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## Education

*PhD in Computer Science*, George Mason University 2013-2020

*Research Interests:* Computer Vision, Robotics, Machine Learning

*Thesis:* 3D Model-Assisted Learning for Object Detection and Pose Estimation [pdf]

*Advisor:* Prof. Jana Kosecka

*MSc in Computer Science*, George Mason University 2013-2015

*Diploma in Electronic and Computer Engineering*, Technical University of Crete 2006-2012

*Thesis:* Field Landmark Recognition and Localization for the RobotStadium

Online Soccer Competition [pdf]

*Advisor:* Associate Prof. Michail G. Lagoudakis

## Positions

*Part-time Lecturer* Jan 2022-  
ESE Department, University of Pennsylvania

*Postdoctoral Researcher* Mar 2020-  
GRASP Lab. Advised by Dr. Kostas Daniilidis  
CIS Department, University of Pennsylvania

*Graduate Research Assistant* Aug 2013-Dec 2019  
Computer Vision and Robotics Lab  
Department of Computer Science, George Mason University

*Research Intern* Summer 2019  
United Imaging Intelligence, Cambridge MA

*Ph.D Research Intern - Vision and Deep Learning* Summer 2017, 2018  
Siemens Corporate Technology, Princeton NJ

## Papers

*Uncertainty-driven Planner for Exploration and Navigation*

**G. Georgakis**, B. Bucher, A. Arapin, K. Schmeckpeper, N. Matni, and K. Daniilidis  
International Conference on Robotics and Automation (ICRA) 2022

*Learning to Map for Active Semantic Goal Navigation*

**G. Georgakis\***, B. Bucher\*, K. Schmeckpeper, S. Singh, K. Daniilidis  
International Conference on Learning Representations (ICLR) 2022

*Object-centric Video Prediction without Annotation*

K. Schmeckpeper\*, **G. Georgakis\***, K. Daniilidis  
International Conference on Robotics and Automation (ICRA) 2021

*Hierarchical Kinematic Human Mesh Recovery*

**G. Georgakis\***, R. Li\*, S. Karanam, T. Chen, J. Kosecka, Z. Wu  
European Conference on Computer Vision (ECCV) 2020

*Robust Multi-modal 3D Patient Body Modeling*

F. Yang, R. Li, **G. Georgakis**, S. Karanam, T. Chen, H. Ling, Z. Wu  
Medical Image Computing and Computer Assisted Interventions (MICCAI) 2020

*Learning Local RGB-to-CAD Correspondences for Object Pose Estimation*

**G. Georgakis**, S. Karanam, Z. Wu, J. Kosecka  
IEEE International Conference on Computer Vision (ICCV) 2019

*End-to-end Learning for Keypoint Detection and Descriptor for Pose Invariant 3D Matching*

**G. Georgakis**, S. Karanam, Z. Wu, J. Ernst, J. Kosecka  
IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2018

*Label Propagation in RGB-D Video*

Md. A. Reza, H. Zheng, **G. Georgakis**, J. Kosecka  
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2017

*Synthesizing Training Data for Object Detection in Indoor Scenes*

**G. Georgakis**, A. Mousavian, A. C. Berg, J. Kosecka  
Robotics: Science and Systems (RSS) 2017

*A Contact Exploitative Approach to the Amazon Robotics Challenge*

E. Dessalene, **G. Georgakis**, Md. A. Reza, Y. Li, Y. Ovcharik, A. Shapiro, J. Kosecka, D. Lofaro  
Warehouse Picking Automation Workshop (ICRA) 2017

*Multiview RGB-D Dataset for Object Instance Detection*

**G. Georgakis**, Md. A. Reza, A. Mousavian, P. H. Le, J. Kosecka  
International Conference on 3D Vision (3DV), 2016

*RGB-D Multiview Object Detection with Object Proposals and Shape Context*

**G. Georgakis**, Md. A. Reza, J. Kosecka  
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2016

\* Denotes equal contribution

## Preprints

*Cross-modal Map Learning for Vision and Language Navigation*

**G. Georgakis**, K. Schmeckpeper, K. Wanchoo, S. Dan, E. Mitsakaki, D. Roth, and K. Daniilidis  
Submitted

*Sample Efficient Tree-based Planning for Learned Prediction Models*

K. Schmeckpeper, Y. Mao, **G. Georgakis**, W. Tang, and K. Daniilidis.  
Submitted

*Bridge Data: Boosting Generalization of Robotic Skills with Cross-Domain Datasets*

F. Ebert\*, Y. Yang\*, K. Schmeckpeper, B. Bucher, **G. Georgakis**, K. Daniilidis, C. Finn, S. Levine  
arXiv:2109.13396

*Simultaneous Mapping and Target Driven Navigation*

**G. Georgakis**, Y. Li, J. Kosecka  
arXiv:1911.07980

*Towards Robust RGB-D Human Mesh Recovery*

R. Li, C. Cai, **G. Georgakis**, S. Karanam, T. Chen, Z. Wu  
arXiv:1911.07383

## Patents Pending

*Systems and Methods for Human Pose and Mesh Recovery*

Z. Wu, S. Karanam, C. Cai, **G. Georgakis**

US16/995,446, filed August 2020, Application no. US20210158028A1

*Systems and Methods for Human Mesh Recovery*

S. Karanam, Z. Wu, **G. Georgakis**

US16/863,382, filed April 2020, Application no. US20210158107A1

*Learning Keypoints and Matching RGB Images to CAD Models*

**G. Georgakis**, S. Karanam, Z. Wu, J. Ernst

PCT/US2019/053827, filed September 2019, Application no. WO2020086217

*Matching RGB Images to CAD Models*

**G. Georgakis**, S. Karanam, Z. Wu, J. Ernst

PCT/US2019/040913, filed July 2019, Application no. WO2020014170A1

*Spare Part Identification Using a Locally Learned 3D Landmark Database*

**G. Georgakis**, S. Karanam, Z. Wu, J. Ernst

PCT/US2018/049100, filed September 2018, Application no. WO2019094094A1

*Learning View-invariant Local Patch Representations for Pose Estimation*

**G. Georgakis**, S. Karanam, V. Manjunatha, K-C. Peng, Z. Wu, J. Ernst

PCT/US2018/013271, filed January 2018, Application no. WO2019139587A1

*Training a Convolutional Neural Network using Task-irrelevant Data*

V. Manjunatha, **G. Georgakis**, K-C. Peng, Z. Wu, J. Ernst

PCT/US2017/067766, filed December 2017, Application no. WO2019125453A1

## Awards

*Doctoral Consortium at ICCV 2019*

*Outstanding Graduate Teaching Assistant Award* by the Department of Computer Science, George Mason University, for the academic year 2015-16

## Selected Talks

*Uncertainty-based Mapping and Navigation*

MURI Review Meeting, October 2021

*Object-centric Video Prediction without Annotation*

Honda Curious Minded Machines Seminar Series, January 2021

*3D Model-Assisted Learning for Object Detection and Pose Estimation*

GRASP Seminar Series, Philadelphia PA, December 2019

*Keypoint Learning for Pose Estimation*

Siemens CT Intern Talk Series, Princeton NJ, August 2018

*Synthesizing Training Data for Object Detection in Indoor Scenes*

RSS Conference Talk, Cambridge MA, July 2017

*RGB-D Multiview Object Detection with Object Proposals and Shape Context*

IROS Conference Talk, Daejeon, South Korea, October 2016

## Teaching

*Instructor* at University of Pennsylvania

ESE650: Learning in Robotics with Oleh Rybkin

Spring 2022

*Guest Lecturer* at George Mason University

CS112: Introduction to Programming - Python

Fall 2015

CS685: Autonomous Robotics

Fall 2018

CS687: Advanced Artificial Intelligence

Spring 2019

CS747: Deep Learning

Spring 2020

*Graduate Teaching Assistant* at George Mason University

CS112: Introduction to Programming - Python

Fall 2014 - Spring 2017

CS310: Data Structures - Java

Fall 2018

CS480: Introduction to Artificial Intelligence

Spring 2019

## Mentoring

*Masters Thesis*

Siddharth Goel, Navigation to Multiple Semantic Targets in Novel Environments, 2021

Shiyani Patel, Vector Graph Neural Network: Point Cloud Prediction into the Future, 2021

*AEOP Apprenticeship (High school)*

Keith Cho and Andy Jiang, Training Behavioral Cloning Models in Open AI Gym, 2021

## Reviewer

CVPR, CVPRW, ICCV, WACV, ACCV, TPAMI, ICRA, RA-L, Pattern Recognition Letters, Transactions on Image Processing (TIP), Signal Processing: Image Communication, IEEE Access, MDPI: Sensors, International Journal of Digital Earth