# Two Dimensional Algorithm

### **Output Primitives**

- The *basic building blocks for pictures* are referred to as output primitives.
- Output primitives are the geometric structures that used to describe the shapes and colors of the objects.
- They include character strings, and geometric entities such as points, straight lines, curved lines, polygons, circles etc.
- Points and straight line segments are the most basic components of a picture.
- In raster scan systems, a picture is completely specified by the set of intensities for the pixel positions in the display. The process that converts picture definition into a set of pixel intensity values is called scan conversion. This is done by display processor.

### **Lines and Points**

- With raster-scan system, a point can be plotted, by simply turning on the electron beam at that point.
  - putpixel(20, 20, RED)
- And a random-scan system stores the point plotting instructions in the display list file.

```
    Load data value 100 into the X register.
```

-LDYAP 450 Draw point at(100, 450)

- In raster scan systems line drawing is accomplished by calculating the intermediate positions along the line path between two specified endpoints.
- In random scan systems, line drawing is accomplished by retrieving line drawing commands from the display list.
- Scan lines are numbered consecutively from 0, starting at the bottom of the screen; and pixel columns are numbered from 0, from left to right across each scan line.

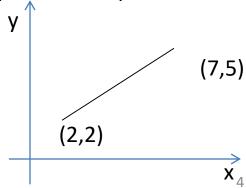
### **Points and Lines**

#### Points

 Plotted by converting co-ordinate position to appropriate operations for the output device (e.g.: in CRT monitor, the electron beam is turned on to illuminate the screen phosphor at the selected location.)

#### Line

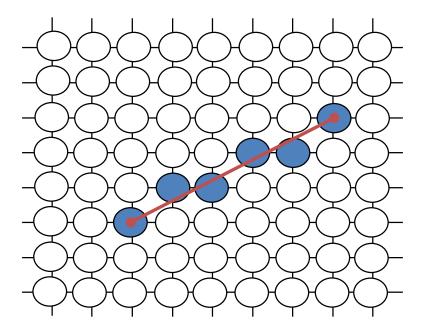
- A line segment in a scene is defined by the coordinate positions of the line end-points
- Plotted by calculating intermediate positions along the line path between two specified endpoint positions.
- Screen locations are referenced with integer values, so plotted positions may only approximate actual line positions between two specified endpoints.
- E.g. position (10.48,20.51)  $\rightarrow$  (10,21).



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### The Problem.....

 But what happens when we try to draw this on a pixel based display?



How do we choose which pixels to turn on?

### Consideration

- Considerations to keep in mind:
  - The line has to look good
    - Avoid jaggies (i.e. the rounding of coordinates values to integers causes lines to be displayed with a stairstep appearance as represented in the figure)
  - It has to be lightening fast!
    - How many lines need to be drawn in a typical scene?

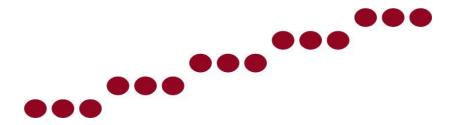


Figure: Stairstep effect (jaggies) produced when a line is generated as a series of pixel position.

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# Line Drawing Algorithms

- Direct use of Line Equation
- Digital Differential Analyzer Algorithm(DDA)
- Bresenham's Line Drawing Algorithm(BSA)

# Direct Use of Line Equation

The slope-intercept equation of a straight line is:

$$y = mx + b$$

where, m = slope of line and, b = y-intercept.

- For any two given points (x<sub>1</sub>, y<sub>1</sub>) and (x<sub>2</sub>, y<sub>2</sub>)
- slope (m) =  $\frac{(y_2 y_1)}{(x_2 x_1)}$

 $b = y_1 - m.x_1$  i.e. from above equation

At any point (x<sub>k</sub>, y<sub>k</sub>)

$$y_k = mx_k + b \dots 1$$

• At  $(x_{k+1}, y_{k+1})$ ,

$$y_{k+1} = mx_{k+1} + b \dots 2$$

Subtracting 1 from 2 we get,

$$y_{k+1} - y_k = m (x_{k+1} - x_k)$$

• Here  $(y_{k+1} - y_k)$  incremental in y as corresponding increment in x.

therefore, 
$$\Delta y = m.\Delta x$$
 or  $\Delta x = \frac{\Delta y}{m}$ 

- For incremental algorithm in line drawing,
  - Increment x by 1
  - Computer corresponding y and display pixel at position ( $x_{i,j}$  round ( $y_{i,j}$ )

For |m| <1

• Set  $\Delta x$  proportional to horizontal deflection voltage. Then

$$\Delta y = m.\Delta x$$

For |m|>1

• Set  $\Delta y$  set proportional to vertical deflection voltage. Then

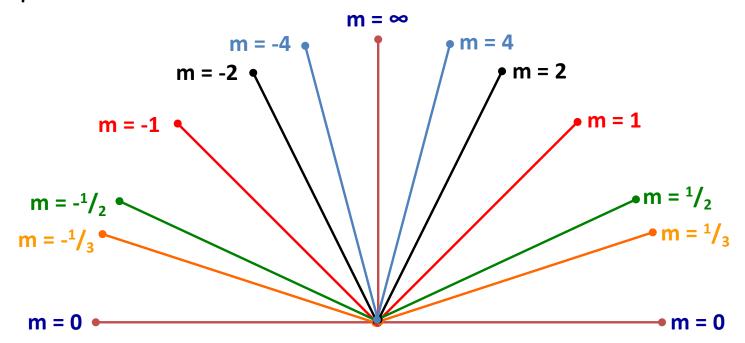
$$\Delta x = \frac{\Delta y}{m}$$

For |m|=1

•  $\Delta x = \Delta y \rightarrow$  horizontal and vertical deflection voltages are equal

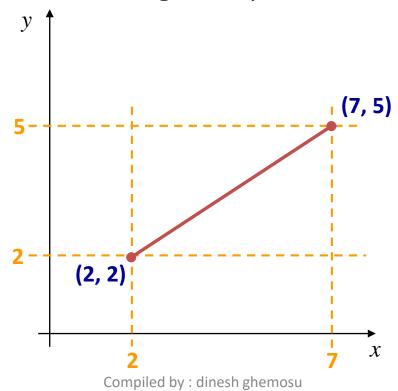
# Lines and Slopes

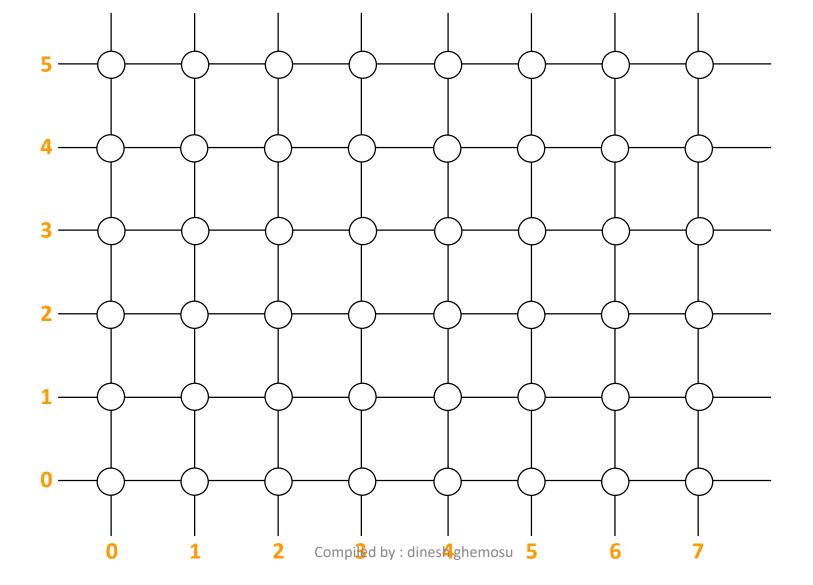
- The slope of a line (m) is defined by its start and end coordinates
- The diagram below shows some examples of lines and their slopes

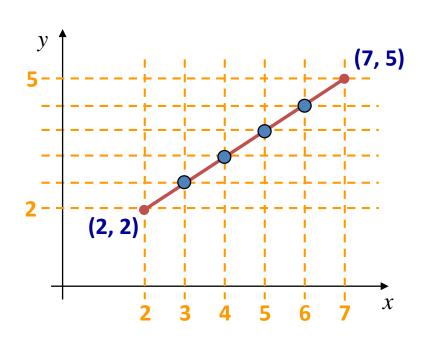


# A very simple solution

- We could simply work out the corresponding y coordinate for each unit x coordinate
- Let's consider the following example:







• First work out *m* and *b*:

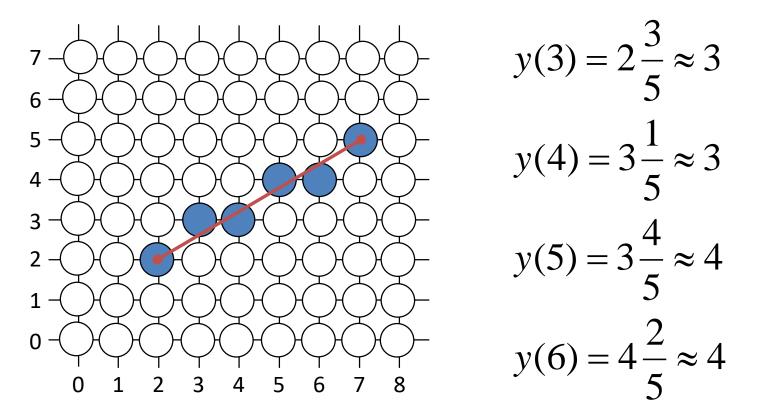
$$m = \frac{5-2}{7-2} = \frac{3}{5}$$

$$b = 2 - \frac{3}{5} * 2 = \frac{4}{5}$$

Now for each x value work out the y value:

$$y(3) = \frac{3}{5} \cdot 3 + \frac{4}{5} = 2\frac{3}{5} \qquad y(4) = \frac{3}{5} \cdot 4 + \frac{4}{5} = 3\frac{1}{5}$$
$$y(5) = \frac{3}{5} \cdot 5 + \frac{4}{5} = 3\frac{4}{5}$$

 Now just round off the results and turn on these pixels to draw our line.



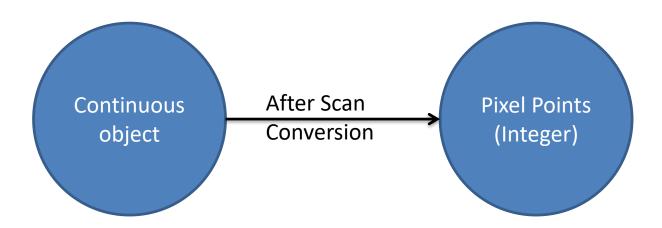
### Some Terms

#### **Vector Generation**

On our raster system, we can generate images by turning the pixels ON or OFF. The
process of turning ON of the pixel for a line segment is called as Vector
Generation.

#### **Scan Conversion**

 The process of conversion of the rasterized picture stored in a frame buffer to the rigid display pattern of video is called as scan conversion.



# DDA Algorithm

• Digital Differential Analyzer (DDA) is a scan conversion line drawing algorithm based on calculating either  $\Delta x$  or  $\Delta y$  from the equation

$$\Delta y = m. \Delta x$$

 We sample the line at unit intervals in one coordinate and determine the corresponding integer values nearest the line path in another co-ordinate.

# Consider a line with positive slope and <u>proceed from</u> <u>left to right</u>

### Case I:

- If m <= 1, we sample x-coordinate. So  $\Delta x = 1$  and compute each successive y values as:  $\Delta x = x_{k+1} x_k = 1$ 
  - $y_{k+1} = y_k + m$  where  $m = \frac{y_{k+1} y_k}{x_{k+1} x_k} = \frac{\Delta y}{\Delta x}$
  - Here k takes from starting point and increase by 1 until final end point.
  - m can be any real value between 0 and 1.

### Case II:

• If m>1, we sample  $\Delta y = 1$  and calculate corresponding x value as:  $x_{k+1} = x_k + \frac{1}{m}$   $\Delta y = y_{k+1} - y_k = 1$ 

Consider a line with positive slope that proceed from right to left.

### Case I:

• If |m| <= 1, we sample  $\Delta x = -1$  and calculate  $y_{k+1} = y_k - m$ 

### Case II:

• If |m|>1, we sample  $\Delta y = -1$  and calculate

$$x_{k+1} = x_k - \frac{1}{m}$$

### DDA Algorithm

```
Step 1: Input the line endpoints and store the left endpoint in (x_1, y_1) and right endpoint in (x_2, y_2).
Step 2: Calculate the values of dx and dy, dx = x_2 - x_1, dy = y_2 - y_1.
Step 3: if(abs(dx) > abs(dy))
                  steplength = abs(dx)
              else
                  steplength = abs(dy)
Step 4: Calculate the values of x-increment and y-increment.
                  xIncrement = dx/ steplength
                  yIncrment = dy/ steplength
Step 5:Set x = x_1 and y = y_1
Step 6: Plot(x, y).
Step 7: for k=1 to steplength do

 x = x + xIncrement

       y = y + yIncrement
```

Step 8: End

Perform round off, and plot each calculated (x, y) i.e. Plot(round(x), round(y)).

# Advantages of DDA Algorithm

- Faster than direct use of the line equation since it calculates the line without any floating point multiplication i.e. only integer calculations.
- Simplest algorithm since does not require special skills for its implementation

# Disadvantages of DDA Algorithm

- It is orientation dependent, due to this, the point accuracy is poor.
- A floating point addition is still needed in determining each successive point which is time consuming.
- Involves, continuous round offs which can cause the calculated pixel positions to drift away from the actual line path. It causes jaggies.

### DDA Algorithm

```
Step 1: Input the line endpoints and store the left endpoint in (x_1, y_1) and right endpoint in (x_2, y_2).
```

Step 2: Calculate the values of dx and dy,  $dx = x_2 - x_1$ ,  $dy = y_2 - y_1$ .

```
Step 3: if( abs(dx) > abs(dy))
```

steplength = abs(dx)

else

steplength = abs(dy)

Step 4: Calculate the values of x-increment and y-increment.

xIncrement = dx/ steplength
yIncrment = dy/ steplength

Step 5:Set  $x = x_1$  and  $y = y_1$ 

Step 6: Plot(x, y).

Step 7: for k=1 to *steplength* do

x = x + xIncrement

y = y + yIncrement

Perform round off, and plot each calculated (x, y) i.e. Plot(round(x), round(y)).

Step 8: End

# Digitize the line with endpoints (1, 5) and (7, 2) using DDA algorithm.

Here, dx = 7-1=6, and dy = 2-5 = -3, So, steplength = 6 (since abs(dx)>abs(dy)). Therefore, xIncrement = dx/steplength = 6/6 = 1, and yIncrement = dy/steplength = -3/6 = -1/2 = -0.5

Based on these values the intermediate pixel calculation is shown in the table below.

k	X <sub>k+1</sub>	<b>y</b> <sub>k+1</sub>	(x <sub>k+1</sub> , y <sub>k+1</sub> )	Plot in screen (x <sub>k+1</sub> , y <sub>k+1</sub> )
1	2	4.5	(2, 4.5)	(2, 5)
2	3	4	(3, 4)	(3, 4)
3	4	3.5	(4, 3.5)	(4,4)
4	5	3	(5,3)	(5,3)
5	6	2.5	(6,2.5)	(6,3)
6	7	2	(7,2)	(7,2)

### Questions

- Consider a line from (0, 0) to (6, 7). Using simple DDA algorithm, rasterize this line.
- Digitize the line with endpoints (1, -6) and (4, 4) using DDA algorithm.
- Digitize the line with endpoints (1, 6), (6, 10) using DDA algorithm.
- Trace DDA algorithm for line with endpoints (1, 2), (5, 6).
- Trace DDA algorithm for endpoints (1, 7), (6, 3).