/* 1a. Write down the GLM command that positions a camera at (0,0,10) looking straight down the z-axis. (5 pts.) */

glm::mat4 view = glm::translate(mat4(), vec3(0.0,0.0,10.0))

/* 1b. Write down the GLM command to create a projection matrix that transforms a view frustum into clip space. Specifically, you want your projection to mimic naturalistic perspective, with a vertical field of view of 60 degrees and a depth of field that captures everything between 1 unit and 100 units away. Moreover you want your view to look good on a window that is 800x600 pixels. (5 pts.) */

glm::mat4 projection = glm::perspective(60.0f, 1.0f, 0.1f, 100.0f)

/* 1c. Using that projection matrix and view matrix, describe each step of how a point would be placed at (2.5,2.5,-2) in 3D space and then transformed into a 2D pixel on your 800x600 window. That is, list the positions of the vertex at each stage of the rendering pipeline: In object coordinates, in model coordinates, in eye coordinates, in clip coordinates/normalized device coordinates, and finally in window coordinates. (30 pts.) */

Object Coordinates: fvec3(2.500000, 2.500000, -2.000000)

```
mat4x4((1.000000, 0.000000, 0.000000, 0.000000),
Model Coordinates:
```

(0.000000, 1.000000, 0.000000, 0.000000),(0.000000, 0.000000, 1.000000, 0.000000),

(2.500000, 2.500000, -2.000000, 1.000000))

Eye Coordinates: mat4x4((1.000000, 0.000000, 0.000000, 0.000000),

(0.000000, 1.000000, 0.000000, 0.000000),

(0.000000, 0.000000, 1.000000, 0.000000),(2.500000, 2.500000, 8.000000, 1.000000))

Clip Coordinates: mat4x4((1.732051, 0.000000, 0.000000, 0.000000),

(0.000000, 1.732051, 0.000000, 0.000000),(0.000000, 0.000000, -1.002002, -1.000000),(4.330127, 4.330127, -8.216216, -8.000000))

Normalized Device Coordinates: fvec3(-0.541266, -0.541266, 1.027027)

Window Coordinates: fvec3(0.458734, 0.458734, 2.027027)

/* 2. A cube is positioned at (2,2,-2) in 3D space. List the GLM commands to move the cube to (4,5,0), and that rotates the cube by 45 degrees around the x-axis and 45 degrees around the zaxis. Write down the 4x4 matrix for each of these operations individually, and then the 4x4 transformation matrix that concatenates all of these operations. (30 pts.) */

Cube model: mat4x4((1.000000, 0.000000, 0.000000, 0.000000), (0.000000, 1.000000, 0.000000, 0.000000),

(0.000000, 0.000000, 1.000000, 0.000000),(4.000000, 5.000000, 0.000000, 1.000000))

mat4x4((1.000000, 0.000000, 0.000000, 0.000000), Rotate 45 degrees around the x-axis:

(0.000000, 0.707107, 0.707107, 0.000000),(0.000000, -0.707107, 0.707107, 0.000000),

(0.000000, 0.000000, 0.000000, 1.000000))

mat4x4((0.707107, 0.707107, 0.000000, 0.000000), Rotate 45 degrees around the z-axis:

(-0.707107, 0.707107, 0.000000, 0.000000),(0.000000, 0.000000, 1.000000, 0.000000),

(0.000000, 0.000000, 0.000000, 1.000000))

Cube model concatenation after rotations and translation:

mat4x4((0.707107, 0.707107, 0.000000, 0.000000), (-0.500000, 0.500000, 0.707107, 0.000000), (0.500000, -0.500000, 0.707107, 0.000000), (0.328427, 5.328427, 3.535534, 1.000000))