



Efficient Coscheduling Model and Implementation for Beowulf Cluster

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- Introduction
- Problem
- Research Goal
- Related Work
- Proposed ECM/EDM model
- Experimental Evaluation
- Conclusion and Future Work







- Cluster computing system is now an important platform for high performance computing
 - Cost effective, scalability, performance
- High performance applications usually developed using Parallel Programming
 - MPI (Message Passing Interface)



- Performance of parallel program in Beowulf clusters environment depend on
 - The minimization of the impact from other tasks sharing the system
 - The good synchronization among tasks in parallel program that allows the speedup of message transmission
- An efficient form of synchronized scheduling is needed



Coscheduling : Introduction

- Traditional System leave local scheduler to schedule its job in each node
 - Performance drawback because of nonsynchronized scheduling
 - Less utilization
- Coscheduling
 - Synchronized scheduling technique that manage multiple processes on a set of nodes together to allows more efficient execution

Research Goal

- Propose a new and efficient co-scheduling method.
- Develop a coscheduling implementation for parallel applications running on Beowulf Clusters
 - All pass work make the decision based on immediate data in the system
 - No algorithm use the accumulated behavior of the transmission to build an effective prediction model for task behavior
 - Past statistics
 - Current system statistics







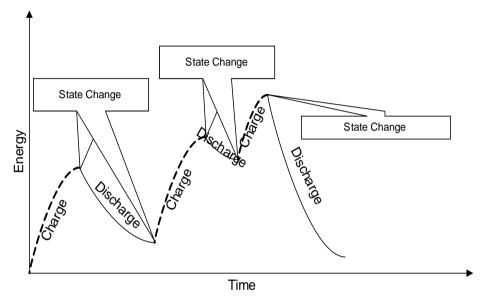
Energy Model for Implicit Coscheduling





Energy Model for Implicit Coscheduling

- Based on Predictive Coscheduling. Priority calculation is based on the idea of "Energy"
- Concept
 - Process charge/discharge "energy" while it executes
 - The amount of charged/discharged energy is calculated by current process parameter.
 - Calculated energy is then saved for later calculation
 - The charging and discharging state changes when communication state changes



- Charge/Discharge rate is calculated from process statistics
 - Communication Frequency
 - Message Size
 - Amount of running process in the system

Energy Charging Model (ECM)

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- The energy is charged while the process is in non-communication state.
- The energy is then convert to the process priority value. Coscheduler will adjust the process priority accordingly.
- Coscheduler adjust the priority only when the process is in communication state. The priority is leave as is while it computes
- The charging algorithm is

$$P = \alpha f t + P_{last} \tag{1}$$

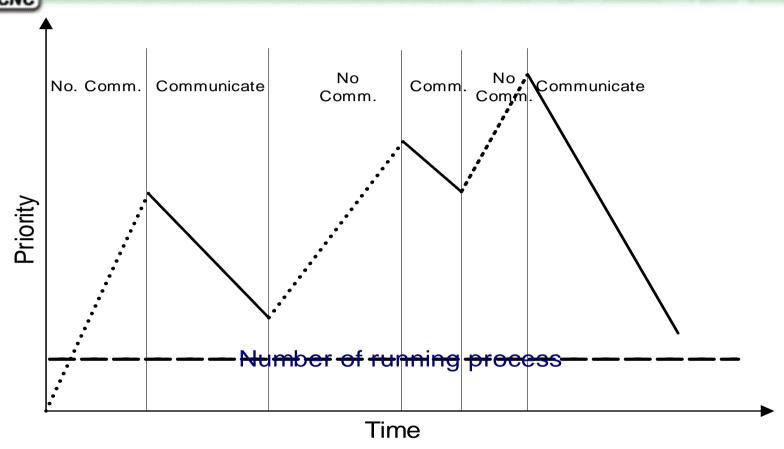
The discharging algorithm is

$$P = \begin{cases} -\beta \frac{t}{m} + P_{last} & \text{if } P > R; \\ R & \text{if } P \le R. \end{cases}$$
 (2)

- Where
 - P = priority
 - P_{last} = Last priority value
 - f = communication frequency
 - t = time elapsed since the execution started

- m = message size
- R = number of running process
- other value are constant value

Energy Charging Model (ECM)



- Energy Charging Model give the fair-share over all job in the system
- The priority will gradually drops when communication, thus prevent starvation problem
- The job with more frequent and larger message size would have lower discharge rate and higher charge rate
- The priority will not fall below the number of running process, thus guarantee priority boost while communication

Energy Discharging Model (EDM)

- As oppose to ECM, EDM reverse the behavior of ECM thus restrain most characteristics of ECM
- The priority will gradually <u>rise</u> while the process communicates
- The charging algorithm is

$$P = \begin{cases} -\gamma \frac{t}{f} + P_{last} & \text{if } P > R; \\ R & \text{if } P \le R. \end{cases}$$
 (3)

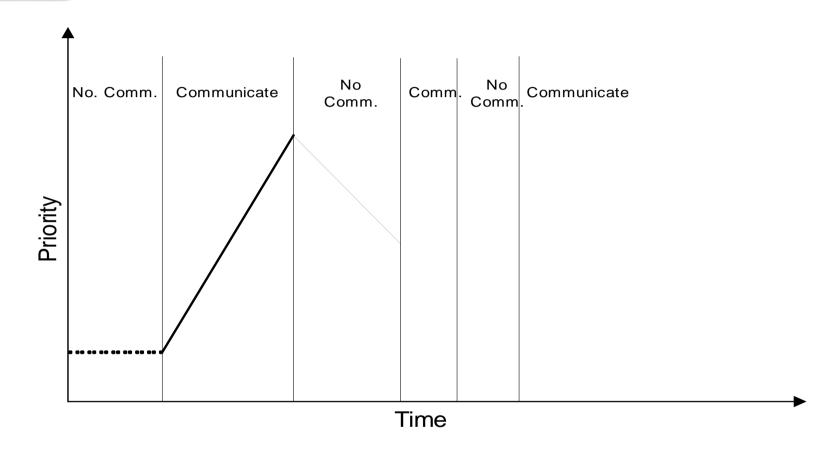
• The discharging algorithm is

$$P = \varepsilon mt + P_{last} \tag{4}$$

- Where
 - P = priority
 - P_{last} = Last priority value
 - f = communication frequency
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- m = message size
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Energy Discharging Model (EDM)



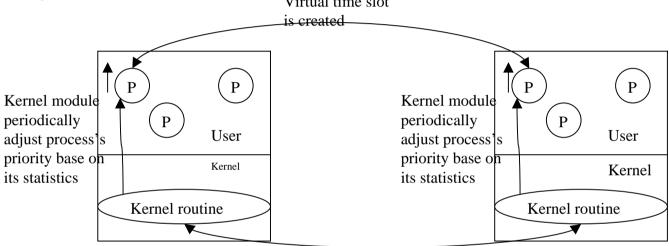
Implementation Details

- Implemented in kernel-level as Linux Kernel Module (LKM)
 - kernel version 2.4.19 (the latest at the time)
 - Using Linux timer mechanism to periodically inspect the kernel task queue and adjust the value of each task_struct
 - User need to tell the system which process to do the coscheduling by using command line.
 - _exit system call is trapped to ensure that all internal variable is cleared when process exit



Implementation Details

• System Overview Virtual time slot



Kernel module adjust the process priority so it send the message faster

Data sending through normal operating system mechanism Kernel module adjust the process priority so it receive the message faster



- The experimental setup is
 - 4 nodes Beowulf Cluster, each node is Athlon
 700 MHz with 128MB ram
 - Fast Ethernet Network
 - RedHat Linux 7.3 with Linux Kernel 2.4.19
 - MPICH 1.2.4



- Using NAS Parallel Benchmark version 2.3 as the test application. Three benchmarks is selected
 - IS and LU represents fine-grain parallel program
 - MG represents coarse-grain parallel program
- infcalc, a program which do infinite floating-point calculation
- All test is running with normal scheduler, Predictive Coscheduling, ECM, and EDM
- All result is the average from 5 runs
- NOTE: The number of application instants is limited due to memory constraint. All application is running with no memory trashing



Sequential Workload Experimental

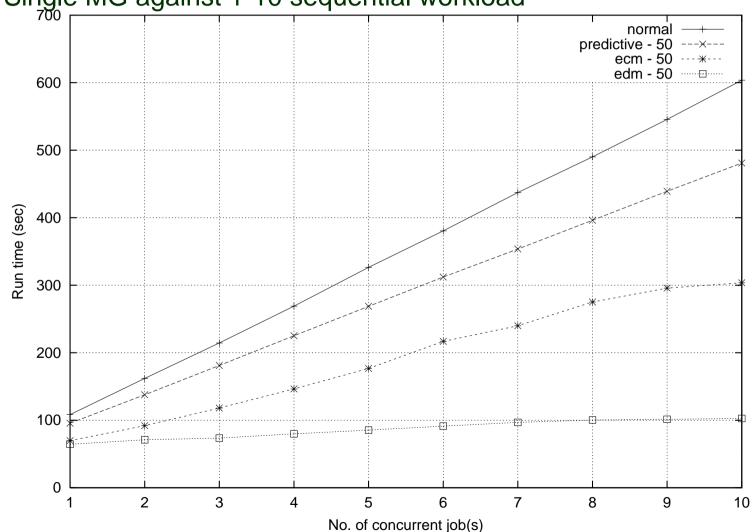
- IS, MG, and LU is running against 1-10 instants of infcalc
- Illustrates the performance of coscheduling against multiple sequential workload





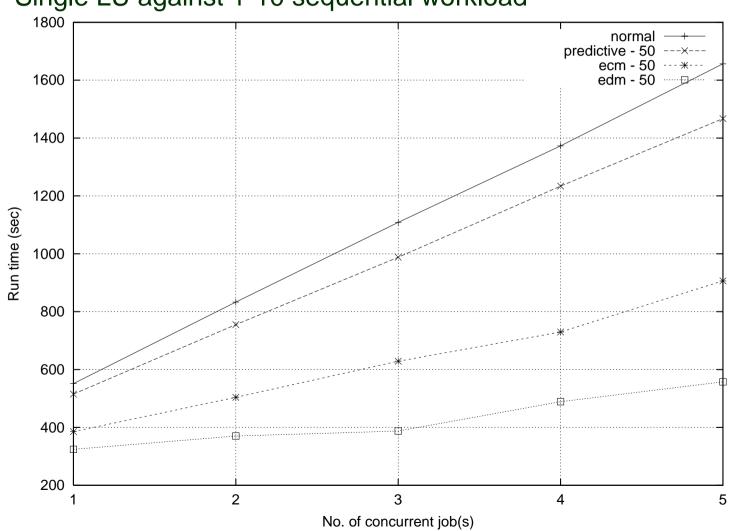
Runtime of parallel application against sequential workload

Single MG against 1-10 sequential workload

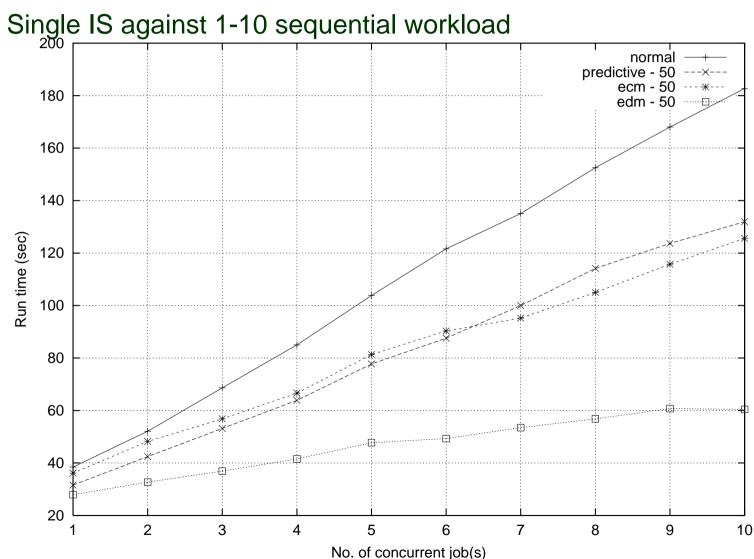


Runtime of parallel application against sequential workload

Single LU against 1-10 sequential workload

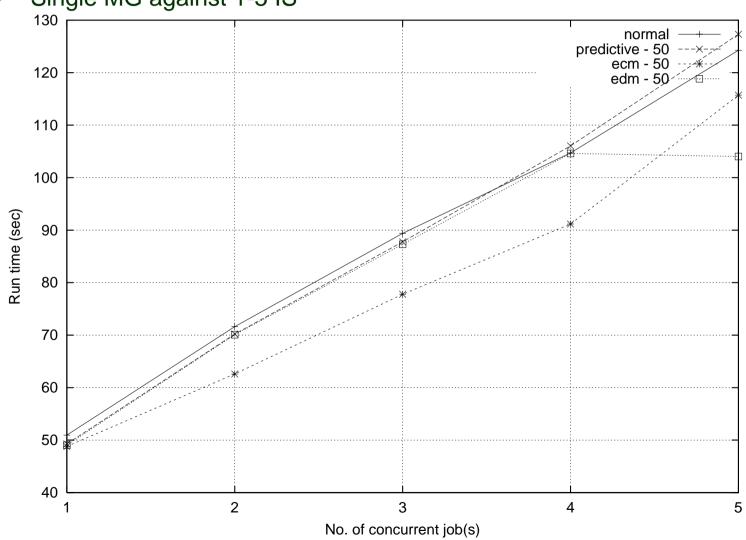


Runtime of parallel application against sequential workload

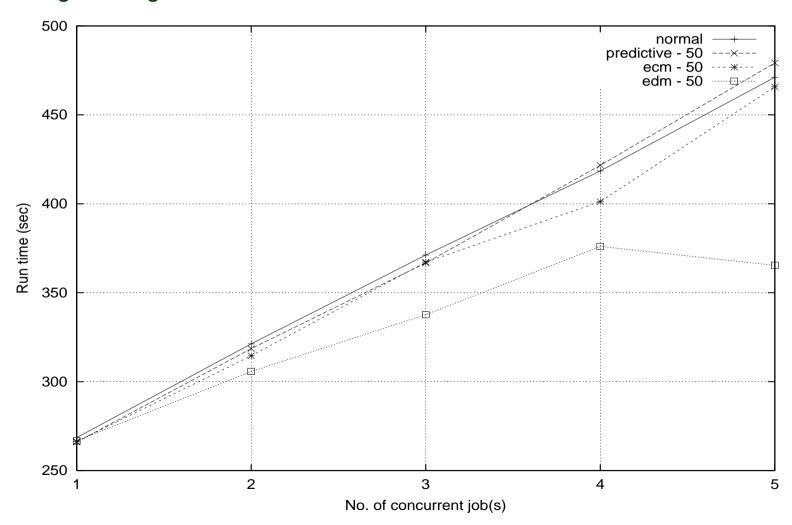


- IS, MG, and LU is running against each other
- Illustrates the performance of coscheduling when running multiple instants of parallel program

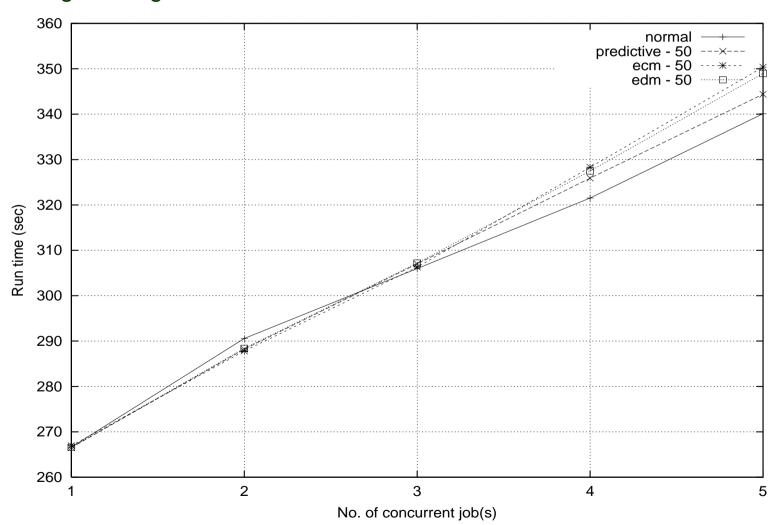
Single MG against 1-5 IS



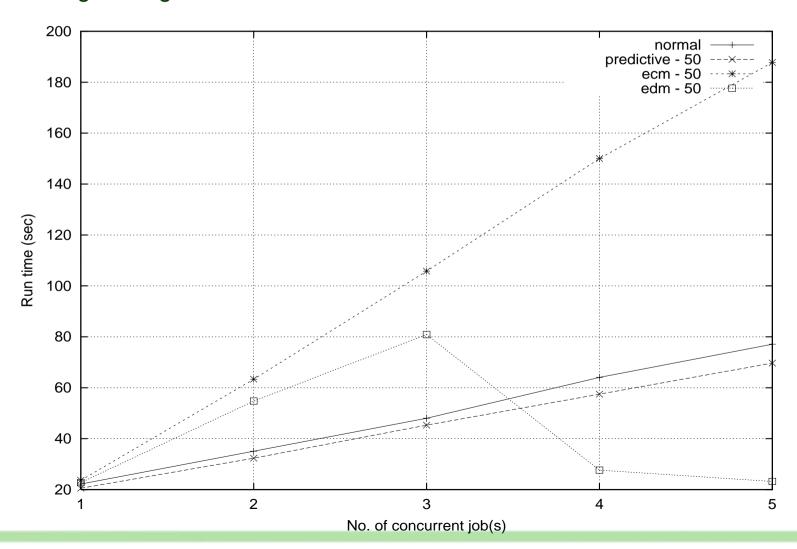
Single LU against 1-5 MG



Single LU against 1-5 IS

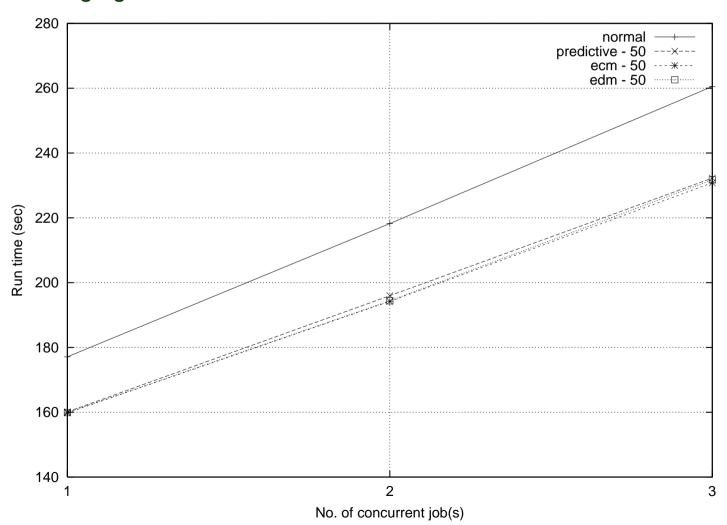


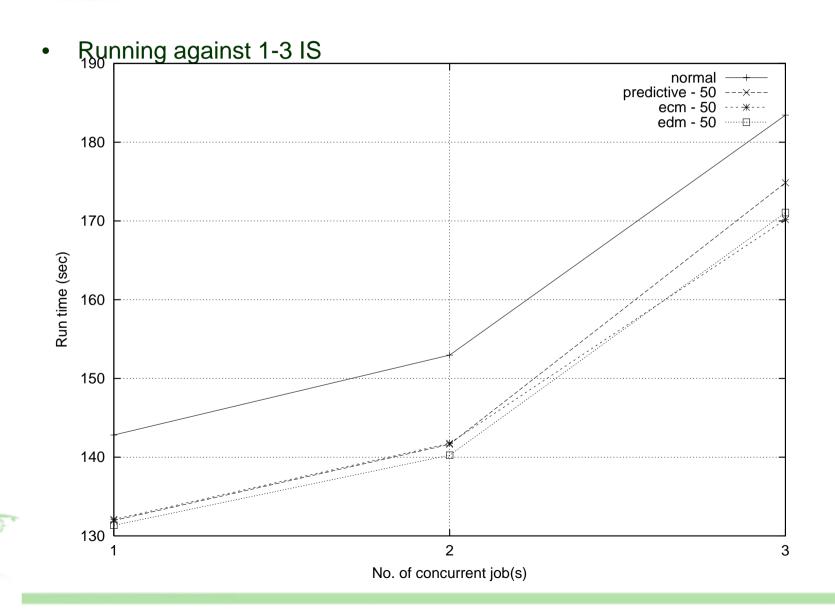
Single IS against 1-5 MG



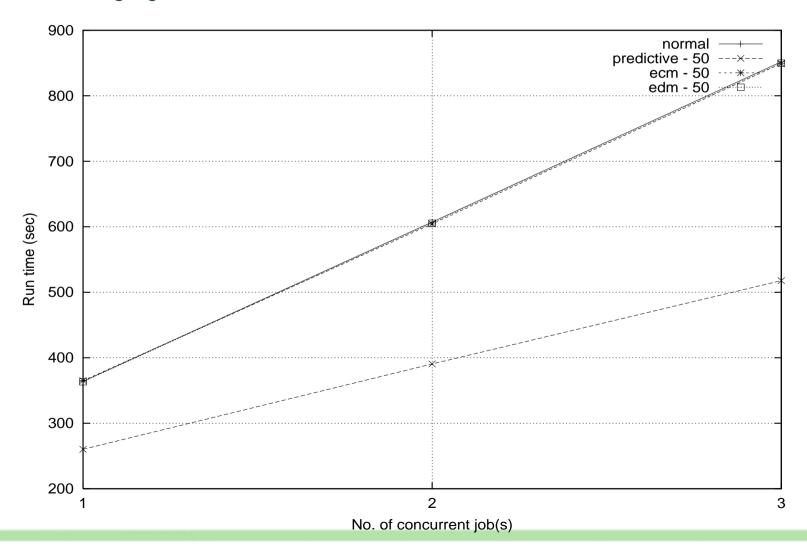
- A sequential program is running against 1-3 instants of MG, IS, and LU
- Illustrates impact on run-time of coscheduling to sequential task

Running against 1-3 MG



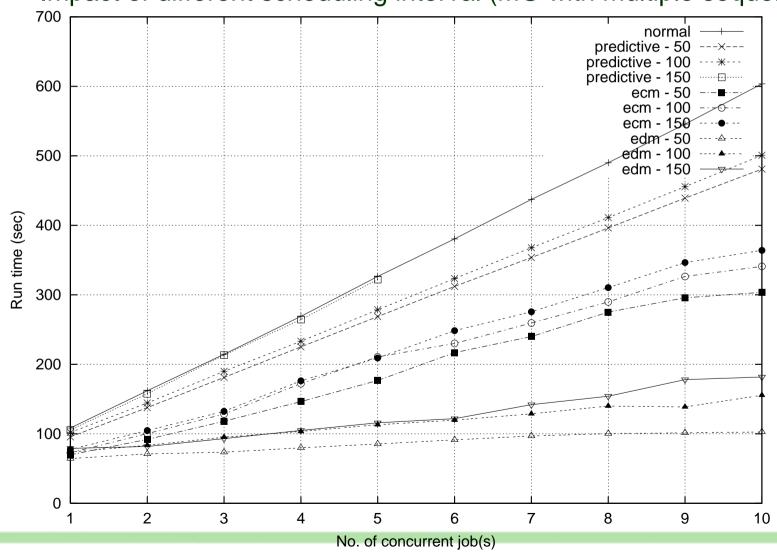


Running against 1-3 LU



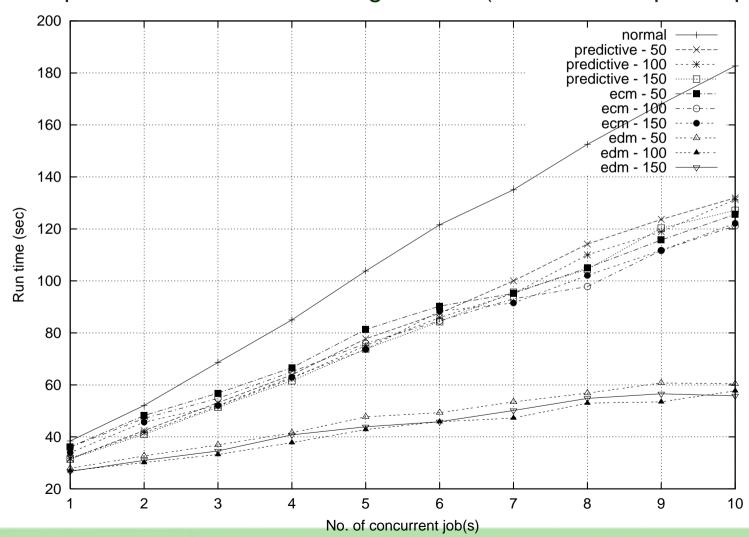
Scheduling Interval Variation

Impact of different scheduling interval (MG with multiple sequential)



Scheduling Interval Variation

Impact of different scheduling interval (MG with multiple sequential)





- EDM perform the best when running against multiple sequential program, it performs better in case of fine-grain parallel program. However, no improvement occurs with coarse-grain
- ECM perform better than Predictive. It perform the best when running coarse-grain program. However, run-time of fine-grain program is worse when running against many fine-grain
- There is almost no overhead occurs in sequential program while running against coscheduled program.
 Because coscheduling just make benefits from the waste cycle.
- The choice of whether using ECM or EDM is depends on the system. ECM for coarse-grain and EDM for fine-grain
- Inspecting the process characteristics as the whole is better than using only snap-shot of statistics



Our contribution

- Propose the Energy Model for Implicit
 Coscheduling that can improve performance of parallel programs.
- Develop a practical implementation in kernel to demonstrates that coscheduling is an applicable solution in Beowulf Cluster environment



- Running the coscheduling framework in large-scale cluster and evaluate the performance behavior of such system.
- Use more process parameter to create a better algorithm. For example, I/O rate, trashing rate.
- Incorporate coscheduling with resource allocation will potentially gain more utilization and performance



Question?



