

ECE1388 VLSI Design Methodology

Lecture 15

Design for Testability

Outline

- ❑ Testing
 - Logic Verification
 - Silicon Debug
 - Manufacturing Test
- ❑ Fault Models
- ❑ Observability and Controllability
- ❑ Design for Test
 - Scan
 - BIST
- ❑ Boundary Scan

Testing

- ❑ Testing is one of the most expensive parts of chips
 - Logic verification accounts for $> 50\%$ of design effort for many chips
 - Debug time after fabrication has enormous opportunity cost
 - Shipping defective parts can sink a company

- ❑ Example: Intel FDIV bug (1994)
 - Logic error not caught until $> 1\text{M}$ units shipped
 - Recall cost \$450M (!!!)

Logic Verification

- ❑ Does the chip simulate correctly?
 - Usually done at HDL level
 - Verification engineers write test bench for HDL
 - Can't test all cases
 - Look for corner cases
 - Try to break logic design
- ❑ Ex: 32-bit adder
 - Test all combinations of corner cases as inputs:
 - 0, 1, 2, $2^{31}-1$, -1, -2^{31} , a few random numbers
- ❑ Good tests require ingenuity

Silicon Debug

- ❑ Test the first chips back from fabrication
 - If you are lucky, they work the first time
 - If not...
- ❑ Logic bugs vs. electrical failures
 - Most chip failures are logic bugs from inadequate simulation
 - Some are electrical failures
 - Crosstalk
 - Dynamic nodes: leakage, charge sharing
 - Ratio failures
 - A few are tool or methodology failures (e.g. DRC)
- ❑ Fix the bugs and fabricate a corrected chip

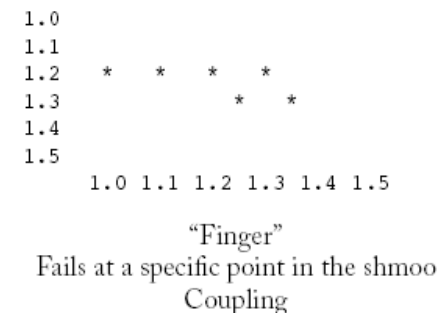
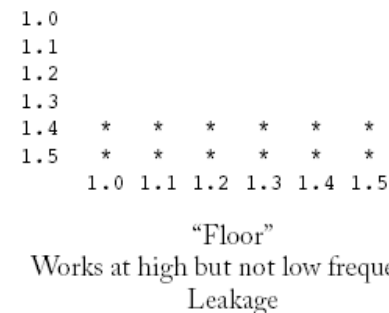
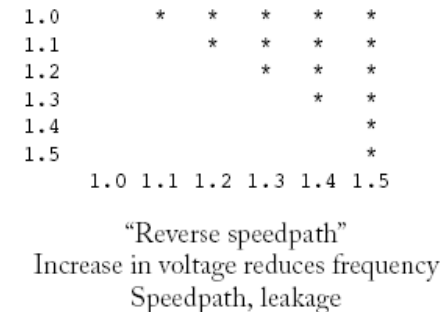
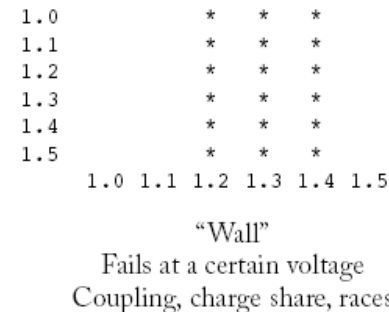
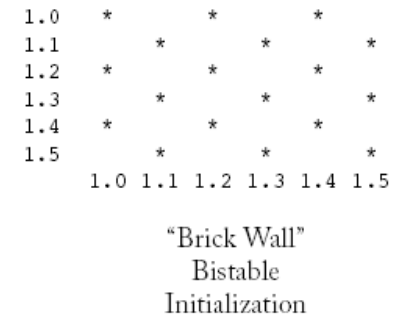
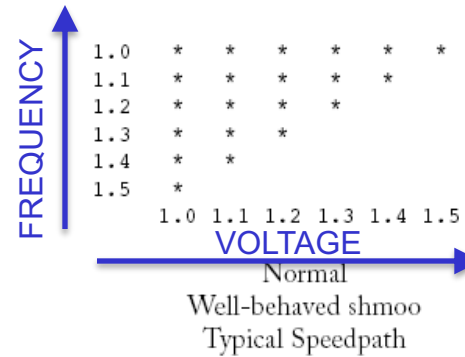
*Clock period in ns on the left, frequency increases going up
Voltage on the bottom, increase left to right*

** indicates a failure*

Shmoo Plots

- ❑ How to diagnose failures?
 - Hard to access chips
 - Picoprobes
 - Electron beam
 - Laser voltage probing
 - Built-in self-test

- ❑ Shmoo plots
 - Vary voltage, frequency
 - Look for cause of electrical failures

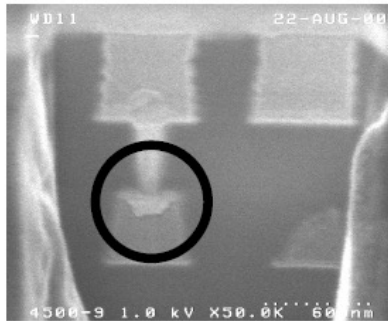


Manufacturing Test

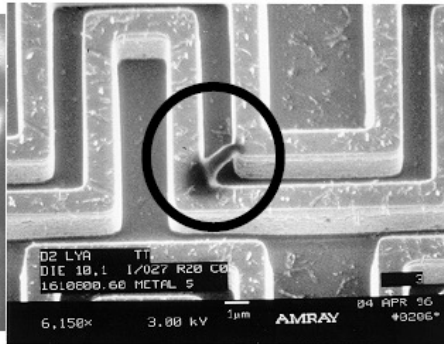
- ❑ A speck of dust on a wafer is sufficient to kill chip
- ❑ *Yield* of any chip is $< 100\%$
 - Must test chips after manufacturing before delivery to customers to only ship good parts
- ❑ Manufacturing testers are very expensive
 - Minimize time on tester
 - Careful selection of *test vectors*



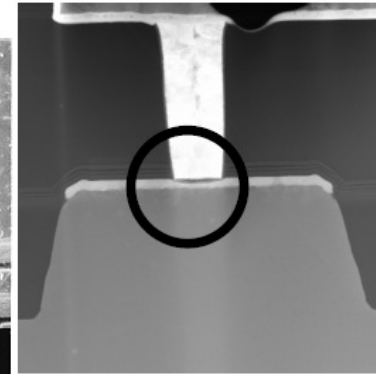
Manufacturing Failures



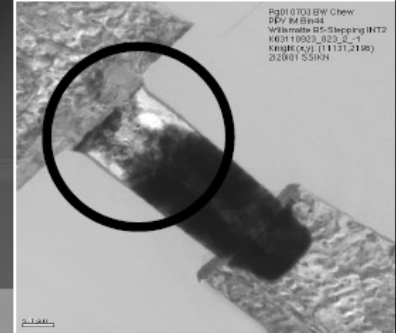
Metal 1 Shelving



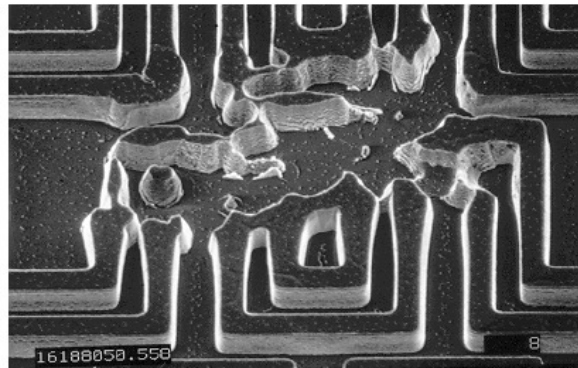
**Metal 5 film particle
(bridging defect)**



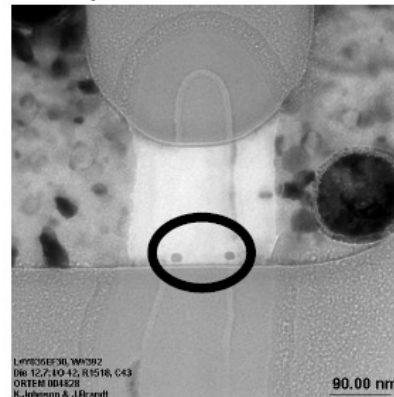
Open defect



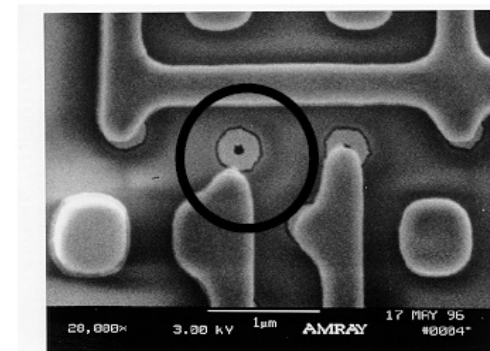
**Spongy Via2
(Infant mortality)**



**Metal 5 blocked etch
(patterning defect)**



**Spot defects
"Co" Defect under Gate**



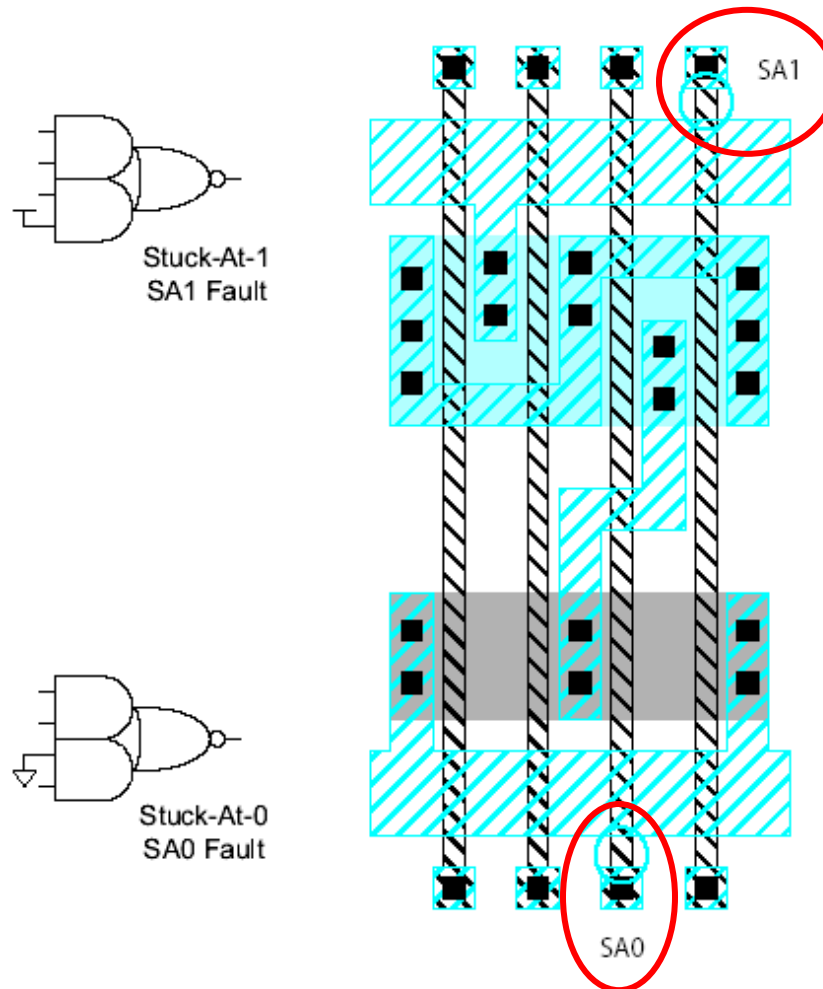
**Metal 1 missing pattern
(open at contact)**

SEM images courtesy Intel Corporation

Stuck-At Faults

- ❑ How does a chip fail?
 - Usually failures are shorts between two conductors or opens in a conductor
 - This can cause very complicated behavior
- ❑ A simpler model: *Stuck-At*
 - Assume all failures cause nodes to be “stuck-at” 0 or 1, i.e. shorted to GND or V_{DD}
 - Not quite true, but works well in practice

Examples



Observability & Controllability

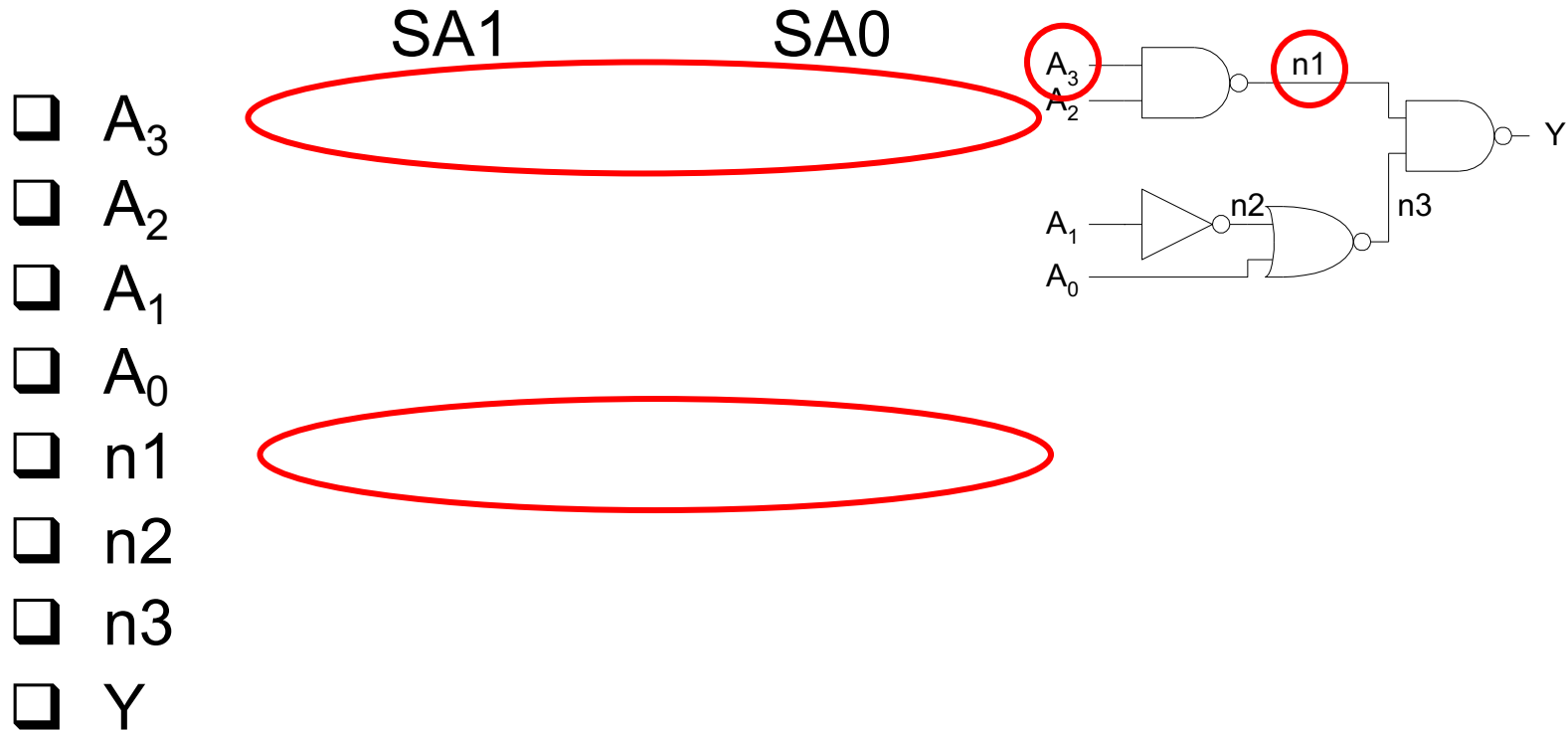
- ❑ *Observability*: ease of observing a node by watching external output pins of the chip
- ❑ *Controllability*: ease of forcing a node to 0 or 1 by driving input pins of the chip

- ❑ Combinational logic is usually easy to observe and control
- ❑ Finite state machines can be very difficult, requiring many cycles to enter desired state
 - Especially if state transition diagram is not known to the test engineer

Test Pattern Generation

- ❑ Manufacturing test ideally would check every node in the circuit to prove it is not stuck
- ❑ Apply the smallest sequence of test vectors necessary to prove each node is not stuck
- ❑ Good observability and controllability reduces number of test vectors required for manufacturing test
 - Reduces the cost of testing
 - Motivates design-for-test

Test Example



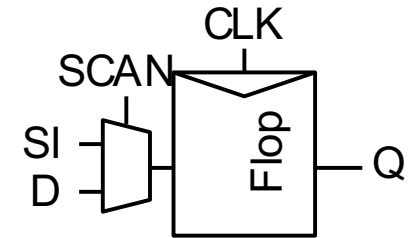
☐ Minimum set:

Design for Test

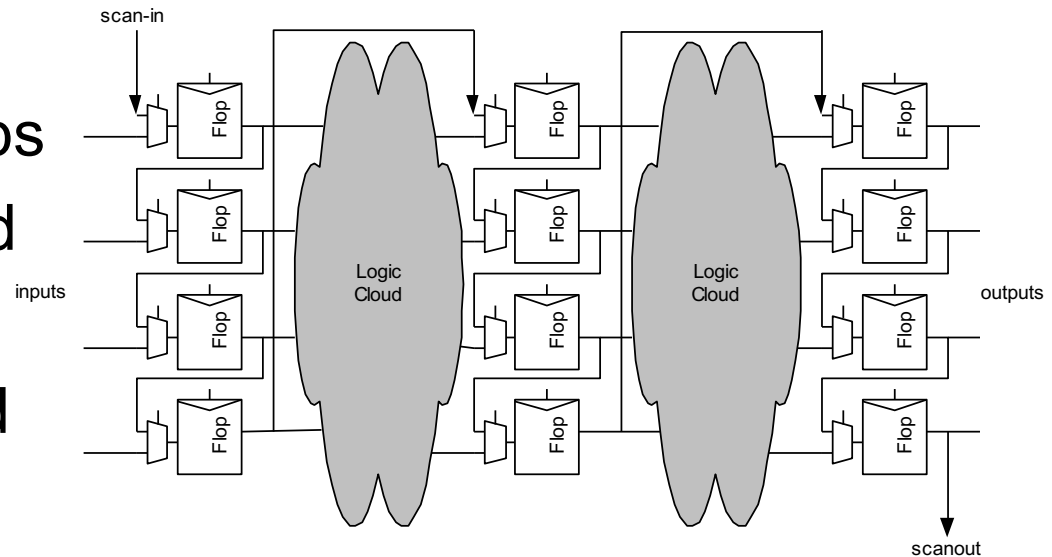
- ❑ Design the chip to increase observability and controllability
- ❑ If each register could be observed and controlled, test problem reduces to testing combinational logic between registers.
- ❑ Better yet, logic blocks could enter test mode where they generate test patterns and report the results automatically.

Scan

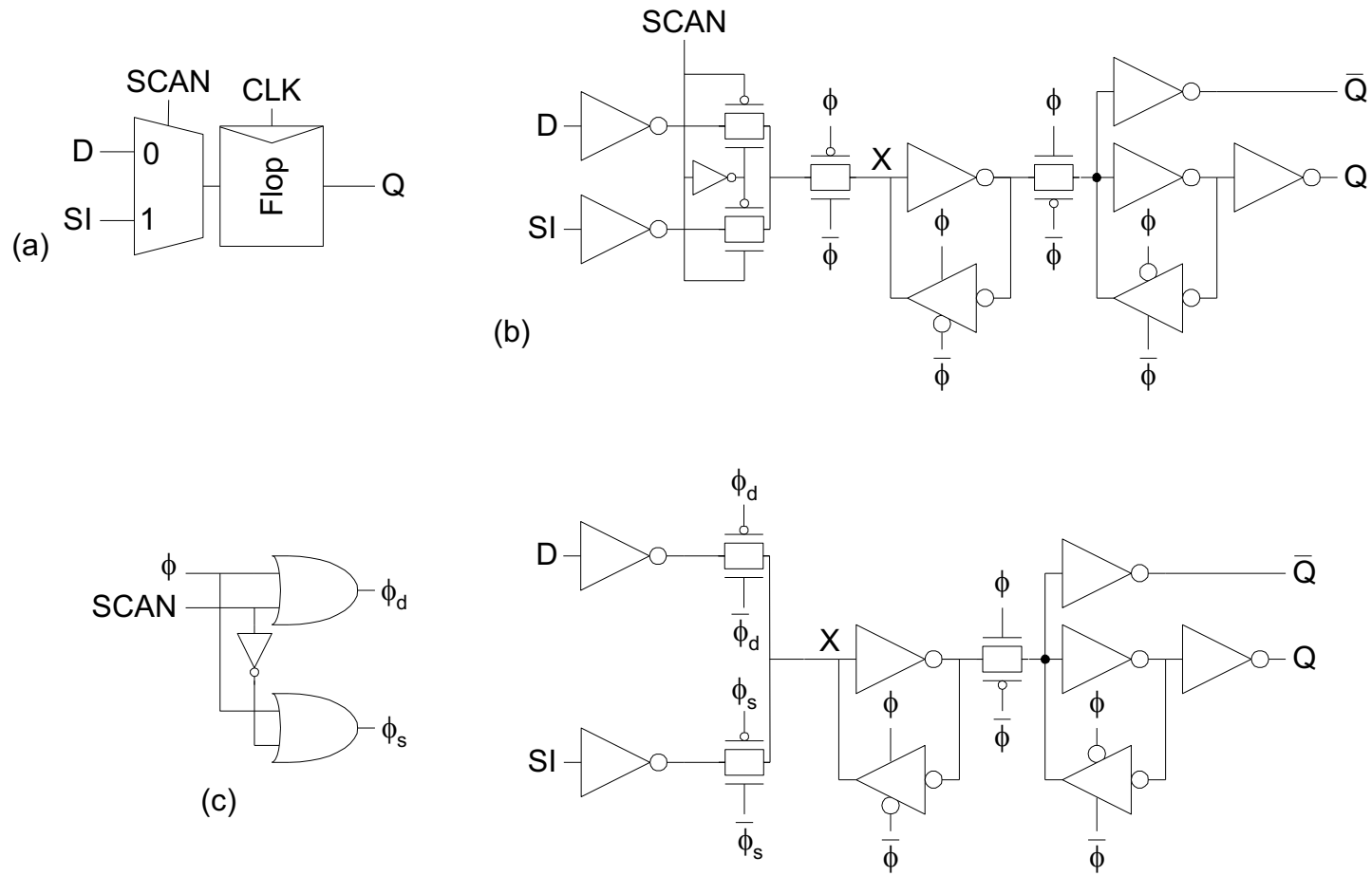
- ❑ Convert each flip-flop to a scan register
 - Only costs one extra multiplexer
- ❑ Normal mode: flip-flops behave as usual
- ❑ Scan mode: flip-flops behave as shift register



- ❑ Contents of flops can be scanned out and new values scanned in



Scannable Flip-flops



ATPG

- ❑ Test pattern generation is tedious
- ❑ Automatic Test Pattern Generation (ATPG) tools produce a good set of vectors for each block of combinational logic
- ❑ Scan chains are used to control and observe the blocks
- ❑ Complete coverage requires a large number of vectors, raising the cost of test
- ❑ Most products settle for covering 90+% of potential stuck-at faults

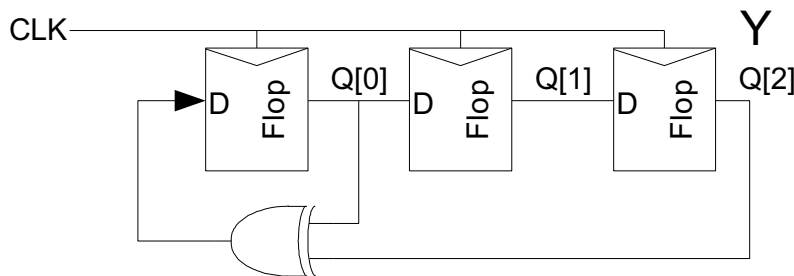
Built-in Self-test

- ❑ Built-in self-test lets blocks test themselves
 - Generate pseudo-random inputs to comb. logic
 - Combine outputs into a *syndrome*
 - With high probability, block is fault-free if it produces the expected syndrome

PRSG

❑ *Linear Feedback Shift Register*

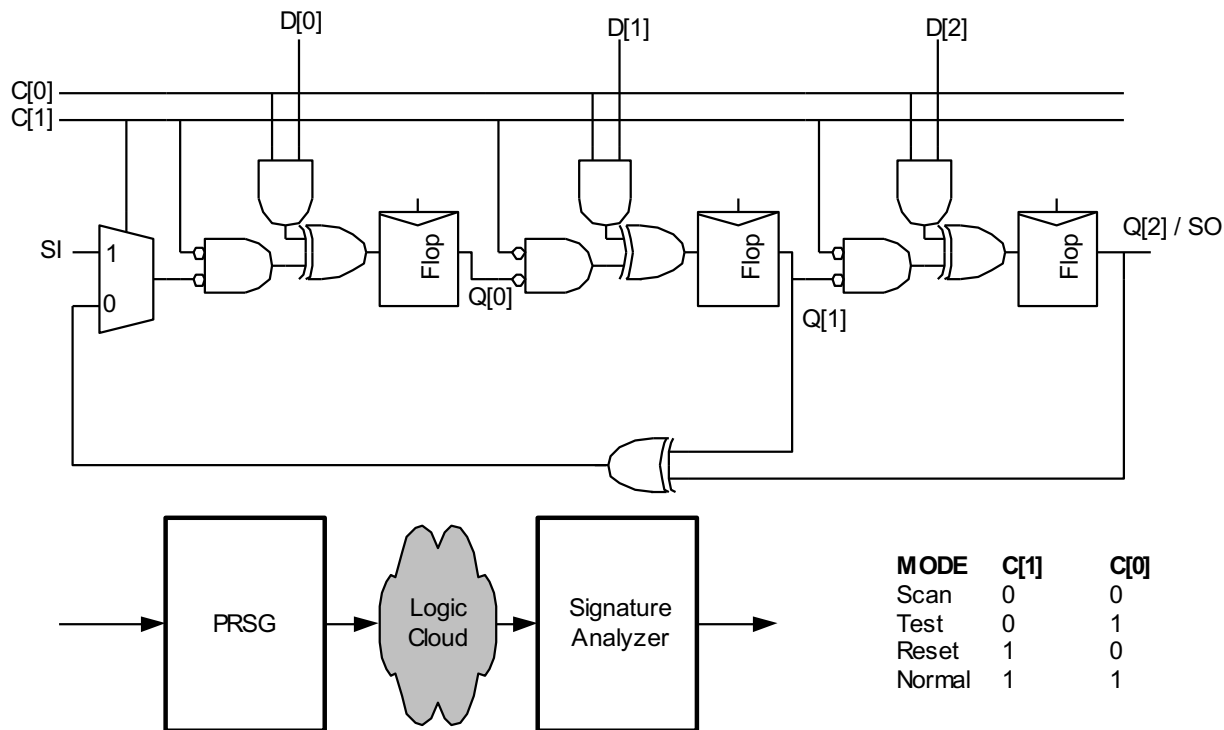
- Shift register with input taken from XOR of state
- *Pseudo-Random Sequence Generator*



Step	Y
0	
1	
2	
3	
4	
5	
6	...
7	

BILBO

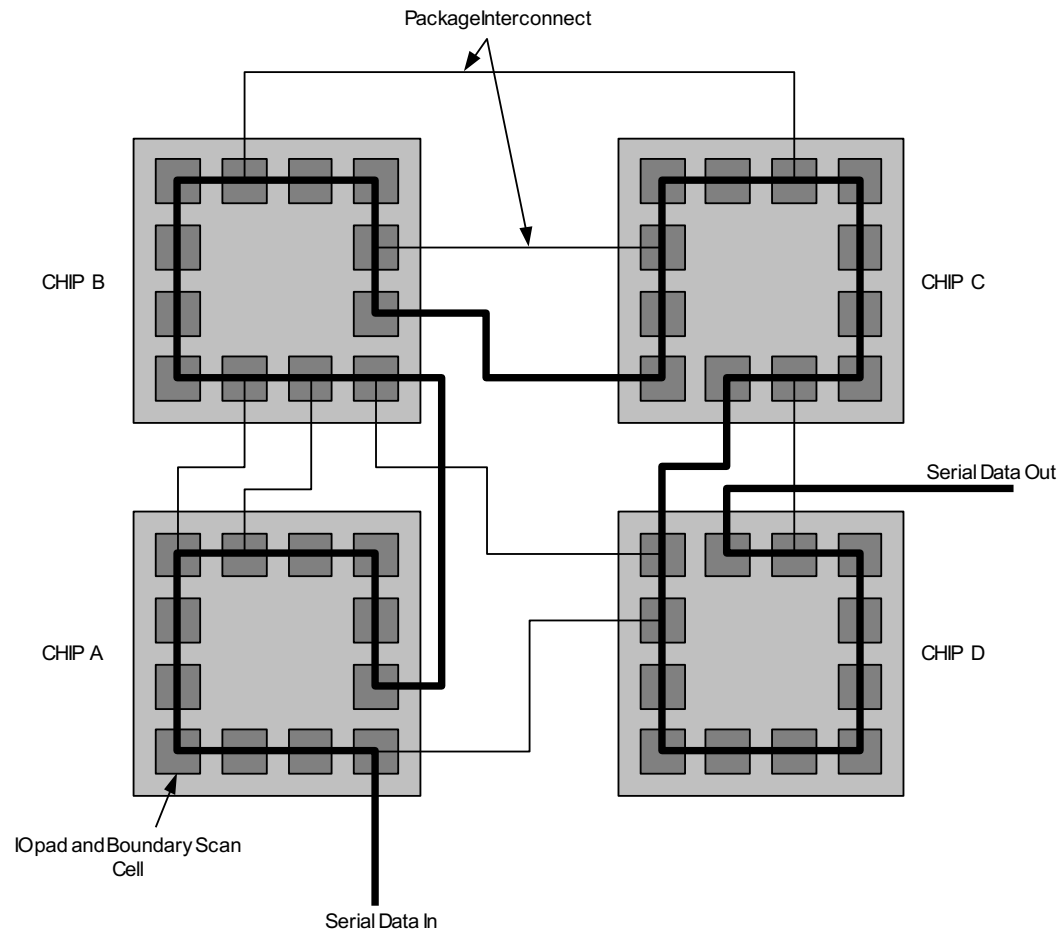
- ❑ Built-in Logic Block Observer
 - Combine scan with PRSG & signature analysis



Boundary Scan

- ❑ Testing boards is also difficult
 - Need to verify solder joints are good
 - Drive a pin to 0, then to 1
 - Check that all connected pins get the values
- ❑ Through-hole boards used “bed of nails”
- ❑ SMT and BGA boards cannot easily contact pins
- ❑ Build capability of observing and controlling pins into each chip to make board test easier

Boundary Scan Example



Boundary Scan Interface

- ❑ Boundary scan is accessed through five pins
 - TCK: test clock
 - TMS: test mode select
 - TDI: test data in
 - TDO: test data out
 - TRST*: test reset (optional)

- ❑ Chips with internal scan chains can access the chains through boundary scan for unified test strategy.

Testing Your Design

❑ Presilicon Verification

- Test vectors: corner cases and random vectors
- HDL simulation of schematics for functionality
- Use 2-phase clocking to avoid races
- Use static CMOS gates to avoid electrical failures
- Use LVS to ensure layout matches schematic

❑ Postsilicon Verification

- Run your test vectors on the fabricated chip
- Use a functional chip tester
- Potentially use breadboard or PCB for full system

Summary

- ❑ Think about testing from the beginning
 - Simulate as you go
 - Plan for test after fabrication

- ❑ “If you don’ t test it, it won’ t work! (Guaranteed)”