

# Weighted LISA (Local indicator of spatial autocorrelation): sketch, v1

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## 1 Introduction

To perform local (or global) weighted auto-correlation, two ingredients are needed :

- a  $n \times n$  exchange matrix  $\mathbf{E} = (e_{ij})$  between “positions”  $i$  and  $j$ , which is symmetric, non-negative, and normalized to  $e_{\bullet\bullet} = 1$ . In addition,  $\mathbf{E}$  has to be *weight-compatible* in the sense that the weights  $\mathbf{f} = (f_i)$  defined by  $f_i := e_{i\bullet} > 0$  are the relevant *strictly positive* weights under consideration.
- a  $n \times n$  matrix of squared Euclidean distances  $\mathbf{D} = (d_{ij})$ .

### 1.1 Markov chains

Let  $\mathbf{\Pi} := \text{diag}(\mathbf{f})$ . Define  $\mathbf{W} := c^{-1}\mathbf{E}$ , that is  $w_{ij} := \frac{e_{ij}}{f_i}$ . By construction,  $\mathbf{W}$  is the  $n \times n$  transition matrix of a reversible Markov chain (we assume to be *regular*, that is irreducible and aperiodic, with stationary distribution  $\mathbf{f}$ ). It obeys  $\mathbf{\Pi W} = \mathbf{W}^\top \mathbf{\Pi} = \mathbf{E}$ .

### 1.2 Relative autocorrelation index $\delta$

Define the global and local inertia by

$$\Delta := \frac{1}{2} \sum_{ij} f_i f_j d_{ij} \quad \Delta_{\text{loc}} := \frac{1}{2} \sum_{ij} e_{ij} d_{ij} \quad (1)$$

The *relative autocorrelation index*  $\delta$  (a weighted, multivariate generalization of Moran’s  $I$ ) is

$$\delta := \frac{\Delta - \Delta_{\text{loc}}}{\Delta} \in [-1, 1] \quad (2)$$

### 1.3 Local autocorrelation index $\delta_i$ (LISA)

There are many ways to define a local autocorrelation index  $\delta_i$  such that  $\delta = \sum_{i=1}^n f_i \delta_i$ . Presumably the most elegant (unpublished, but cited in “Flow autocorrelation : a dyadic approach” by F. Bavaud, M. Kordi, C. Kaiser, The Annals of Regional Science (2018) Vol. 61, Issue 1, pp 95–111, <https://doi.org/10.1007/s00168-018-0860-y>) is

$$\delta_i := \frac{(\mathbf{W}\mathbf{B})_{ii}}{\Delta} \quad (3)$$

where  $\mathbf{B} := -\frac{1}{2}\mathbf{H}\mathbf{D}\mathbf{H}^\top$  is the matrix of (unweighted) *scalar products* and  $\mathbf{H} := \mathbf{I}_n - \mathbf{1}_n \mathbf{f}^\top$  is the (idempotent, generally non symmetric) weighted *centration matrix*.

By construction,  $\mathbf{H}\mathbf{1}_n = \mathbf{0}_n$ , and  $\mathbf{H}^\top \mathbf{f} = \mathbf{0}_n$ .

Note that  $\mathbf{E}\mathbf{H} = \mathbf{E} - \mathbf{f}\mathbf{f}^\top$  and  $\mathbf{H}^\top \mathbf{E} = \mathbf{E} - \mathbf{f}\mathbf{f}^\top$  and finally  $\mathbf{H}^\top \mathbf{E}\mathbf{H} = \mathbf{E} - \mathbf{f}\mathbf{f}^\top$

By construction,

$$\begin{aligned} \sum_i f_i (\mathbf{W}\mathbf{B})_{ii} &= \text{trace}(\mathbf{\Pi}\mathbf{W}\mathbf{B}) = \text{trace}(\mathbf{E}\mathbf{B}) = -\frac{1}{2}\text{trace}(\mathbf{E}\mathbf{H}\mathbf{D}\mathbf{H}^\top) \\ &= -\frac{1}{2}\text{trace}(\mathbf{H}^\top \mathbf{E}\mathbf{H}\mathbf{D}) = \frac{1}{2}\text{trace}((\mathbf{f}\mathbf{f}^\top - \mathbf{E})\mathbf{D}) = \Delta - \Delta_{\text{loc}} \end{aligned}$$

which proves  $\delta = \sum_{i=1}^n f_i \delta_i$ .