

working with time series

Autoregressive (AR) Models

$$X_t = \varepsilon_t + \phi_1 X_{t-1} + \dots + \phi_p X_{t-p}$$

The above generally states that today's value is slightly different from a combination of the last few day's values.

Autocorrelated Models are stationary, but the same cannot be said for Autoregressive Models.

The stationary nature of Autoregressive Models (AR) is dependent on the parameters:

Example Simulation:

Assuming 50,000 noise values generated from $N(0,1)$ (normal distribution with mean μ of 0 and variance σ^2 of 1) to be $\varepsilon_1, \dots, \varepsilon_{50,000}$

$$X_1 = \varepsilon_1$$

For $t = 2$ to 50,000:

$$X_t = \varepsilon_t + 0.5X_{t-1}$$

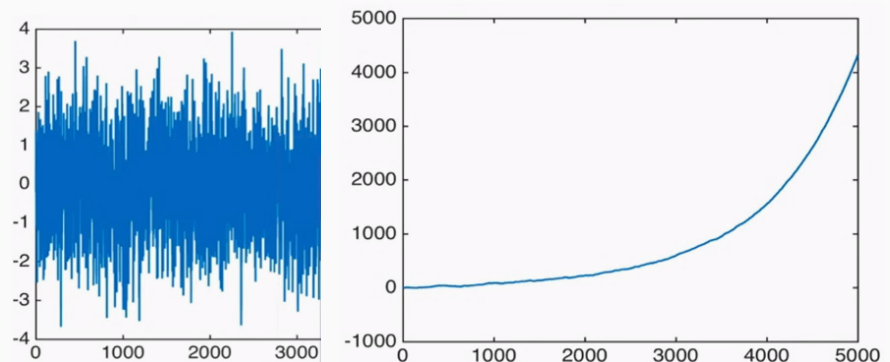
→ appears stationary

$$X_t = \varepsilon_t + 1.001X_{t-1}$$

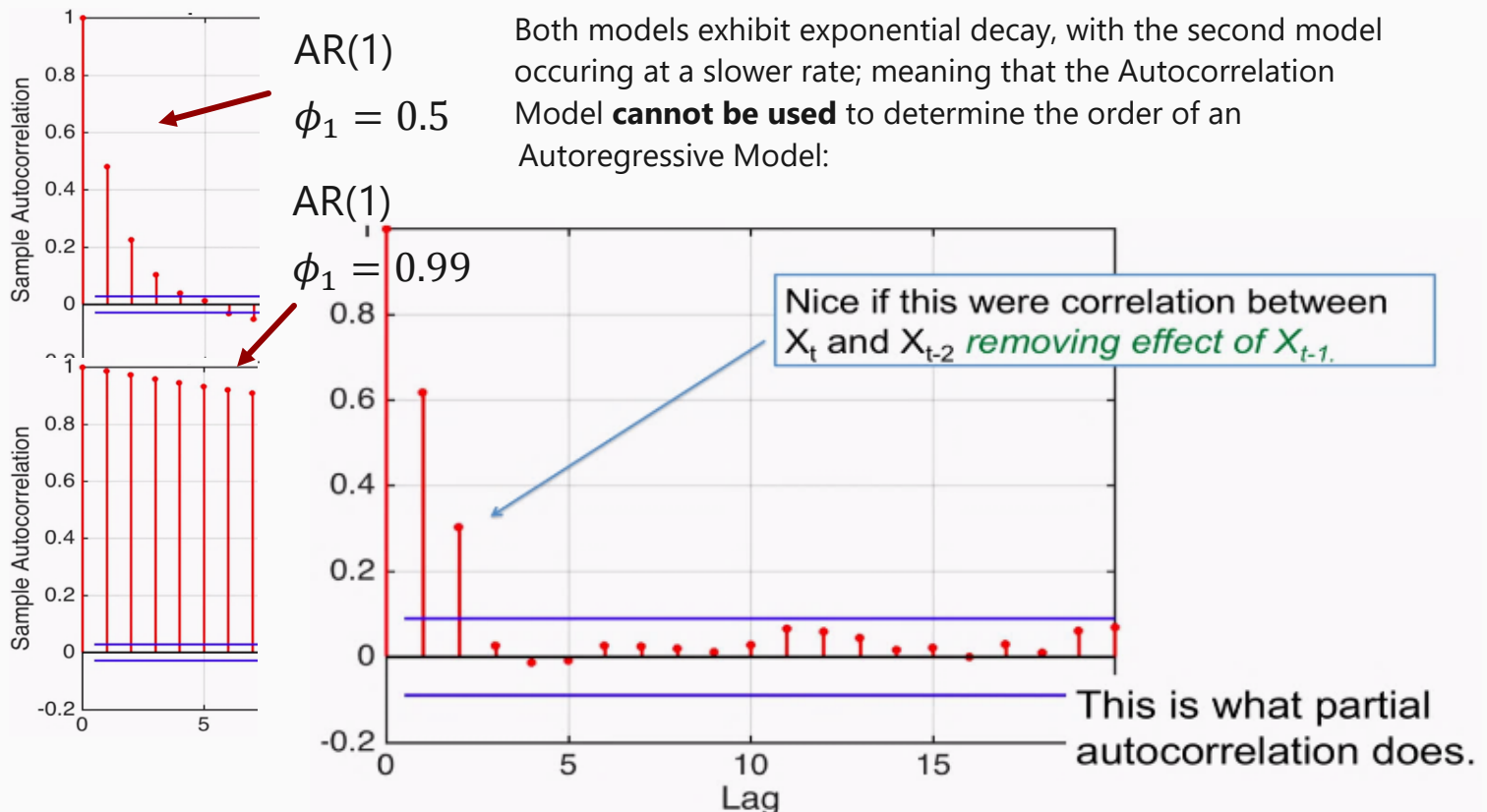
→ appears exponential (positive)

$$X_t = \varepsilon_t + 0.999X_{t-1}$$

→ appears exponential (negative)



Determining the stationary nature of an Autoregressive Model by examining Autocorrelated Models:



Because Autocorrelation experiences exponential decay, the order of an Autoregressive Model cannot be determined when evaluating the stationary nature of the data. Instead, the Partial Autocorrelation function is examined for stationary inference of the data

Partial Autocorrelation

The Partial Autocorrelation of X_1 and X_{t-u} is the correlation not accounted for by lags $1, \dots, u-1$:

Written in terms of lag (u): $\text{PartialAutoCorr}(u) = \text{Cor}(X_t, X_{t-u} \mid X_{t-1}, \dots, X_{t-(u+1)})$

The PAC is the correlation between X_t and X_{t-u} given everything that happened in between the two.

Using the Sleep Model as a working example (the effect of sleep 2 nights ago on tonight's sleep):

In terms of order 2: $\text{PartialAutoCorr}(2) = \text{Cor}(X_t, X_{t-2} \mid X_{t-1})$

→ The correlation between tonight's sleep and two nights ago that is not accounted for last night

To compute the Partial Autocorrelation: Predict correction to X_t from X_{t-1} : $\hat{X}_t = \beta_1 X_{t-1}$

β_1 is the correlation between X_t and X_{t-1} .

\hat{X}_t is predicted based upon the sole fact that X_t is correlated with X_{t-1} .

All predict correction to X_{t-2} from X_{t-1} : $\hat{X}_{t-2} = \beta_1 X_{t-1}$

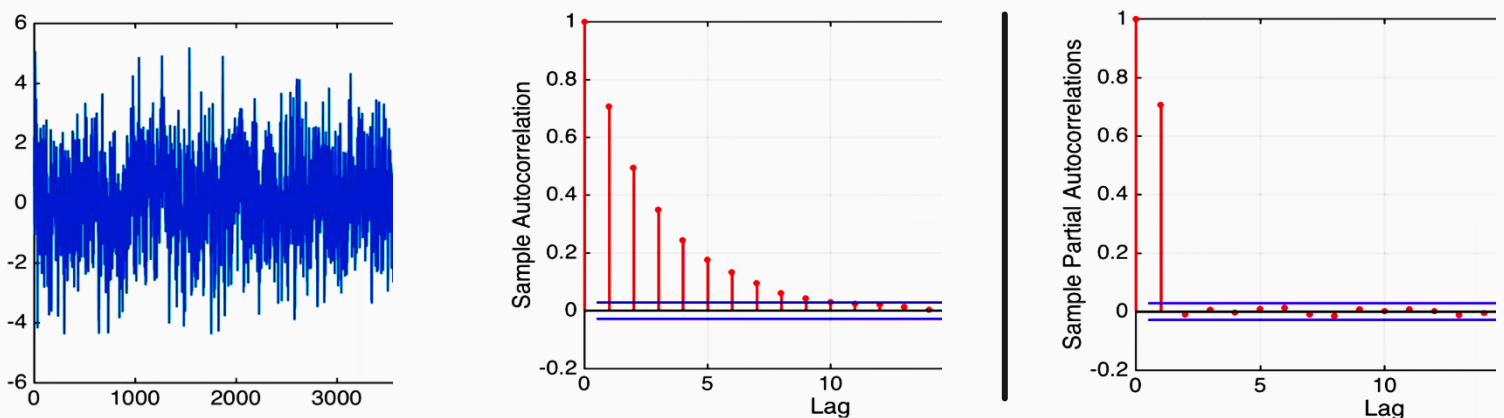
β_1 is the correlation between X_{t-2} and X_{t-1} , which is that same as the correlation between X_t and X_{t-1} . This is attributed to the stationary nature of the series (mean and variance constant)

In terms of order 2: $\text{PartialAutoCorr}(2) = \text{Cor}(X_t - \hat{X}_t, X_{t-2} - \hat{X}_{t-2})$

the above formulates the question that arises: Is it possible to use what cannot be explained about X_{t-2} from X_{t-1} to predict what cannot be explained about X_t from X_{t-1} ?

The Partial Autocorrelation computes the correlation of the prediction error at time t and the prediction error at time $t-2$.

For example: assuming the model $X_1 = \varepsilon_1 + 0.7X_{t-1}$ and stationary timeseries data:



the Sample Autocorrelation Model is not useful as expected, other than proving that the model is not a true moving average model (or else the Sample Autocorrelation plot would have a cutoff). The exponential decay additionally hints the data is an Autoregressive Model (with order still unknown). In contrast, the Sample Partial Autocorrelation Function depicts an order of 1 (AR(1)) due to a single non-zero term in the Partial Autocorrelation Function.

in general terms (u):

$$\text{PartialAutoCorr}(u) = \text{Cor}(X_t - \hat{X}_t, X_{t-u} - \hat{X}_{t-u})$$

The Partial Autocorrelation for lag u is the correlation between the prediction error at time t and the prediction error at time $t-u$; where allowed to explain X_t and X_{t-u} using **everything** in between:

$$\begin{aligned}\hat{X}_t &= \beta_1 X_{t-1} + \beta_2 X_{t-2} + \dots + \beta_{u-1} X_{t-(u-1)} \\ \hat{X}_{t-u} &= \beta_1 X_{t-(u+1)} + \beta_2 X_{t-(u+2)} + \dots + \beta_{u-1} X_{t-1}\end{aligned}$$

The least squares method will be used to determine the value of the β 's

Example: use a linear model to predict from the lags:

$$\hat{X}_t = \beta_1 X_{t-1} + \beta_2 X_{t-2} + \dots + \beta_{u-1} X_{t-(u-1)}$$

use least squares to get the coefficients in a minimized error fashion: $\min_{\beta_0, \beta_1, \dots, \beta_{u-1}} (\hat{X}_t - X_t)^2$

then use a linear model to predict X_{t-u} from the lags:

$$\hat{X}_{t-u} = \beta_1 X_{t-(u+1)} + \beta_2 X_{t-(u+2)} + \dots + \beta_{u-1} X_{t-1}$$

the coefficients are the same in both models because least squares is about correlations (which are not directed forward or backwards in time; no directionality):

$$\text{PartialAutoCorr}(u) = \text{Cor}(X_t - \hat{X}_t, X_{t-u} - \hat{X}_{t-u})$$

The Partial Autocorrelation describes the unexplained part of X_t from the unexplained part of X_{t-u} ; where explanations are derived from all of the lags in between.

Theoretical Summary of Autoregressive Models:

- AR models are not always stationary; this depends on the parameters
- The autocorrelation functions for stationary AR(p) models experiences exponential decay and thus, order cannot be determined
- The partial autocorrelation for stationary (AR(p) models experiences a strict cutoff at (p) and thus, the order can effectively be determined

