# **MVPGPU-Sim User Guide**

This guide is only for how new developer to run application based on MVPGPU-Sim

#### Table of content

- MVPGPU-Sim User Guide
  - Table of content
  - How to compile OpenCL application
    - Host compiling
    - Kernel compiling
  - How to compile Graphic application
  - How to run application based on MVPGPU-Sim
  - How to build and run OpenCL CTS
  - setup\_environment
  - Git
  - Gerrit
  - Aerialvision

## How to compile OpenCL application

### **Host compiling**

If want to build OpenCL file, first to build MVPGPU-SIM to build OpenCL libraries.

```
source setup_environment debug | release
make
make docs
...
```

clang-7 -g -lOpenCL -DCL\_TARGET\_OPENCL\_VERSION=120 -I /usr/local/cuda/include -L ../lib/ hello.

#### Kernel compiling

```
clang-7 -x cl -emit-llvm -S -cl-std=CL1.2 -Xclang -finclude-default-header _cl_iYcT6t -o _cl_iYc
llc -march=mvp _cl_iYcT6t.bc -o _cl_iYcT6t.s
```

## How to compile Graphic application

Kernel compiling

```
clang-7 -emit-llvm -S -std=c++17 -I /usr/local/include/opencv4 -I ${GPGPUSIM_ROOT}/gpu/graphics/
-L ${GPGPUSIM_ROOT}/lib

llc -march=mvp fs_shader.bc -o fs_shader.s
```

# How to run application based on MVPGPU-Sim

- source setup\_environment debug
- make
- Idd application to check if link against MVPGPU-Sim's xxx.so file

```
liuyonggang@edal19:~/repo/mvpgpu-sim$ (dd hello_opencl
./hello_opencl: /home/user/liuyonggang/repo/mvpgpu-sim/lib/gcc-5.3.1/cuda-11000/debug/lib0penCL.so.1: no_version information available (required by ./hello_opencl)
./inux-vuso-so_1 (0x00007ffe74f21000)
.lib0penCL.so.1 > /home/user/liuyonggang/repo/mvpgpu-sim/lib/gcc-5.3.1/cuda-11000/debug/lib0penCL.so.1
.lib0penCL.so.1 > /lib/x86_64-linux-gnu/libc.so.6 (0x00007f8f4af78000)
.libc.so.1 >> /lib/x86_64-linux-gnu/libs.to.1 (0x00007f8f4af78000)
.libstdc++.so.6 >> /lib/x86_64-linux-gnu/libstdc++.so.6 (0x00007f8f4ac47000)
.libm.so.6 >> /lib/x86_64-linux-gnu/libm.so.6 (0x00007f8f4ac47000)
.libgcc_s.so.1 >> /lib/x86_64-linux-gnu/libgcc_s.so.1 (0x00007f8f4ac2000)
```

./hello opencl

## How to build and run OpenCL CTS

Building

```
$
$ cd test/OpenCL-CTS
$ mkdir build
$ cmake -B ./build -DCL_INCLUDE_DIR=$PWD/OpenCL-Headers -DCL_LIB_DIR=/home/user/liuyonggang,
$ cmake --build ./build --config Debug
$ cd build
$ make
```

Running test cases

```
$
$ cd ~/repo/mvpgpu-sim
$ ./test/OpenCL-CTS/build/test_conformance/basic/test_basic -h
$ ./test/OpenCL-CTS/build/test_conformance/api/test_api -h
```

· How to debug

launch.json file content as below.

```
{
    "version": "0.2.0",
    "configurations": [
        {
            "name": "(gdb) ????",
            "type": "cppdbg",
            "request": "launch",
            "program": "${workspaceFolder}/test/OpenCL-CTS/build/test_conformance/api/test_
            "args": ["load_single_kernel"], //This is case name
            "stopAtEntry": true,
            "preLaunchTask": "",
            "cwd": "${workspaceFolder}",
            "environment": [],
            "externalConsole": false,
            "MIMode": "gdb",
            "setupCommands": [
                {
                    "description": "?? gdb ??????????",
                    "text": "-enable-pretty-printing",
                    "ignoreFailures": true
                },
                {
                    "description": "?????????????? Intel",
                    "text": "-gdb-set disassembly-flavor intel",
                    "ignoreFailures": true
            ]
        }
   ]
}
```

## setup\_environment

Env Variables	Meaning	Comments
MVPGPUSIM_CONFIG_FILE_PATH	mvpgpu-sim.config's folder path	

#### Git

Create branch

```
git push origin new-branch-name:new-branch-name
```

Delete branch

```
git push origin --delete delete-branch-name
```

For example, The meaning of *remotes/origin/test* is that you have a branch called test in the remote server origin. So the command would be

```
git fetch --prune
git branch -r
git push origin --delete test
```

Tag

```
git tag //列出所有的标签名
git show <tag_name> //显示标签对应提交记录的具体信息
git ls-remote --tags origin //显示远端的tag

git tag <tag_name> //当前分支所在的提交上打上轻量标签
git tag <tag_name> <commit hash value> //为某次具体的提交打上轻量标签
git tag -a <anotated_name> -m <tag_message> //为当前分支所在提交打上附注标签
git push origin <tag_name> //推送某个标签到远程仓库
git push origin --tags //推送所有标签到远程仓库
git tag -d <tag_name> //删除某个标签
git ls-remote --tags origin //找出要删除的远端标签,类似于ref/tags/<tag_name>的格式
git push origin :refs/tags/<tag_name> //删除远程仓库某个标签
```

#### **Gerrit**

• How to restart (Executing the following bat by root user or wangyuwei@icubecorp.cn)

```
/home/gerrit/review-site/bin/gerrit.sh restart
```

 How to add new user (New user should be added to related group by adminstrator or zhongwei@icubecorp.cn)

```
[liuyonggang@eda mvpgpu-doc]$ groups
hw soc system
```

#### **Aerialvision**

How to start AerialVision

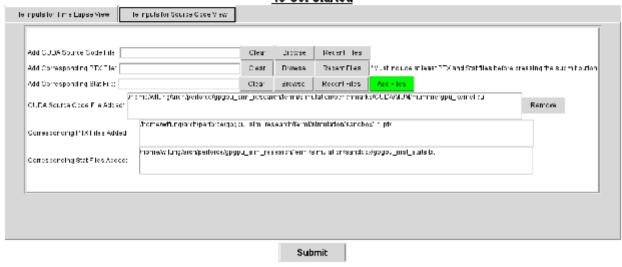
```
cd ~/mvpgpu-sim/
source setup_environment # + debug/release
cd ~/mvpgpu-sim/tool/
python3 aerialvision_main.py
```

· Launch Page



Here we need to upload all the files that are required here. These files are by default in the form gpgpusim\_visualizer\_\_\*.log.gz. We submit files by clicking the Browse button (if you've submitted the file before you can click on the Recent Files button), and then clicking Add File once the file's path is in the Add Input File text field. Notice that you can submit numerous files for visualizing into this tab; however, for the purposes of this walkthrough we have limited it to one.

# AerialVision 1.1 Please Fill Out Specifications to Get Started



Now click on the File Inputs for Source Code View tab. In this tab we submit files that present statistics corresponding to each line of PTX or CUDA/OpenCL source. Before clicking the Add Files button, it is necessary to insert the file paths to three distinct files required by this part of AerialVision. The file that goes in the Add CUDA/OpenCL Source Code File text field is the appropriate CUDA/OpenCL kernel source code file(.cu/.c).

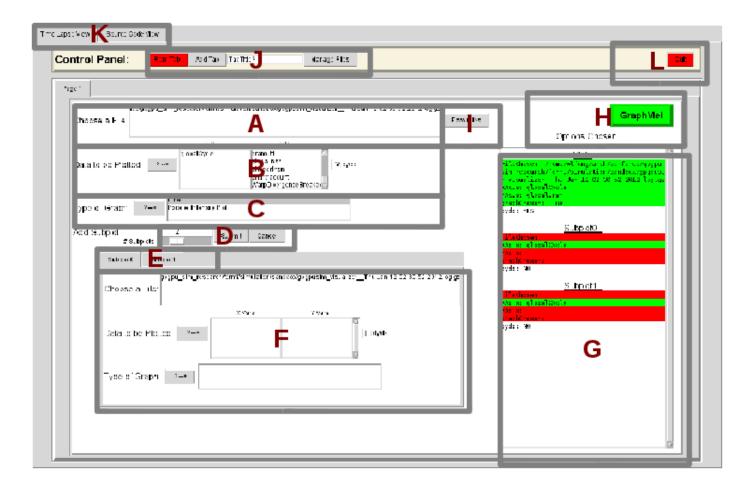
The file that goes in the Add Corresponding PTX File text field is the appropriate PTX file generated.

Finally, the file that goes in the Add Corresponding Stat File is generated by the GPGPU-Sim and is by default named gpgpu inst stats.txt.

Once you have filled the three text fields, click the green Add Files button.

You can now launch AerialVision by clicking the Submit button at the bottom. It should be noted that for your own purposes, it is not necessary to fill both the File Inputs for Time Lapse View and File Inputs for Source Code View tabs as both parts of AerialVision can be used independently of the other.

Time Lapse View

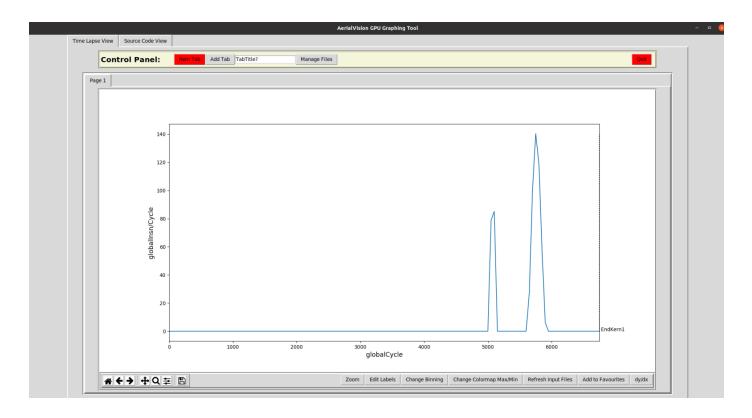


We first need to Choose a File by double clicking on the trace file that we want to extra data from. Double clicking on one of the files should turn the appropriate section of the 'Options Chosen' list green.

In B and C, we can choose which data to plot and their config such as with derivative or not and plot with line or Parallel Intensity Plot.

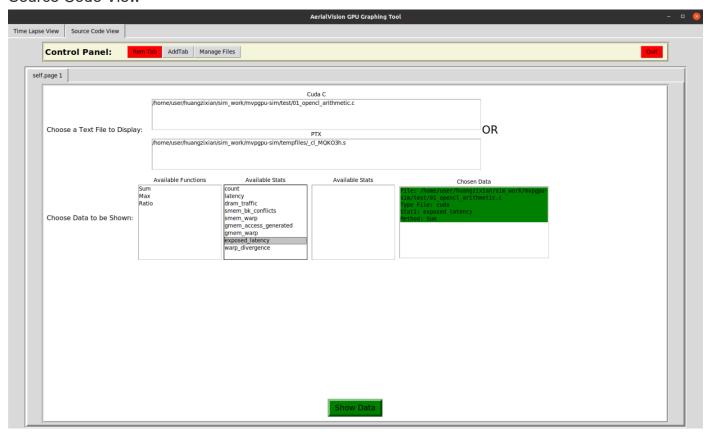
THIS IS DEPEND ON THE STAT TO SHOW. YOU CAN FIND THE CONFIG IN ANOTHER TABLE.

You may now press the green GraphMe! button. If you have followed this walkthrough correctly, all of the fields in the Option Chosen list should be green.



After clicking the green GraphMe! button, your screen should now look something like figure above.

Source Code View



First we must choose the appropriate CUDA/OpenCL source file by clicking the appropriate file under the Cuda C header. This should turn the File: under Chosen Data from red to green. Next,

we will need to choose the appropriate PTX statistic aggregation method from under Available Functions as well as A vailable Stats . Finally, click the green Show Data button at the bottom.