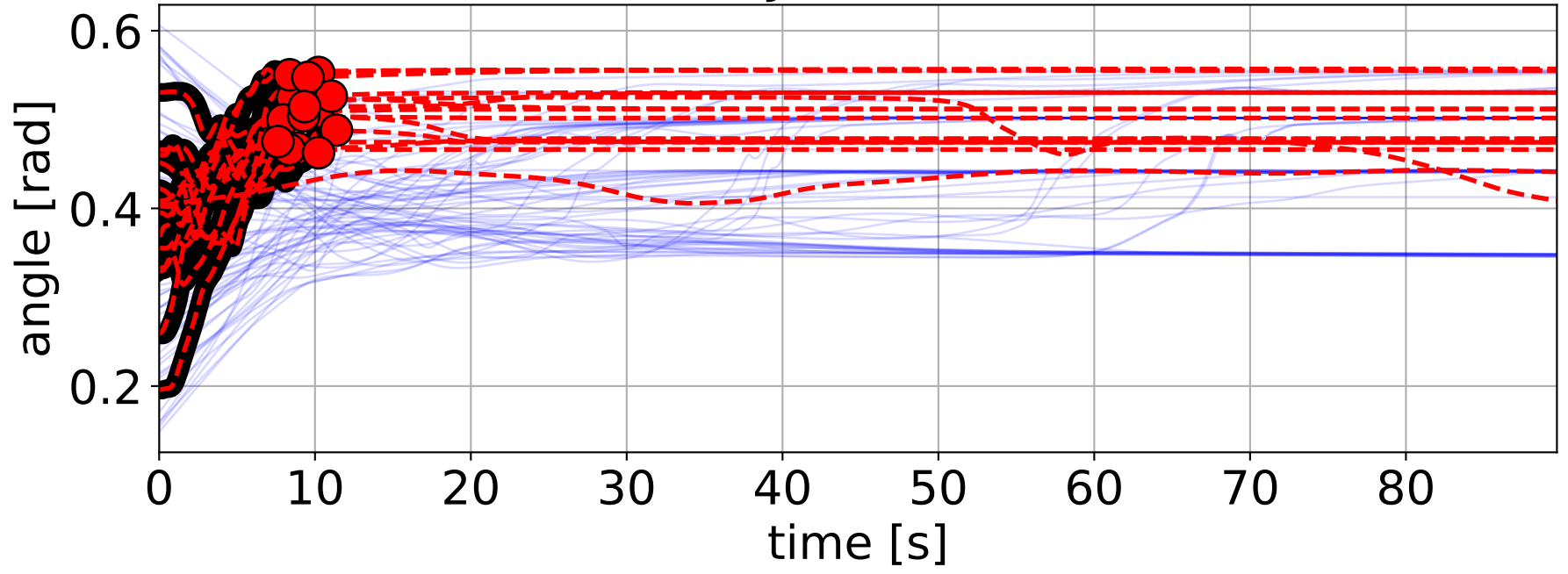
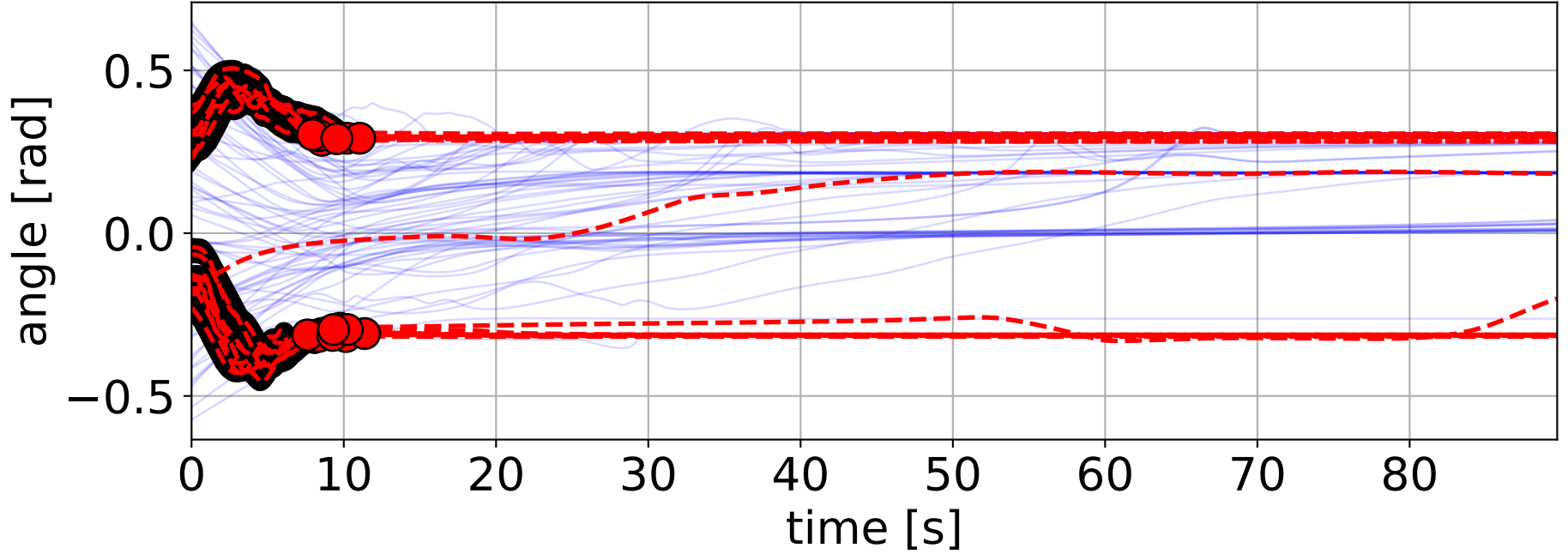


Dynamical System

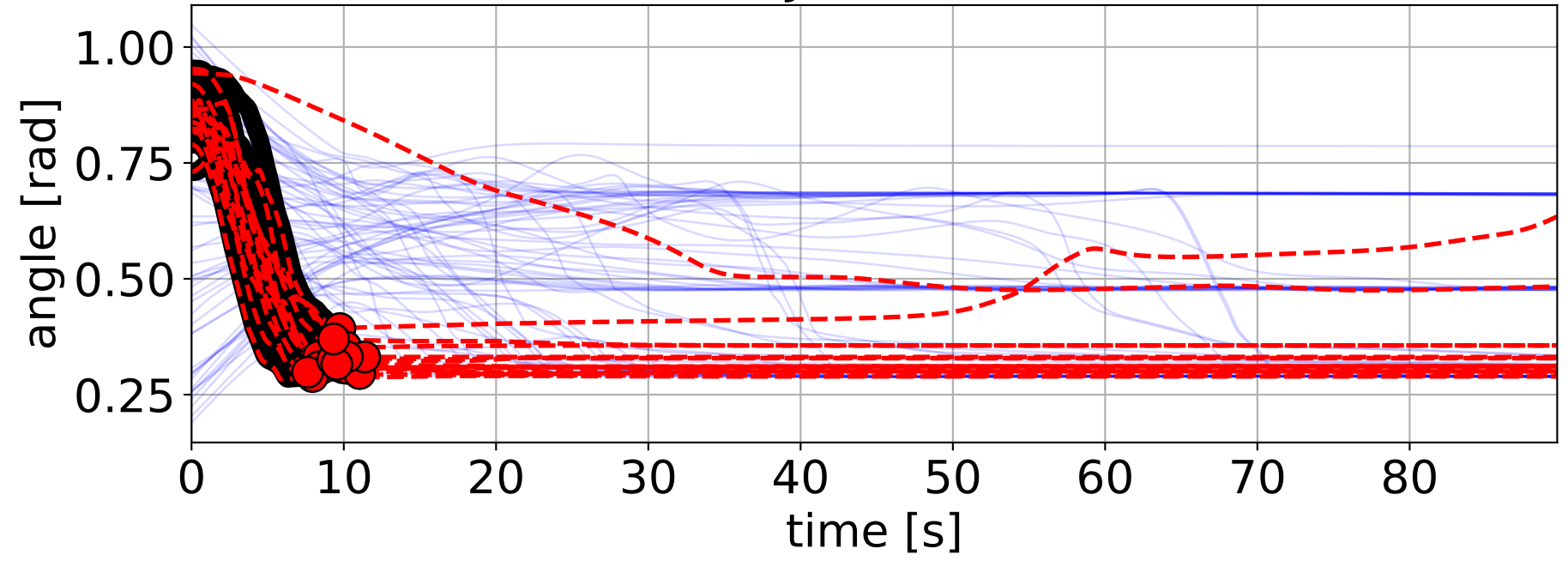
Joint 1



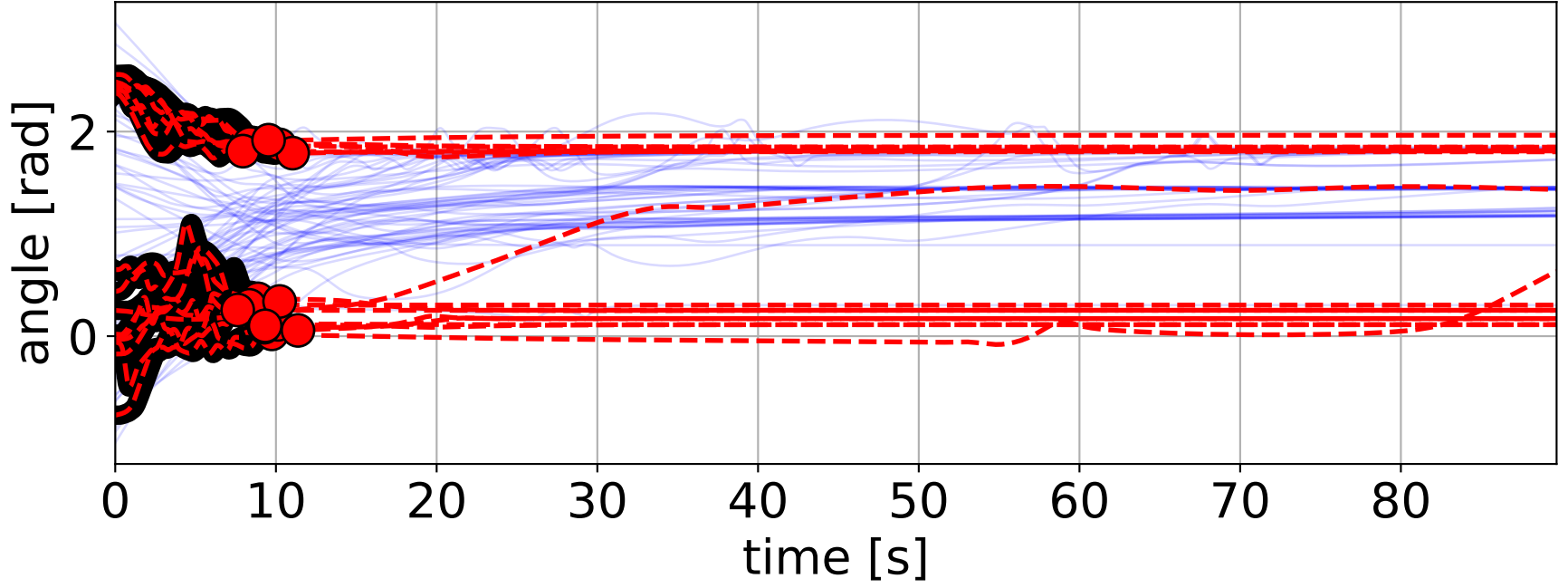
Joint 2



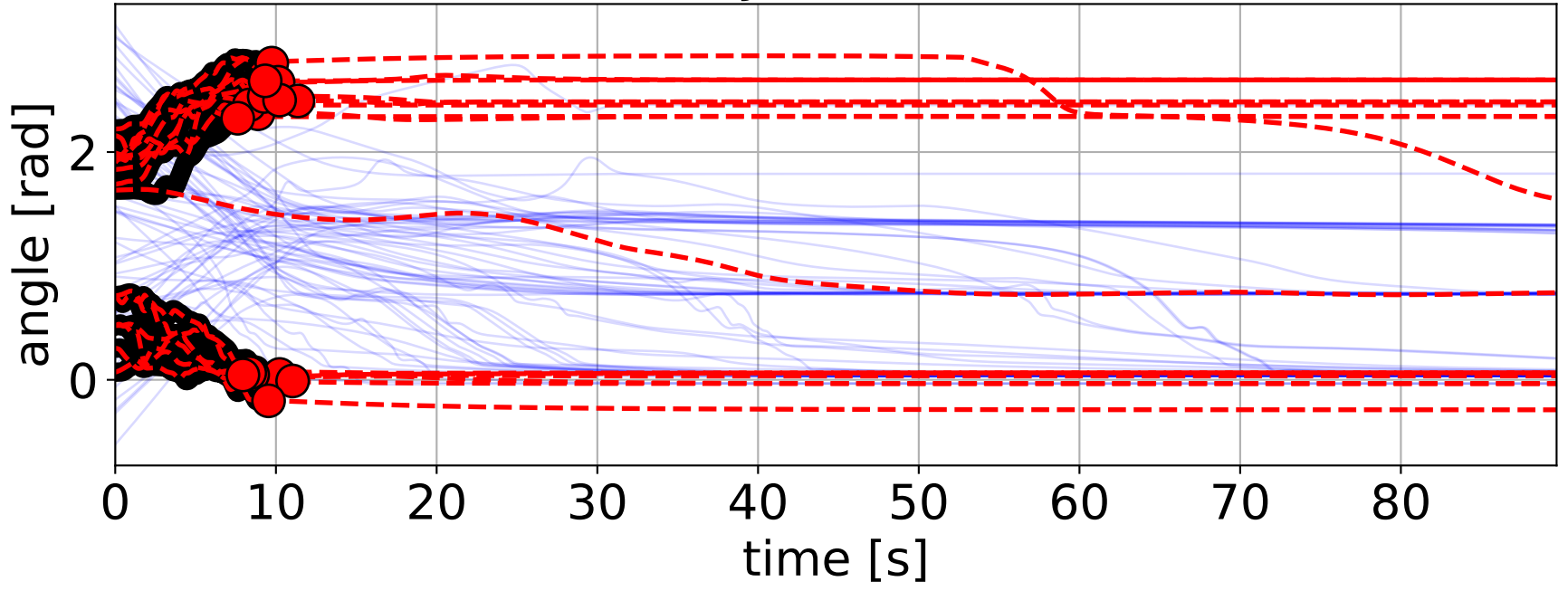
Joint 3



Joint 4



Joint 5



Joint 6

