# Maersk Task: Simulating a container terminal using SimPy

## **Installation and Running**

I used Poetry to manage the dependencies and virtual environment, but there is a requirements.txt file for pip as well. Everything is handled with a Makefile. If Poetry is not installed, it uses Python venv to create a virtual environment.

- 1. Create a virtual environment
- \$ make install
- 2. run the simulation
- \$ make simulate
  # or using proper python command
- \$ python -m maersk\_task

#### 3. Configuration

You can find all configurations in config.py file. You can change the configuration as per your needs.

You can configure:

- Average vessel arrival time
- Capacity of the vessel
- Number of starting vessels (if set to 0, it will wait for the first vessel to arrive)
- Number of berths
- Number of cranes
- Duration of crane to load/unload the container
- Number of trucks
- Duration of truck to load/unload the container
- Log level (I used default logging levels)

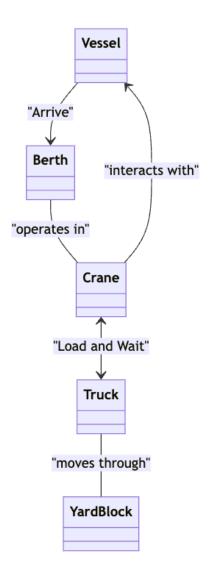
- DEBUG : Truck action logs
- INF0 : Vessel and crane action logs (default)
- WARNING: Only vessel arrival and departure logs
- ERROR : Final summary logs
- Simulation time in minutes
- Based on the task defention I made the assumption that number of cranes and berth should be equal.

```
class Config:
    vessel_average_in_minutes: int = 5 * 60
    vessel_container_capacity: int = 150
    vessels_in_start: int = 1
    berth_count: int = 2
    # crane count should be equal to the berth count
    crane_count: int = 2
    crane_time_in_minutes: int = 3
    truck_count: int = 3
    truck_time_in_minutes: int = 6
# Options: DEBUG, *INFO*, WARNING, CRITICAL
    log_level: int = logging.INFO
    simulation_time_in_minutes: int = SIMULATION_TIME_IN_MINUTES
```

### Design

In the base.py file, you can find abstract classes. These abstract classes were used to define the structure of the simulation.

- The main resources in the simulation are Vessels, Cranes, and Trucks. These resources have actions that interact with each other.
- Class variables were utilized to keep track of the resources. For instance, in a crane, there is a simpy.Resource that allows us to acquire and release the crane, similar to the other resources.
- For the berth, I used a simple simpy. Resource to monitor the availability of the berth.
- The Vessel class has a vessel\_arrival method that handles the arrival of the new vessel.



## **Simulation Output**

The simulation report should look like this: