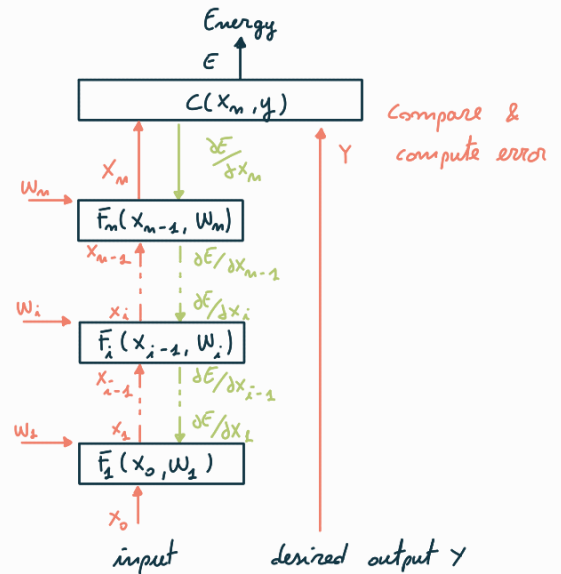


Gradient computation

Information flows forward through the network when computing network output y from input x

The **backpropagation** algorithm is used to propagate gradient computation from the cost function through the whole network



Goal: compute the gradient of the cost function with respect to the parameters:

$$\nabla_{\theta} J(\theta)$$

Backpropagation is not a training algorithm, it is just an algorithm to estimate the gradient. Training will be done by an **optimizer** (e.g. Adam) by means of the **stochastic gradient descent**.

Chain rule

Let $y = g(x)$ and $z = f(g(x)) = f(y)$

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial y} \frac{\partial y}{\partial x}$$

For vector functions $g: \mathbb{R}^m \rightarrow \mathbb{R}^n$ and $f: \mathbb{R}^n \rightarrow \mathbb{R}$ we have:

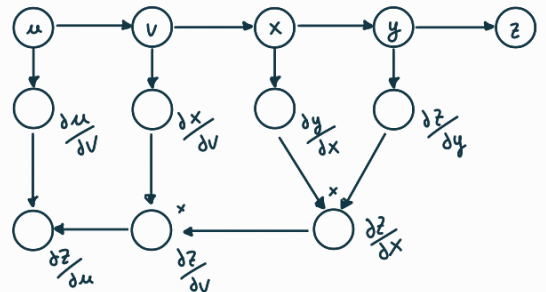
$$\frac{\partial z}{\partial x_i} = \sum_j \frac{\partial z}{\partial y_j} \frac{\partial y_j}{\partial x_i}$$

In vector notation:

$$\nabla_x z = \left(\frac{\partial y}{\partial x} \right)^T \nabla_y z$$

with $\frac{\partial y}{\partial x}$ the $n \times m$ Jacobian matrix of g

Why is it so easy to compute the gradient?



Estimating gradient \longrightarrow **Backpropagation**

Training \longrightarrow training algorithms

- Stochastic Gradient Descent (SGD)
- SGD with momentum
- Algorithms with adaptive learning rates

Backpropagation

Backpropagation consists of two steps : ① forward step and ② backward step

① Forward step

Require: Network depth l

Require: $W^{(i)}, i \in \{1, \dots, l\}$ weight matrices

Require: $b^{(i)}, i \in \{1, \dots, l\}$ bias parameters

Require: x input value

Require: t target value

$$h^{(0)} = x$$

for $k = 1, \dots, l$ **do**

$$\alpha^{(k)} = b^{(k)} + W^{(k)} h^{(k-1)}$$

$$h^{(k)} = f(\alpha^{(k)})$$

end for

$$y = h^{(l)}$$

$$J = L(t, y)$$

The second step computes the derivative of the error with respect to all the parameters of the network, going backwards from the output layer to the input layer

② Backward step

① $g \leftarrow \nabla_y J = \nabla_y L(t, y)$

for $k = l, l-1, \dots, 1$ **do**

Propagate gradients to the pre-nonlinearity activations:

② $g \leftarrow \nabla_{\alpha^{(k)}} J = g \odot f'(\alpha^{(k)})$ { \odot denotes elementwise product }

③ $\nabla_{b^{(k)}} J = g$

④ $\nabla_{W^{(k)}} J = g(h^{(k-1)})^T$

Propagate gradients to the next lower-level hidden layer:

⑤ $g \leftarrow \nabla_{h^{(k-1)}} J = (W^{(k)})^T g$

end for

g is the portion of the gradient that has been computed so far

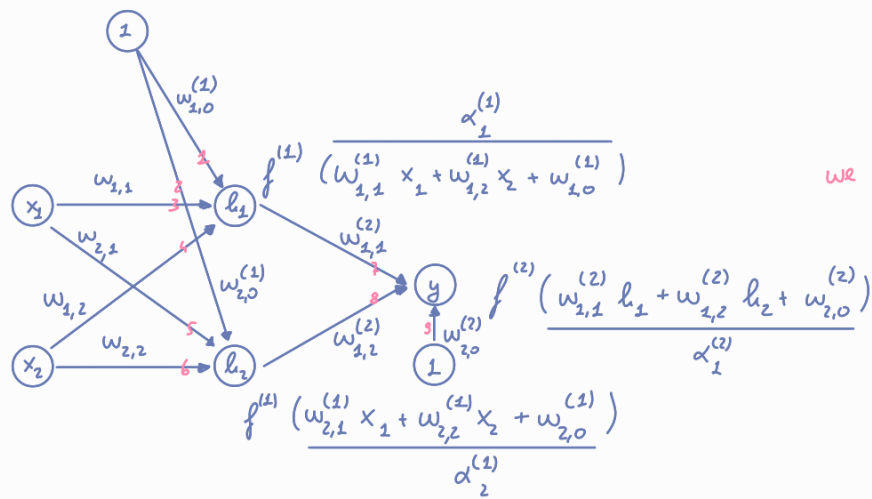
at each layer we need to multiply the contribution of $f(\alpha)$: $f'(\alpha) \cdot \text{derivative}(\alpha)$

$$\alpha_i = w_i^T h_{i-1} + b_i$$

$$\frac{\partial \alpha_i}{\partial w_i} = h_{i-1} \quad \frac{\partial \alpha_i}{\partial b_i} = 1$$

This is not the training, it is just a part of it

Example



we want to compute 9 derivatives

$$\begin{aligned} f^{(1)} &= \text{ReLU} \\ f^{(2)} &= \text{Z} \\ \text{Loss} &= \text{MSE} \end{aligned}$$

Forward step $\left\{ \begin{array}{l} \text{Given } x_1, x_2, w_{i,j}^{(k)}, t \\ \text{Compute } \alpha_1^{(1)}, \alpha_2^{(1)}, \alpha_1^{(2)}, h_1^{(1)}, h_2^{(1)}, h_1^{(2)}, y, J = L(t, y) \end{array} \right.$

$$\begin{aligned} \text{Layer 1} \quad \left\{ \begin{array}{l} \alpha_1^{(1)} = w_{1,0}^{(1)} + w_{1,1}^{(1)} x_1 + w_{1,2}^{(1)} x_2 \\ \alpha_2^{(1)} = w_{2,0}^{(1)} + w_{2,1}^{(1)} x_1 + w_{2,2}^{(1)} x_2 \\ h_1^{(1)} = f(\alpha_1^{(1)}) \\ h_2^{(1)} = f(\alpha_2^{(1)}) \end{array} \right. \quad \left\{ \begin{array}{l} \alpha_2^{(1)} = w_{i,0}^{(1)} + w_{i,1}^{(1)} x_1 + w_{i,2}^{(1)} x_2 \\ h_i^{(1)} = f^{(1)}(\alpha_i^{(1)}) \end{array} \right. \\ \text{Layer 2} \quad \left\{ \begin{array}{l} \alpha_1^{(2)} = w_{1,0}^{(2)} + w_{1,1}^{(2)} h_1^{(1)} + w_{1,2}^{(2)} h_2^{(1)} \\ h_1^{(2)} = f(\alpha_1^{(2)}) \\ y = h_1^{(2)} \end{array} \right. \end{aligned}$$

Let's use the compact notation

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad W^{(1)} = \begin{bmatrix} w_{1,1}^{(1)} & w_{1,2}^{(1)} \\ w_{2,1}^{(1)} & w_{2,2}^{(1)} \end{bmatrix} \quad b^{(1)} = \begin{bmatrix} w_{1,0}^{(1)} \\ w_{2,0}^{(1)} \end{bmatrix} \quad W^{(2)} = \begin{bmatrix} w_{1,1}^{(2)} & w_{1,2}^{(2)} \end{bmatrix} \quad b^{(2)} = \begin{bmatrix} w_{1,0}^{(2)} \end{bmatrix}$$

$$h^{(0)} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x$$

$$\begin{aligned} \text{Layer 1} \quad \alpha^{(1)} = \begin{bmatrix} \alpha_1^{(1)} \\ \alpha_2^{(1)} \end{bmatrix} &= W^{(1)} h^{(0)} + b^{(1)} & h^{(1)} = \begin{bmatrix} h_1^{(1)} \\ h_2^{(1)} \end{bmatrix} &= f^{(1)}(\alpha^{(1)}) = \begin{bmatrix} f^{(1)}(\alpha_1^{(1)}) \\ f^{(1)}(\alpha_2^{(1)}) \end{bmatrix} = \begin{bmatrix} \text{ReLU}(\alpha_1^{(1)}) \\ \text{ReLU}(\alpha_2^{(1)}) \end{bmatrix} \\ \text{Layer 2} \quad \alpha^{(2)} = \begin{bmatrix} \alpha_1^{(2)} \end{bmatrix} &= W^{(2)} h^{(1)} + b^{(2)} & h^{(2)} = \begin{bmatrix} h_1^{(2)} \end{bmatrix} &= f^{(2)}(\alpha^{(2)}) = \begin{bmatrix} \alpha_1^{(2)} \end{bmatrix} \end{aligned} \quad \left\{ \begin{array}{l} \alpha^i = W^i h^{i-1} + b^i \\ h^i = f^i(\alpha^i) \end{array} \right.$$

Compute loss function (MSE) $L(t, y) = \frac{1}{2} (t - y)^2$

Backward step

$$\textcircled{1} \quad g \leftarrow \nabla_{l^{(2)}} J = \nabla_y J = \nabla_y \frac{1}{2} (t-y)^2 = \frac{1}{2} 2 (t-y)^{-1} (-1) = -(t-y) = y-t$$

$$\textcircled{2} \quad g \leftarrow \nabla_{\alpha^{(2)}} J = g \circ f^{(2)'}(\alpha^{(2)}) = g \circ \frac{\partial \alpha^{(2)} - t}{\partial \alpha^{(2)}} = g \circ 1 = g \quad \text{linear activation function}$$

we computed the gradient of J with respect to $\alpha^{(2)}$; now we want to know the influence of the weights and biases on $\partial J / \partial \alpha^{(2)}$; this will be useful later (SGD) to update them in a training algorithm.

layer 2

$$\textcircled{3} \quad \nabla_b^{(2)} J \leftarrow \left[\frac{\partial J}{\partial w_{2,0}^{(2)}} \right] = g$$

$$\textcircled{4} \quad \nabla_{w^{(2)}} J \leftarrow \begin{bmatrix} \frac{\partial J}{\partial w_{2,1}^{(2)}} & \frac{\partial J}{\partial w_{2,2}^{(2)}} \end{bmatrix} = g \cdot (l^{(1)})^T$$

$w^{(2)} = \begin{bmatrix} w_{2,1}^{(2)} & w_{2,2}^{(2)} \end{bmatrix}$

Propagate gradients to the next lower-level hidden layer

$$\textcircled{5} \quad g \leftarrow \nabla_{l^{(k-1)}} J = \nabla_{l^{(1)}} J = (W^{(k)})^T g = (W^{(2)})^T g = \begin{bmatrix} w_{1,1}^{(2)} & w_{1,2}^{(2)} \end{bmatrix}^T g$$

layer 1

$$\textcircled{2} \quad g \leftarrow \nabla_{\alpha^{(1)}} J = g \circ f^{(1)'}(\alpha^{(1)}) = g \circ \begin{bmatrix} \partial \text{ReLU}(\alpha_1^{(1)}) / \partial \alpha_1^{(1)} \\ \partial \text{ReLU}(\alpha_2^{(1)}) / \partial \alpha_2^{(1)} \end{bmatrix} = g \circ \begin{bmatrix} \text{step}(\alpha_1^{(1)}) \\ \text{step}(\alpha_2^{(1)}) \end{bmatrix}$$

$$\textcircled{3} \quad \nabla_b^{(1)} J \leftarrow \begin{bmatrix} \frac{\partial J}{\partial w_{1,0}^{(1)}} \\ \frac{\partial J}{\partial w_{2,0}^{(1)}} \end{bmatrix} = g$$

$$\textcircled{4} \quad \nabla_{w^{(1)}} J \leftarrow \begin{bmatrix} \frac{\partial J}{\partial w_{1,1}^{(1)}} & \frac{\partial J}{\partial w_{1,2}^{(1)}} \\ \frac{\partial J}{\partial w_{2,1}^{(1)}} & \frac{\partial J}{\partial w_{2,2}^{(1)}} \end{bmatrix} = g \cdot (l^{(1)})^T$$