

Solutions to TD6

1 SCC-based Büchi Emptiness test

1. By way of contradiction, suppose that some inactive SCC C in the explored graph is not an SCC of \mathcal{B} . Then there is a state or a transition outside the explored graph that is reachable from C . However, since the DFS has concluded at every state of C , any state or transition reachable from C must have been visited by the time C becomes inactive.
2. In any active SCC, there is a state v on the search path, i.e., the DFS has not yet concluded at v . Since the root of the SCC is visited before v , the DFS should conclude at the root after it concludes at v . Thus each active SCC has its root on the search path.

Let s be an active state, and suppose that it is in the active SCC of r_i . By the definition of a root, $r_i.\text{num} \leq s.\text{num}$. To show that $s.\text{num} < r_{i+1}.\text{num}$, suppose on the contrary that $r_{i+1}.\text{num} \leq s.\text{num}$. Since r_{i+1} is on the search path when s is visited, there is a path from r_{i+1} to s . But then we obtain a cycle as there are paths from s to r_i and from r_i to r_{i+1} . Thus $r_i.\text{num} \leq s.\text{num} < r_{i+1}.\text{num}$.

For the converse direction, assume that $r_i.\text{num} \leq s.\text{num} < r_{i+1}.\text{num}$. Assume that s does not belong to the active SCC of r_i . Then s must belong to the active SCC of some r_j where $j \neq i$. We cannot have $j < i$, because then we would have a path in the active graph from r_i to s , then from s to r_j and then from r_j to r_i . This shows that the root of a new active SCC occurs between r_i and r_{i+1} , which is not possible.

3. Algorithm 2 maintains a stack of active SCCs of the explored subgraph. When a back-edge is found to one of the active SCCs, closing a cycle, the SCCs forming that cycle are merged.
4.
 - We prove this by induction on the number of active SCCs in the explored graph. The induction hypothesis is that if the active graph consists of the SCCs C_1, \dots, C_m where r_i is the root of C_i and $r_i.\text{num}$ increases with i , then W consists of $(r_1, C_1), \dots, (r_m, C_m)$ (rightmost element at the top).

Assume that the I.H. is true for some value of m . Continuing, DFS looks at the successor t of some vertex $s \in C_m$. For the cases where t is not visited or is visited but not active, it is easy to check that the I.H. holds. Suppose t is active and that it belongs to some C_i , where $i \leq m$. Then the new active SCCs become $C_1, \dots, C_{i-1}, C_i \cup \dots \cup C_m$, with r_i being the root of $C_i \cup \dots \cup C_m$.

To see that this is also reflected in the stack W , note that the algorithm iteratively keeps popping (r_j, C_j) till $j = i$ and obtains $D = C_i \cup \dots \cup C_m$, and finally pushes (r_i, D) onto W .

- A vertex v becomes inactive once the DFS concludes at the root r_i of its active SCC C_i .

Right before the DFS concludes at r_i , (r_i, C_i) must be on the top of W . Once the DFS concludes at r_i , Algorithm 2 does not find any more new transitions out of r_i and goes to line 21, and marks all states in C_i as inactive. Thus the algorithm behaves correctly.

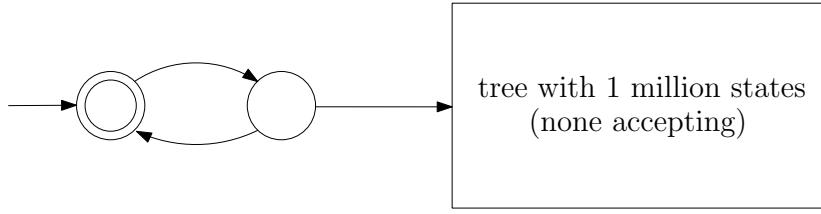


Figure 1: Example in which nested DFS takes a long time to find a counterexample

5. Consider the point at which the explored graph contains a counterexample for the first time. This must have happened because an edge (u_k, u_1) was added, completing the cycle $(u_1, u_2, \dots, u_k, u_1)$ and for some $1 \leq f \leq k$, state u_f is an accepting state. The following sequence of observations show that the algorithm returns false immediately.

Observation 1: State u_1 must have been an active state at this time; otherwise if u_1 was inactive, by Question 1 the cycle $(u_1, u_2, \dots, u_k, u_1)$ would belong to the inactive SCC containing u_1 , which is a contradiction since u_k is definitely active when (u_k, u_1) is added. \square

Observation 2: Stack W must have contained $(u_f, \{u_f\})$; otherwise W would have contained some element (r, C) where $u_f \in C$ and $|C| \geq 2$, but then a counterexample would already have been formed before (u_k, u_1) was added. \square

Thus Algorithm 2 starts popping elements from W , merging the second components until the first component becomes less than $u_1.\text{num}$. We need to show that it encounters $(u_f, \{u_f\})$.

Observation 3: $u_f.\text{num} > u_1.\text{num}$. Suppose on the contrary that $u_f.\text{num} < u_1.\text{num}$. Then there is a path from u_f to u_1 in the explored graph that existed before (u_k, u_1) was added. But then joining this path with the path (u_1, \dots, u_f) implies that there was a counterexample in the explored graph before (u_k, u_1) was added. \square

Thus the algorithm encounters $(u_f, \{u_f\})$ and returns false.

6. Instead of keeping track only of the roots of the SCCs and said SCCs, we also keep track of the final sets that have a representative in the SCC (that is, we keep track of the (r, C, R) where $R \subseteq \{1, \dots, n\}$ is such that $i \in R$ if and only if there exists v in C such that $v \in F_i$). We then return false when we find an SCC containing a representative of each final set and a non-trivial path.
7. The nested DFS algorithm uses only two bits per state. Algorithm 2 assigns a number to each state, thus requires more space.

Algorithm 2 outputs false as soon as a counterexample occurs in the explored graph, whereas this is not the case for the nested DFS algorithm, as demonstrated by the example in Figure 1.

2 Exercise 2

1. Consider some LTL(AP, U) formula φ . We will show by induction that for any stuttering equivalent words σ and ρ that we have $\sigma \models \varphi \Leftrightarrow \rho \models \varphi$.

- The cases $\varphi = \top, p \in AP, \neg\varphi, \varphi_1 \vee \varphi_2$ are trivial.
- Consider then $\varphi = \psi_1 \mathbf{U} \psi_2$ and suppose that for any two stuttering equivalent words ζ and γ we have $\zeta \models \psi_1$ iff $\gamma \models \psi_1$ and $\zeta \models \psi_2$ iff $\gamma \models \psi_2$. Take two stuttering equivalent words σ and ρ . Consider then two sequences $0 = i_0 < i_1 < \dots$ and $0 = j_0 < j_1 < \dots$ such that for all ℓ we have $\sigma_{i_\ell} = \dots = \sigma_{i_{\ell+1}-1} = \rho_{j_\ell} = \dots = \rho_{j_{\ell+1}-1}$. Now suppose there exists k such that $\sigma, k \models \psi_2$ and for all $k' < k$ we have $\sigma, k' \models \psi_1$. Consider ℓ such that $i_\ell \leq k < i_{\ell+1}$. We can easily show that $\sigma_{\geq k}$ and ρ_{j_ℓ} are stuttering equivalent, and hence $\rho, j_\ell \models \psi_2$. Similarly, for all n such that $n < j_\ell$ there exists $\ell' < \ell$ such that $\sigma_{i_{\geq \ell'}}^{\geq \ell'}$ and $\rho_{\geq n}$ are stuttering equivalent (ℓ' is such that $j_{\ell'} \leq n < j_{\ell'+1}$ and $\ell' < \ell$), and since $\sigma, i_{\ell'} \models \psi_1$ we have $\rho, n \models \psi_1$. Hence we have shown $\sigma, 0 \models \varphi$ implies $\rho, 0 \models \varphi$ and since σ and ρ play a symmetrical role the mirror implication is also true.

2. Consider the sequence i_0, i_1, \dots defined as

- $i_0 = 0$
- for $k \geq 0$, i_{k+1} is the smallest number strictly greater than i_k such that $\sigma_{i_{k+1}} \neq \sigma_{i_k}$ if one such number exists, $i_k + 1$ else.

Then σ' defined by $\sigma'_k = \sigma_{i_k}$ is the only stutter-free word that is stuttering equivalent to σ .

3. (a) If a stutter-free word σ is such that $\sigma, 0 \models a \wedge \mathbf{X} a$ then it is such that $\sigma_0 = a$ and $\sigma_1 = a$, hence by definition $\sigma = a^\omega$. Thus $\psi_{a,a} = \neg(\top \mathbf{U} \neg a) = \mathbf{G} a$ works.
- (b) The formula $\psi_{a,b} = a \wedge (a \mathbf{U} b)$ works.
4.
 - $\tau(\top) = \top$
 - $\tau(p) = p$ where $p \in AP$
 - $\tau(\neg\psi) = \neg\tau(\psi)$
 - $\tau(\psi_1 \vee \psi_2) = \tau(\psi_1) \vee \tau(\psi_2)$
 - $\tau(\psi_1 \mathbf{U} \psi_2) = \tau(\psi_1) \mathbf{U} \tau(\psi_2)$
 - The case $\mathbf{X} \psi$ is more involved. It can be rewritten as

$$\begin{aligned} \mathbf{X} \psi &= \bigvee_{a \in \Sigma} a \wedge \mathbf{X} \psi = \bigvee_{a \in \Sigma} \left[a \wedge \bigvee_{b \in \Sigma} \mathbf{X}(\psi \wedge b) \right] \\ &= \bigvee_{a \in \Sigma} \left[(a \wedge \mathbf{X}(\psi \wedge a)) \vee \bigvee_{b \neq a} a \wedge \mathbf{X}(\psi \wedge b) \right] \end{aligned}$$

Following the same ideas in Question 3, we see that for stutter-free words, $a \wedge \mathbf{X}(\psi \wedge a)$ and $\mathbf{G} a \wedge \psi$ are equivalent, and if $a \neq b$ then $a \wedge \mathbf{X}(b \wedge \psi)$ and $a \wedge (a \mathbf{U} (b \wedge \psi))$ are equivalent. Hence:

$$\tau(\mathbf{X} \psi) = \bigvee_{a \in \Sigma} \left((\mathbf{G} a \wedge \tau(\psi)) \vee \bigvee_{b \neq a} a \wedge (a \mathbf{U} (b \wedge \tau(\psi))) \right)$$

5. For any word σ , let $f(\sigma)$ be the only stutter-free word that is stuttering-equivalent to σ (as seen in Question 2). Then if $L(\varphi)$ is stutter-invariant we have $\sigma \models \varphi \Leftrightarrow f(\sigma) \models \varphi \Leftrightarrow f(\sigma) \models \tau(\varphi)$. However from Question 1 we know that $L(\tau(\varphi))$ is stutter-invariant, and hence $f(\sigma) \models \tau(\varphi) \Leftrightarrow \sigma \models \tau(\varphi)$. This means $\sigma \models \varphi \Leftrightarrow \sigma \models \tau(\varphi)$ and thus $L(\varphi) = L(\tau(\varphi))$.