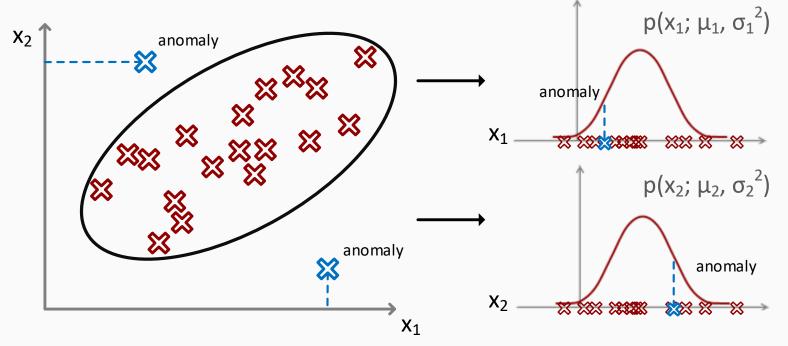
# multivariate gaussian L distribution

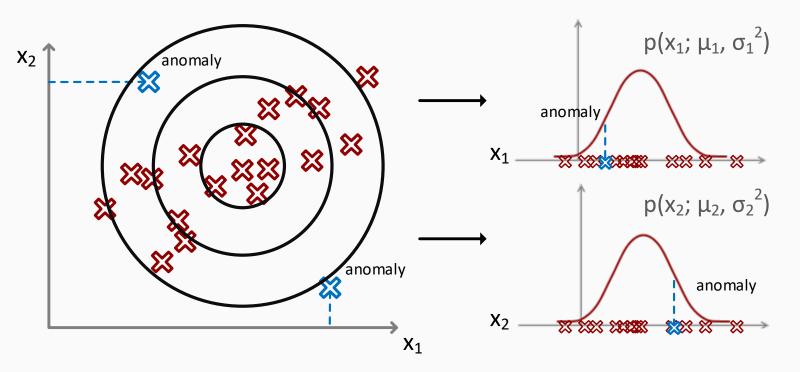
certain instances of single variable gaussian distribution might register examples amongst separtaley evaluated features as normal or non-anomalous. There are instances in which a multivariate gausian distribution would otherwise detect anomaly within a dataset that otherwise would have been misclassified elsewhere

multivariate gaussian model classification (left):



both variables plotted with a single variable gausian distribution algorithm would identify the anomolous probability regions not as the ellispe is shown in the above left illustration but as a serious of circles representative of the distributions'  $\sigma$ 

single variable gaussian distribution (left):



 $x \in \mathbb{R}^n$ , do not model multiple variables  $p(x_1, x_2, ..., x_n)$  separately. model p(x) together at once.

parameters:  $\mu \in \mathbb{R}^n$ ,  $\Sigma \in \mathbb{R}^{n \times n}$  covariance matrix

$$p(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\right)$$
$$|\Sigma| = \text{determinant of } \Sigma \mid \text{det(Sigma)}$$

effects of transforming parameters in  $p(x; \mu, \Sigma)$ 

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 0.6 & 0 \\ 0 & 0.6 \end{bmatrix} \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

$$x_2 \qquad x_1 \qquad x_2 \qquad x_2 \qquad x_1 \qquad x_2 \qquad x_2 \qquad x_2 \qquad x_1 \qquad x_2 \qquad x_3 \qquad x_4 \qquad x_4 \qquad x_4 \qquad x_4 \qquad x_4 \qquad x_4 \qquad x_5 \qquad$$

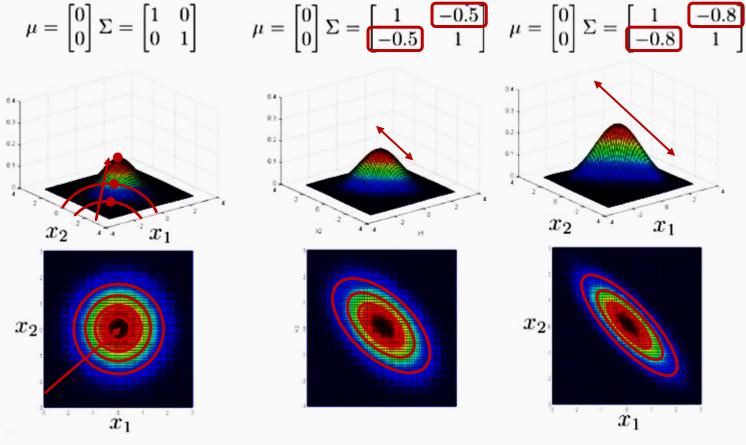
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 0.6 \end{bmatrix} \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

multivariate gaussian distribution can measure correlation amongst features:

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix} \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0.8 \\ 0.8 & 1 \end{bmatrix}$$

$$x_2$$

in contrast when sigma  $\Sigma$  is set to negative values:

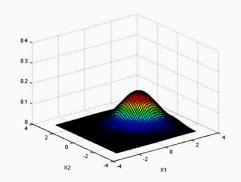


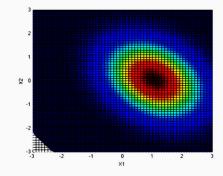
additionally, the  $\mu$  parameter can also be varied:

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \mu = \begin{bmatrix} 0 \\ 0.5 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \mu = \begin{bmatrix} 1.5 \\ -0.5 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$x_{2}$$

Consider the following multivariate Gaussian:





Which of the following are the  $\mu$  and  $\Sigma$  for this distribution?

$$\mu = egin{bmatrix} 1 \ 0 \end{bmatrix}, \ \Sigma = egin{bmatrix} 1 & 0.3 \ 0.3 & 1 \end{bmatrix}$$

$$\mu = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \ \Sigma = \begin{bmatrix} 1 & 0.3 \\ 0.3 & 1 \end{bmatrix}$$

• 
$$\mu = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
,  $\Sigma = \begin{bmatrix} 1 & -0.3 \\ -0.3 & 1 \end{bmatrix}$ 

**Correct Respons** 

$$\mu = egin{bmatrix} 0 \ 1 \end{bmatrix}, \ \Sigma = egin{bmatrix} 1 & -0.3 \ -0.3 & 1 \end{bmatrix}$$

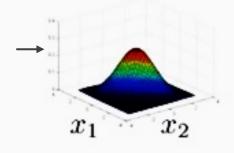
## anaomaly detection using the multivariate gaussian distribution

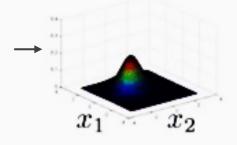
multivariate gaussian (normal) distribution

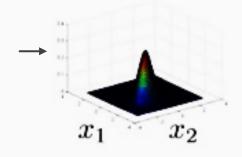
parameters  $\mu$ ,  $\Sigma$ 

$$\mu \in \mathbb{R}^2$$
 and  $\sigma \in \mathbb{R}^2$ 

$$p(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\right)$$







parameter fitting:

given training set  $\{x^{(1)}, x^{(2)}, ..., x^{(m)}\} \leftarrow x \in \mathbb{R}^n$ 

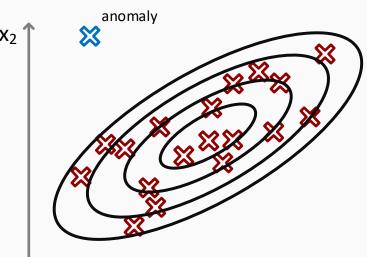
$$\mu = \frac{1}{m} \sum_{i=1}^{m} x^{(i)}$$
 and  $\Sigma = \frac{1}{m} \sum_{i=1}^{m} (x^{(i)} - \mu)(x^{(i)} - \mu)^{T}$ 

### anamoly detection with multvariate gaussian

1) Fit the model p(x) by setting

$$\mu = \frac{1}{m} \sum_{i=1}^{m} x^{(i)}$$

$$\Sigma = \frac{1}{m} \sum_{i=1}^{m} (x^{(i)} - \mu) (x^{(i)} - \mu)^{T}$$



2) given a new example x, compute

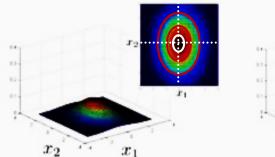
$$p(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\right)$$

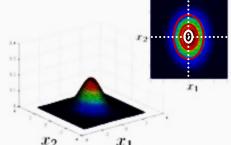
flag an anomaly if  $p(x) < \varepsilon$ 

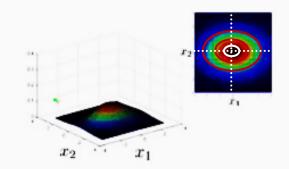
relationship to the original single variable model

original model: 
$$p(x) = p(x_1; \mu_1, \sigma_1^2) \times p(x_2; \mu_2, \sigma_2^2) \times ... \times p(x_n; \mu_n, \sigma_n^2)$$

$$= \prod_{j=1}^n p(x_j; \mu_j, \sigma_j^2)$$







the original model corresponds to multivariate gaussians, where the contours of the gaussian are always axis aligned.

constraint: 
$$\Sigma = \begin{bmatrix} \sigma_1 & \sigma_1 & \sigma_2 & \sigma_1 \\ 0 & \sigma_1^2 & 0 & \sigma_1 \\ 0 & 0 & \ddots & \sigma_n^2 \end{bmatrix}$$

### original model

$$p(x_1; \mu_1, \sigma_1^2) \times ... \times p(x_n; \mu_n, \sigma_n^2)$$

manually create features to capture anomalies where  $x_1, x_2$  take unusual combinations of values

$$\frac{x_1}{x_2} = x_5$$
 or  $\frac{(x_4)^2}{x_3} = x_6$  etc...

computationally cheaper and scales better to larger n's

$$n = 10,000, n = 100,000$$

sufficient model even if m (training set size) is small

### multivariate gaussian

$$= \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right)$$

automatically captures correlations between multiple features

$$\Sigma = \mathbb{R}^{n \times n}$$
  $\Sigma^{-1}$ 

computationally more expensive

$$\Sigma \sim \frac{n^n}{2}$$

must have m > n or else  $\Sigma$  is noninvertible  $\rightarrow m \gg n$ 

Consider applying anomaly detection using a training set  $\{x^{(1)},\dots,x^{(m)}\}$  where  $x^{(i)}\in\mathbb{R}^n$ . Which of the following statements are true? Check all that apply.

The original model  $p(x_1; \mu_1, \sigma_1^2) \times \cdots \times p(x_n; \mu_n, \sigma_n^2)$  corresponds to a multivariate Gaussian where the contours of  $p(x; \mu, \Sigma)$  are axis-aligned.

#### **Correct Response**

■ Using the multivariate Gaussian model is advantageous when m (the training set size) is very small (m < n).

### **Correct Response**

#### **Correct Response**

The original model can be more computationally efficient than the multivariate Gaussian model, and thus might scale better to very large values of n (number of features).

### **Correct Response**