

```
cd ..
make -f makefile-Tnum
cd $ici
```

Some parameters for the compilation

```
../Tnum.exe << ** > res
&geom
```

Useful parameters to define coordinates:

zmat=t: coordinates defined with a zmatrix

nat: number of atoms

**sym: if t, enables to perform linear combination of coordinates**

```
zmat=T
nat=3
sym=t
```

### Zmatrix:

The integers are the numbers of the previously defined atoms.

You can change the atomic symbol by a mass (real)

```
/
O
H 1
H 1 2
sym R+ R- a
3
1 1. 1. 0.
2 1. -1. 0.
3 0. 0. 1.
```

Defined the linear transformation between the z-matrix (Qzmat) and the symmetrized (Qsym) coordinates (see below)

```
1 0 0
&niveau
```

List of 3nat-6 numbers:

1 active coordinates

0 frozen coordinates

```
nrho=2
read_nameQ=t
unit='angs'
```

nrho helps to define the volume element:

0: Euclidian (rho=jacobian)

1: Wilson (rho=1)

2: product of 1D-volume element: dR.dphi.sin(th)dth...

```
/
R+ 1.
R- 0.
a 90.
**
```

read\_nameQ: if t, reads the name of the variables

unit='angs' => uses angstrom instead of bohr radian

Name and value of variable in the sym order (Qsym0).

For the symmetrization, we need to set up the linear relation between the z-matrix coordinates and the symmetrized ones:

$$Q_{\text{zmat}}(i) = \sum_k \text{Mat}(i,k) * Q_{\text{sym}}(k)$$

Just the matrix  $\text{Mat}(i,k)$  is needed ( $3N-6 \times 3N-6$ ). It is given in the following way:

After the last atom of the z-matrix :

A comment line (not read) used to remember the order of the symmetrized coordinates (here : R+ R- a)

```
sym  R+   R-   a
```

Then, an integer, n (usually the  $3N-6$ ). If n is smaller than  $3N-6$ , the matrix will be read in several block of n columns. Here  $n=3$

```
3
```

Then, the matrix itself. The symmetrized coordinates are in the columns and the z-matrix ones in the lines. In the first column, integers to count the lines.

For the water :

```
1      1.      1.      0.
2      1.     -1.      0.
3      0.      0.      1.
```

Therefore:

$Q_{\text{zmat}}(1) = \text{ROH1} = 1. Q_{\text{sym}}(1) + 1. Q_{\text{sym}}(2)$

$Q_{\text{zmat}}(2) = \text{ROH2} = 1. Q_{\text{sym}}(1) - 1. Q_{\text{sym}}(2)$

$Q_{\text{zmat}}(3) = \text{aHOH} = Q_{\text{sym}}(3)$

With  $Q_{\text{sym}}(1) = \text{R+}$  (symmetric stretch)

$Q_{\text{sym}}(2) = \text{R-}$  (antisymmetric stretch)

$Q_{\text{sym}}(3) = \text{a}$  (bending HOH)

**Be careful:** You can mix only the coordinates with the same "type" (distance, valence angle, dihedral angles). For example, you cannot mix an angle and a distance.