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- Q1.** Draw the timing diagram of a 8255 PPI, when its Port-A is used as input port having interrupt request with a 8-bit data of all '0' and Port-B is used as output port having no interrupt requested with a 8-bit data of all '1'; If Port-C is in the handshaking mode then also derive the command register value. **08**
- Q2.** Suppose, your student ID is 180041X₁X₂X₃. Now, for CAN Bus Protocol consider two component nodes N₁ having 11-bit Identifier X₁X₂X₃ and N₂ having 11-bit Identifier X₃X₂X₁. Using the identifier values draw the timing diagram for CSMA/CD Non-Destructive Arbitration (NDA) concept of CAN. Your answer should clearly state the *bit-by-bit* scenario to show which node becomes the dominant to access the CAN Bus and transmit data first. **07**
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