

Towards Artifact-Free Image Defogging

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Defogging



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Defogging (or dehazing) is the task of removing the fog from an input image, aimed at reconstructing the same scene as if it were taken in good weather conditions.

- ▶ Easier with stereo images or a 3D reconstruction of the scene (e.g., LIDAR).
- ▶ More difficult with single images, especially in presence of severe fog.

Useful in:

- ▶ Autonomous driving.
- ▶ Security.
- ▶ Improving photographs aesthetics.
- ▶ ...



Current approaches and problems



Classical methods [1]–[3] are often surpassed by DNN-based ones [4]–[8], using CNN or GANs. However, they often require paired data.

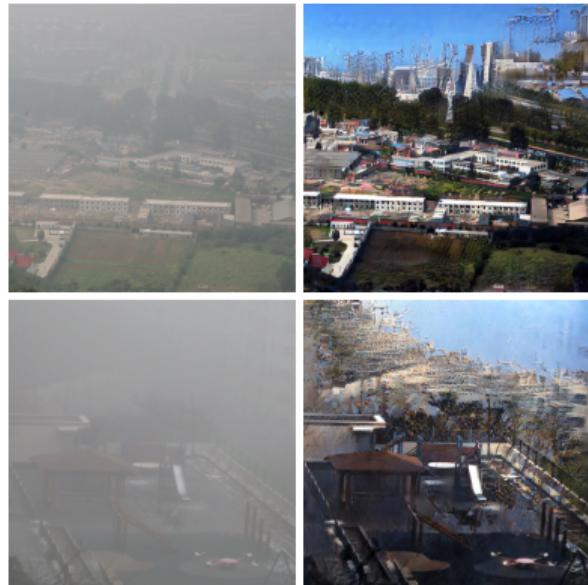
Problems

- ▶ Impossible to obtain the same identical scene with and without fog.
- ▶ Often, fog is inserted artificially in the training images.
 - Not precise since the exact depth map is needed.
 - Synthetic fog \neq real fog.

Totally unpaired approaches [9] show promising results in real fog conditions.

Problems

- ▶ Models often insert unwanted artifacts in the defogged images.
 - Due to the unrestricted nature of the unpaired training.



CurL-Defog (Curriculum Learning Defog)



- ▶ **Goal:** use real foggy images but limit as much as possible the insertion of artifacts.
- ▶ We use a curriculum learning [10] strategy.
 - First, model is trained with paired data → artifact insertion highly penalized.
 - Then, real images are used → high quality on real fog.
- ▶ Gradual transition between paired and unpaired data.
- ▶ Model can be seen as:
 - Paired training → two different pix2pix models [11].
 - Unpaired training → unique cycleGAN model [12].



CurL-Defog (Curriculum Learning Defog)



$$\mathcal{L}_{adv}^{defog} = (D_{clear}(c))^2 + (D_{clear}(G_{defog}(f)) - 1)^2$$

$$\mathcal{L}_{adv}^{fog} = (D_{fog}(f))^2 + (D_{fog}(G_{fog}(c)) - 1)^2$$

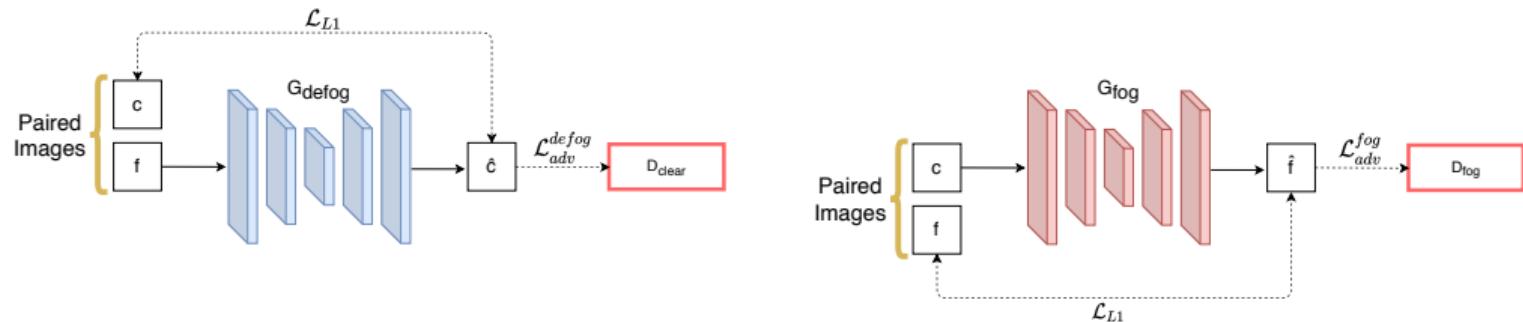
CurL-Defog (Curriculum Learning Defog)



$$\mathcal{L}_{adv}^{defog} = (D_{clear}(c))^2 + (D_{clear}(G_{defog}(f)) - 1)^2 \quad \mathcal{L}_{adv}^{fog} = (D_{fog}(f))^2 + (D_{fog}(G_{fog}(c)) - 1)^2$$

$$\mathcal{L}_{L1} = \|G_{defog}(f) - c\|_1 + \|G_{fog}(c) - f\|_1$$

CurL-Defog (Curriculum Learning Defog)

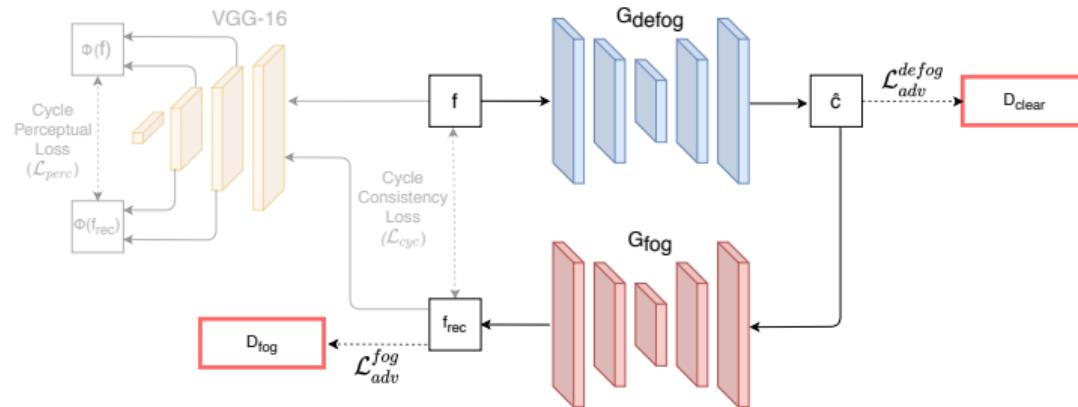


$$\mathcal{L}_{adv}^{defog} = (D_{clear}(c))^2 + (D_{clear}(G_{defog}(f)) - 1)^2 \quad \mathcal{L}_{adv}^{fog} = (D_{fog}(f))^2 + (D_{fog}(G_{fog}(c)) - 1)^2$$

$$\mathcal{L}_{L1} = \|G_{defog}(f) - c\|_1 + \|G_{fog}(c) - f\|_1$$

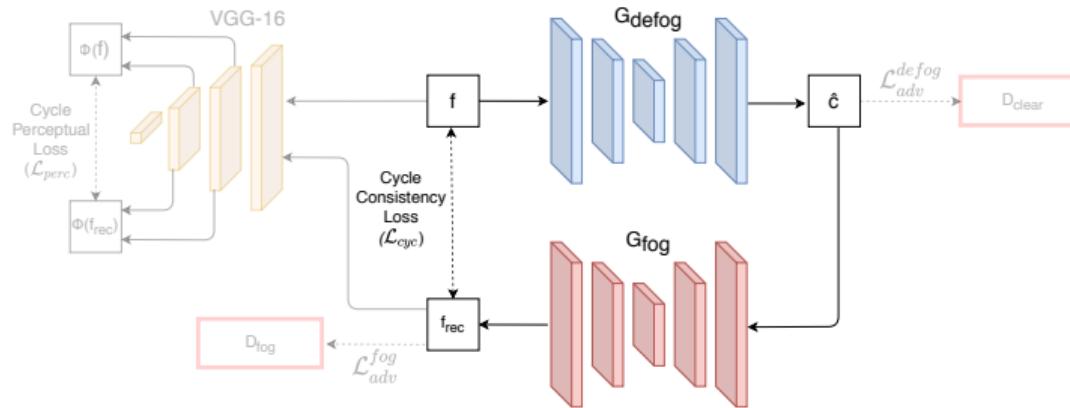
$$\mathcal{L}_{pair} = \mathcal{L}_{adv}^{defog} + \mathcal{L}_{adv}^{fog} + \lambda_{L1} \mathcal{L}_{L1}$$

CurL-Defog (Curriculum Learning Defog)



$$\mathcal{L}_{adv}^{defog} = (D_{clear}(\hat{c}))^2 + (D_{clear}(G_{defog}(f)) - 1)^2 \quad \mathcal{L}_{adv}^{fog} = (D_{fog}(f))^2 + (D_{fog}(G_{fog}(\hat{c})) - 1)^2$$

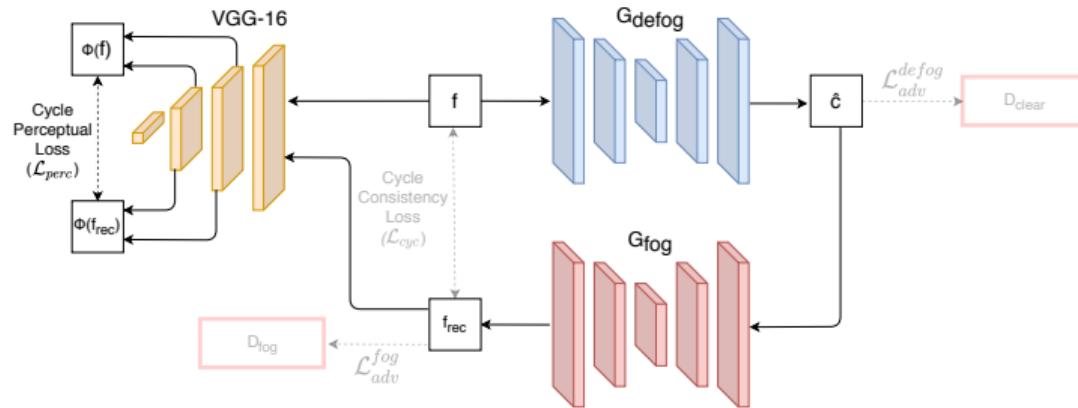
CurL-Defog (Curriculum Learning Defog)



$$\mathcal{L}_{adv}^{defog} = (D_{clear}(\hat{c}))^2 + (D_{clear}(G_{defog}(f)) - 1)^2 \quad \mathcal{L}_{adv}^{fog} = (D_{fog}(f))^2 + (D_{fog}(G_{fog}(f)) - 1)^2$$

$$\mathcal{L}_{cyc} = \|G_{fog}(G_{defog}(f)) - f\|_1 + \|G_{defog}(G_{fog}(f)) - f\|_1$$

CurL-Defog (Curriculum Learning Defog)

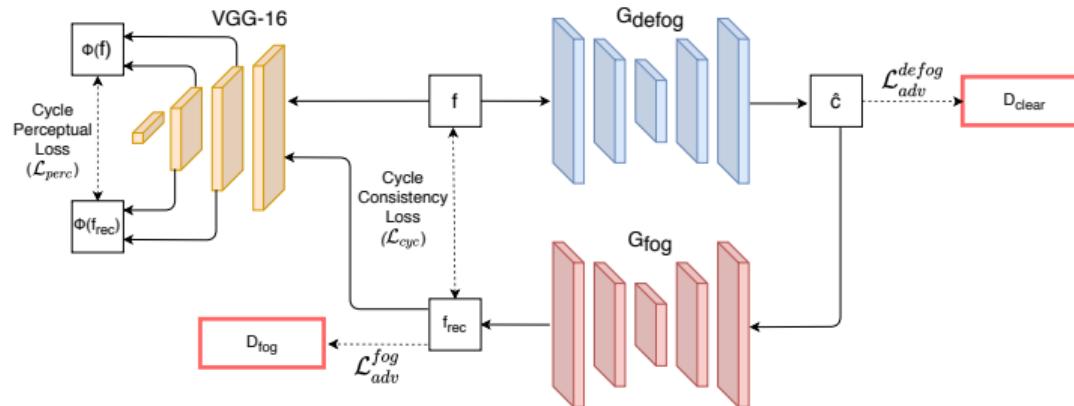


$$\mathcal{L}_{adv}^{defog} = (D_{clear}(c))^2 + (D_{clear}(G_{defog}(f)) - 1)^2 \quad \mathcal{L}_{adv}^{fog} = (D_{fog}(f))^2 + (D_{fog}(G_{fog}(c)) - 1)^2$$

$$\mathcal{L}_{cyc} = \|G_{fog}(G_{defog}(f)) - f\|_1 + \|G_{defog}(G_{fog}(c)) - c\|_1$$

$$\mathcal{L}_{perc} = \|\phi(f) - \phi(G_{fog}(G_{defog}(f)))\|_2^2 + \|\phi(c) - \phi(G_{defog}(G_{fog}(c)))\|_2^2$$

CurL-Defog (Curriculum Learning Defog)



$$\mathcal{L}_{adv}^{defog} = (D_{clear}(c))^2 + (D_{clear}(G_{defog}(f)) - 1)^2 \quad \mathcal{L}_{adv}^{fog} = (D_{fog}(f))^2 + (D_{fog}(G_{fog}(c)) - 1)^2$$

$$\mathcal{L}_{cyc} = \|G_{fog}(G_{defog}(f)) - f\|_1 + \|G_{defog}(G_{fog}(c)) - c\|_1$$

$$\mathcal{L}_{perc} = \|\phi(f) - \phi(G_{fog}(G_{defog}(f)))\|_2^2 + \|\phi(c) - \phi(G_{defog}(G_{fog}(c)))\|_2^2$$

$$\mathcal{L}_{unpair} = \mathcal{L}_{adv}^{defog} + \mathcal{L}_{adv}^{fog} + \lambda_{cyc} \mathcal{L}_{cyc} + \lambda_{perc} \mathcal{L}_{perc} + \lambda_{idt} \mathcal{L}_{idt}$$



- ▶ No defogging metrics takes into account the presence of artifacts.
- ▶ Some metrics may be deceived by the presence of artifacts.
 - E.g. the metrics that counts the number of visible edges [13].
- ▶ How to detect the insertion of artifacts without the ground truth real images?
 - Idea: no edges in the foggy image → no edges in the defogged image.
 - Find the regions in both images that contains edges and compare them.
 - Regions with edges in the defogged image and not in the foggy one → artifacts.

Algorithm 1 HArD pseudocode

Require: f = original foggy image

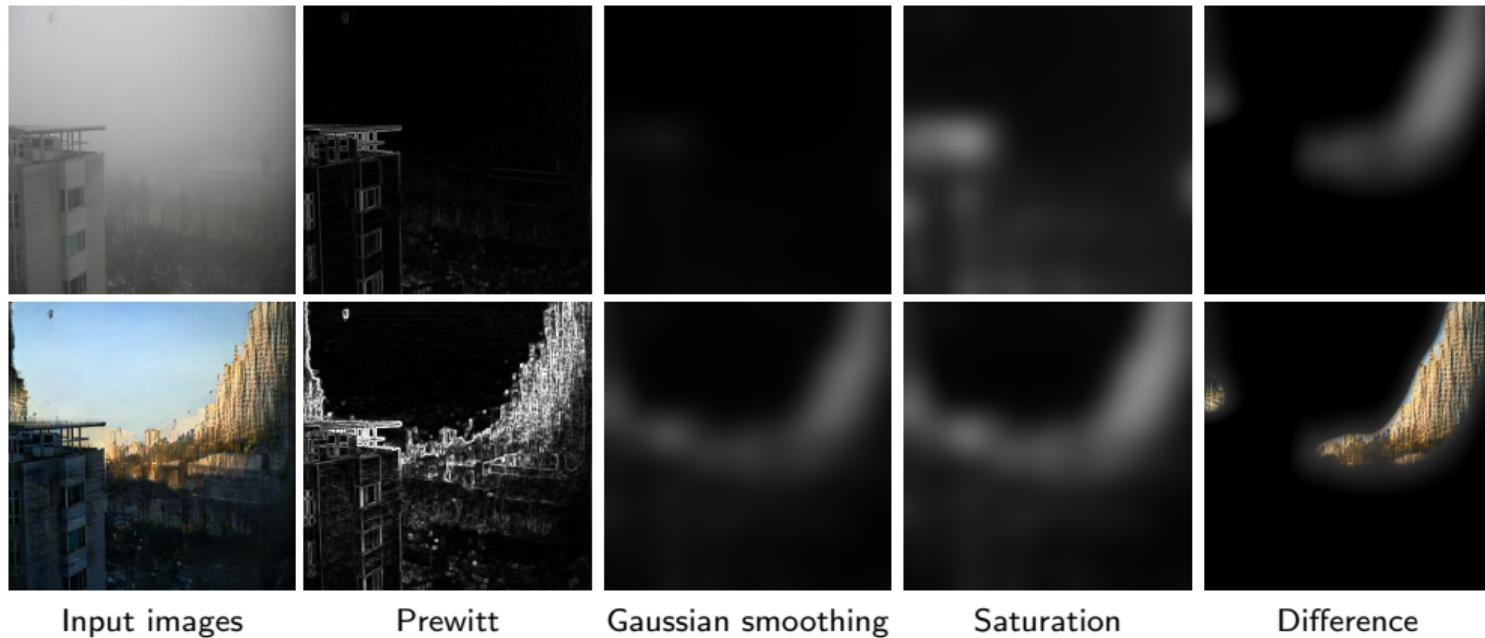
Require: d = defogged image

```
1: procedure HARD( $f, d$ )
2:    $f' \leftarrow \text{PREWITT}(f_{gray})$ 
3:    $d' \leftarrow \text{PREWITT}(d_{gray})$ 
4:    $f'_{smooth} \leftarrow \text{GAUSSIANFILTER}(f')$ 
5:    $d'_{smooth} \leftarrow \text{GAUSSIANFILTER}(d')$ 
6:    $f'_{scaled} \leftarrow \text{NORMALIZE}(f'_{smooth})$ 
7:    $f'_{sat} \leftarrow \tanh(\nu_{fog} \cdot f'_{scaled})$ 
8:    $d'_{scaled} \leftarrow \text{NORMALIZE}(d'_{smooth})$ 
9:    $d'_{sat} \leftarrow \tanh(\nu_{defog} \cdot d'_{scaled})$ 
10:   $diff \leftarrow \min(0, d'_{scaled} - f'_{sat})$ 
11:  return MEAN( $diff$ )
12: end procedure
```

HArD (Haze Artifact Detector)



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Input images

Prewitt

Gaussian smoothing

Saturation

Difference

Experiments on synthetic data

- ▶ Comparison with SOTA method that use paired data.
- ▶ All method trained on OTS synthetic dataset [14].
- ▶ Real training dataset (for CurL-Defog): LIVE Image Defogging [15].
- ▶ Test dataset: HSTS synthetic dataset [14].

	DCP [3]	CAP [1]	NLD [2]	DehazeNet [4]
PSNR	14.84	21.53	18.92	24.48
SSIM	0.7609	0.8727	0.7411	0.9183

	MSCNN [6]	AOD-Net [5]	Pix2Pix [11]	CurL-Defog
PSNR	18.64	20.55	24.22	24.83
SSIM	0.8168	0.8973	0.8991	0.9037



Experiments on real data

- ▶ Synthetic dataset: OTS [14].
- ▶ Real Dataset: LIVE Image Defog real dataset [15].
- ▶ Test dataset: LIVE Image Defog real test set [15].

	CycleDehaze [9]	Pix2Pix [11]	CurL-Defog
e (\uparrow)	32.70	25.74	28.41
\bar{r} (\uparrow)	3.290	2.135	2.636
HArD (\downarrow)	2.535	0.3786	1.374



Experiments on severe fog

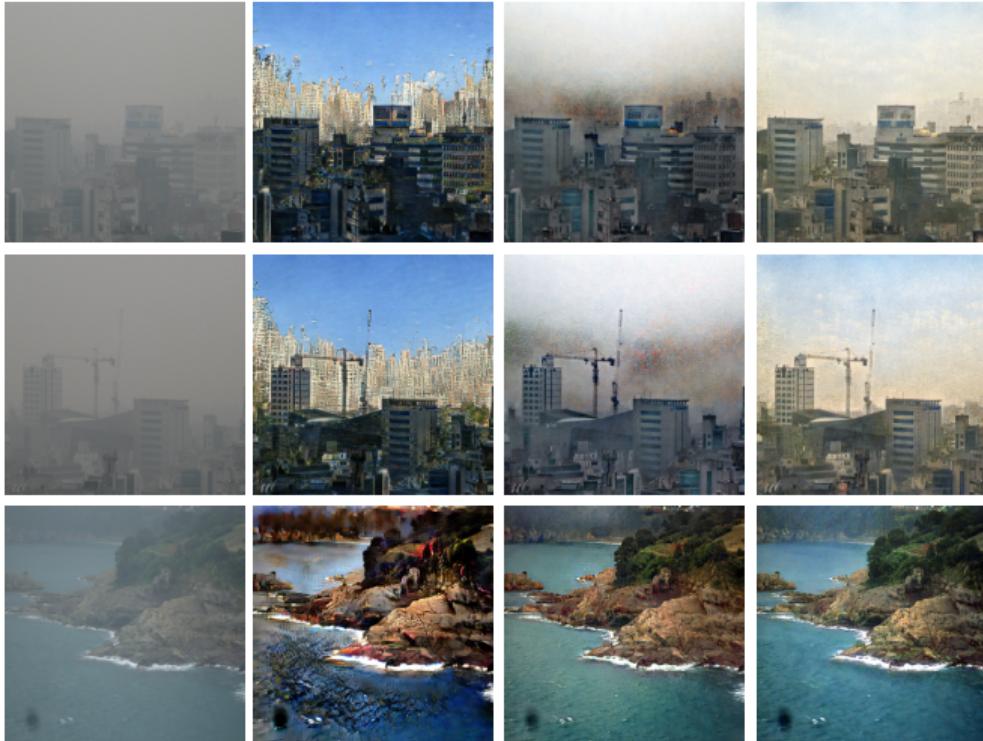
- ▶ Synthetic dataset: OTS [14].
- ▶ Real Dataset: O-Haze dataset [16].
- ▶ Test dataset: Dense-Haze dataset [17].

	MSCNN [6]	DehazeNet [4]	CycleDehaze [9]	Pix2Pix [11]	CurL-Defog
PSNR	12.52	11.36	10.54	10.55	12.24
SSIM	0.369	0.374	0.261	0.311	0.469

Experiments and Results



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Foggy image

CycleDehaze [9]

Pix2Pix [11]

CurL-Defog



Conclusions

- ▶ CurL-Defog: a curriculum learning-based novel defogging method.
- ▶ Artifacts minimized while maintaining good quality on real images.
- ▶ Effective defogging even with severe fog.
- ▶ A new referenceless metric (HArD) to numerically estimate the amount of defogging artifacts.

Future Work

- ▶ Combine the HArD metric with other defogging metrics (e.g. [13]) in order to penalize the insertion of artifacts.
- ▶ Use the HArD metric as a loss function during training.
- ▶ Scale the CurL-Defog method to HD images or videos.



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Thank you
for your attention



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