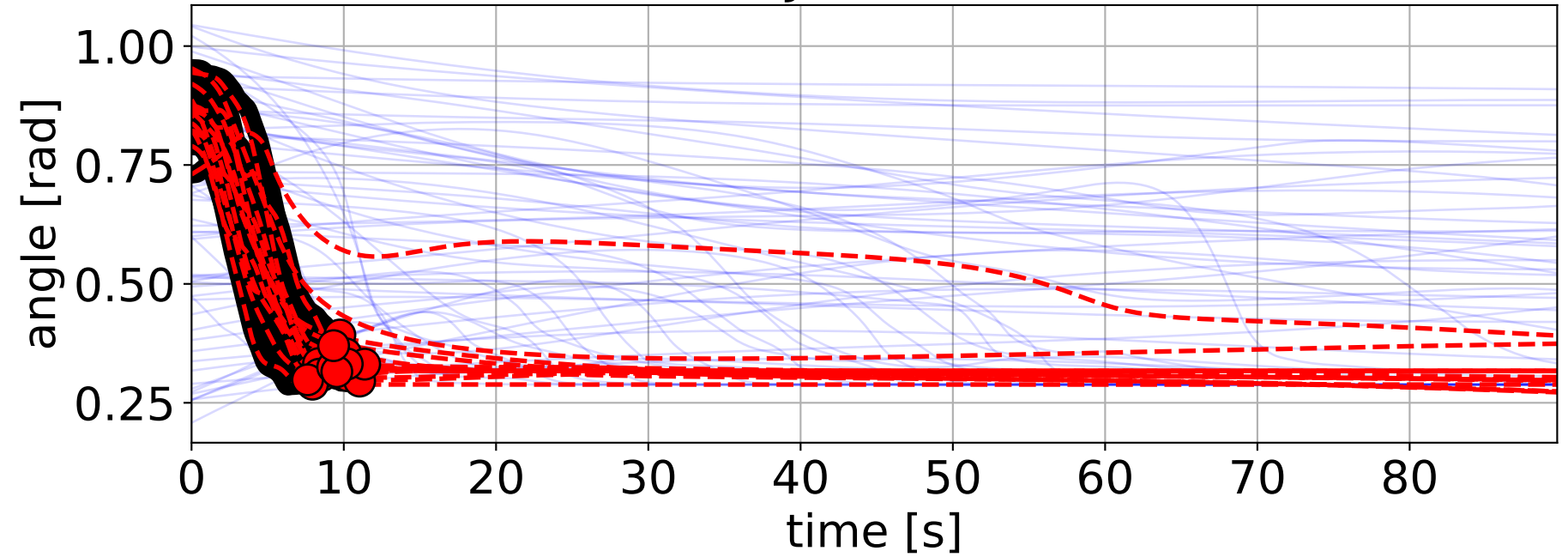
## Joint 1



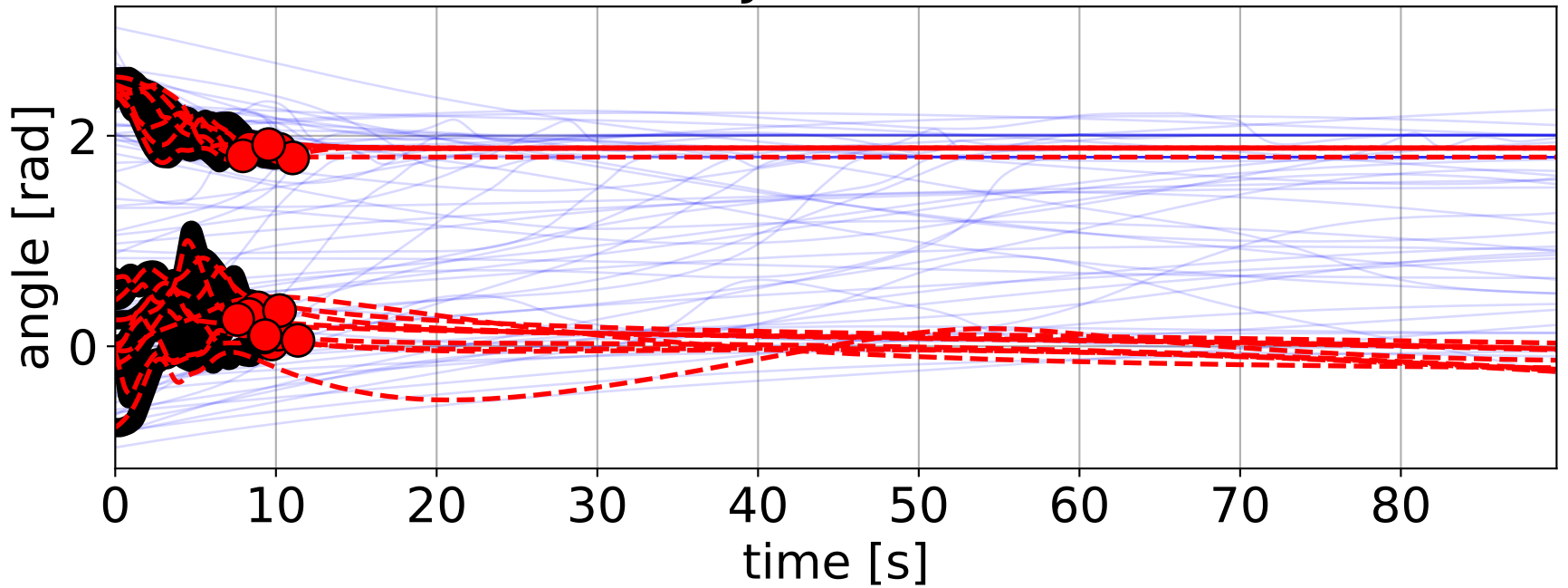
## Joint 2



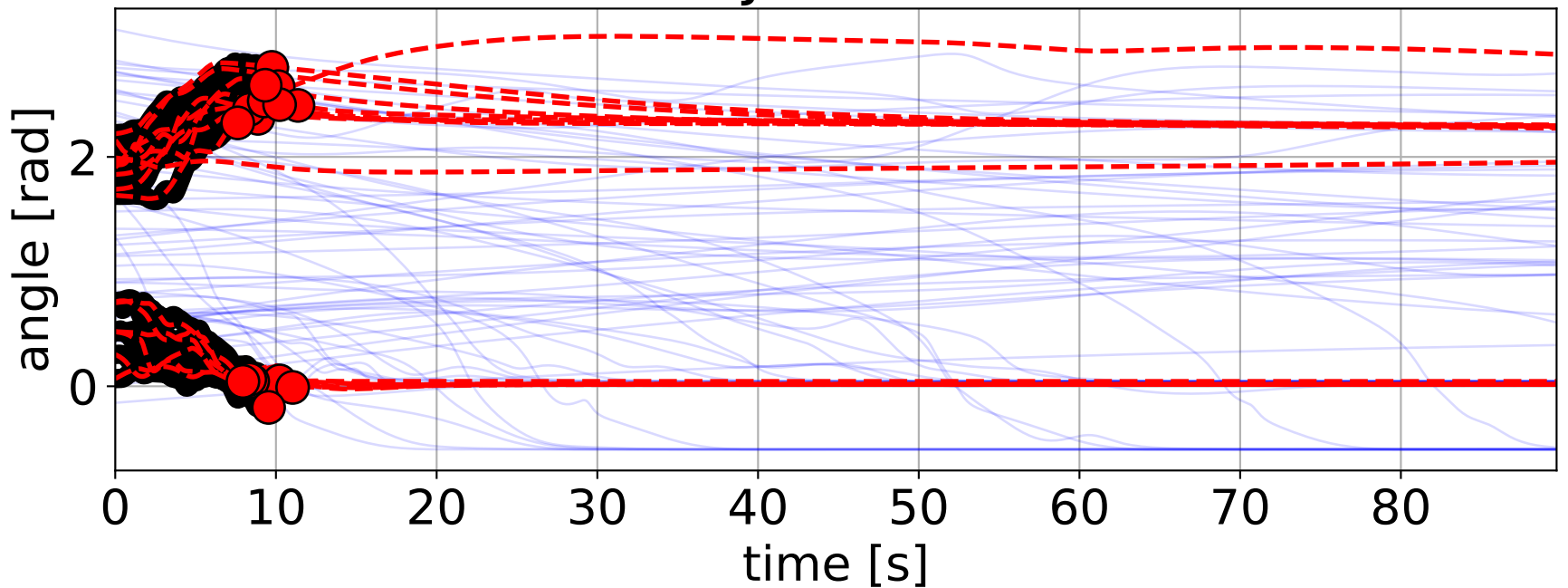
## Joint 3



## Joint 4



## Joint 5



## Joint 6

