# Transportation network with multiple lines

notes GG

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# 1 Formalism

## 1.1 The transportation network with multiple lines

Let  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$  be a simple, oriented, and connected graph representing a transportation network between  $|\mathcal{V}| = n$  nodes, having  $|\mathcal{E}| = m$  edges, and possessing p different transportation lines. Each node belongs to only one line, i.e.  $\mathcal{V} = \bigcup_{k=1}^p \mathcal{V}_k$  and  $\bigcap_{k=1}^p \mathcal{V}_k = \emptyset$ , where  $\mathcal{V}_k$  represents the set of nodes in line k. The edge set  $\mathcal{E}$ , can also be decomposed with

$$\mathcal{E} = \mathcal{E}_{\mathrm{W}} \cup \mathcal{E}_{\mathrm{B}}, \qquad \mathcal{E}_{\mathrm{W}} := \bigcup_{k=1}^{p} \mathcal{E}_{k}, \qquad \mathcal{E}_{\mathrm{W}} \cap \mathcal{E}_{\mathrm{B}} = \emptyset, \quad \mathcal{E}_{k} \cap \mathcal{E}_{l} = \emptyset, \quad \forall k, l. \quad (1)$$

where  $\mathcal{E}_k$  is the set of edges composing line k,  $\mathcal{E}_W$  the set containing all edges inside lines, and  $\mathcal{E}_B$  the set of transfer edges, connecting the different lines. The graph  $\mathcal{G}$  can be represented by its adjacency matrix  $\mathbf{A} = (a_{ij})$ , which can also be decomposed with

$$\mathbf{A} = \mathbf{A}_{\mathrm{W}} + \mathbf{A}_{\mathrm{B}}, \qquad \mathbf{A}_{\mathrm{W}} = \sum_{k=1}^{p} \mathbf{A}_{k}, \tag{2}$$

with  $\mathbf{A}_k = (a_{ij}^k)$  are edges of line k,  $\mathbf{A}_{\mathrm{W}} = (a_{ij}^{\mathrm{W}})$  edges of inside all lines, and  $\mathbf{A}_{\mathrm{B}} = (a_{ij}^{\mathrm{B}})$  transfer edges. We suppose that there is an uniquely define route inside lines, i.e.

$$a_{i\bullet}^k \le 1 \text{ and } a_{\bullet i}^k \le 1, \qquad \forall i, k.$$
 (3)

where • designates a summation over the replaced index.

### 1.2 The origin-destination matrix

The  $(n \times n)$  origin-destination matrix, denoted by  $\mathbf{N} = (n_{st}), n_{st} \geq 0, \forall s, t$ , contains the flow (e.g. the number of passengers) entering the network in source node s and leaving it in target node t. We can denote its margins with

$$\sigma_{\rm in} := Ne_n$$
 (4)

$$\boldsymbol{\sigma}_{\text{out}} := \mathbf{N}^{\top} \mathbf{e}_n \tag{5}$$

where  $\mathbf{e}_n$  is the vector of ones of size n. The vector  $\boldsymbol{\sigma}_{\mathrm{in}} = (\sigma_i^{\mathrm{in}})$  is the vector of flow entering the network and  $\sigma_{\rm in} = (\sigma_i^{\rm in})$  is the vector of flow escaping the network. We have

$$\sigma_{\bullet}^{\text{in}} = \sigma_{\bullet}^{\text{out}}.$$
 (6)

#### 1.3 The flow matrix

A flow on edges is represented by the  $(n \times n)$  flow matrix  $\mathbf{X} = (x_{ij})$ , verifying

$$x_{ij} \ge 0, \qquad \forall i, j,$$
 (7)

$$a_{ij} = 0 \Rightarrow x_{ij} = 0, \quad \forall i, j,$$
 (8)

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$$x_{i\bullet} + \sigma_i^{\text{in}} = x_{\bullet i} + \sigma_i^{\text{out}}, \quad \forall i.$$
(9)

Again, we can decompose the flow matrix with

$$\mathbf{X} = \mathbf{X}_{\mathrm{W}} + \mathbf{X}_{\mathrm{B}} \qquad \mathbf{X}_{\mathrm{W}} := \sum_{k=1}^{l} \mathbf{X}_{k}$$
 (10)

where  $\mathbf{X}_k$  represent the flow inside line k,  $\mathbf{X}_{\mathrm{W}}$  is the flow inside all lines, and  $\mathbf{X}_{\mathrm{B}}$ the flow between lines. This decomposition allows us to define the  $vector\ of\ flow$ entering lines  $\rho_{\rm in} = (\rho_i^{\rm in})$  and the vector of flow escaping lines  $\rho_{\rm out} = (\rho_i^{\rm out})$ , with

$$\boldsymbol{\rho}_{\mathrm{in}} := \boldsymbol{\sigma}_{\mathrm{in}} + \mathbf{X}_{\mathrm{B}}^{\mathsf{T}} \mathbf{e}_{n},\tag{11}$$

$$\rho_{\text{out}} := \sigma_{\text{out}} + \mathbf{X}_{\text{B}} \mathbf{e}_n, \tag{12}$$

where  $\mathbf{e}_n$  is the vector of ones of size n. It is easy to see that we still have  $\rho_{\bullet}^{\rm in} = \rho_{\bullet}^{\rm out}.$ 

#### 1.4 Shortest-paths flow

Let  $\mathcal{P}_{st}$  be the set of admissible shortest-paths between s and t on  $\mathcal{G}$ . We can denote by  $P_{st}(i,j)$  the probability of having edge  $(i,j) \in \wp$  when drawing a path  $\wp$  from  $\mathcal{P}_{st}$ . We have

$$P_{st}(i,j) := \frac{1}{|\mathcal{P}_{st}|} \sum_{\wp \in \mathcal{P}_{st}} \delta((i,j) \in \wp), \tag{13}$$

where  $\delta(.)$  designate the indicator function. If we are given an origin-destination matrix  $\mathbf{N} = (n_{st})$ , we can compute the shortest-path flow matrix, noted  $\mathbf{X}_{sp} =$  $(x_{ij}^{\rm sp})$ , with:

$$x_{ij}^{\rm sp} = \sum_{st} P_{st}(i,j) n_{st} \tag{14}$$

This matrix contains the flow on each edge if we suppose that the flow follows shortest-paths.

### 1.5 Problem definition

We suppose that we know the flow entering and leaving each line, i.e.  $\rho_{\text{in}}$  and  $\rho_{\text{out}}$  and we are interested in finding trajectories  $n_{st}$  of the flow in the network knowing the set  $\mathcal{A}$  of admissible pair (s,t), i.e. pairs of nodes where there is a possible use of the network for traveling. This set can be given by the matrix  $\mathbf{T} = (t_{st})$  defined by

$$t_{st} = \begin{cases} 1 & \text{if } (s,t) \in \mathcal{A}, \\ 0 & \text{otherwise.} \end{cases}$$
 (15)

# 1.6 Algorithm

Set  $\sigma_{\rm in}^{(0)} = \rho_{\rm in} + \epsilon$  and  $\sigma_{\rm out}^{(0)} = \rho_{\rm out} + \epsilon$ , with  $\epsilon$  a small positive scalar. Until convergence, do:

- 1. Compute  $\mathbf{N}^{(i)} = \mathbf{Diag}(\mathbf{a}^{(i)})(\mathbf{T} + \epsilon)\mathbf{Diag}(\mathbf{b}^{(i)})$  with iterative fitting, such that  $\mathbf{N}^{(i)}\mathbf{e}_n = \boldsymbol{\sigma}_{\mathrm{in}}^{(i)}$  and  $(\mathbf{N}^{(i)})^{\top}\mathbf{e}_n = \boldsymbol{\sigma}_{\mathrm{out}}^{(i)}$ .
- 2. Compute the associated shortest-path flow matrix  $\mathbf{X}^{(i)}$  with (14).
- 3. Compute  $\boldsymbol{\sigma}_{\text{in}}^{(i+1)} = \boldsymbol{\rho}_{\text{in}} (\mathbf{X}_{\text{B}}^{(i)})^{\top} \mathbf{e}_{n}$  and  $\boldsymbol{\sigma}_{\text{out}}^{(i+1)} = \boldsymbol{\rho}_{\text{out}} \mathbf{X}_{\text{B}}^{(i)} \mathbf{e}_{n}$ .