UNIVERSITY NAME

DOCTORAL THESIS

Hand Gesture Recognition via Leap Motion Sensor

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A thesis submitted in fulfillment of the requirements for the degree of Doctor of Philosophy

in the

Research Group Name Department or School Name

August 17, 2017

Declaration of Authorship

I, Jahangir IQBAL, declare that this thesis titled, "Hand Gesture Recognition via Leap Motion Sensor" and the work presented in it are my own. I confirm that:

- This work was done wholly or mainly while in candidature for a research degree at this University.
- Where any part of this thesis has previously been submitted for a degree or any other qualification at this University or any other institution, this has been clearly stated.
- Where I have consulted the published work of others, this is always clearly attributed.
- Where I have quoted from the work of others, the source is always given. With the exception of such quotations, this thesis is entirely my own work.
- I have acknowledged all main sources of help.
- Where the thesis is based on work done by myself jointly with others, I have made clear exactly what was done by others and what I have contributed myself.

Signed:			
Date:			

"Thanks to my solid academic training, today I can write hundreds of words on virtually any topic without possessing a shred of information, which is how I got a good job in journalism."

Dave Barry

University Name

Abstract

Faculty Name Department or School Name

Doctor of Philosophy

Hand Gesture Recognition via Leap Motion Sensor

by Jahangir IQBAL

The Thesis Abstract is written here (and usually kept to just this page). The page is kept centered vertically so can expand into the blank space above the title too...

Acknowledgements

The acknowledgments and the people to thank go here, don't forget to include your project advisor. . .

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List of Abbreviations

LAH List Abbreviations HereWSF What (it) Stands For

Physical Constants

Speed of Light $c_0 = 2.99792458 \times 10^8 \,\mathrm{m\,s^{-1}}$ (exact)

xxi

List of Symbols

a distance

P power $W(J s^{-1})$

 ω angular frequency rad

xxiii

For/Dedicated to/To my...

Chapter 1

Background

1.1 Leap Motion (v2)

-introduction to the sensor. when it was made. company behind it. what its used for. price

1.1.1 Java API

hand class, fingers bones. vector.

1.1.2 Native Libraries

-read the page on lm website and summarize

1.1.3 Limitations of Sensor and Documentation

-occulusion -discontinuation of publishing v2 apps -sensor resetting by opening palm -not enough documentation for linux/ubuntu.

1.2 JavaFx

JavaFX is a framework provided by Oracle Corporation that is intended to replace the Swing framework as the standard GUI library for developing desktop applications that can be run on any platform that supports Java. Since the JavaFX 2.0 release, JavaFX application can be written in pure Java code. Before that release, applications written using JavaFX libraries had to be written in Java FX Script, a scripting language designed and used specifically for the purpose of creating GUI applications with JavaFX. This project uses the latest version of this framework, JavaFX 8, which also added support for 3D graphics and sensor support.

1.2.1 Java vs FXML

When writing a JavaFX application, there are two very different approaches that can be used to create the actual user interface (UI) for the application. These are pure Java code and FXML. A brief introduction both of these approaches will be given below.

The pure Java approach constructs the JavaFX application scene graph procedurally through code. Below is a simple "Hello World" program that shows a quick example of this approach in action.

This small snippet of code contains the overall structure and all of the basic components of a JavaFX application. The first point to note is that the main class

```
public class HelloWorld extends Application {
   public static void main(String[] args) {
      launch(args);
   }
4
   @Override
   public void start(Stage primaryStage) {
      primaryStage.setTitle("Hello World!");
      Button btn = new Button();
      btn.setText("Say 'Hello World'");
      btn.setOnAction(new EventHandler<ActionEvent>() {
        @Override
12
        public void handle(ActionEvent event) {
13
           System.out.println("Hello World!");
        }
15
      });
16
17
      StackPane root = new StackPane();
      root.getChildren().add(btn);
19
      primaryStage.setScene(new Scene(root, 300, 250));
20
      primaryStage.show();
21
22
23
   }
```

FIGURE 1.1: A simple hello world program using JavaFX written using just Java code.

which will run the JavaFX application must extend from the abstract base class called javafx.application.Application and implement is abstract start() method. The start() method serves as the main entry point for all JavaFX applications. In the application's main() method, which is common to all Java applications, a call must be made to the launch() method which is a method defined in the base Application JavaFX class that actually launches the application in doing so makes a call to the start() method.

The start() method receives a parameter of type Stage which serves as the primary Stage object for the application. Stage is the top-level user interface container object used by JavaFX to house the whole application. In colloquial terms it can be considered to be the "window" object of the whole application. The Stage object is has a setScene() method which requires a Scene object to be passed in. Scene class is the container of current content being displayed by the application. An application can have multiple scenes which display different pages of the the application. In JavaFX, the actual UI components, such as the StackPane layout Node shown in the simple HelloWorld example above, must be added to the Scene object in order for them to be displayed. This relationship between the Stage, Scene and "root" Node components of a JavaFX application is depicted in Figure 1.2.

The UI components all extend from a parent Node class. One of the improvements that JavaFX brought in regards to its predecessor Swing, is that it represents the entire content of the scene as a tree. More specifically, all of the nodes displayed in a Scene container object must extend from a root level node and be part of the hierarchical scene graph of nodes. Figure 1.3 displays an example of the JavaFX scene graph.

Now that the pure Java code approach of writing JavaFX applications has been

1.2. JavaFx 3

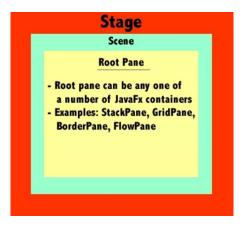


FIGURE 1.2: The layout components of every JavaFX application.

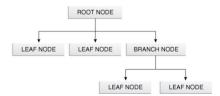


FIGURE 1.3: The Scene Graph architectural model for UI components in JavaFX applications.

introduced, let us discuss the other approach to writing JavaFX applications; FXML. FXML is a XML-based language created by Oracle Corporation for the purpose of making it easier to define the UI of a JavaFX application. While the pure Java code approach is a much more imperetive and procedural way to write JavFX applications, FXML is a more declartive way. It resembles HTML and can also reference a controller java class which can access and modify the UI elements defined in the FXML file. Figure 1.4 shows a very simple FXML file that creates a VBox layout and adds a button to it. This FXML file also has a Java controller class attached to it which is called MyController.java and shown in Figure 1.5

```
<?xml version="1.0" encoding="UTF-8"?>
<?language JavaScript?>

<?!import javafx.scene.control.*?>

<?iimport javafx.scene.layout.*?>

<p
```

FIGURE 1.4: A FXML file defining a simple layout and referencing a controller java class.

```
public class MyController
  {
      @FXML
     private void initialize()
      // this method runs first after all the UI components have been loaded and
      }
     @FXML
     private void printHelloWorld()
10
11
        System.out.println("hello world!");
12
      }
13
14
   }
```

FIGURE 1.5: A controller for the FXML file. The "FXML" annotation in is used to bind certain elements to java objects in the class.

(ending paragraph discussion) The large difference between these two different approaches makes it difficult to combine them effectively, but it is possible to use them in conjunction with each other (as this project does in the design of its application).

1.2.2 SceneBuilder

-explain what scenbuilder is. mention gluon. how -how to use it. - show different windows and what they mean.

Chapter 2

Constructing Hand UI Model

2.1 Basic 3D Modeling

The Leap Motion Java API's Hand class contains all the possible functions one might need to use when gaining more information about the heirarchical structure of this Java object. For example, given a Hand class object "hand", we can access the fingers objects for this hand via "hand.fingers()". Each Finger object contains four Bone objects which are indexed from 0-3. The Bone class does contain an Enum Type that allows one to easily access them via their anatomical names (distal, intermediate, proximal, metacarpal) rather than just using a numerical index. In abstract terms, the Bone object is a vector of sorts and the ends of this bone vector represent the joints at which the bone attaches to its neighboring bones. These "joints" can be accessed via the prevJoint() and nextJoint() methods which respectively return a vector position of the Bone closer to the wrist and of the Bone object endpoint closer to the tip of the finger. The figure below shows the bones and joints of the hand for which the Leap Motion sensor records data.

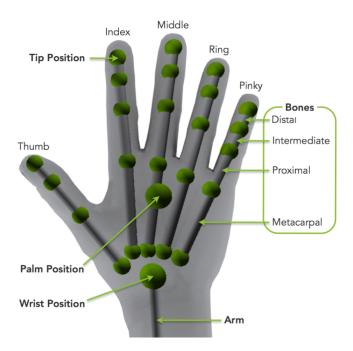


FIGURE 2.1: The Bones of the hand that Leap Motion device records data on.

A Hand object is only valid if it is detected by the Leap Motion device to be a physical object; if a Hand object is created via code using the Hand() constructor, that hand is considered "invalid" and will return true when the hand.invalid() method

is called it. The information contained within a valid Hand object read in from the device is Read Only and can not be changed or updated.

The Leap Motion device records numerical data about the hand and finger positions. Using the Hand class provided by the Leap Motion Java API and described above in the previous paragraph, a graphical model was constructed. For this GUI construction, a graphical representation of the hand was built using basic 3D geometric classes provided by the JavaFx framework. The bones of the hand model were represented by the Cylinder class and the joints were represented by the Sphere JavaFx class. This Hand model is contained inside the UIHand_SimpleJava class. This class extends a base abstract UIHand class which itself inherits from the Javafx class called Group. Group is a type of Node in Javafx that contains an ObservableList of children Nodes that will be added to the Javafx Scene Graph in the order that they are added to the Group. An important point to note is that any transform, effect or property change applied to a Group will also be applied to all the children of that group. The figure below shows an example of how a Group Node can can contain multiple children nodes.

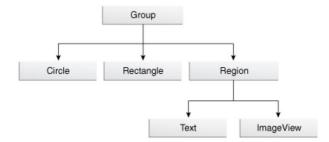


FIGURE 2.2: The Group Node structure in the JavaFx framework.

The UIHand_Simpleclass stores all the fingers bones in two dimensional array of Cylinder objects and all the respective joints in a different two dimensional array of Spheres. These arrays are of dimensions 5x3 to account for the five fingers and the three types of primary finger bones: distal, intermediate and proximal. In addition to these arrays, there is an array containing the four metacarpal bones of the hand; the thumb does not have a corresponding metacarpal bone like the other fingers. The also contains two more cylinders and a sphere to construct the palm section of the hand. To provide the hand with a uniform, well-blended color shading a Phong-Material object is set as the hand's material property. Below is a figure showing an excerpt from code which shows the initialization of the UIHand_Simpleand part of its constructor.

Each element of the hand, such as all the cylinders and spheres representing the various bones and joints, is added to the children of the encompassing parent group that represents the hand.

2.2 Set Location Method

The UIHand_Simpleclass also contains a method that allows for the graphical hand to be positioned according to the exact postions recorded in a Leap Motion Hand object. This method, which is called setLoc(Hand h), goes through each of the fingers and their respective bones and joints and sets the position and rotation of these these Javafx nodes based upon the Hand object passed in. This method relies on a helper class called ViewMath which contains static methods that are called to position each

```
public class UHAnd_Simple extends UHAnd {

private Static float *ingerRadius* = 14f;

private Cylinder[][] fingerBones;
private Cylinder [] fingerBones;

private Cylinder palmWints;

private Sphere pinkyJoint;

public UHAnd_Simple(Color color, boolean wireframe) {

super();

PhongMaterial dark = new PhongMaterial(color);
 PhongMaterial light = new PhongMaterial(color.brighter());

fingerBones = new Cylinder[3];

for (int i = 0; i < 5; ++i) {
    fingerBones(i) = new Cylinder(3);
    for (int j = 0; j < 3; ++j) {
        fingerBones(i) = new Cylinder();
        fingerBones(i)[j] = new Cylinder();
```

FIGURE 2.3: A snippet of code showing how a the UIHandSimple class, representing the graphical hand, is constructed.

individual cylinder representing a bone. Two of the important methods in View-Math are setPositionByVector(Node n, Vector v) and setRotationByVector(Node n, Vector v). The method setPositionByVector sets the translate properties of the Javafx Node passed in to the xyz position recorded in the vector. The setRotationByVector method rotates the Javafx Node passed into it by the direction which is represented by the second argument vector. This method first takes the direction and "corrects" it by flipping the z-value. This is done because Javafx's coordinate system has the Z-axis increasing outward from the computer screen, while Leap Motion has the Z-axis increasing into the screen. The setRotationByVector finds the angle of rotation finding the the angle of the passed in direction to the Y-axis. In addition to the angle of rotation, the axis upon which the rotation will occur also needs to be defined. The axis of the rotation is found by taking the cross-product between the Y-axis and the "corrected" direction. Below is a snippet of code that shows the setRotationByVector method.

```
//This method rotates a given JavaFx node to point in the direction passed in
public static void setRotationByVector (Node node, Vector direction) {
    //Correct the direction to correspond to JavaFx Coordinate system
    Vector correctedDirection = new Vector(direction.getX(), direction.getY(), -direction.getZ());

//Find the angle of the direction to the y-axis; in degrees
double angle = correctedDirection.angleTo(Vector.yAxis()) * 180 / Math.PI;

//Find the axis of rotation by taking the cross product of the corrected direction with the y-axix
PointJD axis = vectorToFoint(correctedDirection.cross(Vector.yAxis()));

//set the axis and angle of rotation on the Node object
node.setRotate(angle);
node.setRotationAxis(axis);
```

FIGURE 2.4: A snippet of code showing how the rotation is set for an arbitrary Node object of the JavaFX Hand Model.

2.3 Concurrency

to be written..

-read some code about javafx application threading stuff. research. write it in a paragraph and explain what it means.

-look at the code that does task setting. read it a little try to understand. make some notes about what it means and how its wired. write about it.

```
// Hello.java
import javax.swing.JApplet;
import java.awt.Graphics;

public class Hello extends JApplet {
   public void paintComponent(Graphics g) {
       g.drawString("Hello, world!", 65, 95);
   }
}
```

FIGURE 2.5: A snippet of code showing how the rotation is set for an arbitrary Node object of the JavaFX Hand Model.

– also write about the frame controller methods offered by leap ui. and talk about the controller2. read code, understand, make notes. and then write about it.

Appendix A

Frequently Asked Questions

A.1 How do I change the colors of links?

The color of links can be changed to your liking using:

\hypersetup{urlcolor=red}, or

 $\label{lem:citecolor} $$ \displaystyle \sup\{citecolor=green\}, or $$$

\hypersetup{allcolor=blue}.

If you want to completely hide the links, you can use:

\hypersetup{allcolors=.}, or even better:

\hypersetup{hidelinks}.

If you want to have obvious links in the PDF but not the printed text, use:

\hypersetup{colorlinks=false}.