

Part1a

1 Derivation of 2-body interaction

$$\begin{aligned}
V &= \frac{1}{2} \sum_{p\sigma_p, q\sigma_q, r\sigma_r, s\sigma_s} \langle p\sigma_p, q\sigma_q | v | r\sigma_r, s\sigma_s \rangle a_{p\sigma_p}^\dagger a_{q\sigma_q}^\dagger a_{s\sigma_s} a_{r\sigma_r} \\
&= \frac{1}{2} \sum_{p\sigma_p, r} \langle p\sigma_p, p - \sigma_p | v | r\sigma_p, r - \sigma_p \rangle a_{p\sigma_p}^\dagger a_{p-\sigma_p}^\dagger a_{r-\sigma_p} a_{r\sigma_p} \\
&= \frac{1}{2} \sum_{p\sigma_p, r} (-g) a_{p\sigma_p}^\dagger a_{p-\sigma_p}^\dagger a_{r-\sigma_p} a_{r\sigma_p} \\
&= \frac{1}{2} \sum_{p, r} (-g) \left(\left(a_{p+}^\dagger a_{p-}^\dagger a_{r-} a_{r+} \right) + \left(a_{p-}^\dagger a_{p+}^\dagger a_{r+} a_{r-} \right) \right) \\
&= \frac{1}{2} \sum_{p, r} (-g) \left(\left(a_{p+}^\dagger a_{p-}^\dagger a_{r-} a_{r+} \right) + (-1)^2 \left(a_{p+}^\dagger a_{p-}^\dagger a_{r-} a_{r+} \right) \right) \\
&= -g \sum_{p, r} a_{p+}^\dagger a_{p-}^\dagger a_{r-} a_{r+} \\
&\equiv -g \sum_{p, r} P_p^+ P_r^-.
\end{aligned}$$

2 Commutation relation

2.1 useful relation

$$\begin{aligned}
[A, BC] &= B[A, C] + [A, C]B, \\
\{A, BC\} &= B\{A, C\} - \{A, C\}B,
\end{aligned}$$

then

$$[AB, CD] = A\{B, C\}D - \{A, C\}BD + CA\{B, D\} - C\{A, D\}B.$$

2.2 S_z vs H_0

By making use of the relation in sec.2.1, we get

$$\begin{aligned}
[S_z, H_0] &= \sum_{p\sigma_p} \frac{\sigma_p}{2} \sum_{q\sigma_q} (q-1) [a_{p\sigma_p}^\dagger a_{p\sigma_p}, a_{q\sigma_q}^\dagger a_{q\sigma_q}] \\
&= \sum_{p\sigma_p} \frac{\sigma_p}{2} \sum_{q\sigma_q} (q-1) \delta_{p,q} \delta_{\sigma_p, \sigma_q} \left(a_{p\sigma_p}^\dagger a_{q\sigma_q} - a_{q\sigma_q}^\dagger a_{p\sigma_p} \right) \\
&= \sum_{p\sigma_p} \frac{\sigma_p}{2} (p-1) \left(a_{p\sigma_p}^\dagger a_{p\sigma_p} - a_{p\sigma_p}^\dagger a_{p\sigma_p} \right) \\
&= 0.
\end{aligned}$$

2.3 S^2 vs H_0

By making use of the relation in sec.2.1, we get

$$\begin{aligned}
[S_+, H_0] &= \sum_{p\sigma_p} (p-1) [a_{p+}^\dagger a_{p-}, a_{p\sigma_p}^\dagger a_{p\sigma_p}] \\
&= \sum_{p\sigma_p} (p-1) \left(-\delta_{\sigma_p+} a_{p\sigma_p}^\dagger a_{p-} + \delta_{\sigma_p-} a_{p+}^\dagger a_{p\sigma_p} \right) \\
&= \sum_p (p-1) \left(-a_{p+}^\dagger a_{p-} + a_{p+}^\dagger a_{p-} \right) \\
&= 0,
\end{aligned}$$

$$[S_-, H_0] = (-[S_+, H_0])^\dagger = 0,$$

therefore we get

$$\begin{aligned}
[S^2, H_0] &= [S_z^2 + \frac{1}{2}(S_+ S_- + S_- S_+), H_0] \\
&= [S_z, H_0] S_z + S_z [S_z, H_0] + \frac{1}{2} ([S_+, H_0] S_- + S_+ [S_-, H_0] + [S_-, H_0] S_+ + S_- [S_+, H_0]) \\
&= 0.
\end{aligned}$$

2.4 S_z vs V

By making use of the relation in sec.2.1, we get

$$\begin{aligned}
[P_p^+, S_z] &= \sum_{\sigma_p} \frac{\sigma_p}{2} [a_{p+}^\dagger a_{p-}^\dagger, a_{p\sigma_p}^\dagger a_{p\sigma_p}] \\
&= \sum_{\sigma_p} \frac{\sigma_p}{2} \left(a_{p\sigma_p}^\dagger a_{p+}^\dagger \delta_{\sigma_p-} - a_{p\sigma_p}^\dagger a_{p-}^\dagger \delta_{\sigma_p+} \right) \\
&= \left(-\frac{1}{2} \right) a_{p-}^\dagger a_{p+}^\dagger - \left(\frac{1}{2} \right) a_{p+}^\dagger a_{p-}^\dagger \\
&= 0,
\end{aligned}$$

$$[P_p^-, S_z] = (-[P_p^+, S_z])^\dagger = 0,$$

therefore we get

$$\begin{aligned} [S_z, V] &= -g \sum_{p,q} [S_z, P_p^+ P_q^-] \\ &= -g \sum_{p,q} ([S_z, P_p^+] P_q^- + P_p^+ [S_z, P_q^-]) \\ &= 0. \end{aligned}$$

2.5 S^2 vs V

By making use of the relation in sec.2.1, we get

$$\begin{aligned} [P_p^+, S_+] &= [a_{p+}^\dagger a_{p-}^\dagger, a_{p+}^\dagger a_{p-}] \\ &= a_{p+}^\dagger a_{p+}^\dagger \{a_{p-}^\dagger, a_{p-}\} \\ &= 0 \end{aligned}$$

and

$$\begin{aligned} [P_p^-, S_+] &= (a_{p-} a_{p+}, a_{p+}^\dagger a_{p-}) \\ &= a_{p-} \{a_{p+}, a_{p+}^\dagger\} a_{p-} \\ &= 0, \end{aligned}$$

then

$$\begin{aligned} [S_+, V] &= -g \sum_{p,q} [S_+, P_p^+ P_q^-] \\ &= -g \sum_{p,q} ([S_+, P_p^+] P_q^- + P_p^+ [S_+, P_q^-]) \\ &= 0, \end{aligned}$$

$$[S_-, V] = (-[S_+, V])^\dagger = 0.$$

Therefore we get

$$\begin{aligned} [S^2, V] &= [S_z^2 + \frac{1}{2}(S_+ S_- + S_- S_+), V] \\ &= [S_z, V] S_z + S_z [S_z, V] + \frac{1}{2} ([S_+, V] S_- + S_+ [S_-, V] + [S_-, V] S_+ + S_- [S_+, V]) \\ &= 0. \end{aligned}$$