

Inverse Laplace Transforms & Differential Equations – Cheat Sheet (Theory Only)

1. Definition of Inverse Laplace Transform

The **Inverse Laplace Transform** converts a function from the **Laplace domain (frequency domain)** back to the **time domain**.

Helps solve **differential equations, control system problems, and signal processing applications**.

Used to **find original time-domain functions** from their Laplace-transformed counterparts.

2. Convolution Theorem (Without Proof)

The **Laplace transform of the convolution of two functions** is the **product of their individual Laplace transforms**.

Helps solve **integral equations** and analyze **system responses**.

Used in **engineering, physics, and signal processing applications**.

3. Solutions of Linear Ordinary Differential Equations (ODEs)

Definition of Second-Order ODE with Constant Coefficients

A second-order **linear ordinary differential equation (ODE)** has the general form:

- $a \frac{d^2y}{dt^2} + b \frac{dy}{dt} + c y = f(t)$

Where:

- **a, b, c** are constants.
- **y(t)** is the unknown function.
- **f(t)** is a given function (forcing function).

Used in **mechanical vibrations, electrical circuits, and control systems**.

4. Solving Second-Order ODEs Using Laplace Transforms

Step 1: **Apply Laplace Transform** to the given equation.

Step 2: **Use Laplace properties** (differentiation property for derivatives).

Step 3: **Convert the equation into an algebraic equation** in terms of the Laplace variable.

Step 4: **Solve for Y(s)** (Laplace-transformed solution).

Step 5: **Apply the Inverse Laplace Transform** to obtain the time-domain solution.

5. Applications of Laplace Transform in ODE Solutions

Mechanical Systems → Spring-mass-damper systems, oscillations.

Electrical Circuits → RLC circuits, step response analysis.

Control Systems → Stability analysis and system response.

This **Inverse Laplace Transform Cheat Sheet** covers **definition, convolution theorem (without proof), and solving second-order ODEs with constant coefficients** using Laplace Transforms. Let me know if you need further explanations!