

PDDL exercise

Define il dominio:

```
(define (domain name_domain) //define
  (:requirements :equality) //requirements
  (:predicates (...)(...)(...)) //predicates
  (:action name_action
    :parameters (?.. ?.. ?..)
    :effect (and (...)(...)(...)(not(...)))
    :precondition (and (or(...)(...)(...))) //action
  (:action ... ) //action 2
) //domain
```

Define le instance

```
define (problem name)
  (:domain name_domain)
  (:objects a b c..)
  (:init (action a) (action b)... ) ← STATO INIZIALE
  (:goal (and (action a) (action b)...)) ← STATO FINALE
```

PDDL

template

Domain file:

```
(define (domain <domain name>)  
  <PDDL predicates>  
  <PDDL actions>  
)
```




Diagram illustrating the expansion of the <PDDL actions> placeholder in the domain file template. A blue bracket connects the placeholder to the following action definition template:

```
Action(ActionName,  
  PARAM: var1 ... varN  
  PRECOND: list of preconditions  
  EFFECT: list of effects  
)
```

Problem file:

```
(define (problem <problem name>)  
  (:domain <domain name> )  
  <PDDL objects>  
  <PDDL initial state>  
  <PDDL goal specification>  
)
```

Exercises.

1) The monkey and bananas problem

INITIAL STATE: $At(x)$, $Level(low)$, $BoxAt(c)$,
 $BananasAt(B)$

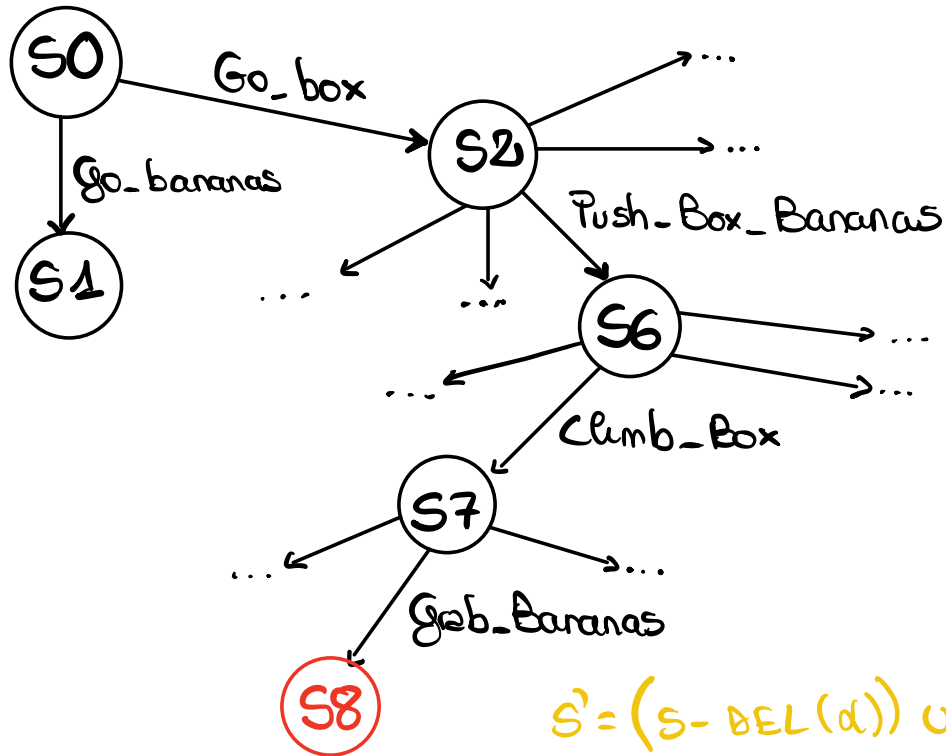
GOAL STATE: Have(bananas)

ACTIONS:

- ① move to box location $\left\{ \begin{array}{l} GoBox(x) \\ \text{PRECONDITION: } At(x), Level(low) \\ \text{EFFECT: } notAt(x), At(c) \end{array} \right.$
- ② climb up on the box $\left\{ \begin{array}{l} ClimbBox(x), \\ \text{PRECONDITION: } At(x), BoxAt(x), Level(low) \\ \text{EFFECT: } Level(high), not Level(low) \end{array} \right.$
- ③ Move monkey and box to bananas location $\left\{ \begin{array}{l} PushBoxBananas(x) \\ \text{PRECONDITION: } At(x), BoxAt(x), Level(low) \\ \text{EFFECT: } BoxAt(B), not BoxAt(x), At(B), not At(x) \end{array} \right.$
- ④ Take the bananas $\left\{ \begin{array}{l} GrabBananas(x) \\ \text{PRECONDITION: } At(x), BananasAt(x), Level(high) \end{array} \right.$

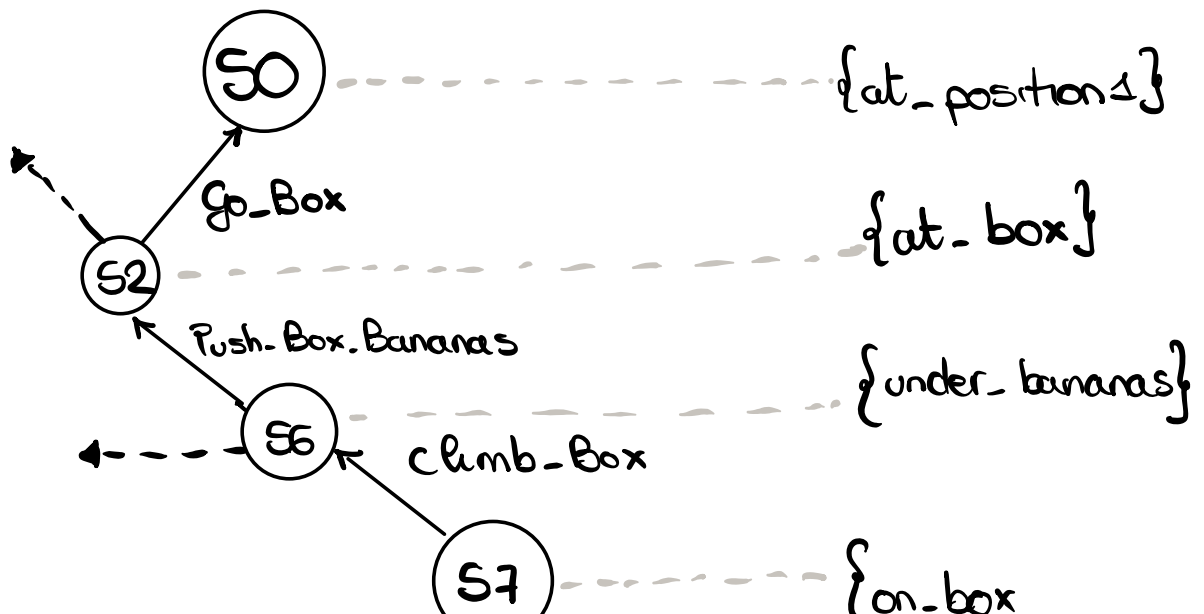
EFFECT: Have(bananas)^c

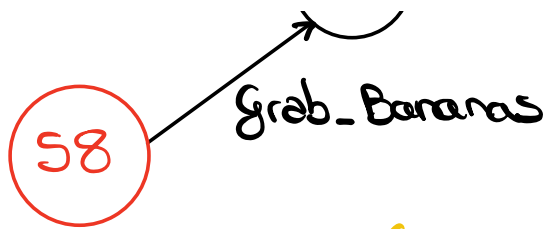
FORWARD search:



$$S' = (S - \text{DEL}(\alpha)) \cup \text{ADD}(\alpha)$$

Backward search:





under-bananas }

$$g' = (g - \text{ADD}(a)) \cup \{\text{PRECOND}(a)\}$$

PDDL CODE:

```

define (domain monkey-bananas)
  (:requirements :strips)
  (:predicates on, box, holding, on-ceiling)

  (:action go
    :parameters (?who ?from ?to)
    :precondition (At(?who ?from))
    :effect (At(?who ?to), not(At(?who ?from)))
  )

  (:action climb
    :parameters (?who ?what ?under-what)
    :precondition (AND (At(?who ?under-what)
                        At(?what ?under-what)))
    :effect (on(?who ?what))
  )

```

(action push

:parameters (?who ?what ?from ?to)

:precondition (At(?who ?from) At(?what ?from))

:effect (AND(At(?who ?to) At(?what ?to)
Not(?what ?from) Not(?who ?from))

)

(:action grab

:parameters (?who ?what ?under-what)

:precondition (AND(At(?who ?under-what)
On(?what ?under-what)))

:effect (Have(bananas))

)

)//domain

define (problem monkey-problem)

(:domain monkey-bananas)

(:objects monkey box bananas c1
c2 c3)

(:init At(monkey c1) At(bananas c2)
At(box c3) not Have(bananas))

(:goal Have(bananas))