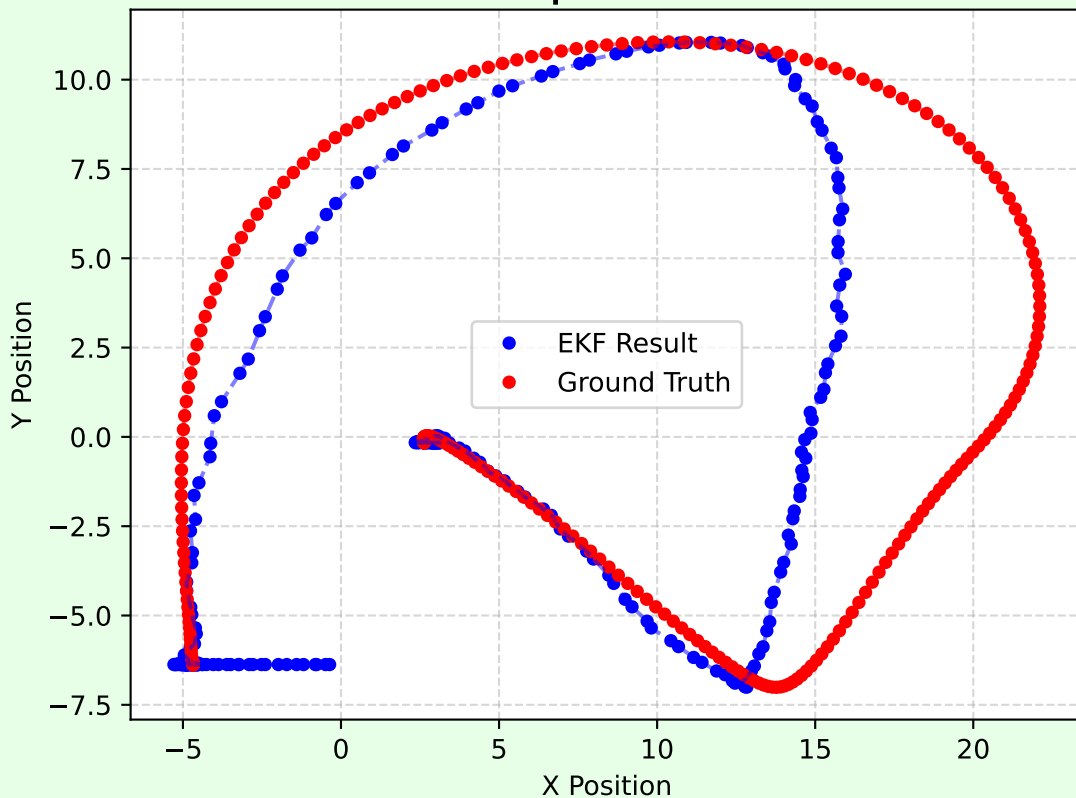
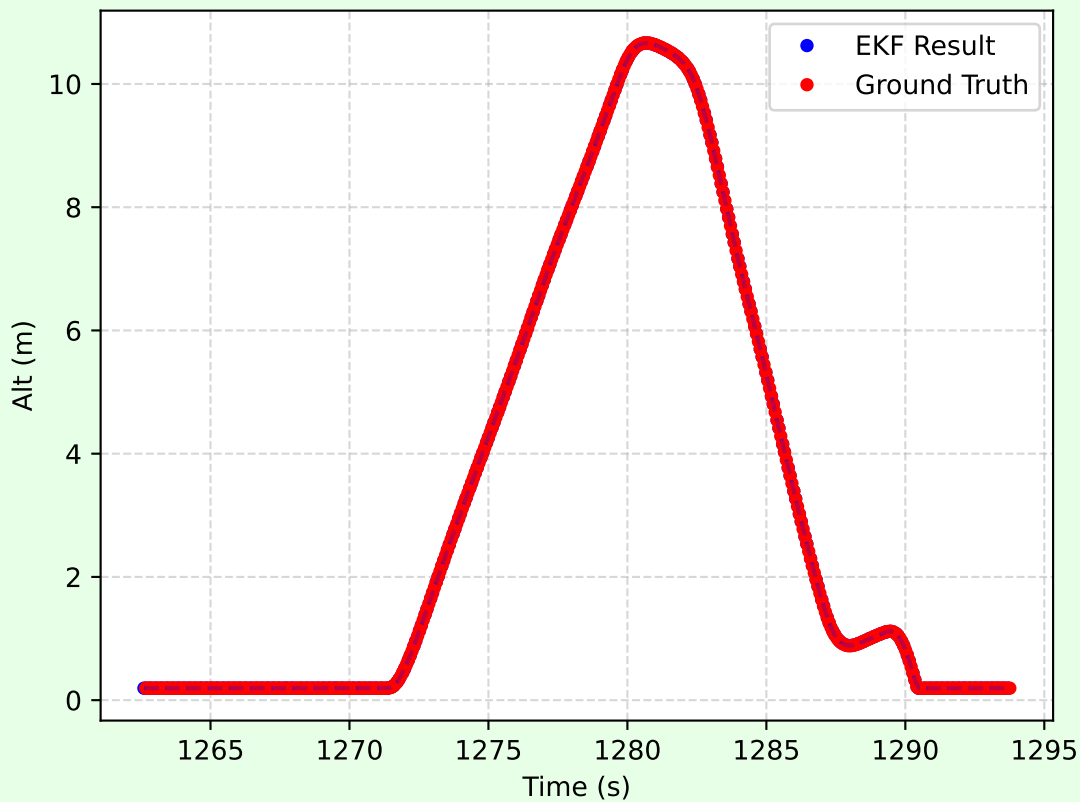


# Map in X-Y

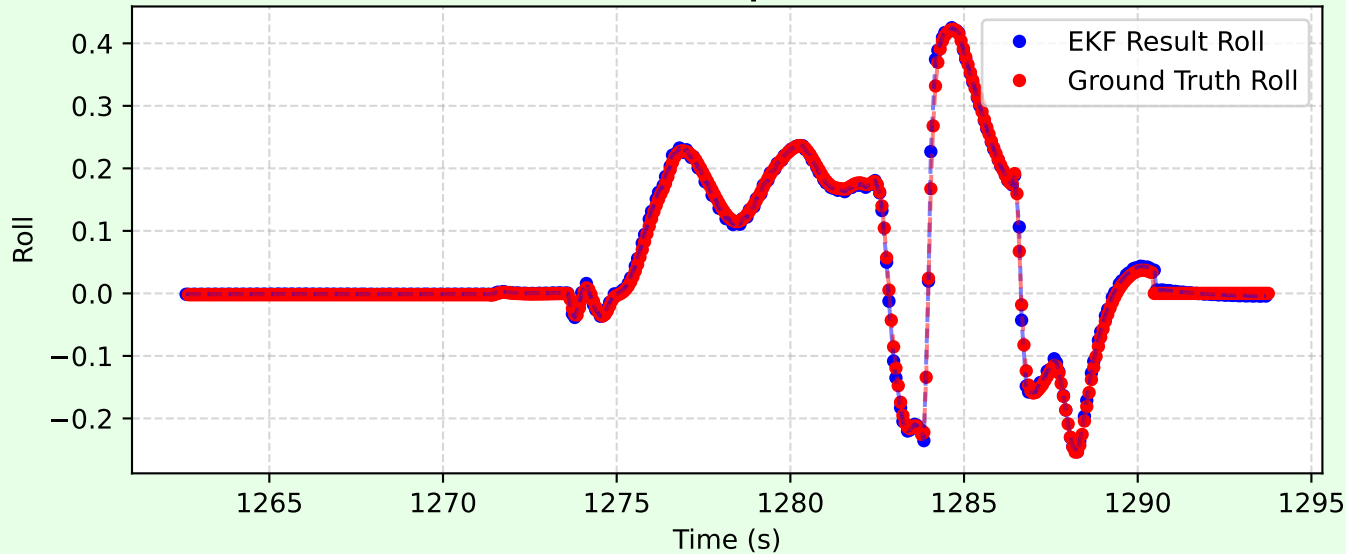


# Pose Z

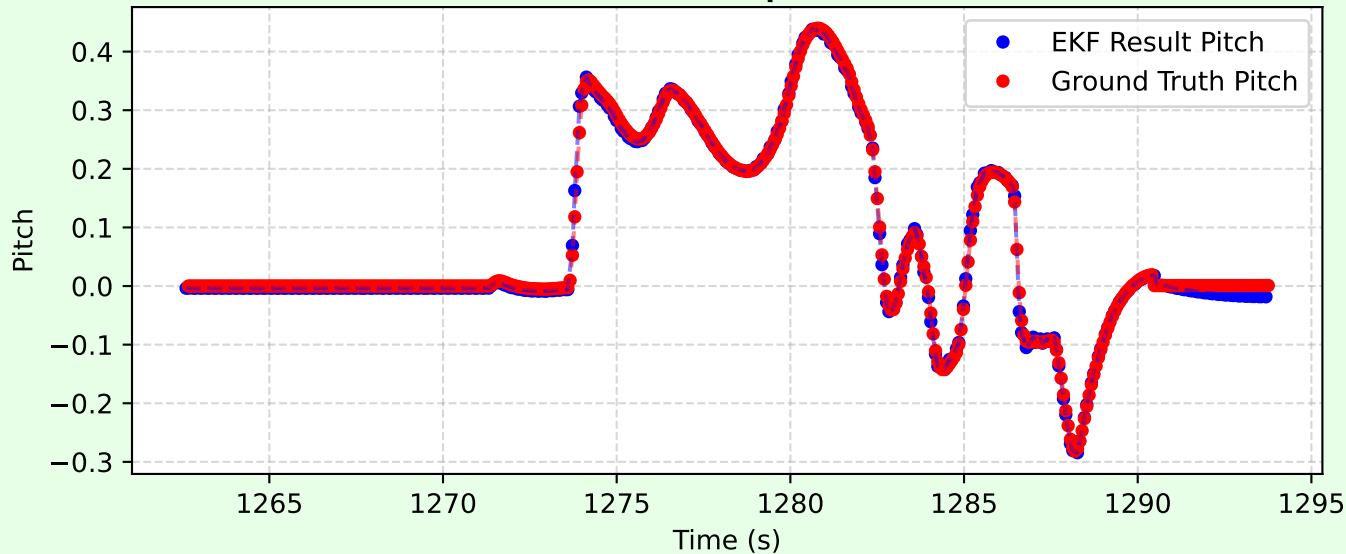


# RPY Orientation

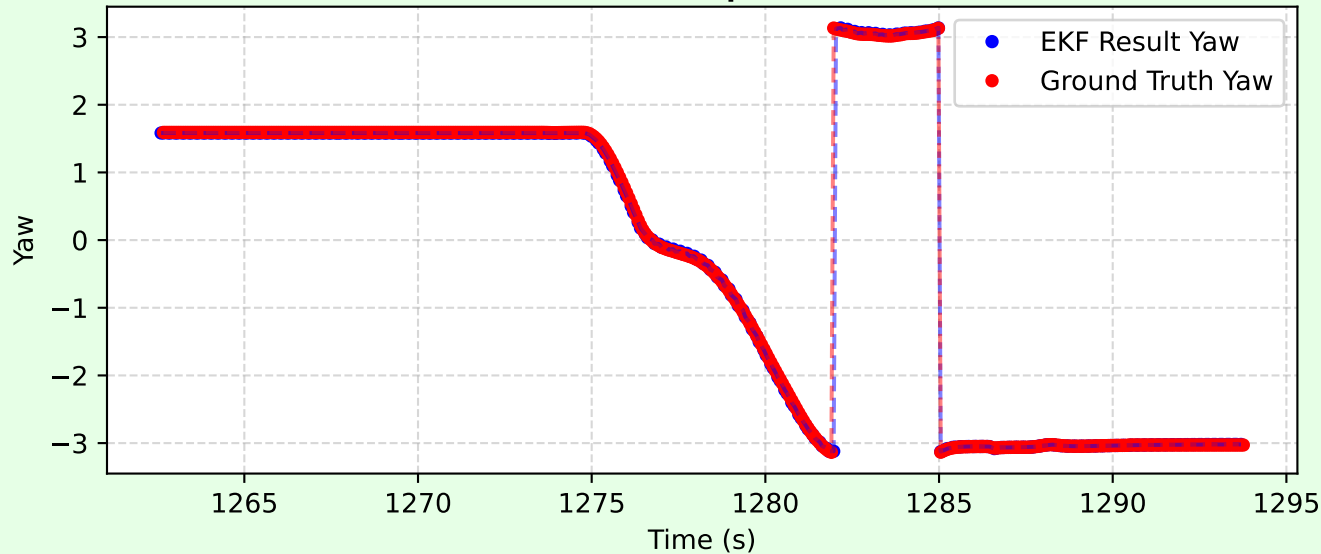
## Roll Comparison



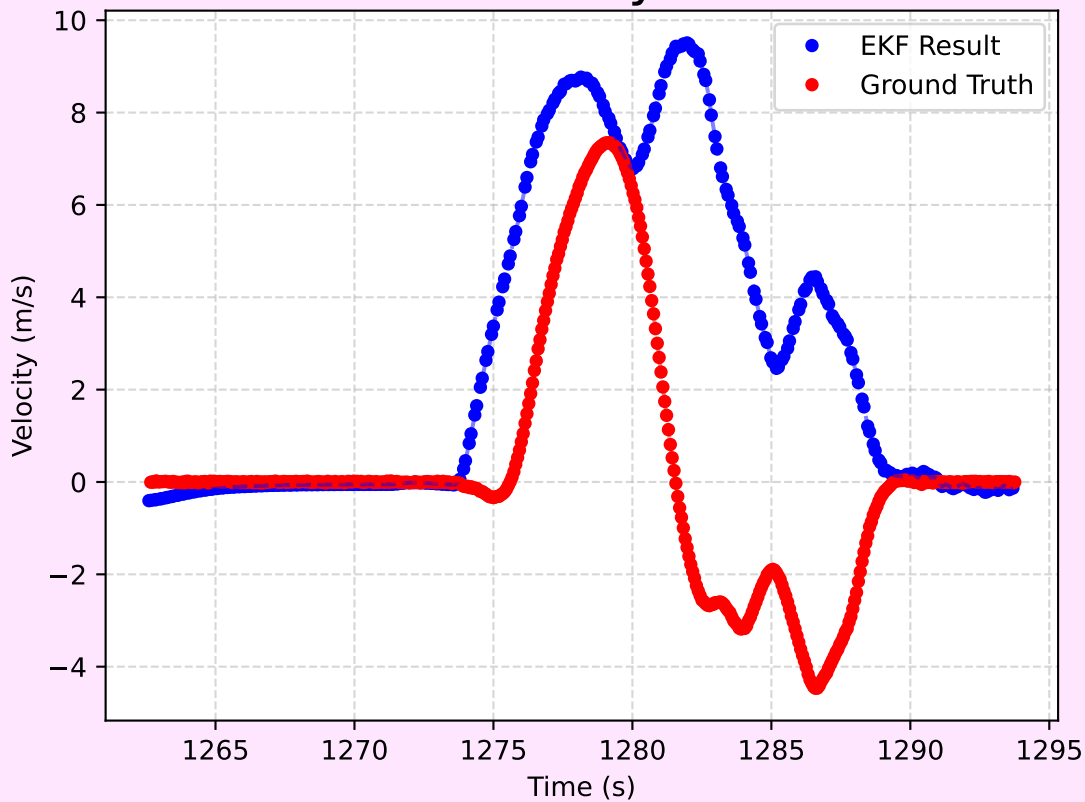
## Pitch Comparison



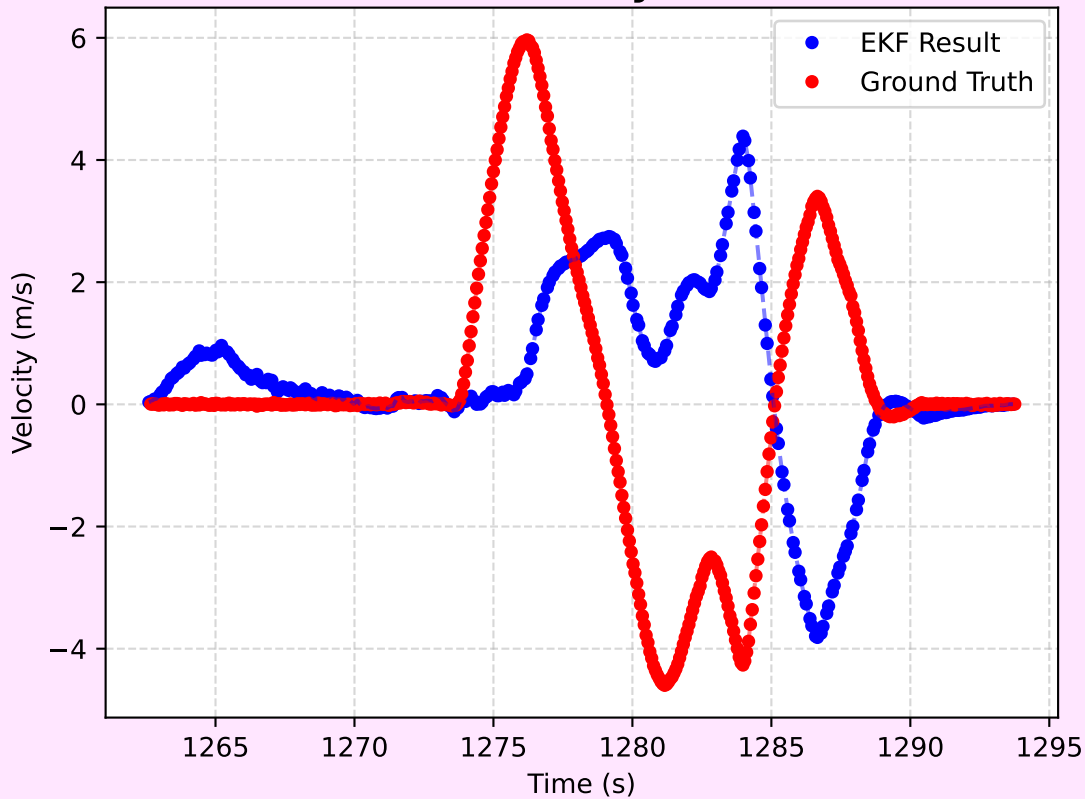
## Yaw Comparison



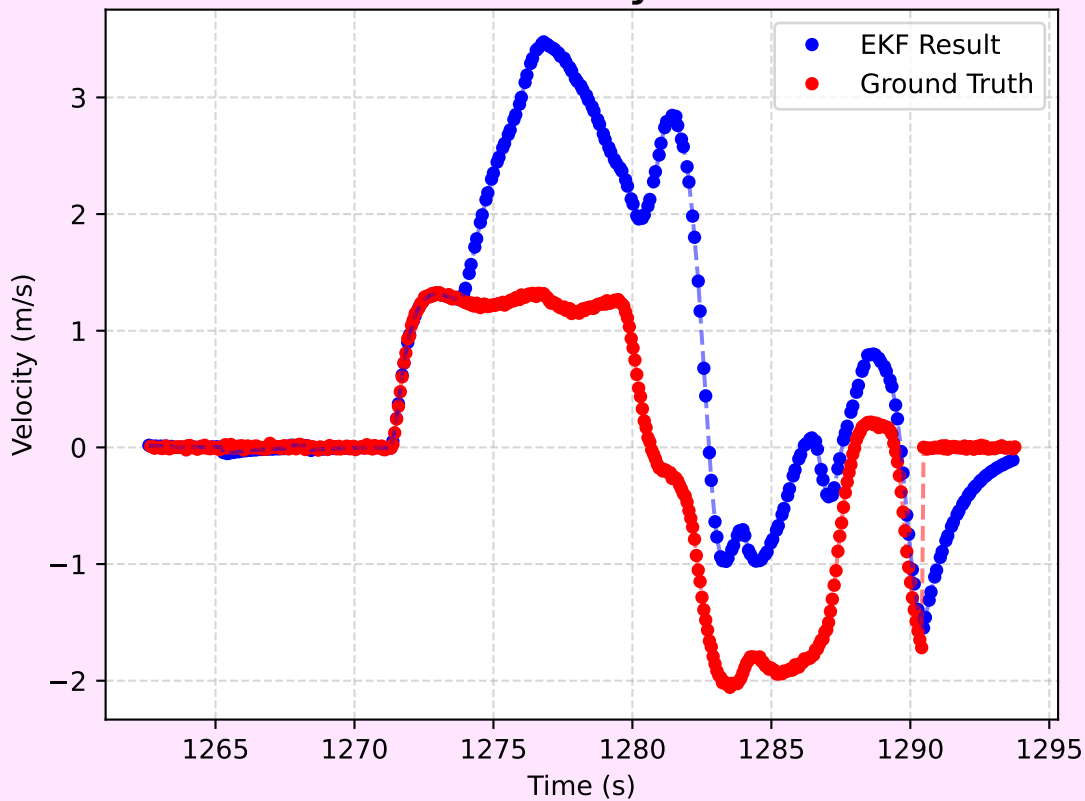
# Velocity X



# Velocity Y

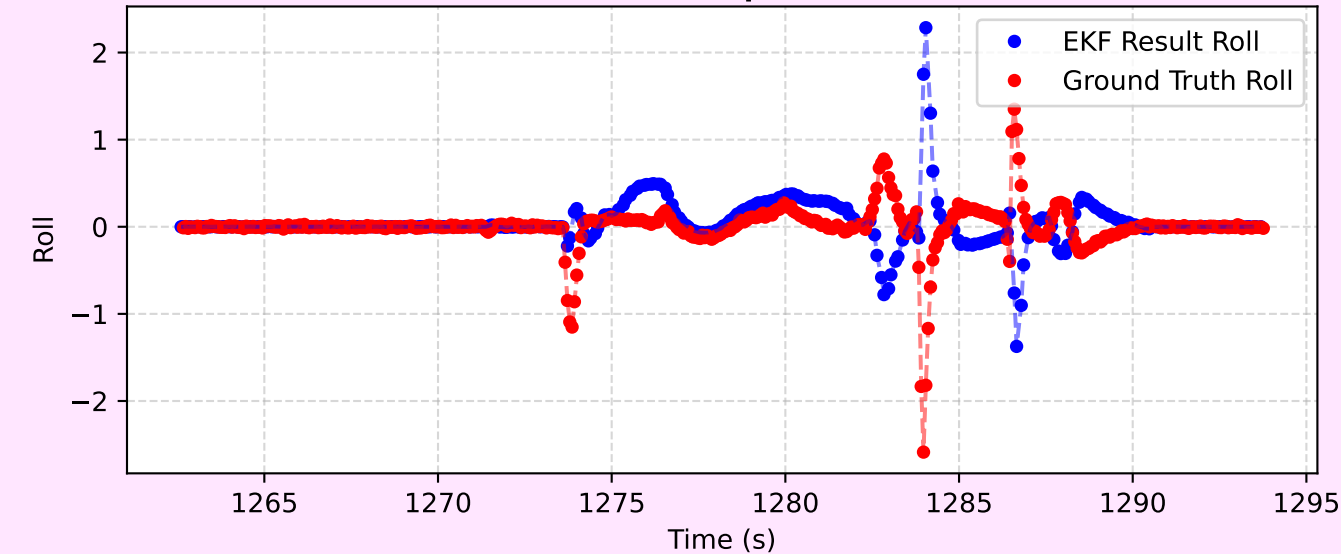


# Velocity Z

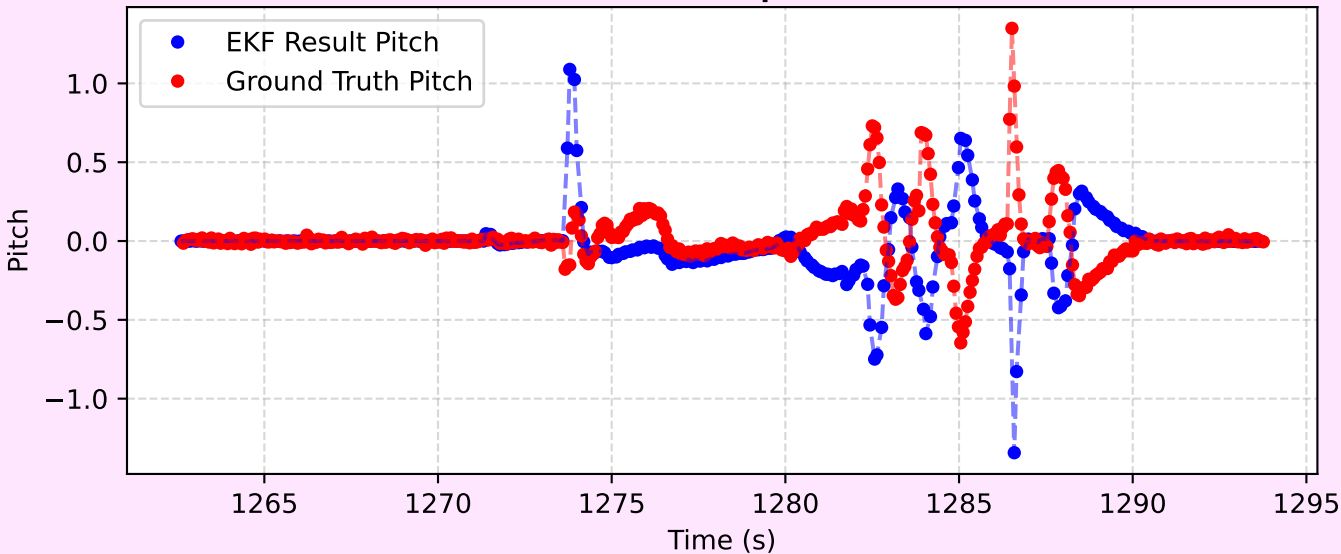


# RPY Velocities

## Roll Comparison



## Pitch Comparison



## Yaw Comparison

