
Parallel Programming Environment for a V-Bus based PC Cluster

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Introduction

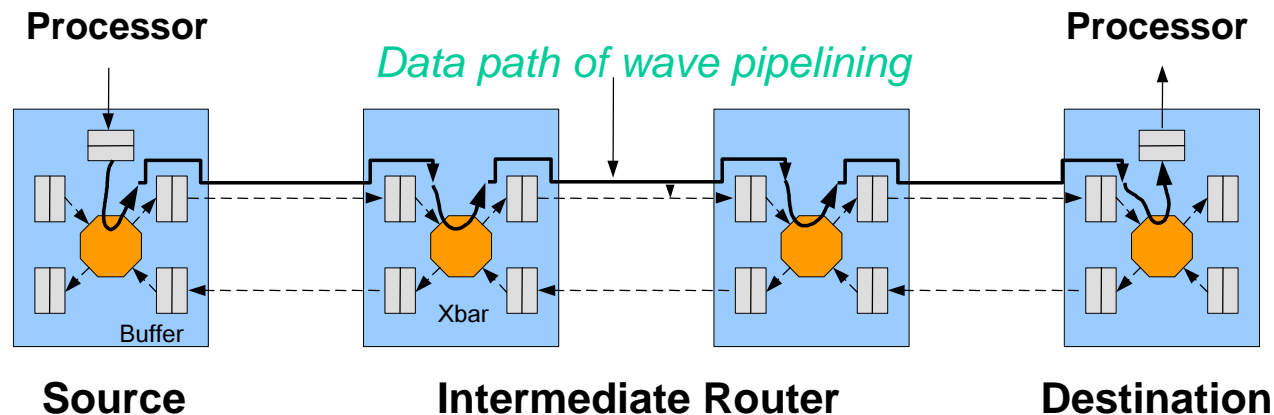
- V-Bus based PC cluster
 - PCs are interconnected with V-Bus network cards
 - V-Bus network card implemented on FPGA technology
- Programming environment for a V-Bus based PC cluster
 - MPI : MPI and one sided communication
 - Parallelizing compiler : CORE-polaris

CORE

Core Polaris

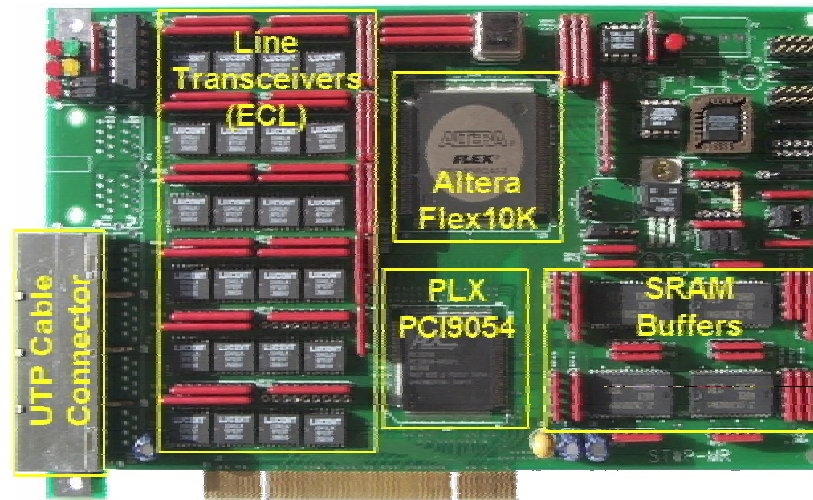
V-Bus based PC Cluster(2)

- V-Bus
 - Network establish a bus virtually only when a bus is required
 - *Efficient broadcasting* without extra physical buses
- Skew tolerant wave pipelining
 - Automatic skew sampling circuit



V-Bus based PC cluster(3)

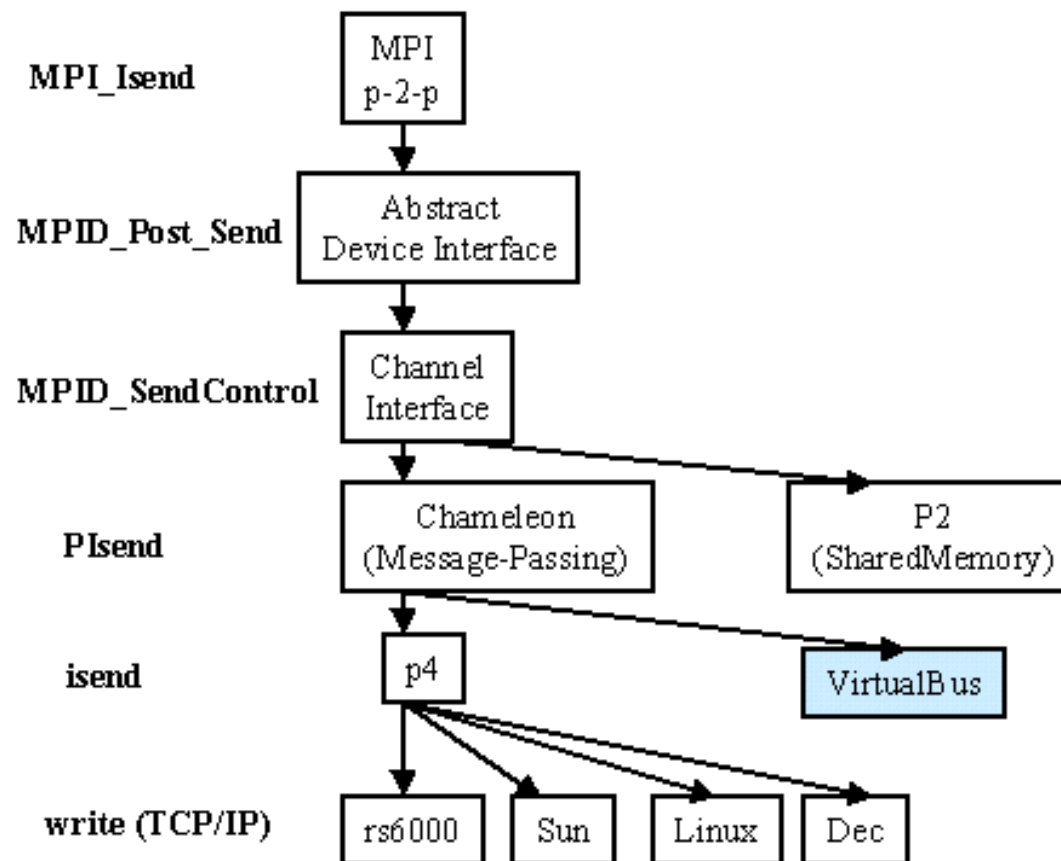
- The interconnection network architecture
 - Mesh interconnection network



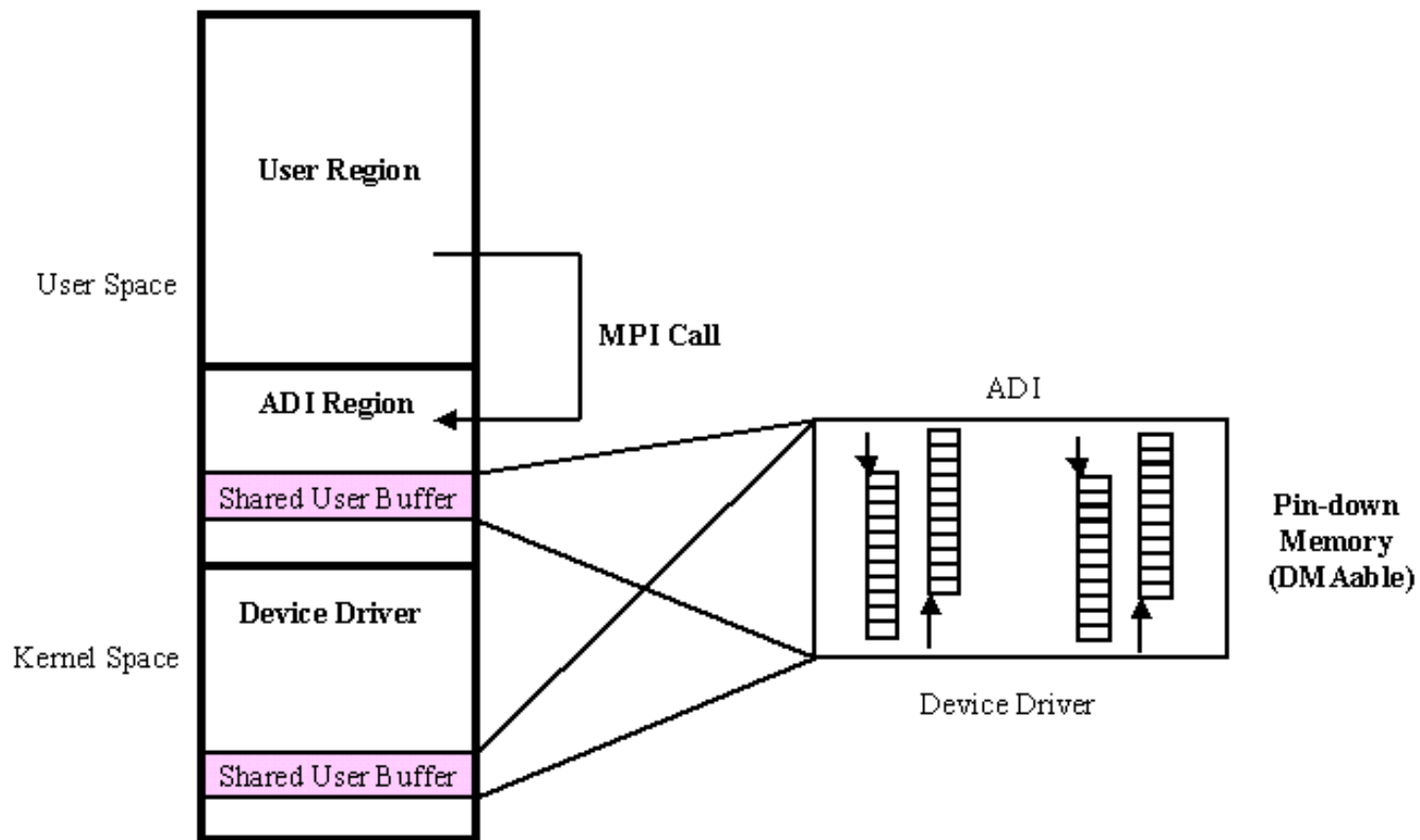
MPI (1)

- Extensions to the Message Passing Interface
 - Develop a new ADI in MPICH for a V-Bus network card
 - Support all functions of MPI-1
 - A part of MPI-2
 - One sided communication
 - Mpi_put/Mpi_get : strided and contiguous region transferring
 - Mpi_Win_lock, Mpi_Win_unlock, Mpi_fence etc.
- Feature of our MPI-2
 - Optimization of collective communication primitives using *V-Bus Broadcasting operation*
 - User-level communication

MPI (2) : MPICH

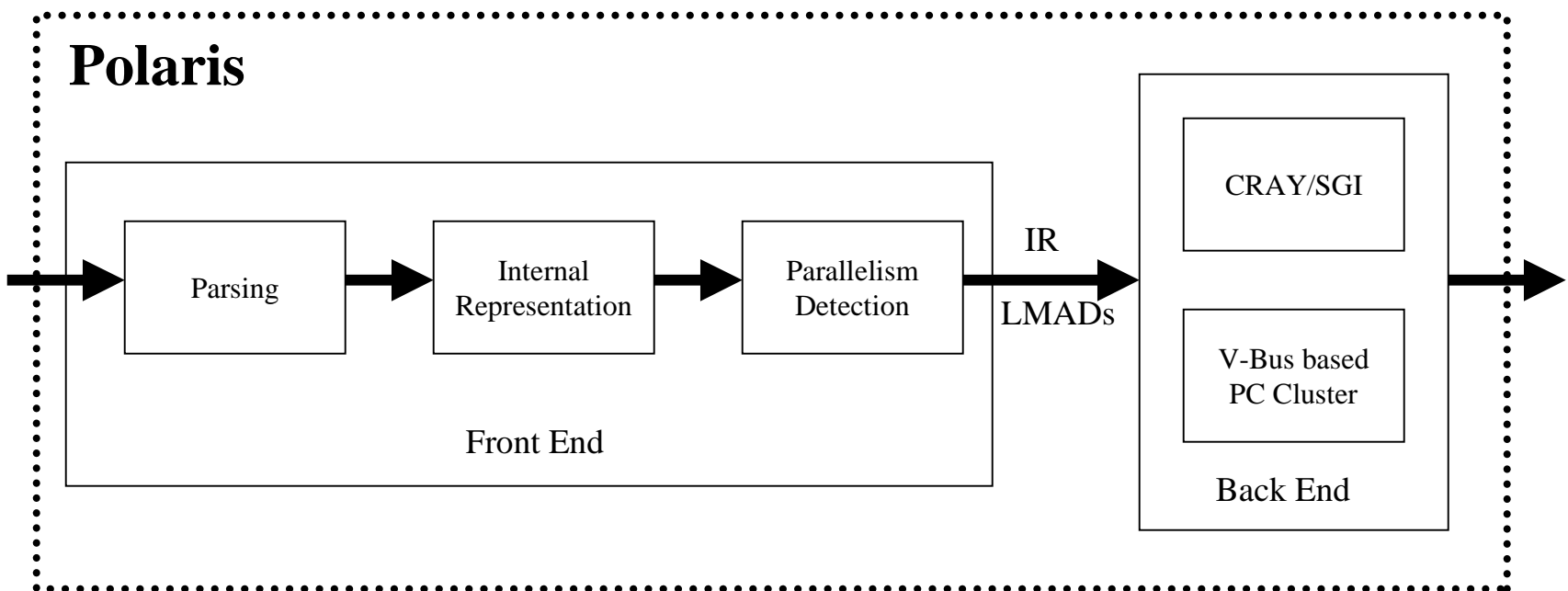


Communication Mechanism



Parallelizing Compiler: polaris

- Generate a parallel program targeted for shared memory machines



LMAD(1)

- To detect a parallel loop, the compiler need to analyze the memory access patterns of all variables
- Accuracy of array access analysis is important
- Linear Memory Access Descriptor : LMAD
 - Array access representation
 - Dependency test : Access Region Test
 - Communication generation
 - Data scattering and collecting

LMAD(2)

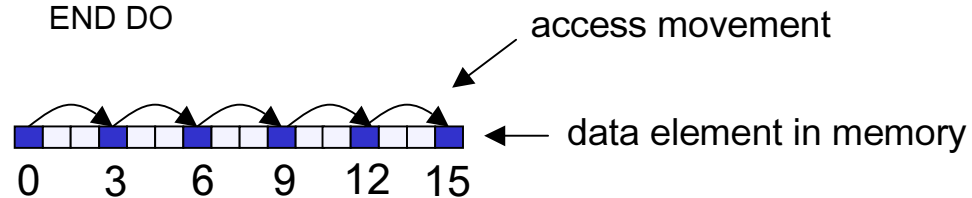
- Describes access movement through memory in terms of a series of dimensions
- Three elements
 - Stride, span, base offset
 - notation

$$A_{\text{stride1}=\alpha_1, \text{stride2}=\alpha_2, \dots, \text{stride n}=\alpha_n}^{\text{span1}=\delta_1, \text{span2}=\delta_2, \dots, \text{span n}=\delta_n} + B$$

LMAD(3)

- Stride
 - Movement through memory

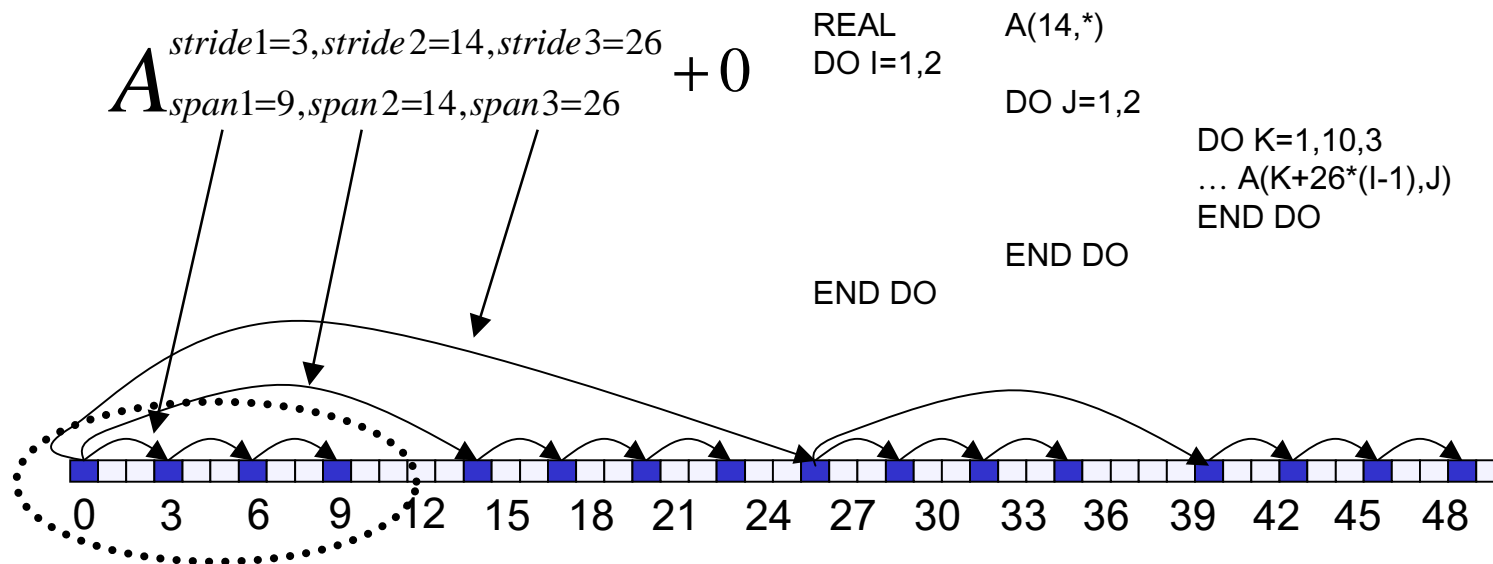
```
DO I=1,11,3  
  ... A(I) ...  
END DO
```



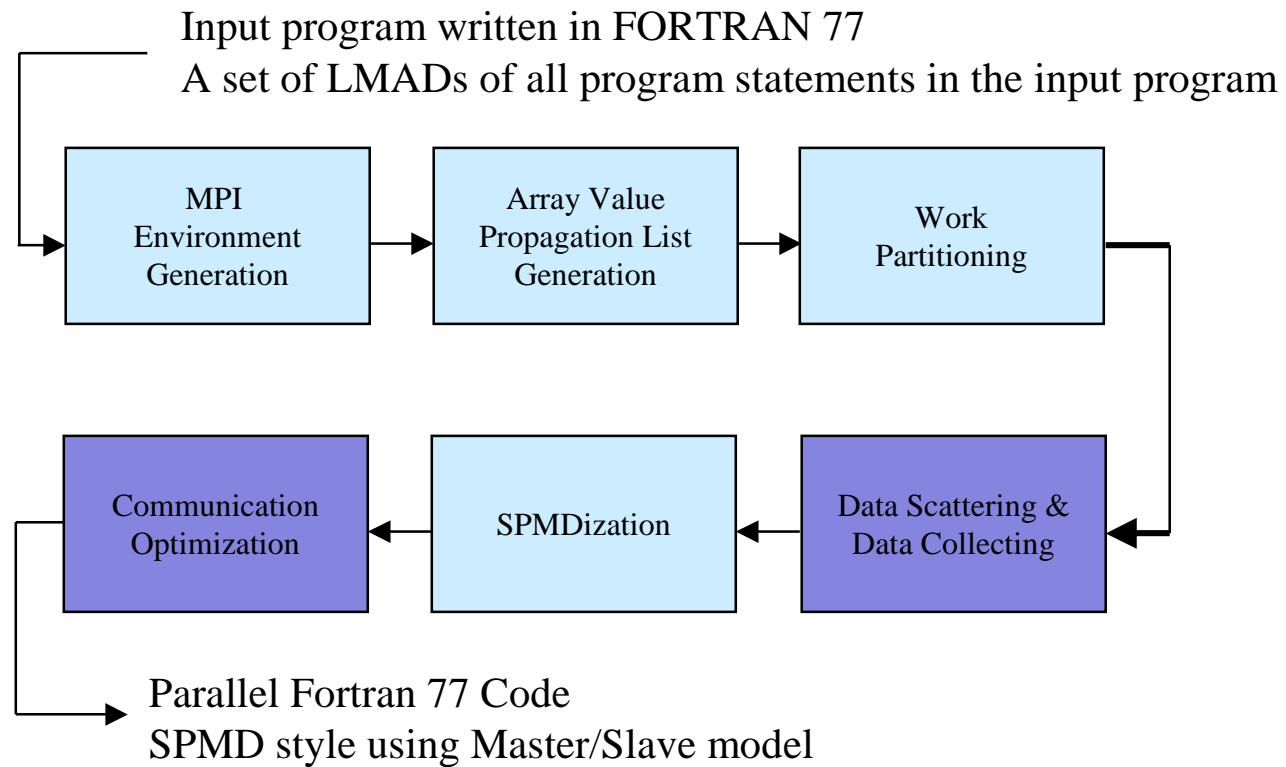
- Base offset
 - The data element access movement starts from...

LMAD(4)

- Span
 - The total element length that the access traverses when the index iterate its entire ranges
- Example



CORE-polaris

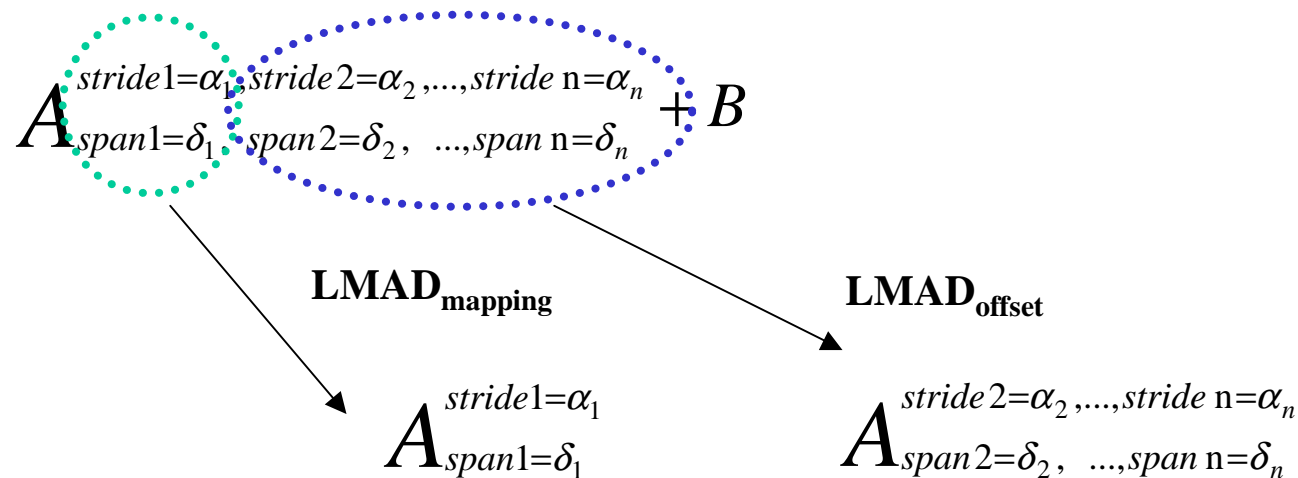


Data scattering and collecting

- Data scattering
 - At the entrance of a parallel region the master identifies the objects that each slave *may access* within the regions
 - Copies the objects to the memory of each slave
- Data collecting
 - Identifying any *modified data* from slaves at the end of the parallel region
 - Updating the copies in *master's memory* with the modified data

Data scattering using LMAD(1)

- Original LAMD is splitted into two sub-LMADs
 - $\text{LMAD}_{\text{offset}}$: calculate a set of data offsets from base address i in a sequence of communication primitive generation
 - $\text{LMAD}_{\text{mapping}}$: map data access into communication primitives provided by the MPI-2 library

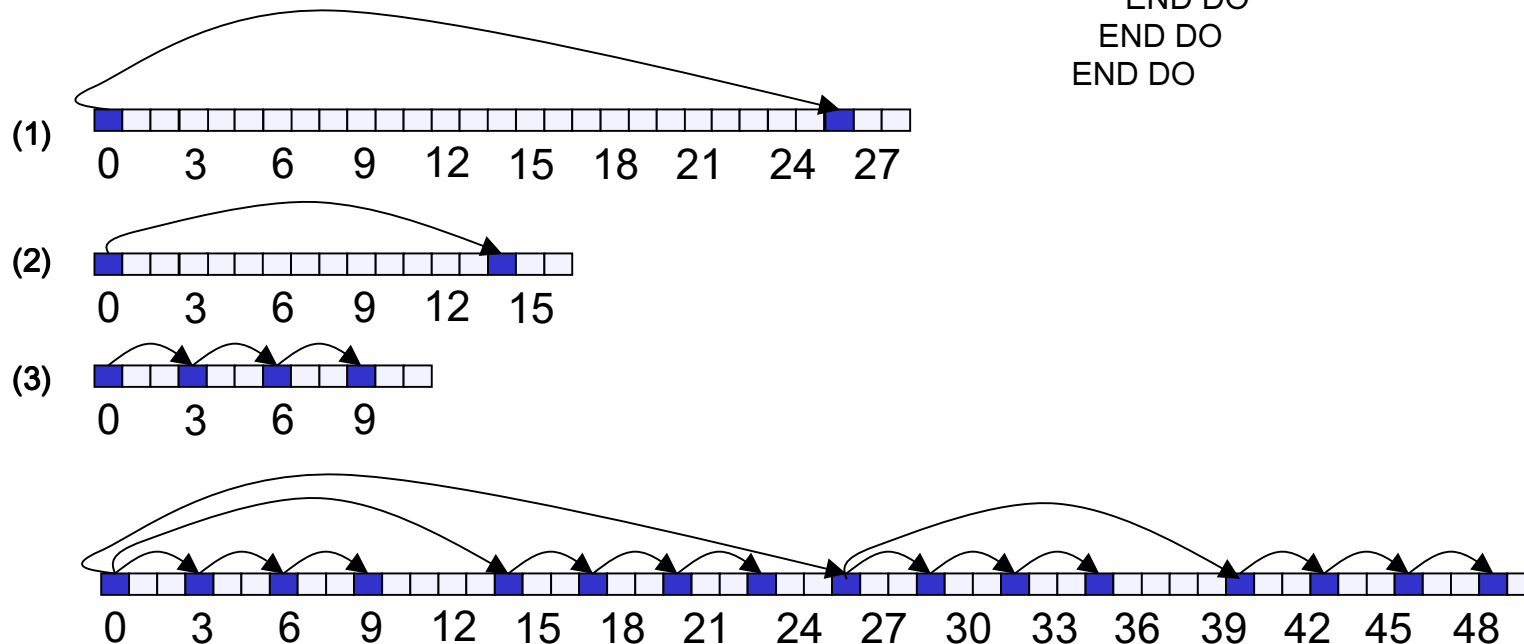


Data scattering using LMAD(2)

$$A_{9,14,26}^{(3)(2)(1)3,14,26} + 0$$

```

REAL      A(14,*)
(1) DO I=1,2
(2)   DO J=1,2
(3)     DO K=1,10,3
           ... A(K,J+26*(I-1))
        END DO
      END DO
    END DO
  
```



Data scattering using LMAD(3)

- The set of offsets that are calculated from $\text{LMAD}_{\text{offset}}$
$$\{x_1 \times \alpha_2 + x_2 \times \alpha_3 + \dots + x_n \times \alpha_n \mid 0 \leq x_i \leq \delta_i / \alpha_i,$$

where x_i is non - negative integer}
- $\text{LMAD}_{\text{mapping}}$ is mapped into Mpi_put/Mpi_get as follows
 - If the stride of $\text{LMAD}_{\text{mapping}}$ is constant and
 - stride of $\text{LMAD}_{\text{mapping}} = 1$: *contiguous Mpi_put/Mpi_get*
 - stride of $\text{LMAD}_{\text{mapping}} > 1$: *stride Mpi_put/Mpi_get*
 - If the stride of $\text{LMAD}_{\text{mapping}}$ is not constant
 - one memory element by one memory element

Communication optimization(1)

- Network latency is higher than conventional supercomputers
- Small *exact* regions -> *approximate* regions
- Three granularity levels based on LMAD
 - Fine, Middle, Coarse granularity

Communication optimization(2)

- *Fine* granularity
 - Exact regions are always transferred
 - The number of communication
$$(\delta_2 / \alpha_2) \times (\delta_3 / \alpha_3) \times \dots \times (\delta_n / \alpha_n) + 1$$
- *Middle* granularity
 - $\text{LMAD}_{\text{mapping}}$ is always mapped into contiguous Mpi_put/get, even the stride is greater than 1.
 - Contiguous Mpi_put/get has high throughput and low latency than those of stride Mpi_put/get
 - The number of communication
$$(\delta_2 / \alpha_2) \times (\delta_3 / \alpha_3) \times \dots \times (\delta_n / \alpha_n) + 1$$

Communication optimization(3)

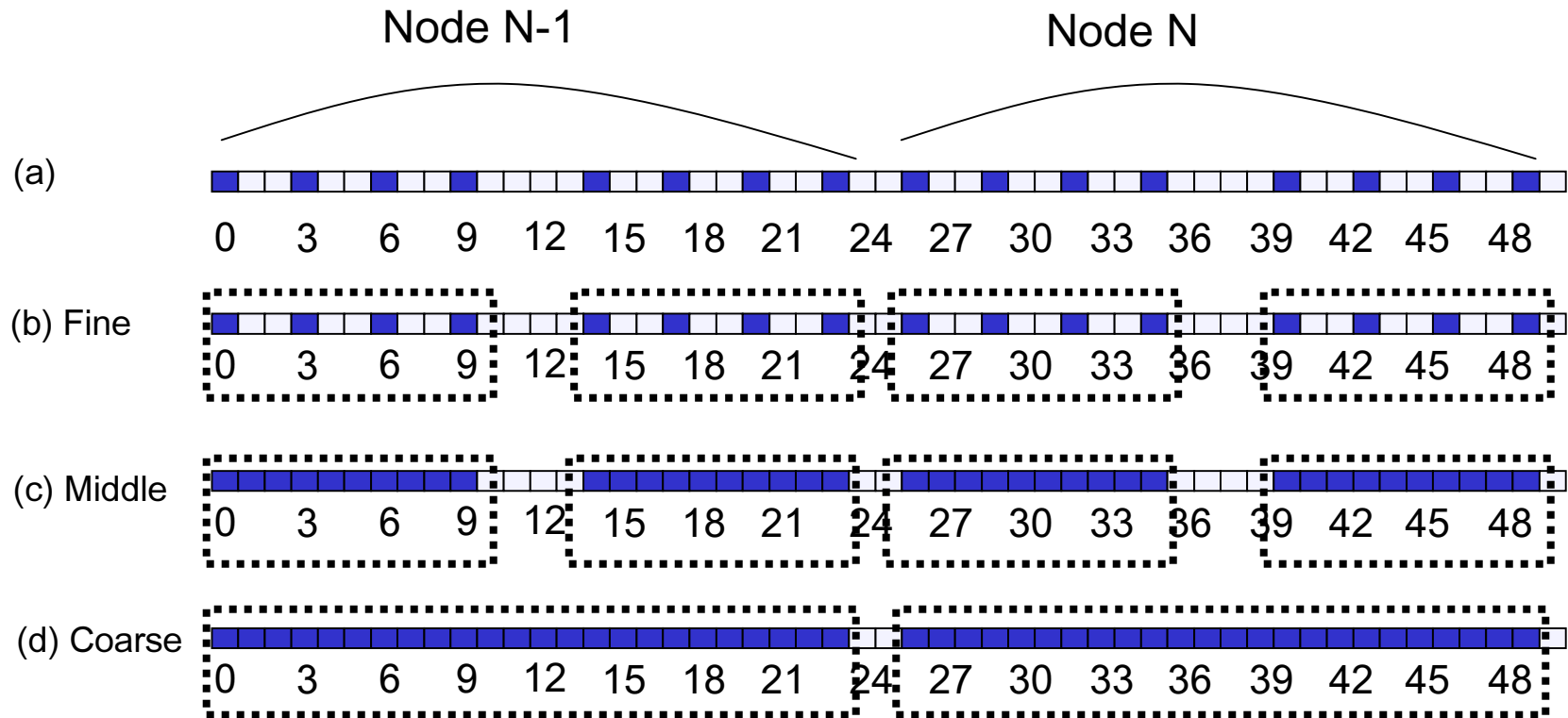
- *Coarse* granularity
 - Merging scattered regions into a big approximate regions

$$\text{LMAD}_{\text{offset}} \quad A_{\text{span } n-1=\delta_{n-1}}^{\text{stride } n-1=\alpha_{n-1}} \quad \text{LMAD}_{\text{mapping}} \quad A_{\text{span } 1=\delta_n}^{\text{stride } 1=\alpha_n}$$

- The number of communication

$$(\delta_n / \alpha_n) + 1$$

Communication optimization(4)

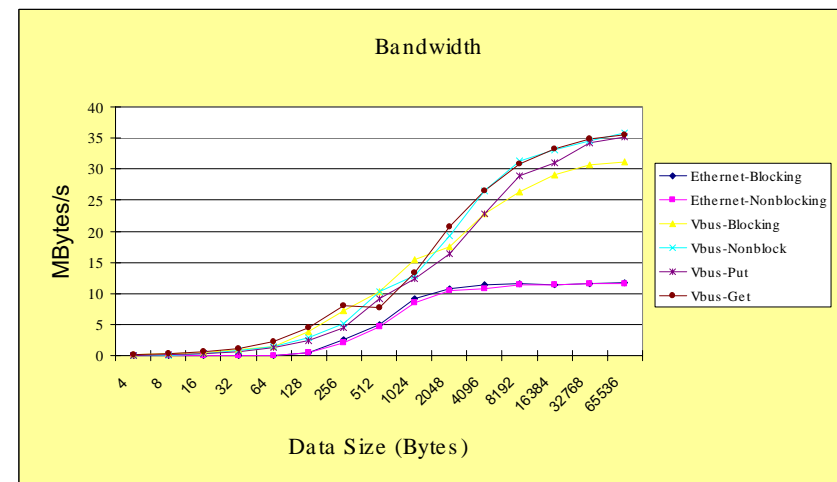
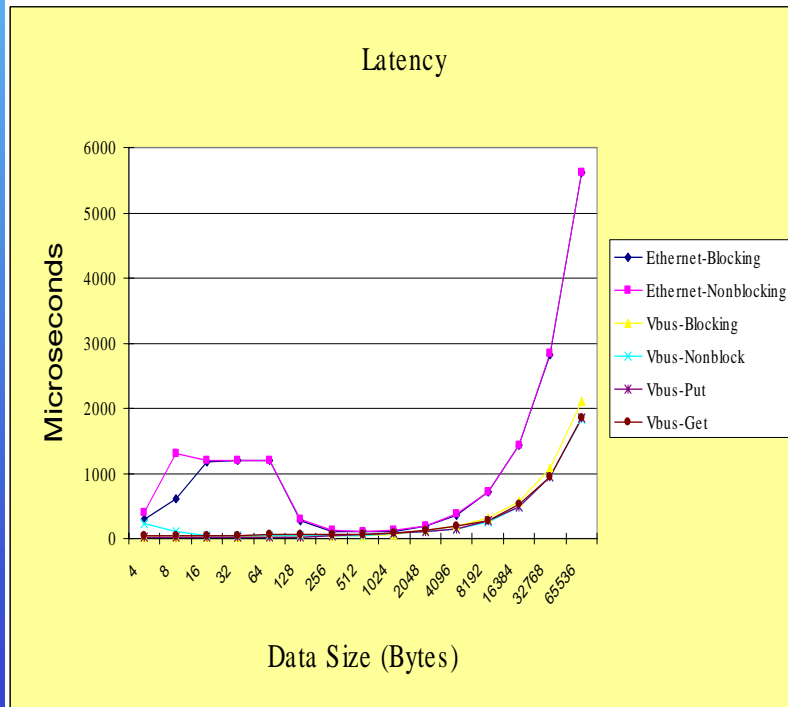


Communication optimization(5)

- If *overlapped data objects* in approximate regions
 - Race condition happens at data collecting phase
 - Check the upper and lower bound of approximate regions
 - If overlapped data objects exist
 - *Fine granularity* communication
- For now, it is up to the user that select the optimal granularity with the help of profiling routines

Experiment : MPI-2

- 100Mbps Ethernet VS V-Bus network



Experiment : CORE-polaris

- 300MHz , 64MB memory

Table 1. Total execution time of the MM code

Speedups		Array Size		
		256*256	512*512	1024*1024
# of Nodes	1	0.96	0.96	0.96
	2	1.086	1.53	1.60
	4	1.75	2.74	3.033

Table 2. Communication time for matrix multiplication, swim and CFFZINIT of TFFT

Total Communication Time (sec)	Granularity		
	fine	middle	coarse
MM(1024*1024)	0.72	0.89	0.01128
Swim(ITMAX=1)	0.20590	*	0.072166
CFFZINIT(M=11)	0.3584	0.0768	0.0068

Conclusion/Further work

- Two programming interfaces for a V-Bus based PC cluster
 - MPI and MPI-2
 - One sided communication
 - User level communication
 - Optimized for V-Bus network
 - CORE-polaris
 - Data scattering/collecting using LMAD
 - Communication optimization for V-Bus based network
- Further work
 - More large scale PC-cluster(4 by 4)
 - Cross loop/subroutine communication optimization