Georgios Georgakis

October 20th 2024

NASA-Jet Propulsion Laboratory, Caltech 198-120, 4800 Oak Grove Dr, Pasadena, CA 91109 https://ggeorgak11.github.io/ georgios.georgakis@jpl.nasa.gov

Education

PhD in Computer Science

2013-2020

George Mason University

Research Interests: Computer Vision, Robotics, Machine Learning

Thesis: 3D Model-Assisted Learning for Object Detection and Pose Estimation [pdf]

Advisor: Prof. Jana Kosecka

MSc in Computer Science

2013-2015

George Mason University

Diploma in Electronic and Computer Engineering

2006-2012

Technical University of Crete

Thesis: Field Landmark Recognition and Localization for the RobotStadium

Online Soccer Competition [pdf]

Advisor: Associate Prof. Michail G. Lagoudakis

Positions

Robotics Technologist

Jan 2023-

NASA-Jet Propulsion Laboratory California Institute of Technology

Postdoctoral Researcher

Mar 2020-Jan 2023

GRASP Lab. Advised by Dr. Kostas Daniilidis CIS Department, University of Pennsylvania

Part-time Lecturer

Spring 2022

ESE Department, University of Pennsylvania

Graduate Research Assistant

Aug 2013-Dec 2019

Computer Vision and Robotics Lab

CS Department, George Mason University

Research Intern

Summer 2019

United Imaging Intelligence, Cambridge MA

Ph.D Research Intern - Vision and Deep Learning

Summer 2017, 2018

Siemens Corporate Technology, Princeton NJ

Papers

Learning Illumination Invariant Features for Lunar South Pole with Deep Learning

G. Georgakis, A. Ansar

Space Imaging Workshop (SIW) 2024

Pixel to Elevation: Learning to Predict Elevation Maps at Long Range using Images

for Autonomous Offroad Navigation

C. Chung, G. Georgakis, P. Spieler, C. Padgett, A. Agha, S. Khattak

IEEE Robotics and Automation Letters (RA-L) 2024

Icy Moon Surface Simulation and Stereo Depth Estimation for Sampling Autonomy R. Bhaskara, **G. Georgakis**, J. Nash, M. Cameron, J. Bowkett, A. Ansar, M. Majji, P. Backes IEEE Aerospace Conference (AeroConf) 2024

Unordered Navigation to Multiple Semantic Targets in Novel Environments
B. Bucher, K. Ashton, B. Wu, K. chmeckpeper, S. Goel, N. Matni, **G. Georgakis**, K. Daniilidis Embodied AI Workshop at CVPR 2023

Bridge Data: Boosting Generalization of Robotic Skills with Cross-Domain Datasets F. Ebert*, Y. Yang*, K. Schmeckpeper, B. Bucher, G. Georgakis, K. Daniilidis, C. Finn, S. Levine Robotics: Science and Systems (RSS) 2022

Cross-modal Map Learning for Vision and Language Navigation

G. Georgakis, K. Schmeckpeper, K. Wanchoo, S. Dan, E. Miltsakaki, D. Roth, and K. Daniilidis IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2022

Learning to Map for Active Semantic Goal Navigation

G. Georgakis*, B. Bucher*, K. Schmeckpeper, S. Singh, K. Daniilidis International Conference on Learning Representations (ICLR) 2022

Uncertainty-driven Planner for Exploration and Navigation

G. Georgakis, B. Bucher, A. Arapin, K. Schmeckpeper, N. Matni, and K. Daniilidis International Conference on Robotics and Automation (ICRA) 2022

 $Object\text{-}centric\ Video\ Prediction\ without\ Annotation$

K. Schmeckpeper*, **G. Georgakis***, K. Daniilidis

International Conference on Robotics and Automation (ICRA) 2021

Hierarchical Kinematic Human Mesh Recovery

G. Georgakis*, R. Li*, S. Karanam, T. Chen, J. Kosecka, Z. Wu European Conference on Computer Vision (ECCV) 2020

Robust Multi-modal 3D Patient Body Modeling

F. Yang, R. Li, **G. Georgakis**, S. Karanam, T. Chen, H. Ling, Z. Wu Medical Image Computing and Computer Assisted Interventions (MICCAI) 2020

Towards Robust RGB-D Human Mesh Recovery

R. Li, C. Cai, G. Georgakis, S. Karanam, T. Chen, Z. Wu arXiv:1911.07383

Simultaneous Mapping and Target Driven Navigation

G. Georgakis, Y. Li, J. Kosecka

arXiv:1911.07980

Learning Local RGB-to-CAD Correspondences for Object Pose Estimation

G. Georgakis, S. Karanam, Z. Wu, J. Kosecka

IEEE International Conference on Computer Vision (ICCV) 2019

End-to-end Learning for Keypoint Detection and Descriptor for Pose Invariant 3D Matching

G. Georgakis, S. Karanam, Z. Wu, J. Ernst, J. Kosecka

IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2018

Label Propagation in RGB-D Video

Md. A. Reza, H. Zheng, G. Georgakis, J. Kosecka

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2017

Synthesizing Training Data for Object Detection in Indoor Scenes

G. Georgakis, A. Mousavian, A. C. Berg, J. Kosecka

Robotics: Science and Systems (RSS) 2017

A Contact Exploitative Approach to the Amazon Robotics Challenge

E. Dessalene, G. Georgakis, Md. A. Reza, Y. Li, Y. Ovcharik, A. Shapiro, J. Kosecka, D. Lofaro Warehouse Picking Automation Workshop (ICRA) 2017

Multiview RGB-D Dataset for Object Instance Detection

G. Georgakis, Md. A. Reza, A. Mousavian, P. H. Le, J. Kosecka International Conference on 3D Vision (3DV), 2016

RGB-D Multiview Object Detection with Object Proposals and Shape Context

G. Georgakis, Md. A. Reza, J. Kosecka

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2016

* Denotes equal contribution

Patents Awarded/Pending

Method and System for On-board Localization

R. Brockers, F. Dietsche, J. Delaune, P. Proença, R. Hewitt, **G. Georgakis** US18/312,444 filed May 2023, Application no. US20230360547A1

Systems and Methods for Human Pose and Mesh Recovery

Z. Wu, S. Karanam, C. Cai, G. Georgakis

US16/995,446, filed August 2020, Application no. US20210158028A1

Systems and Methods for Human Mesh Recovery

S. Karanam, Z. Wu, G. Georgakis

US16/863,382, filed April 2020, Application no. US20210158107A1

Learning Keypoints and Matching RGB Images to CAD Models

G. Georgakis, S. Karanam, Z. Wu, J. Ernst

PCT/US2019/053827, filed September 2019, Application no. WO2020086217

Matching RGB Images to CAD Models

G. Georgakis, S. Karanam, Z. Wu, J. Ernst

PCT/US2019/040913, filed July 2019, Application no. WO2020014170A1

Spare Part Identification Using a Locally Learned 3D Landmark Database

G. Georgakis, S. Karanam, Z. Wu, J. Ernst

PCT/US2018/049100, filed September 2018, Application no. WO2019094094A1

Learning View-invariant Local Patch Representations for Pose Estimation

G. Georgakis, S. Karanam, V. Manjunatha, K-C. Peng, Z. Wu, J. Ernst

PCT/US2018/013271, filed January 2018, Application no. WO2019139587A1

Training a Convolutional Neural Network using Task-irrelevant Data

V. Manjunatha, G. Georgakis, K-C. Peng, Z. Wu, J. Ernst

PCT/US2017/067766, filed December 2017, Application no. WO2019125453A1

Awards

Technology Spotlight Award, Autonomous Systems Division, Jet Propulsion Lab, 2024

"Disentangling Jupiter's Complex Atmospheric Processes Through the Application of Machine Learning Methods to JunoCam Data"

NASA Research Opportunities in Space and Earth Science (ROSES), 2023, \$711K

Doctoral Consortium at ICCV 2019

Outstanding Graduate Teaching Assistant Award by the Department of Computer Science, George Mason University, for the academic year 2015-16

Selected Talks

Learning Illumination Invariant Features for Lunar South Pole with Deep Learning Space Imaging Workshop, Atlanta GA, October 2024

Vision-based Navigation in Novel Environments

Jet Propulsion Lab Section 347 Talks, Virtual, July 2022

Cross-modal Map Learning for Vision and Language Navigation

GRASP SFI Seminar Series, Philadelphia PA, April 2022

Uncertainty-based Mapping and Navigation

MURI Review Meeting, Virtual, October 2021

Object-centric Video Prediction without Annotation

Honda Curious Minded Machines Seminar Series, Virtual, January 2021

3D Model-Assisted Learning for Object Detection and Pose Estimation

GRASP Seminar Series, Philadelphia PA, December 2019

Keypoint Learning for Pose Estimation

Siemens CT Intern Talk Series, Princeton NJ, August 2018

Synthesizing Training Data for Object Detection in Indoor Scenes

RSS Conference Talk, Cambridge MA, July 2017

RGB-D Multiview Object Detection with Object Proposals and Shape Context

IROS Conference Talk, Daejeon, South Korea, October 2016

Teaching

Instructor at University of Pennsylvania

ESE650: Learning in Robotics with Oleh Rybkin Spring 2022

Guest Lecturer at George Mason University

CS112: Introduction to Programming - Python

CS685: Autonomous Robotics

CS687: Advanced Artificial Intelligence

CS747: Deep Learning

Fall 2015

Fall 2018

Spring 2019

Spring 2020

Graduate Teaching Assistant at George Mason University

CS112: Introduction to Programming - Python (Head TA)

Fall 2014 - Spring 2017

CS310: Data Structures - Java Fall 2018

Mentoring & Collaborations

Master's Thesis

Siddharth Goel, Navigation to Multiple Semantic Targets in Novel Enviornments, Fall 2021 Shiyani Patel, Vector Graph Neural Network: Point Cloud Prediction into the Future, Fall 2021 Bo Wu, The Role of Mapping in Modern Robot Navigation Tasks, Spring 2023

Aditya Singh, Instruction-guided Path Generation on Allocentric Maps using Diffusion Models, Spring 2023

Project Supervision

Dimitrios Chatziparaschis (JPL PhD Intern, Fall 2024)

Dario Pisanti (JPL PhD Intern, Spring 2023-Fall 2024)

Jakub Lucki (JPL Msc Intern, Fall 2024)

Haakon Moe (JPL Msc Intern, Fall 2024)

Ramchander Bhaskara (JPL PhD Intern, Summer 2023)

Aditya Singh (Penn CIS MSc, Fall 2022-Spring 2024)

Bo Wu (Penn ROBO MSc, Summer 2022-Spring 2023)

Anton Arapin (Google, Summer 2021-Spring 2022)

Karan Wanchoo (Penn CIS MSc, Fall 2021-Spring 2022)

Yihui Mao (Penn ROBO MSc, Summer 2021-Spring 2022)

Sharon Shaji (Penn ROBO MSc, Spring 2022)

Siddharth Singh (Amazon, Fall 2020-Spring 2021)

PhD Student Collaborations

Stefanos Pertigkiozoglou (Penn CIS PhD, Spring 2023-Spring 2024)

Katrina Ashton (Penn CIS PhD, Spring 2022-Fall 2023)

Ron DiTullio (Penn Neuroscience PhD, Fall 2021-Fall 2022)

Bernadette Bucher (Penn CIS PhD, Spring 2020-Spring 2023)

Karl Schmeckpeper (Penn CIS PhD, Spring 2020-Spring 2023)

Soham Dan (Penn CIS PhD, Fall 2021-Fall 2022)

Frederick Ebert (UC Berkeley CS PhD, Spring 2021-Summer 2021)

High School Student Supervision

Keith Cho (AEOP Apprenticeship, Summer 2021)

Andy Jiang (AEOP Apprenticeship, Summer 2021)

Hita Gupta (GRASP Intern, Fall 2021)

Reviewer

Conferences: NeurIPS, ICLR, CVPR, CVPRW, ICCV, ECCV, WACV, ACCV, ICRA, IROS

TPAMI, RA-L, Autonomous Robots, Transactions on Robotics, Journals:

Transactions on Image Processing, Pattern Recognition Letters,

Signal Processing: Image Communication, IEEE Access