

# Intelligent SoC Robot War 2017

*System Design Innovation & Application Research Center*

- I. Intelligent SoC Robot Algorithm
- II. SoC
- III. Brain Board
- IV. Image Processing
- V. Embedded OS
- VI. SoC Robot SW
- VII. SoC Robot

# Intelligent SoC Robot System

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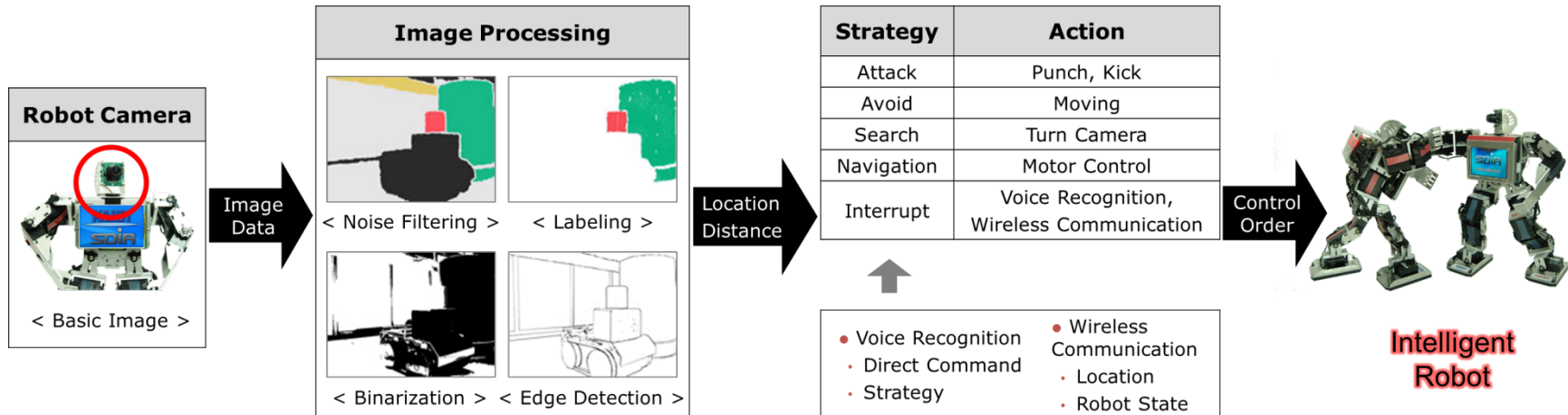
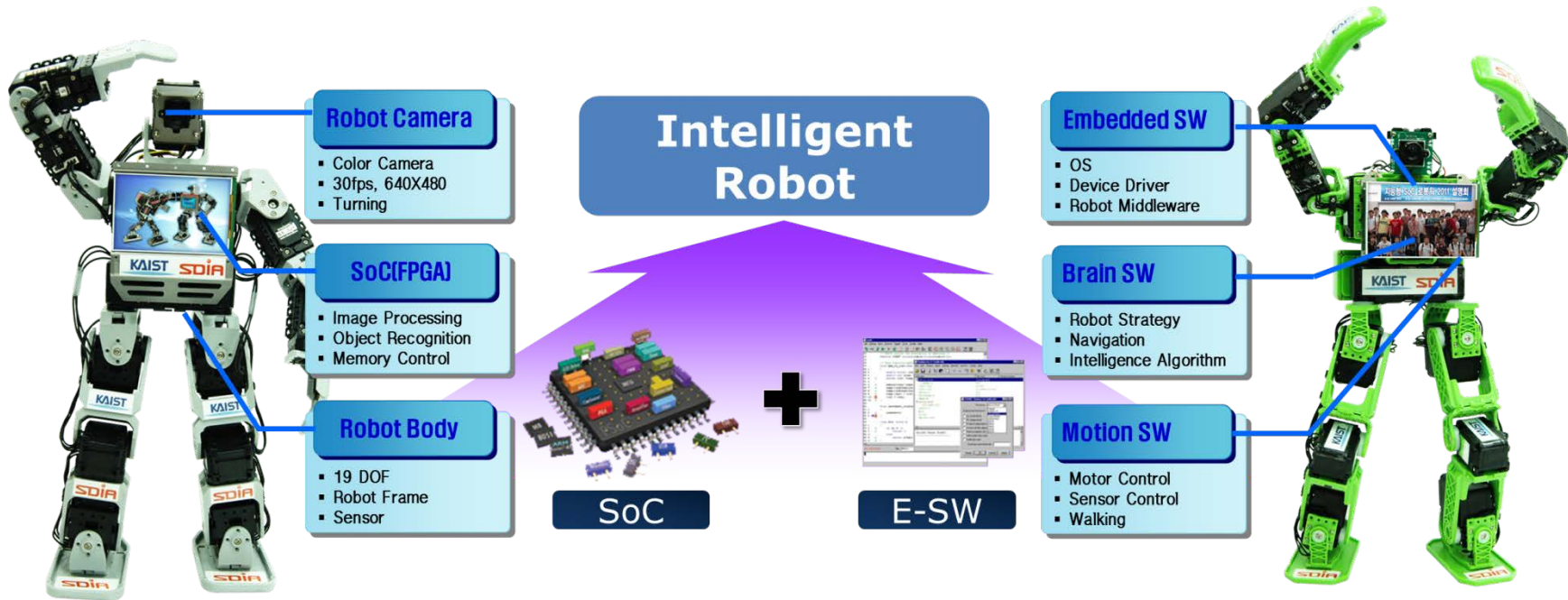
**MINI ROBOT**  
(주)미니로봇

**DSP Robot**  
디에스티로봇

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DS7 Robot 디에스티로봇

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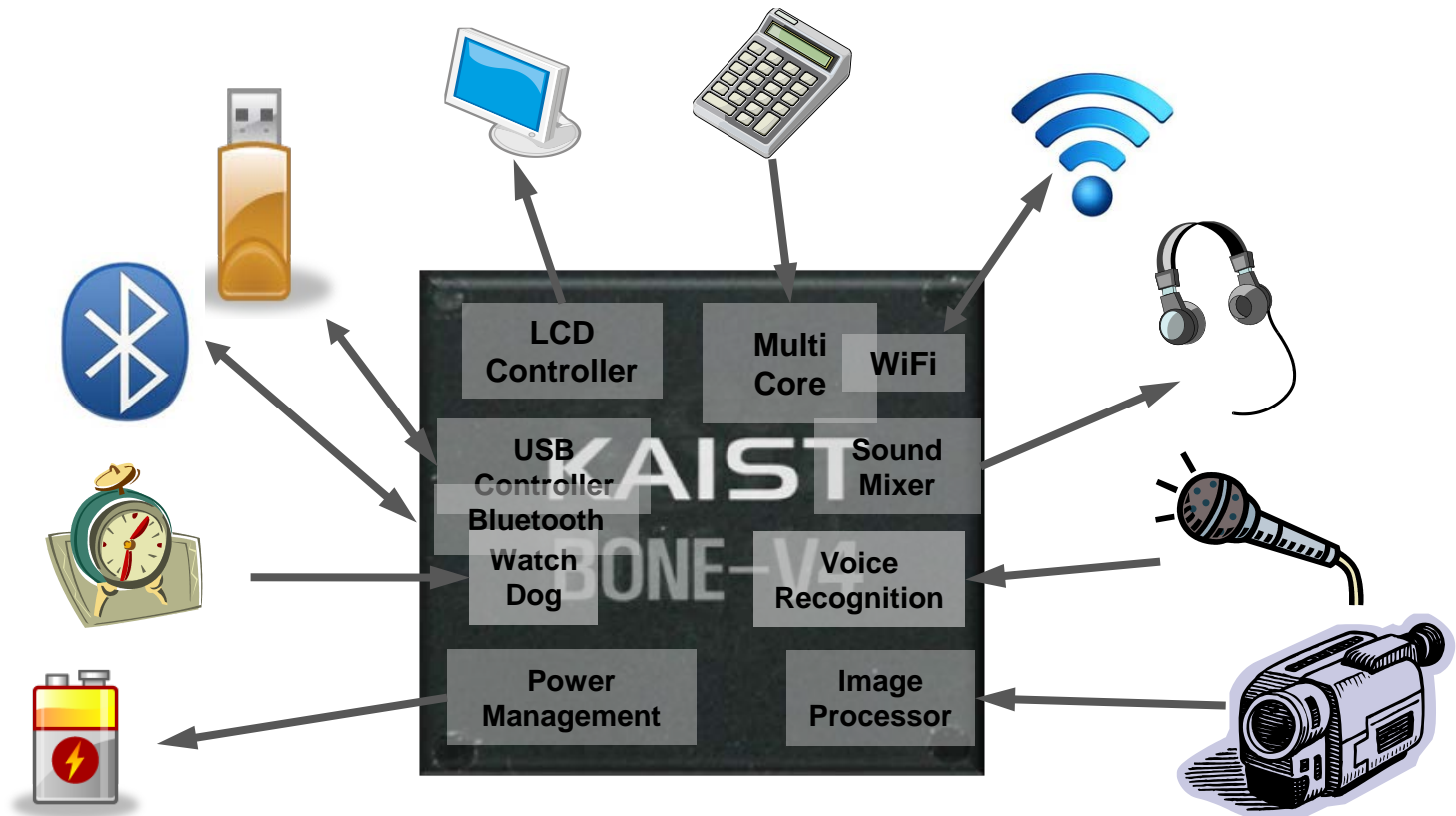
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## SoC (System On Chip)

단일 칩 시스템(SoC)는 하나의 집적회로에 집적된 컴퓨터나 전자 시스템 부품을 말함.

디지털신호, 알라로그 신호, 음성 신호와 RF 기능 등이 단일 칩에 구현

임베디드 시스템 영역에서 주로 사용



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## Real-time Object Recognition Applications



Mobile Robot  
Vision



Smart Phone

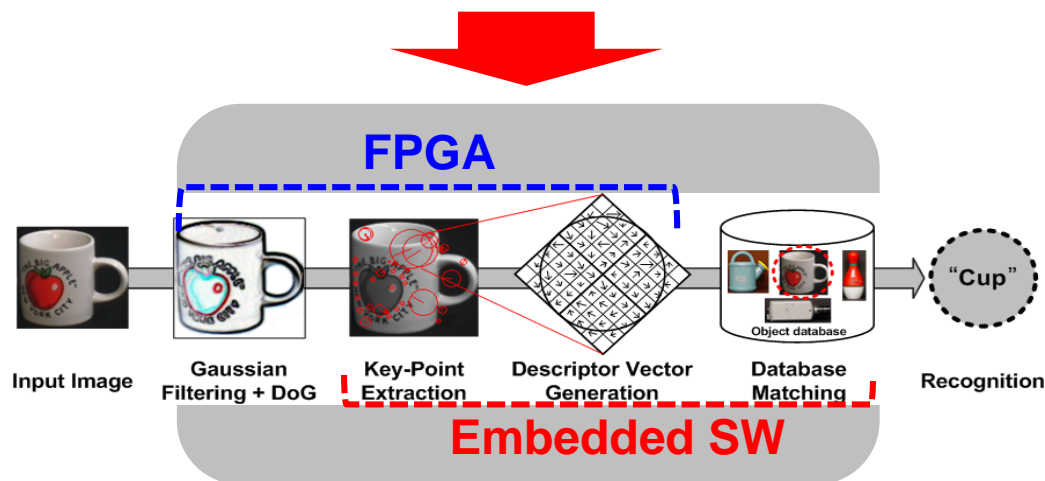


Surveillance  
System



Smart Car  
Vision

- 지능형 비전시스템에서의 핵심 기술
- 많은 양의 이미지 데이터 처리 및 복잡한 연산이 요구
- 실시간 처리/인식에 어려움이 발생



**FPGA + Embedded SW, Object Recognition Process**





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Item	Specification
MCU	ADChips Amazon II (EISC CPU) 160MHz
Memory	DDR2 - 128MB NAND Flash - 64MB
FPGA	Altera Cyclone – EP4CE75 Altera EPCS64
Video Decoder	SAA7111A
UART	1 Port USB to Serial – PC 1 Port TTL Level – Robot
USB	1 Port – Mini USB
Camera Input	2 Port – 3Pins
Display	3.5Inch TFT-LCD (320 X 480)
Size	88mm X 55mm



# Brain Board (Main Board)

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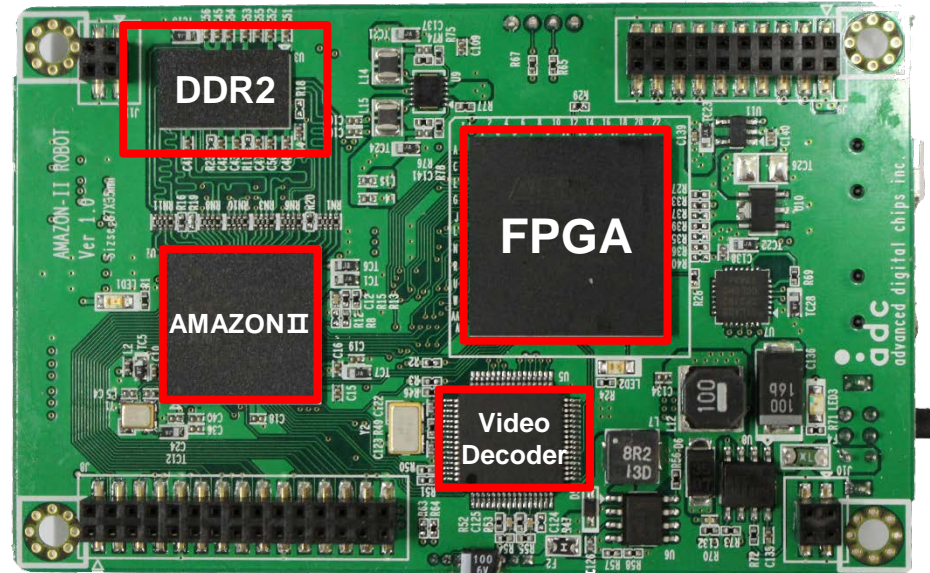
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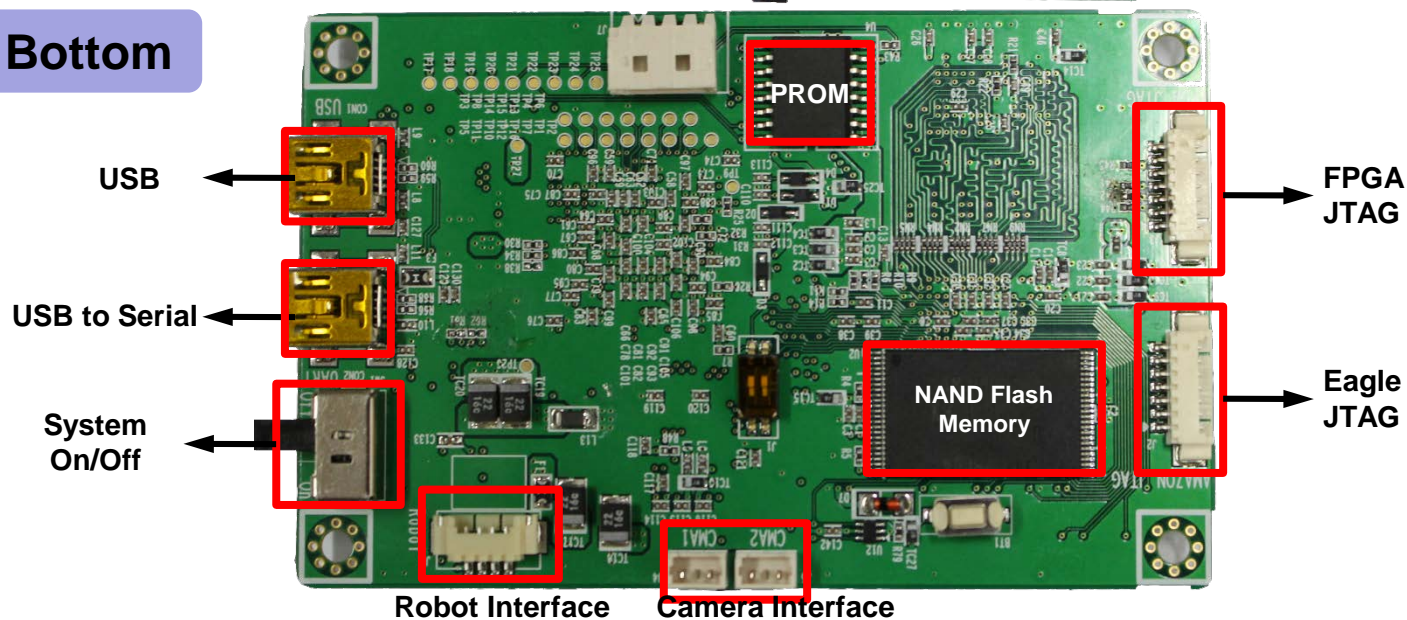
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**Top**



**Bottom**

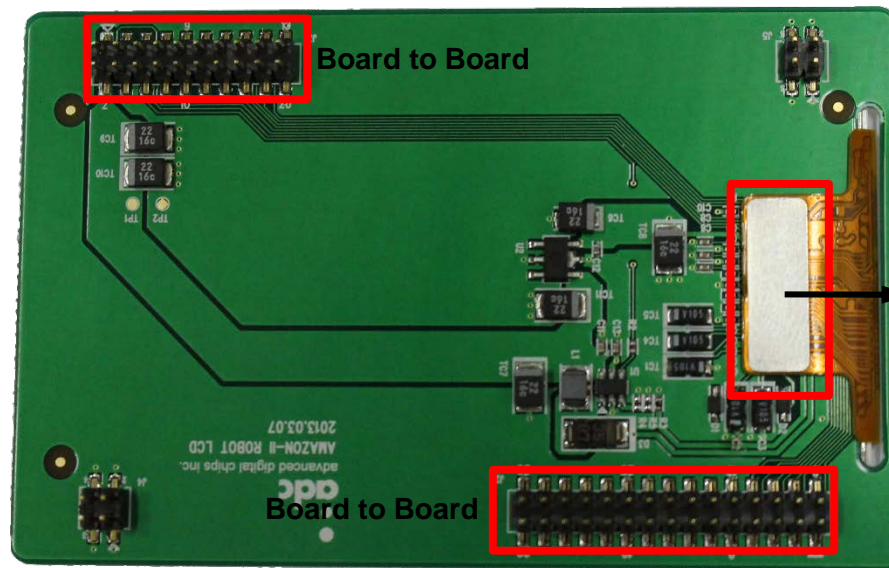




Top



Bottom



LCD  
Connector

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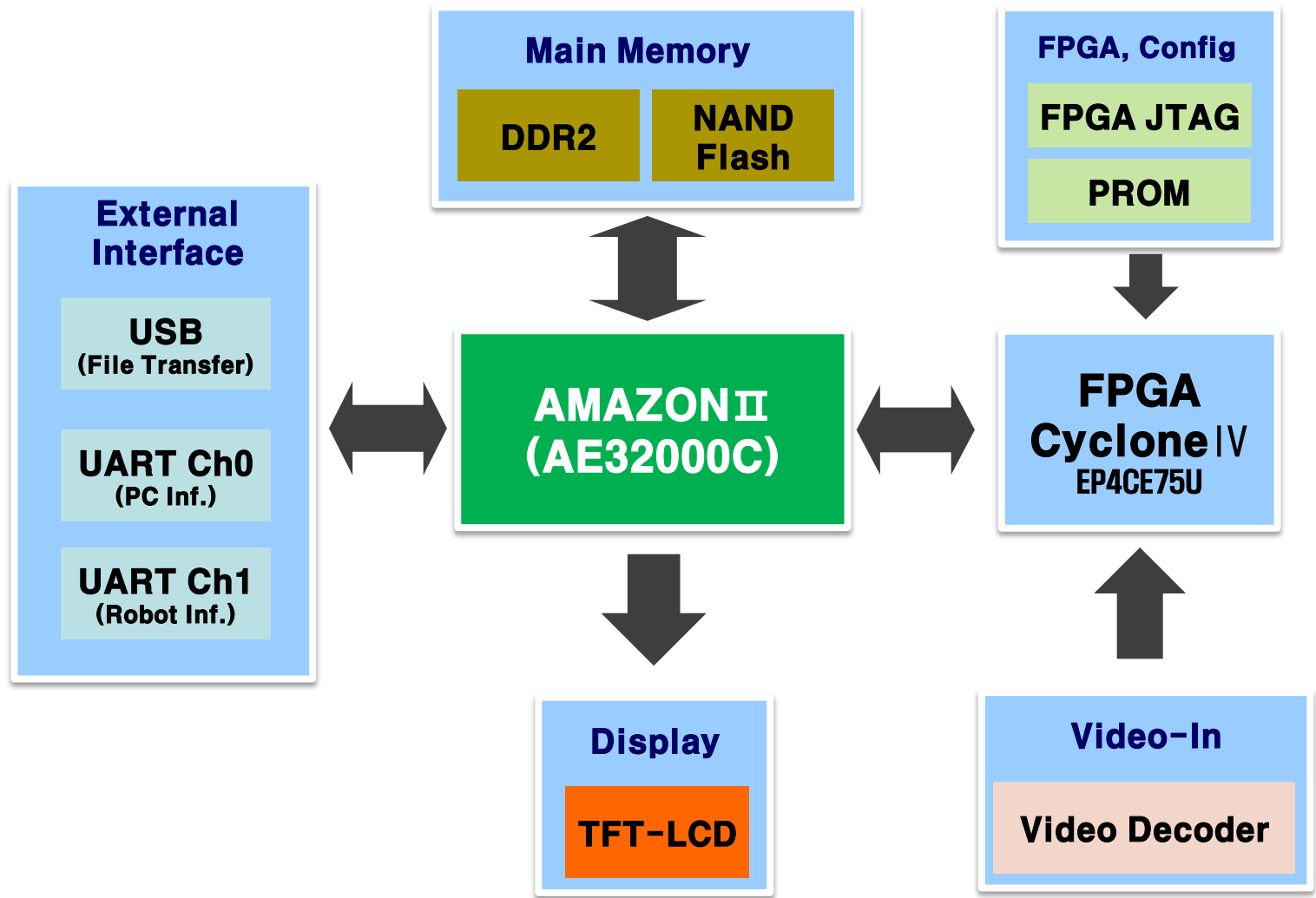




# Brain Board Block Diagram



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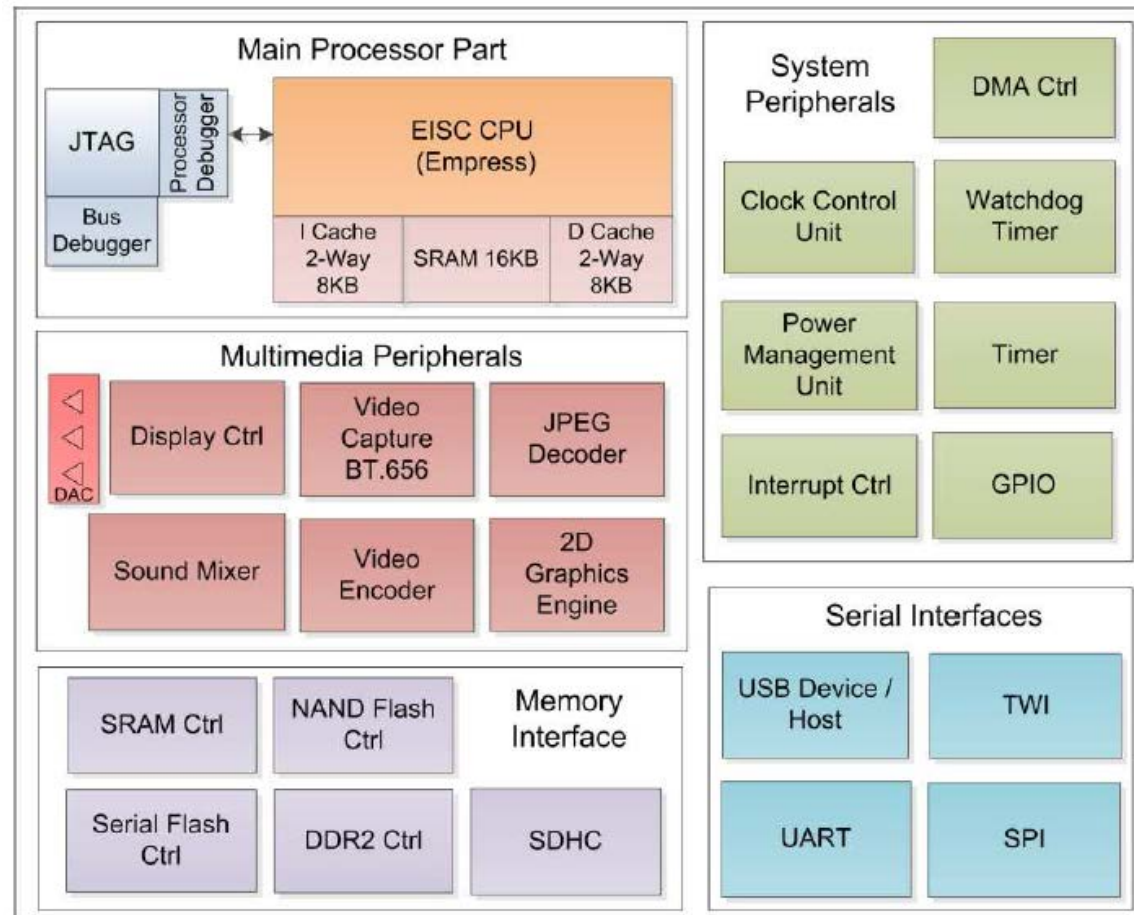


## EISC “Extendable Instruction Set Computing”

국내 순수기술로 개발된 Embedded Processor (에이디칩스)

CISC와 RISC의 단점을 보완

<http://www.adc.co.kr>





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## FPGA “Field-Programmable Gate Array”

프로그래머블 논리요소와 프로그래밍 가능 내부선이 포함된 반도체 소자  
ASIC 보다 느리고, 복잡한 설계에 적용할 수 없고, 소비전력이 큼  
개발시간이 짧고, 오류에 대한 재 수정이 가능, 초기 개발비가 저렴

### HDL (Hardware Description Language)

- 전자회로를 정밀하게 기술하는 데 사용하는 컴퓨터 언어
- 소프트웨어 프로그래밍 언어와 달리 하드웨어의 주요특징인 시간과, 동시성의 표현 가능
- ABEL, AHDL, MyHDL, SystemC, VHDL, Verilog

#### VHDL

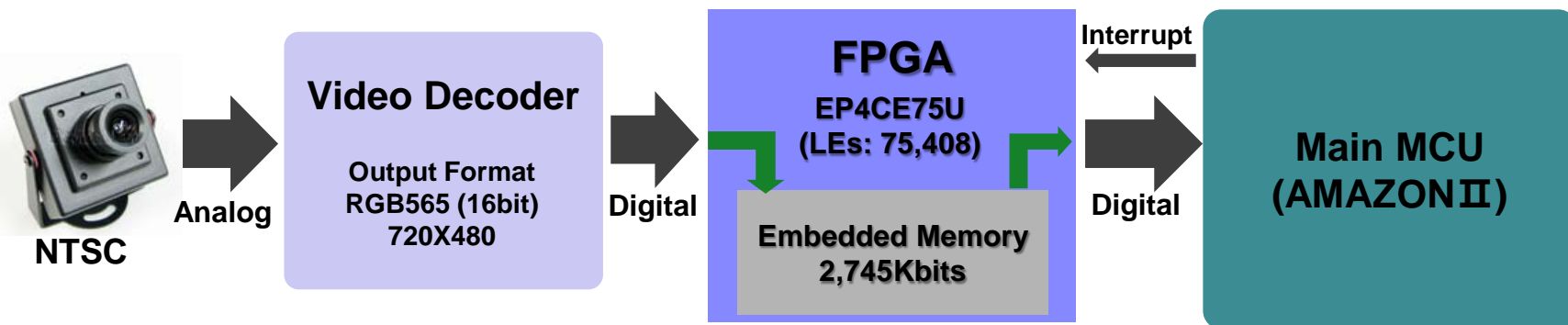
- 국방 (Department of Defense)
- 1993 (IEEE 1164)
- 

#### Verilog

- Gateway Design Automation
- 1985
- C



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## Camera

- CCD Color Camera
- 30 frame/sec

## Video Decoder

- Analog 영상을 디코딩
- 720X480, RGB565 출력
- 30 frame/sec

## FPGA

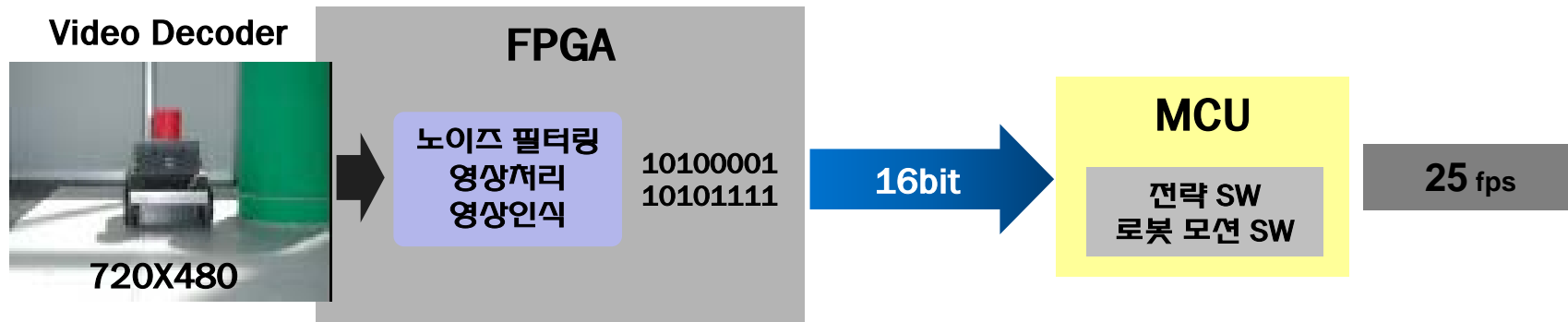
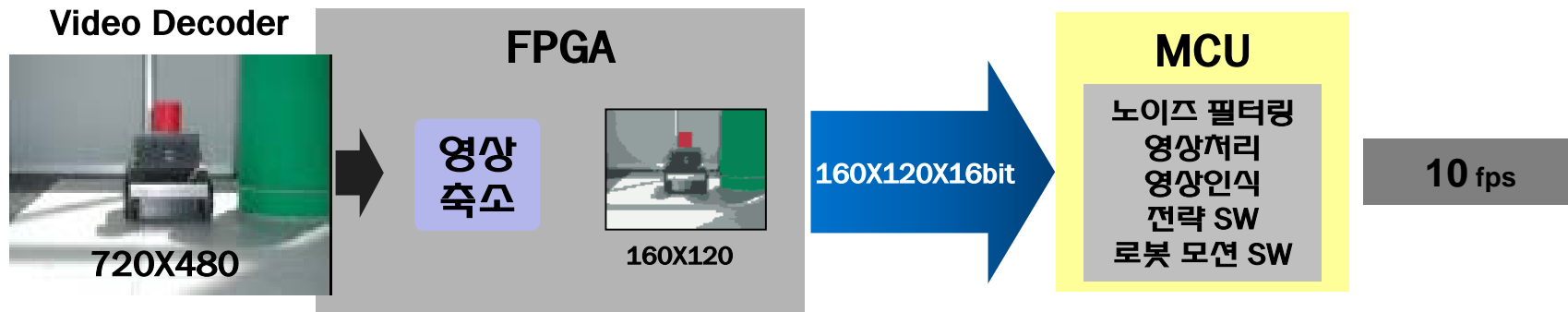
- Video Decoder로부터 Image Data 입력
- 영상 처리/인식
- Main MCU 요청에 의한 Image 전달

## Main MCU

- Robot Strategy
- Decision
- Robot Motion SW



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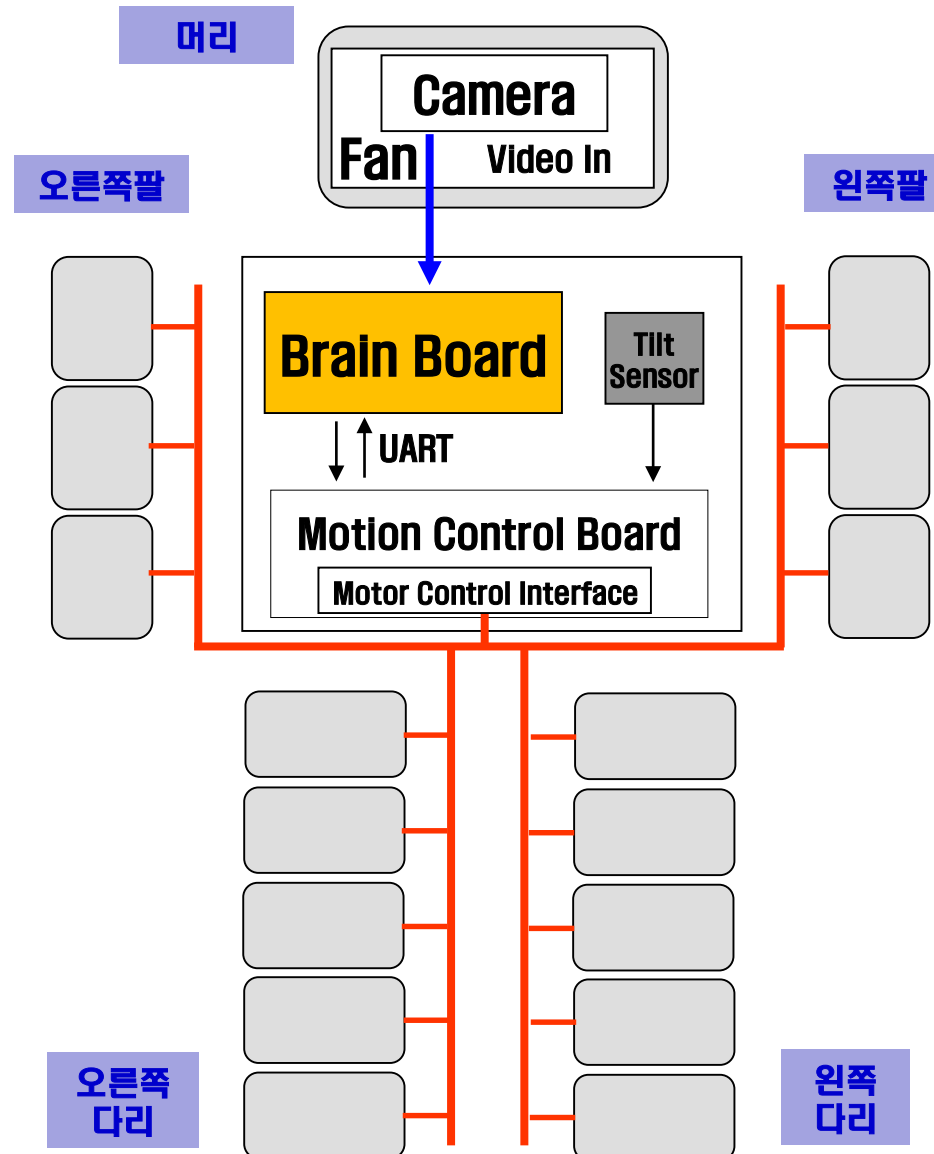
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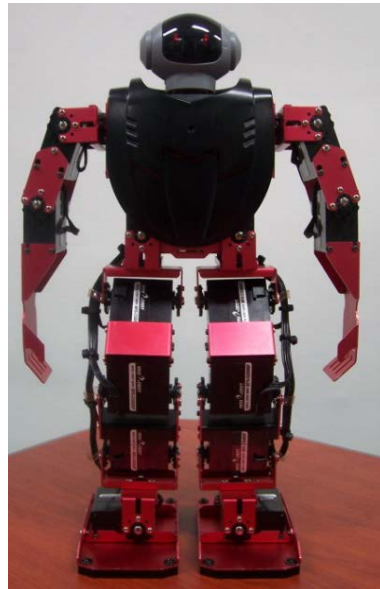
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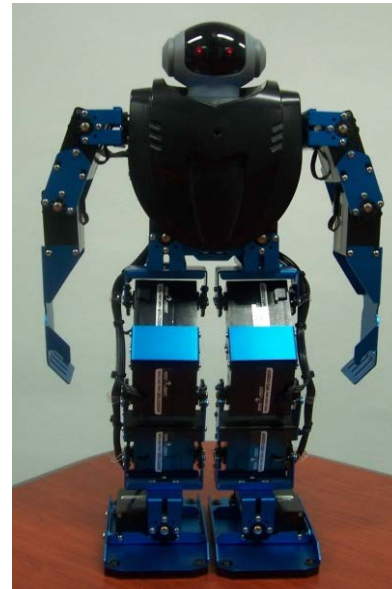
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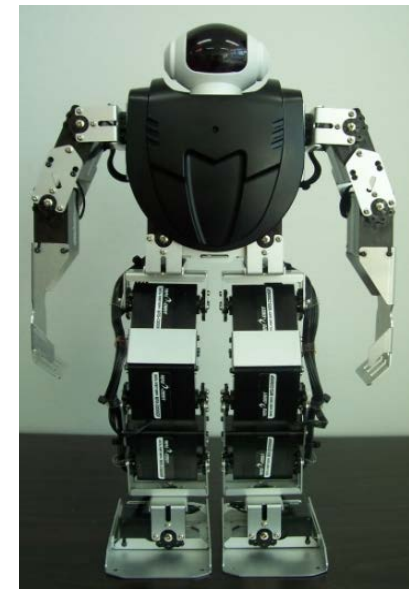
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〈메탈파이터-레드〉



〈메탈파이터-블루〉



〈메탈파이터-실버〉

로봇명: ( , , )

: MRS- D2009SP x 17ea

: 310x180x90mm

: 1.2kg

Controller: MR- C3024

: NiMH 1000mA

Motion SW:

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〈로보티즈-프리미엄〉

로봇명: 티  
: x 19ea(A type)  
: 397mm  
: 1.7kg  
Controller: CM-510  
: , 1000mA  
Motion SW:



〈로보티즈-GP〉

: 티 GP  
: x 17ea  
: 346mm  
: 1.6kg  
Controller: CM-510  
: , 1000mA  
Motion SW:

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로봇명: HOVIS Lite

제어모터: DRS-0101 X 19ea

크기: 348 X 175 X 112 (mm)

중량: 1.45Kg

Motor Controller: ATmega128

Battery: 7.4V 3,000mA Li- Po



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로봇명: 로보티즈 프리미엄키트

제어모터: 다이나믹셀 x 19ea

키: 397mm

중량: 1.7Kg

Motor Controller: CM-530

Battery: 리튬폴리머, 1000mA

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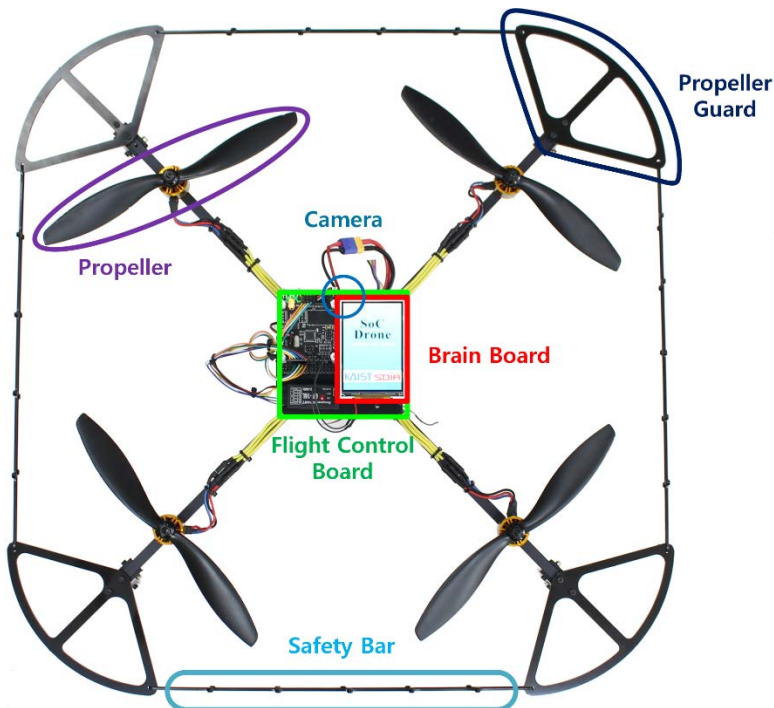
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인터보드: SoC Drone

Motor: 1000KV

Battery: LIPO, 2200mA – 3Cell

초음파 자율고도 유지 시스템

Size: 620 x 620 x 182(mm)