

Coordinated Coscheduling in Time-Sharing clusters through a Generic Framework

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Clusters Today

Scientific
Applications

Web / Wireless
Application Servers

Typical cluster based Application Characteristics

Parallel and Distributed.

Possibly Communication Intensive (High/Medium/Low).

Very common and is our research focus.

Requirement for progress ?

Time for inter-Node communication.

Implication ?

Parallel Jobs must be co-scheduled !

Outline Today

What is the **combinatorial scheduling** problem ?

How has it been solved **earlier** ?

Batch scheduling, DCS, ICS (SB), PB

Why previous solutions **not enough** ?

What can we **propose** ?

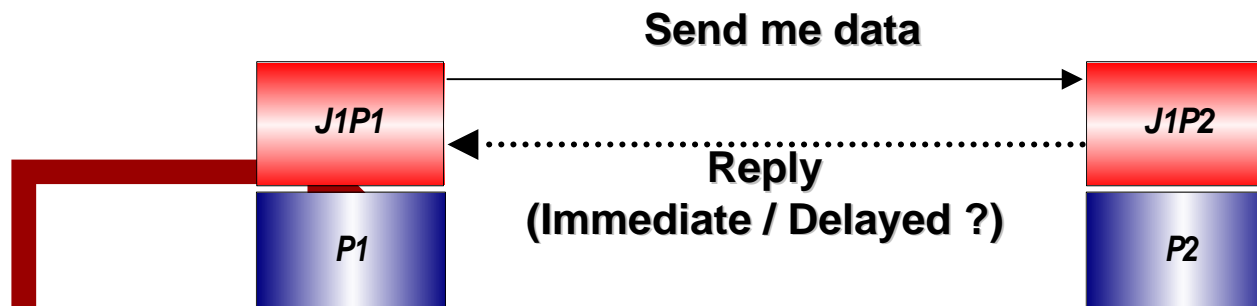
What are the **results** ?

What can we **conclude** ?

Is there a **future** for this ?

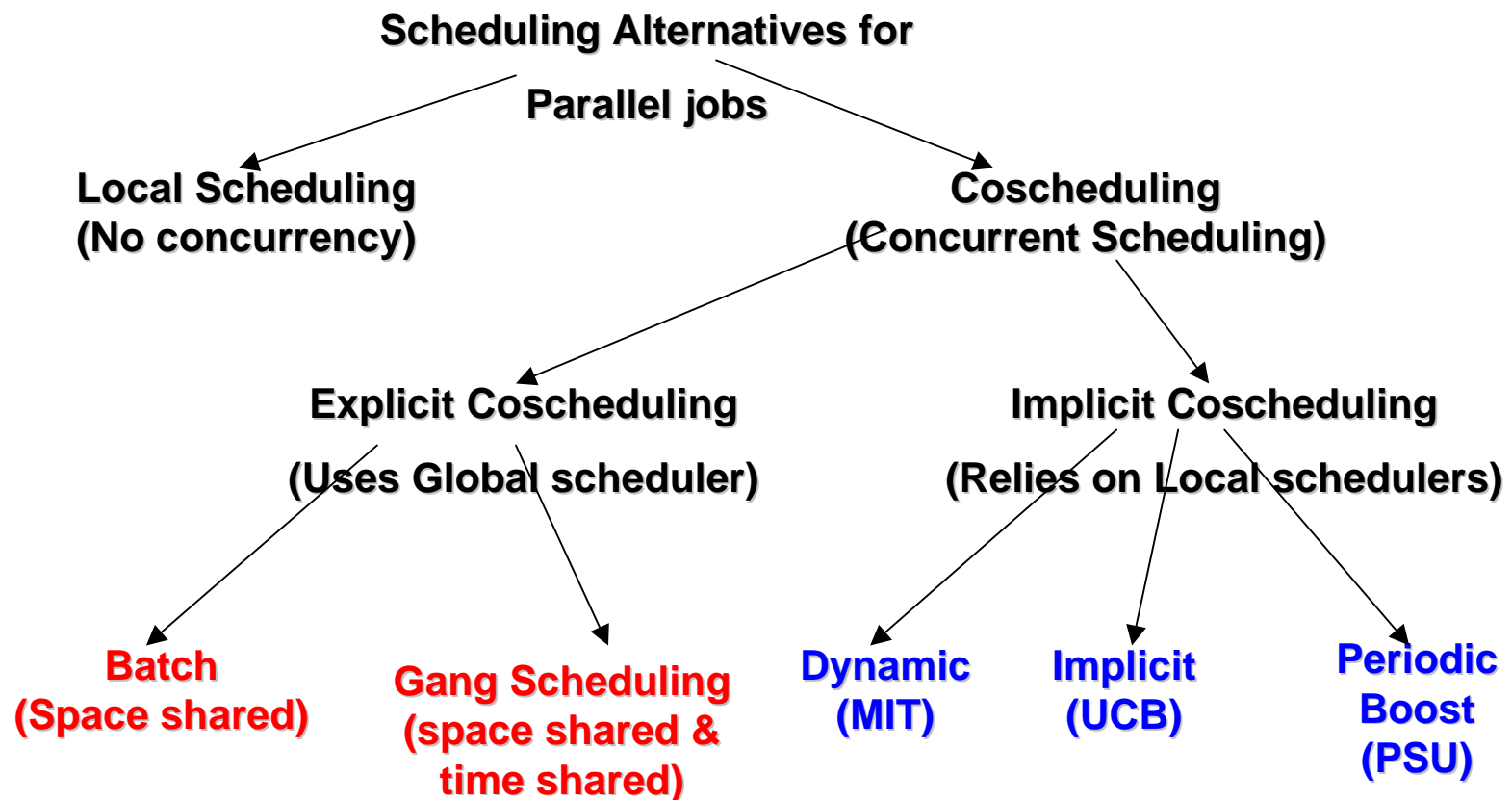
What is CoScheduling ?

CoScheduling* : Concurrently Schedule processes of a parallel job on individual nodes of a time-sharing cluster.

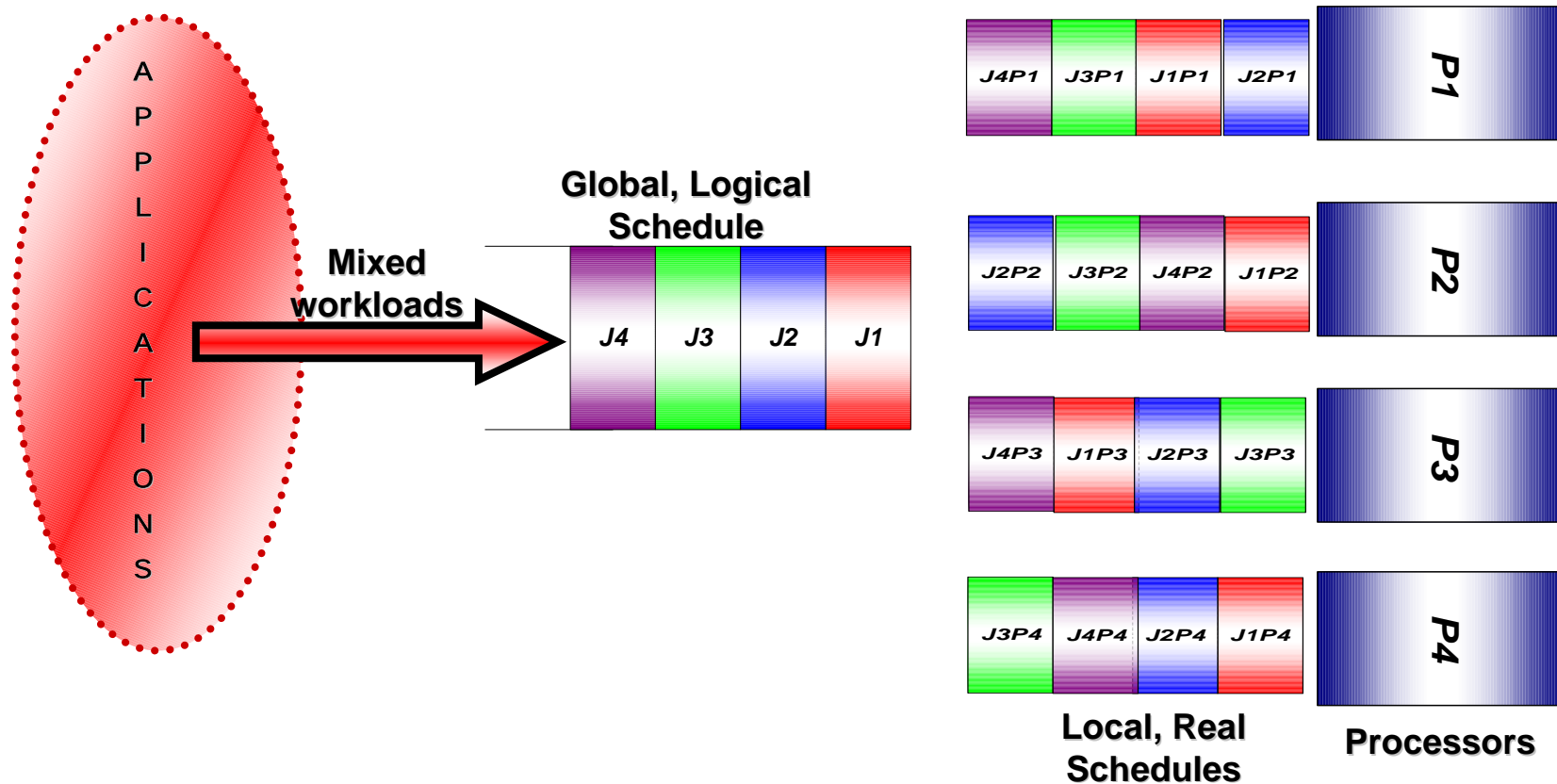


Why Needed ? : Performance

Parallel job Scheduling Techniques (Hierarchy)



Un-coordinated (Local) scheduling



Explicit Scheduling: Batch Scheduling

1 job runs on all CPUs until completion

Once job is done scheduler queue for their turn

Problems

Low utilization

Low response times

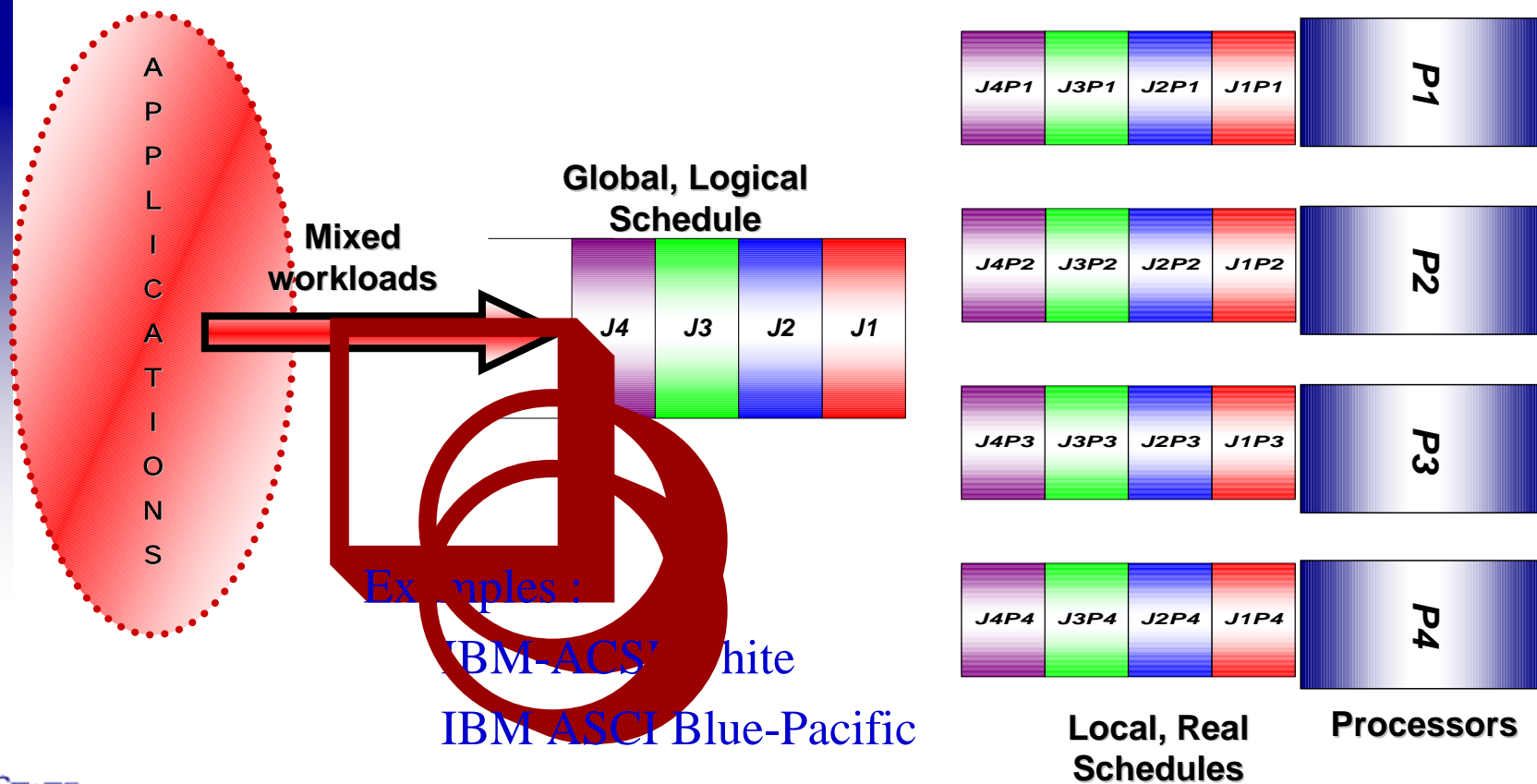
Examples :

IBM-SP2 (uses Load Leveler)

Intel Paragon (Uses Network Queuing System (NQS))

Many research COTS clusters use PBS

Explicit Coscheduling: Gang Scheduling



Why No Gang Scheduling on Clusters ?

Need a scheduler controlling jobs on ALL nodes

Implement as :-

1. Frequent Synchronization (Order milli-sec)

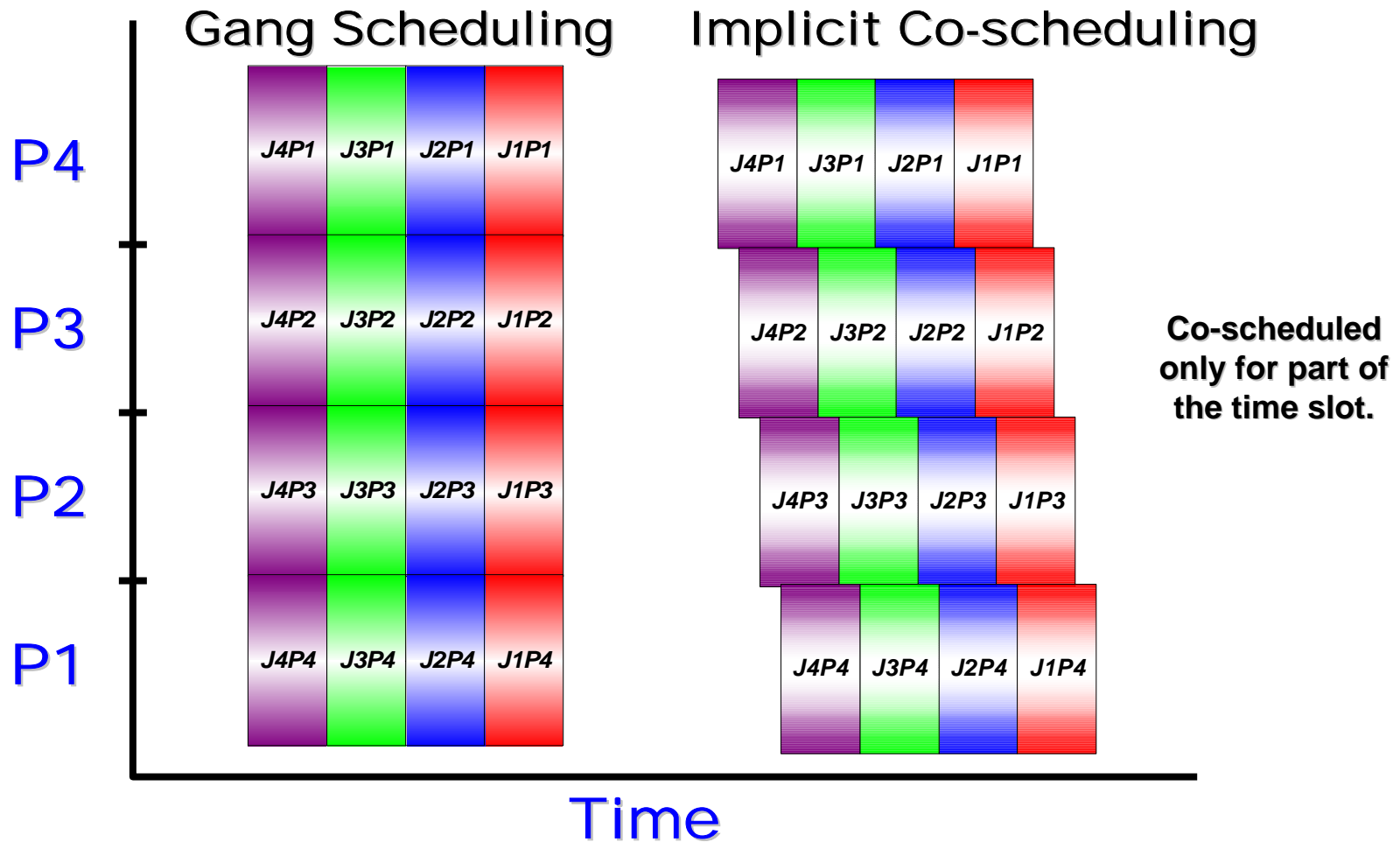
2. Synchronization in **NOW** because of higher wire latencies (Order milli-sec).

3. Large change in 'time quantum' (of order seconds).

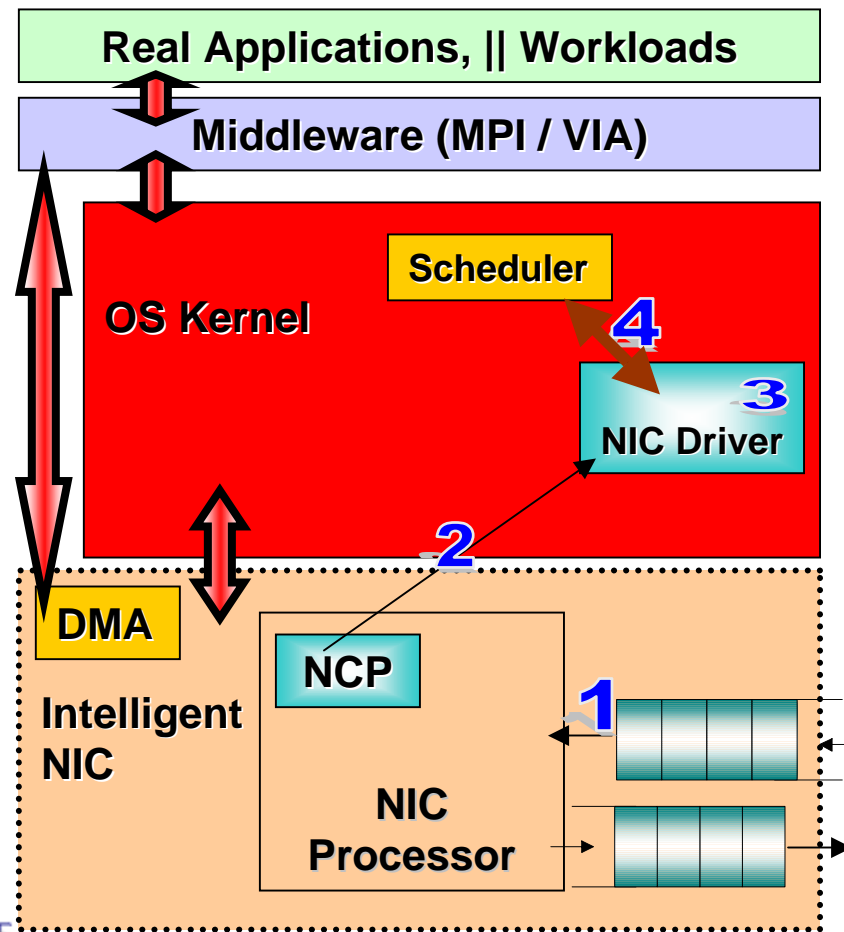
4. Reduces system responsiveness.

Not scalable for NOW (For same reason as above).

What is the solution ?



DCS : Dynamic Coscheduling



“Dynamic Adjustment” of process priorities by using **“messages”** (from communicating jobs) as hints.

NIC Control Program (NCP)

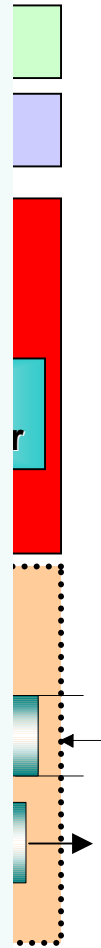
senses incoming message.

NCP raises interrupt(s) to **NIC Driver**, *if required*.

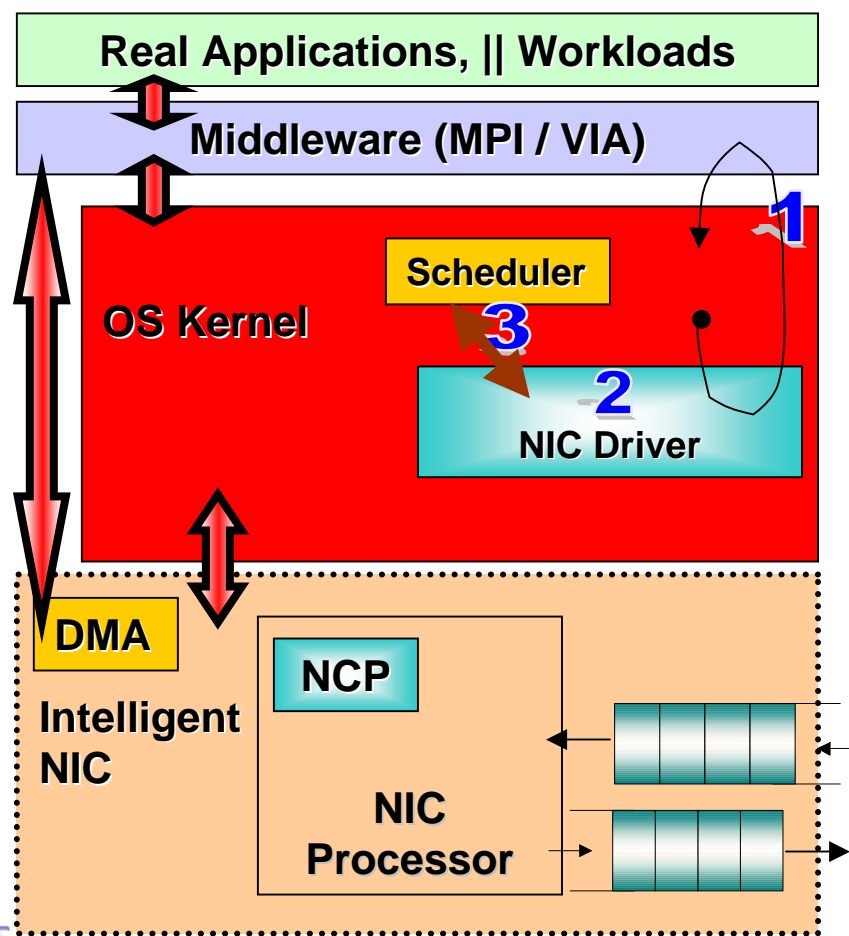
NIC Driver *finds & places* relevant process into the **highest-priority queue**.

Scheduler schedules that process.

in Block



PB : Periodic Boost



“Periodically” check end-points in host memory, **“Boost”** the process with pending messages.

Driver polls VI end-points in user-pinned memory, every 10 ms.

Picks 1st pending-message VI, **finds** corresponding process, **boosts** its priority.

Scheduler schedules that process next.

'Implicit' Coscheduling: Various Issues

DC

Too many interrupts ($< 1\text{ms}$)

Reason: Per VI, instead of per process

SD

No cost

No code optimization.

Very slow

For Tightly coupled (Split-C) environment.

PE

Unpleasant form.

Democracy : Polling done after DMAs

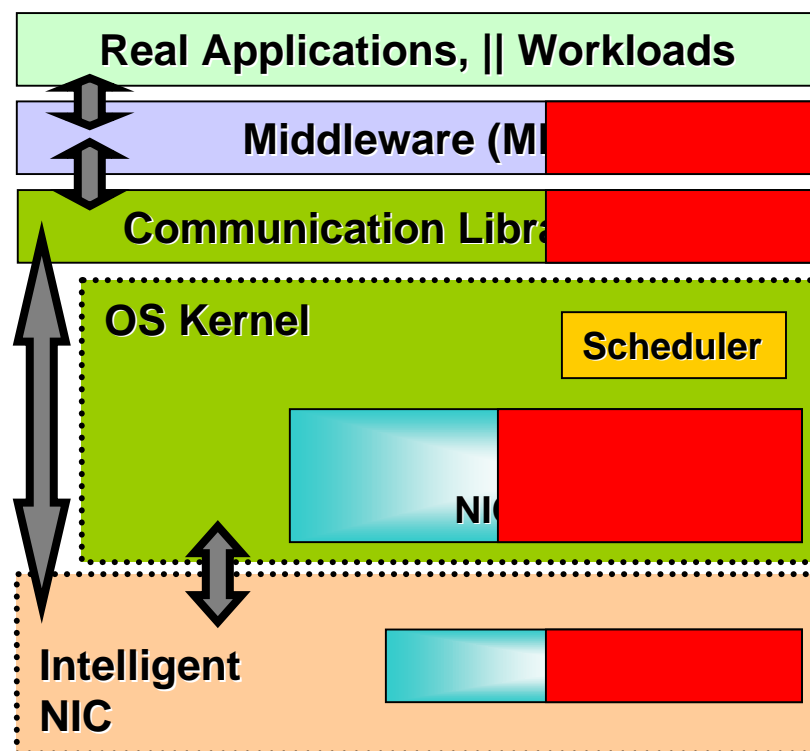
Low polling in fair version. (Too many polls)

Reason : Per VI, instead of per process.

No Commercial Implementation. WHY ?

1. Lack of exhaustive experimentation on multiple platforms.
 - Not easy to code custom-solutions for each platform.
 - No general standard approach available.
2. No scheme better for all types of workloads.
 - None provides extensibility, generality, adaptability ?
 - Support for QoS not addressed at all.
3. No real incentives (results) demonstrated yet
 - Coscheduling against batch scheduling ?
 - Presence of other sequential workloads (CPU, I/O) ?
 - High Multi-programming degree ?

Addressing global issue 1 :- Prior Design



Parts of code to change :

MPI Library (SB)
VIA Library (SB, PB)
Device driver (DCS, SB, PB)
Firmware (DCS, SB, PB)

Drawbacks

Flexibility

Tight driver/firmware coupling

Generality

: Different implementations for each scheme.

Modularity

: No re-use across platforms.

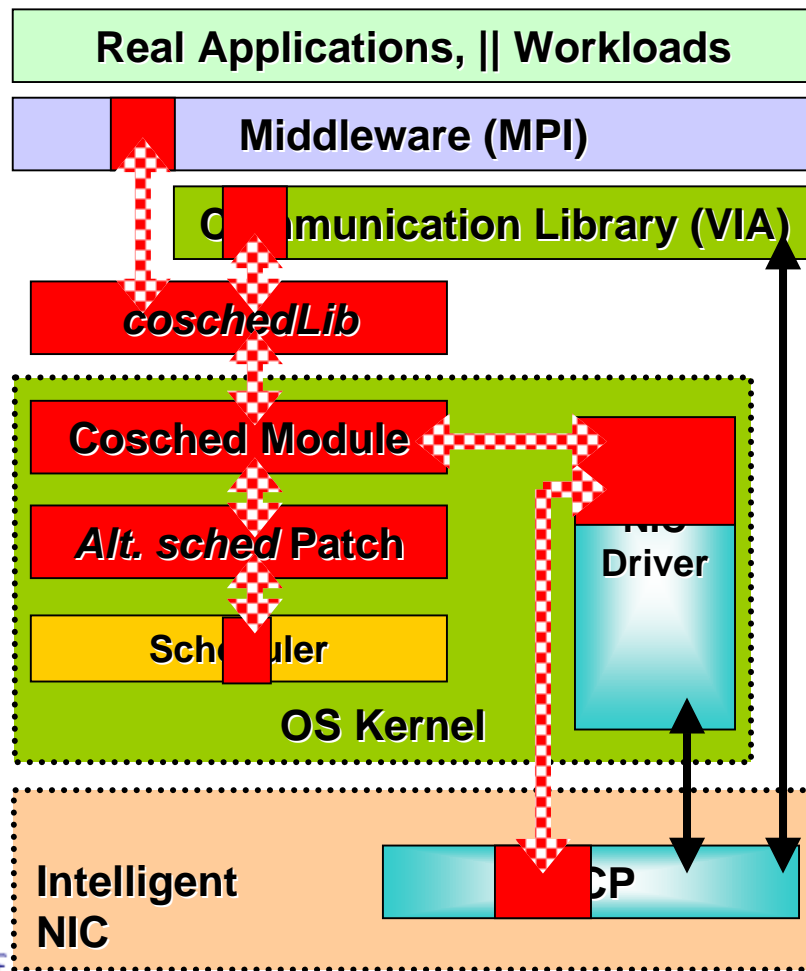
Portability

: No standard interface

Integrity

: Local scheduler isolated.

Proposed Design



Big Picture :

Identify and isolate “*policies*”
and “*mechanisms*”.

Re-use “*policies*”

Re-implement “*mechanisms*”

Advantages

Flexibility : Coscheduling independent
of device driver / firmware.

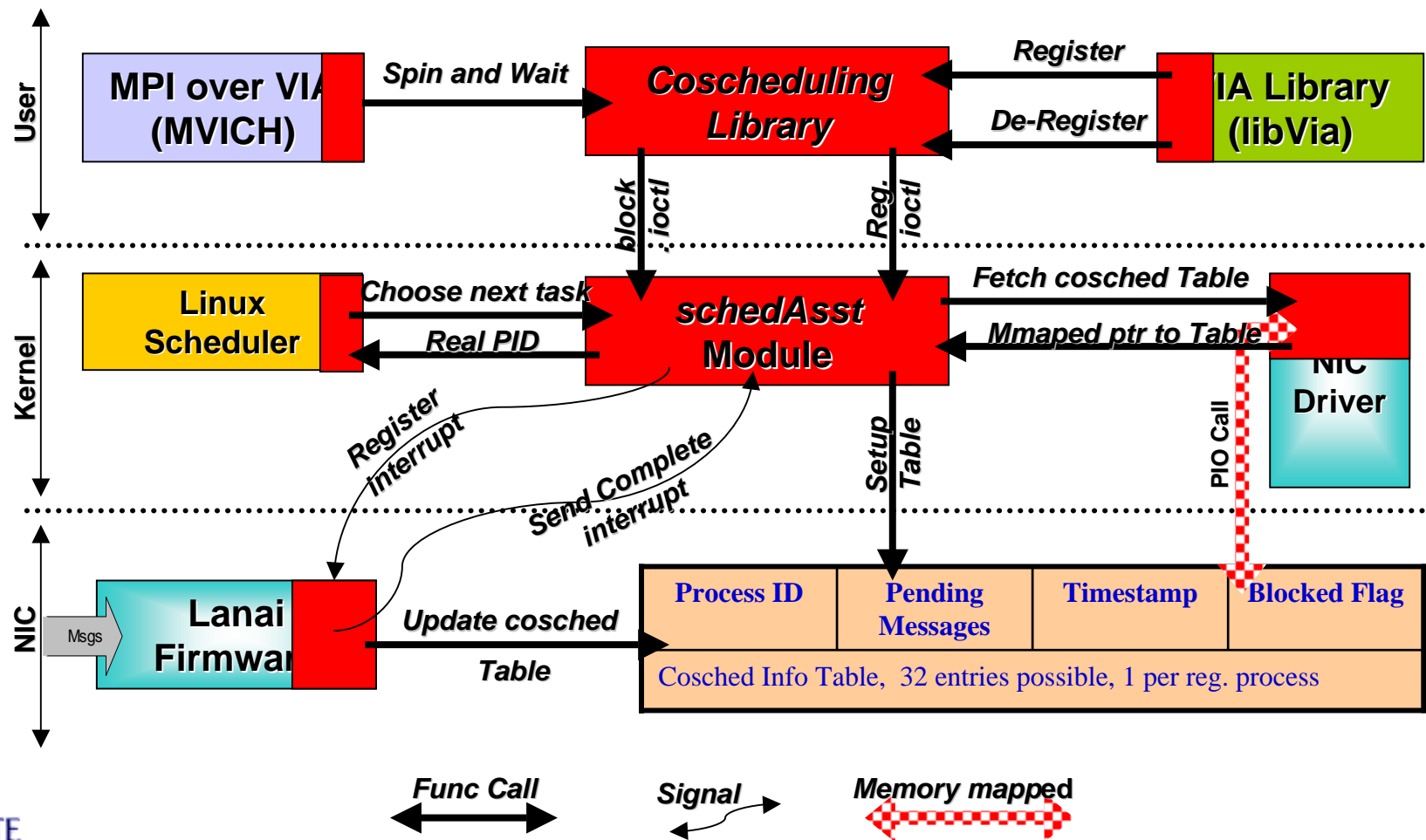
Generality : Same module for all schemes.

Modularity : Re-use across platforms.

Portability : Standard interfaces defined.

Integrity : Local scheduler involved.

Addressing global issue 2 :- Coordinated Coscheduling



Addressing global issue 3 :- Workload / Environment

16 node Myrinet connected cluster, 1GB RAM .

Linux 2.4 MPI over VIA, Berkeley-VIA

Lanai-9 Myrinet NI cards, 8MB on-chip memory.

Workload	Applications	Communication Intensity
<i>Wl1</i>	(EP, EP, EP, EP, EP, EP)	lo:lo:lo:lo:lo:lo
<i>Wl2</i>	(EP, EP, EP, MG, MG, MG)	lo:lo:lo:hi:hi:hi
<i>Wl3</i>	(MG, MG, MG, MG, MG, MG)	hi:hi:hi:hi:hi:hi
<i>Wl4</i>	(EP, EP, LU, LU, MG, MG)	lo:lo:me:me:hi:hi
<i>Wl5</i>	(LU, LU, LU, LU, LU, LU)	me:me:me:me:me:me

(a) Parallel Workload Composition (MPL6)

Category	Workload Mix
Parallel Only	<i>wl1, wl2, wl3, wl4, wl5</i>
Parallel + CPU	(<i>wl1...wl5</i>) + 1 <i>sb</i> (1,2,4,6) <i>sb</i> + 2 MGs
Parallel + IO	(<i>wl1...wl5</i>) + 1 <i>iobench</i>

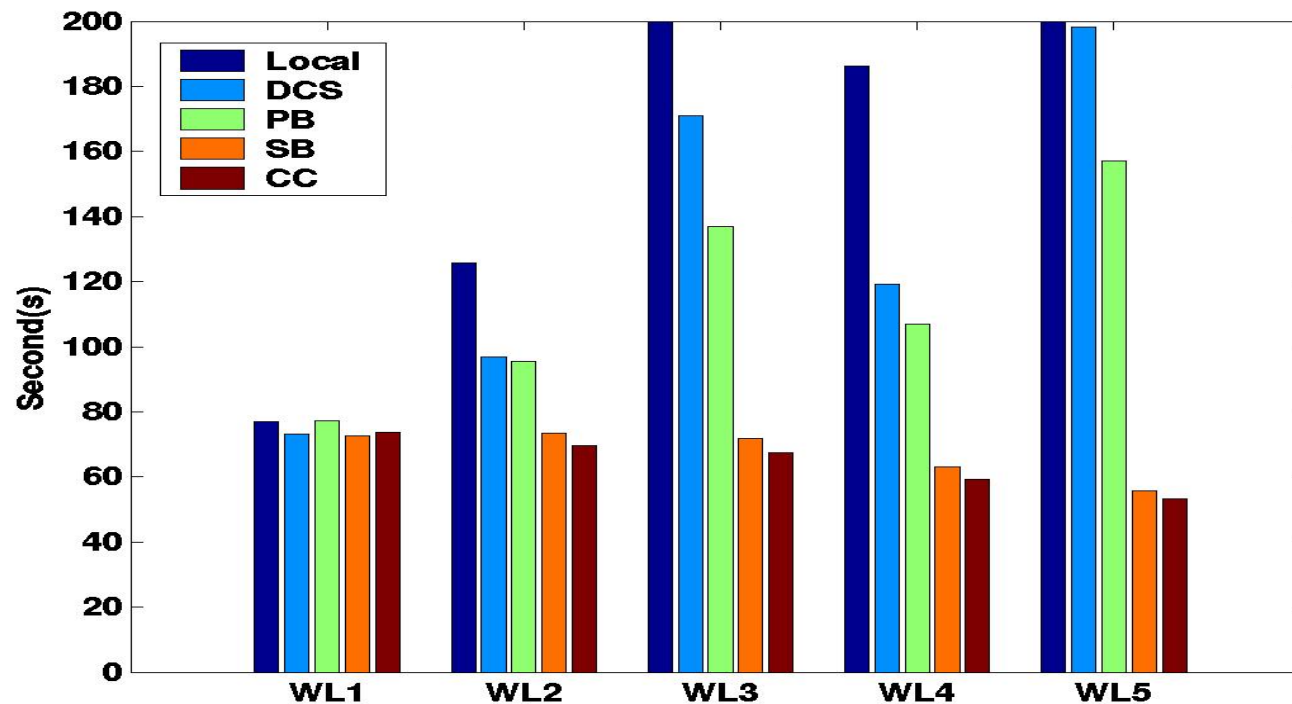
(b) Executed Combinations (*sb* : *sched_bench*)

Table : Workload mixes used in this study.

Performance : Execution Time

MPL = 6

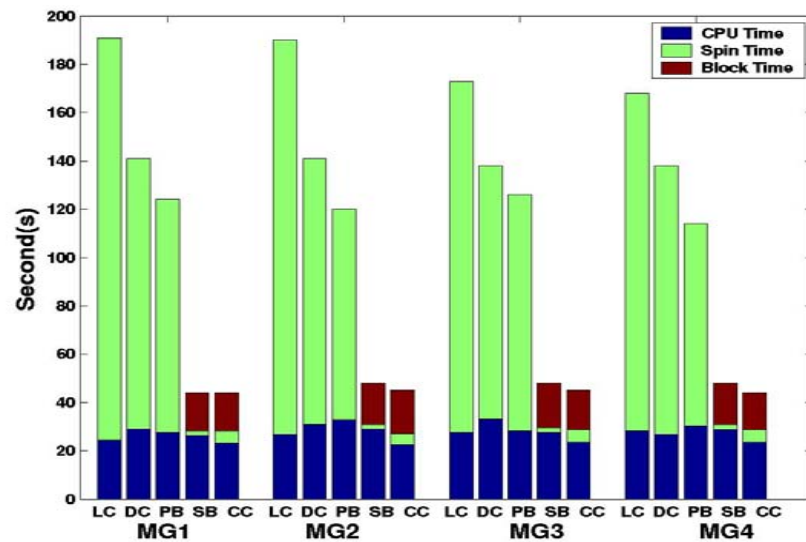
CC > SB > PB > DCS > Local



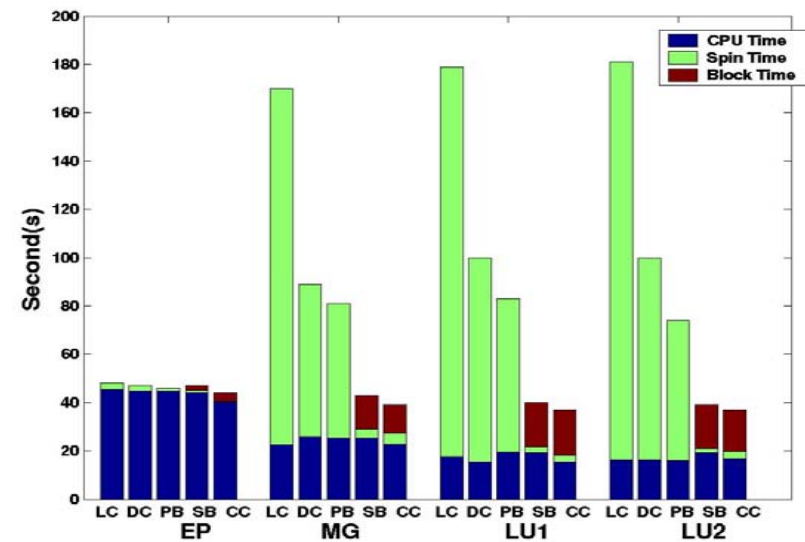
Where does time go ?

Total CPU Time = Useful work time + Non-useful spin time

Wall Clock Time = Total CPU time + Block time + others...



Workload – w/3

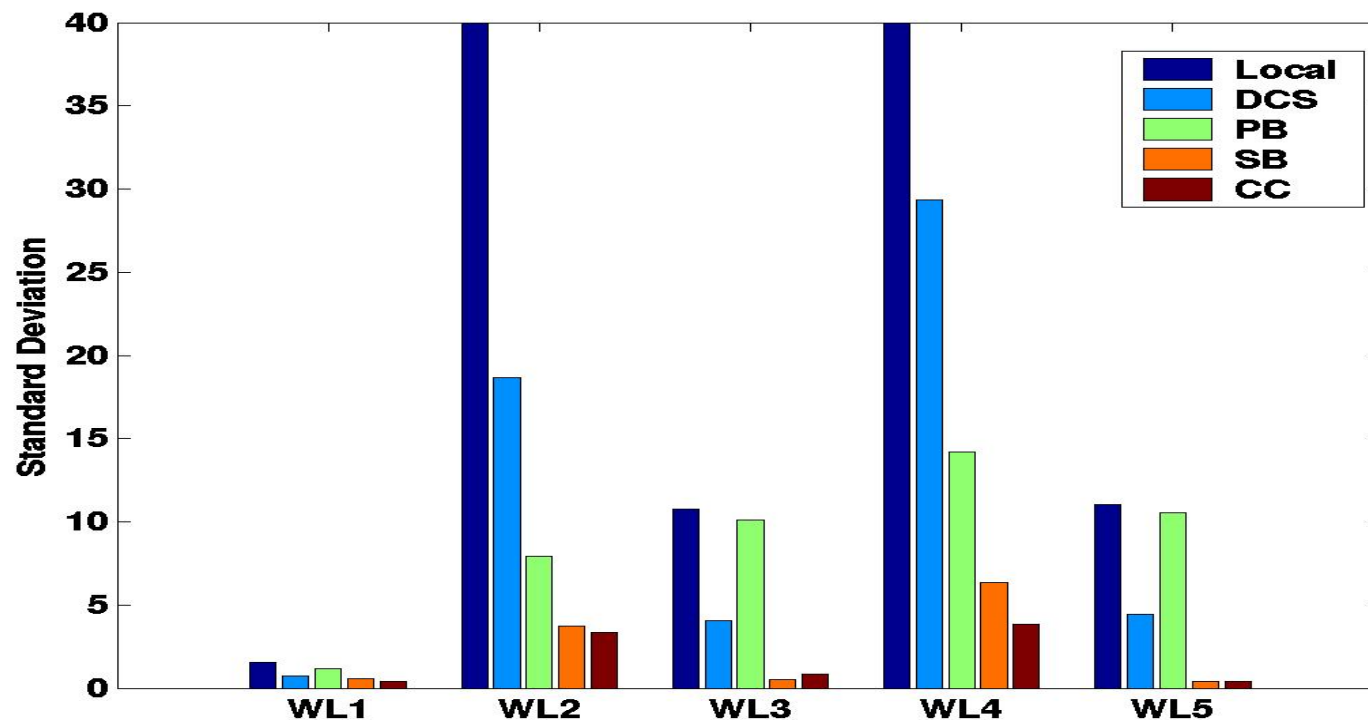


Workload – w/4

Tolerance : Standard Deviation

WL2, WL4 : Mixed

WL1, WL3, WL5 : Uniform



Fairness : CPU Utilization

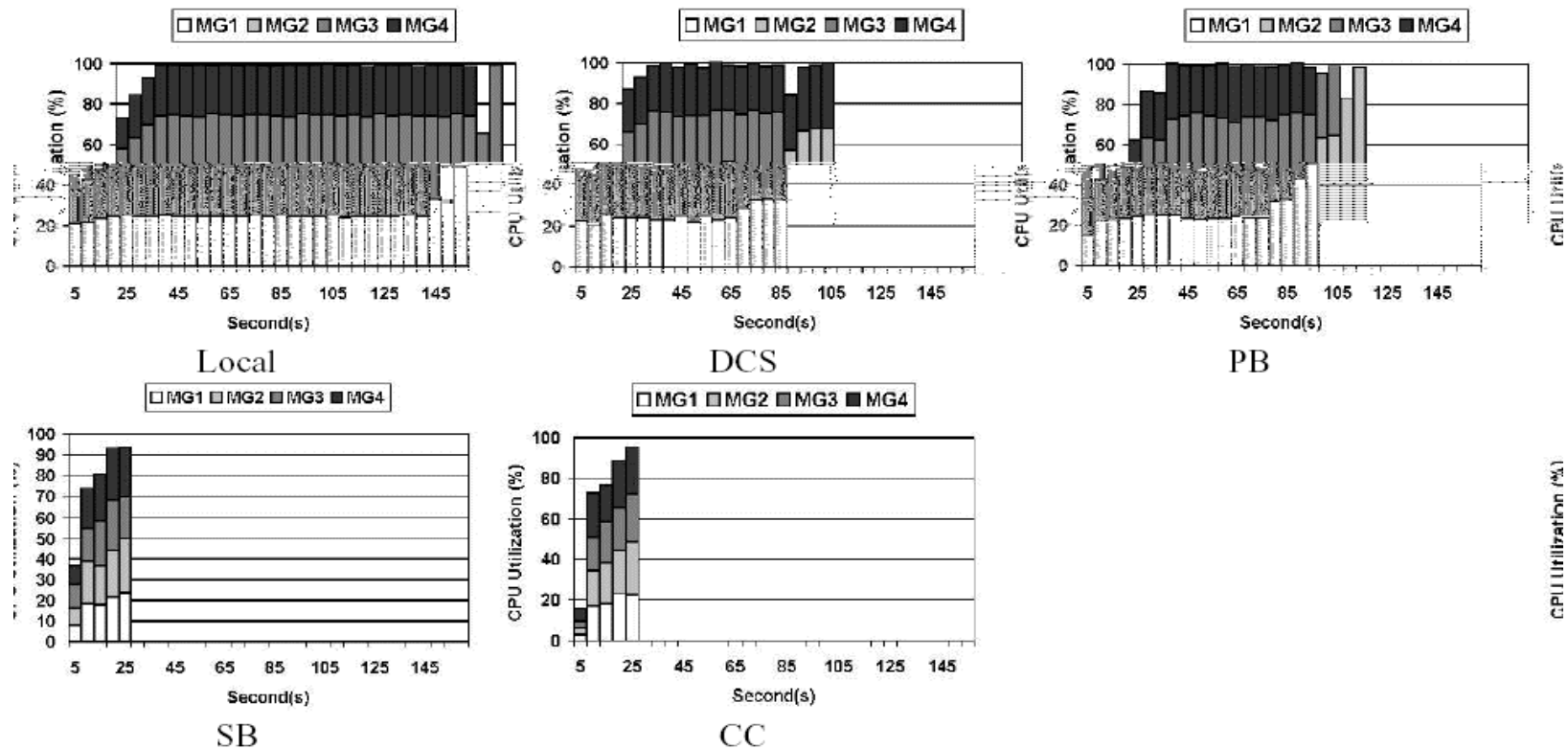
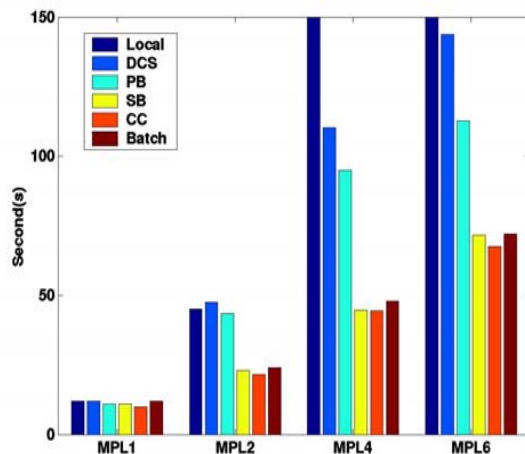


Figure : CPU Utilization results for *wl3* (MPL=4)

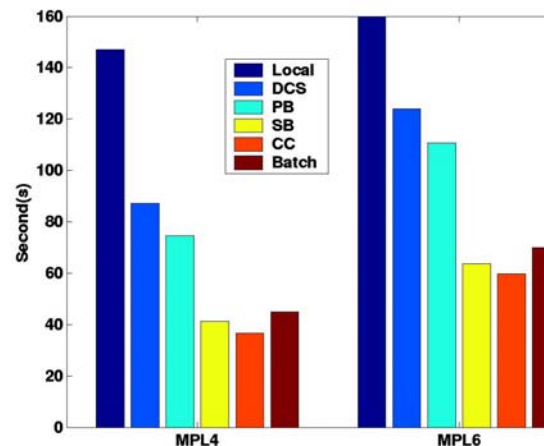
Scalability (vertical) Effect of MPL

Rate of increase higher in Local, DCS, PB than SB, CC.

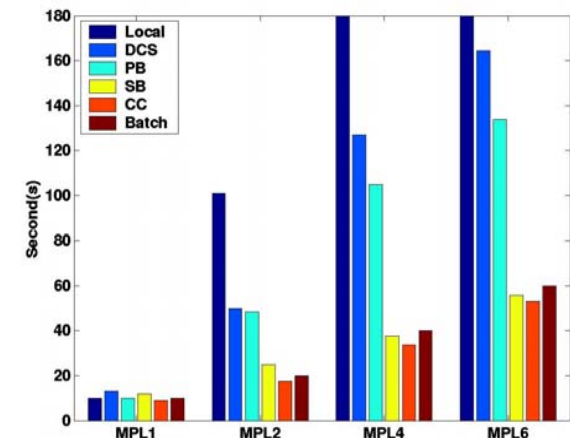
Glimpse comparison to batch scheduling.



Workload – $w/3$



Workload – $w/4$

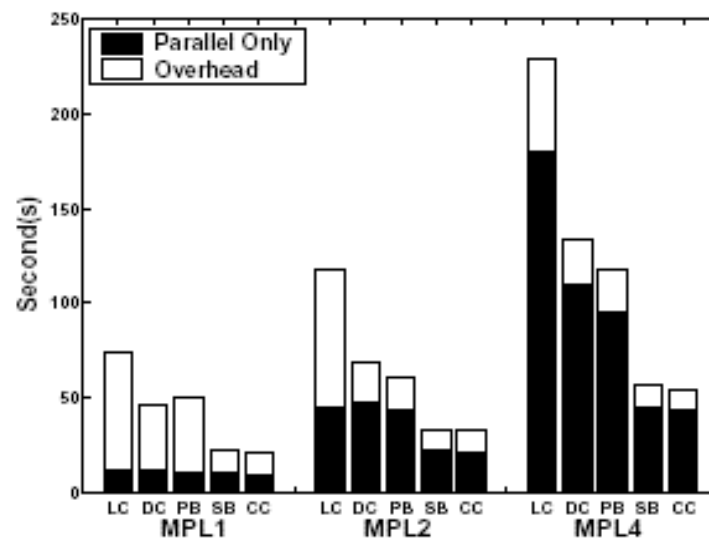


Workload – $w/5$

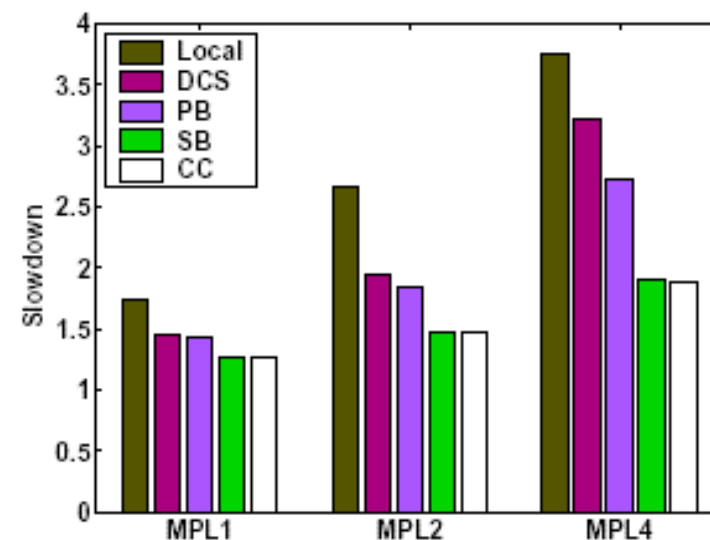
Mixing CPU intensive jobs (W/3)

CC & SB tolerate load better (low *overhead* in (a)).

CC and SB exploit idle cycles well (low *slowdown* in (b))



(a) Effect on parallel job

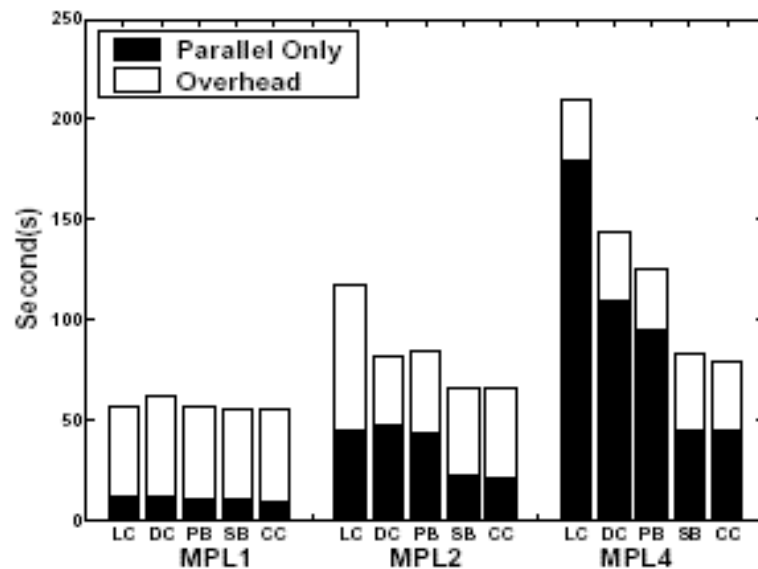


(b) Effect on CPU job

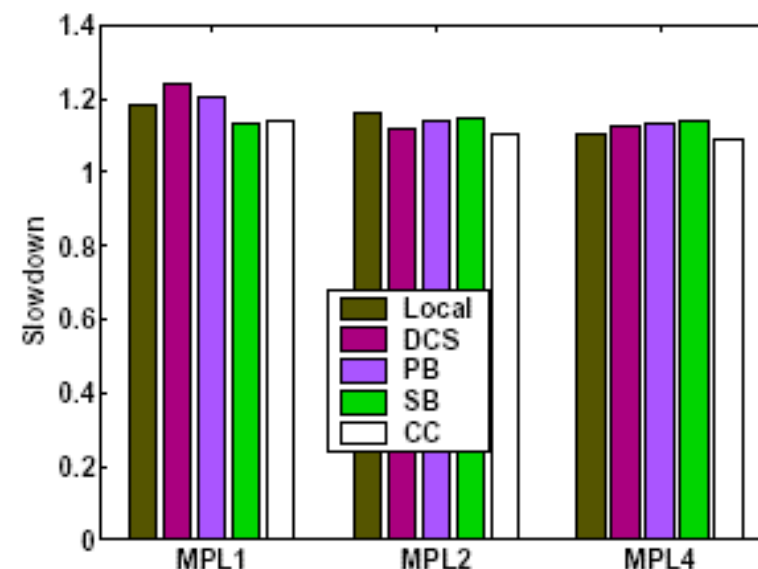
Mixing I/O intensive jobs (W/3)

|| jobs in all schemes get equally affected (similar *overheads*).

Very Insignificant *slowdown* in I/O across all schemes.



(a) Effect on parallel job



(b) Effect on I/O job

Conclusions

Primary Contributions :-

- Modular, flexible framework for deploying coscheduling.
- Fair, high performing, new CC scheme.

Significant findings :-

- Selected schemes better than spinning (Linux).
- CC approach scale well (Vertically) at high MPL of 6.
- CC approach get equal or better than Batch scheduling.
- CC much better than SB, added QoS Potential.

Other Advantages :-

- Can implement all policies with CC approach.
- Can use framework with all ULN libraries.

Future Work

Horizontal scalability (> nodes, GM)

Deployment scenarios :

No pre-emption (all apps fit well in memory).

Homogeneous nodes availability.

All apps of same priority.

Optimizations in CC mechanism.

Allocation problems in coscheduling.

Dynamic communication pattern identification.

Integrated coscheduling as a feature in OS.

True end-to-end QoS with support from scheduler.



Questions ?

Thanks for your Time !!



Difference with ICS ? (Optional slide)

SR registers for ALL incoming messages.

ICS registers for expected messages for which a send has been done earlier.

ICS is more tightly coupled (works on a send-recv pair).

ICS is not too suitable in MPI environment.