Uniwersytet Warszawski

Wydział Matematyki, Informatyki i Mechaniki

Michał Garmulewicz

Nr albumu: 304742

L_p -cohomologies of Riemannian f-horns.

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Potwierdzam, że niniejsza praca została przygotowana pod moim kierunkiem i kwalifikuje się do przedstawienia jej w postępowaniu o nadanie tytułu zawodowego.

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Świadom odpowiedzialności prawnej oświadczam, że niniejsza praca dyplomowa została napisana przeze mnie samodzielnie i nie zawiera treści uzyskanych w sposób niezgodny z obowiązującymi przepisami.

Oświadczam również, że przedstawiona praca nie była wcześniej przedmiotem procedur związanych z uzyskaniem tytułu zawodowego w wyższej uczelni.

Oświadczam ponadto, że niniejsza wersja pracy jest identyczna z załączoną wersją elektroniczną.

Data

Podpis autora (autorów) pracy

Abstract

In this thesis L_p -cohomologies of Riemannian f-horn are calculated.

Słowa kluczowe

kohomologie de Rhama, topologia różniczkowa

Dziedzina pracy (kody wg programu Socrates-Erasmus)

- 11.0 Matematyka, Informatyka:
- $11.1 \; \mathrm{Matematyka}$

Klasyfikacja tematyczna

14 Algebraic Geometry14F (Co)homology theory14F40 de Rham cohomology

Tytuł pracy w języku angielskim

An implementation of a difference blabalizer based on the theory of σ – ρ phetors

Contents

1.	Introduction	5
	troduction	
2.	Preliminaries2.1. Vector spaces and tensors2.2. Differetial forms2.3. Explaination about induced maps etc	7
	2.1. Vector spaces and tensors	7
	2.2. Differential forms	7
	2.3. Explaination about induced maps etc	8
3.	Computation	Ć
Co	3.1. Setting 3.2. Norms	ç
	3.1. Setting	Ć
	3.2. Norms	Ć
Ri	hliography	13

Chapter 1

Introduction

In [Weber] the author considers a cone over Riemannian pseudomanifold. The cone is given a metric of the form $dt \otimes dt \oplus t^2g$ and g is the metric on the nonsingular part of the original pseudomanifold. In the mentioned work, L_p cohomology of this space is presented.

This line of research can be traced back to Cheeger [Cheeger]. A similar approach was presented by Youssin [Youssin], where f-horns were considered.

We present a slight modification of this notions, by considering manifolds where the Riemannian metric is of the for

Chapter 2

Preliminaries

2.1. Vector spaces and tensors

Let us recall some basic facts about behaviour of norm when scaling tensors. If we consider a finite-dimensional vector space V with a given metric $||\cdot||$ and define a new metric $||x||_r = r||x||$. Then in the space $(V, ||\cdot||_r)^*$ dual to $(V, |||\cdot|||)$, the normed is scaled by the factor $\frac{1}{r}$, that is for any $\varphi \in V^*$ we get $||\varphi||_r = \frac{1}{r}||\varphi||$.

We will make a simple observation that we will later use in the computations. We consider a Riemannian manifold M and tagent T_x M and cotangent T_x^* M spaces in the point x. Let the bases of these spaces be $e_1, e_2, ..., e_n$ and dual $e_1^*, e_2^*, ..., e_n^*$. The volume form of this manifold is dvol $= \pm e_1^* \wedge e_2^* \wedge ... \wedge e_n^*$.

We now want to compute how forms from $\Lambda(\mathcal{M})$ are scaled with respect to such a change in the norm. Suppose we are considering space of k-forms on \mathbb{M} at some arbitrary point. Then every k-form can be locally expressed in a basis consisting of products of covectors belonging to basis dual to the standard basis. That is every k-form in the point x using some local coordinates $(x_1, x_2, ...x_n)$ can be written $\sum_{I \in I} a_I dx_i$, where I is the set of k-indices of form $(i_1, i_2, ..., i_k)$, with $i_1, i_2, ... \in \{1, 2, ..., n\}$. (following Einstein convention). Let us see how

basis vector is scaled:

$$\begin{split} ||dx_{i_1} \wedge dx_{i_2} \wedge \ldots \wedge dx_{i_k}||_t &= ||dx_{i_1}||_t \cdot ||dx_{i_2}||_t \cdot \ldots \cdot ||dx_{i_k}||_t = \\ & \frac{1}{t} ||dx_{i_1}|| \cdot \frac{1}{t} ||dx_{i_2}||_t \cdot \ldots \cdot \frac{1}{t} ||dx_{i_k}||_t = \frac{1}{t^k} ||dx_{i_1} \wedge dx_{i_2} \wedge \ldots \wedge dx_{i_k}||_t = \\ & \frac{1}{t^k} ||dx_{i_1} + \frac{1}{t^k} ||dx_{i_2} + \frac{1}{t^k} ||dx_{i_2} + \frac{1}{t^k} ||dx_{i_1} + \frac{1}{t^k} ||dx_{i_2} + \frac{1}{t^k} |$$

This means that any k form is scaled by $1/t^k$ when metric is scaled by a factor of t. This applies also to the volume form, so we obtain:

$$d\text{vol}_t = \frac{1}{t^n}d\text{vol}$$

2.2. Differential forms

Riemannian metric is a smooth symmetric covariant 2-tensor field on manifold \mathcal{M} that is positive definite at each point. (attaching a field of linear functions that takes two variables to every point of the manifold).

Consulting page 328 of Lee gives us that in any smooth local coordinates (x^i) , Riemannian metric can be written as:

$$g = g_{ij}dx^i \otimes dx^j = g_{ij}dx^i dx^j$$

where g_{ij} is a positive definite matrix of smooth functions.

The simplest example of Riemannian metric is *Euclidean metric* on \mathbb{R}^n given in standard coordinates by

$$g = \delta_{ij} dx^i dx^j$$
.

Citing prof. Lee, it is common to abbreviate the symmetric product of a tensor α with itself by α^2 , so the Euclidean metric can also be written as

$$g = (dx^1)^2 + \dots + (dx^n)^2$$
,

so now it is way easier to understand what exactly is meant by $dt \otimes dt + f^2g$, which should be the same as $dt^2 + f^2g$.

Induced map For any smooth map $F: M \to N$ between two smooth manifolds with or without boundary, the pullback $F^*: \Omega^p N \to \Omega^p M$ carries closed forms to closed forms and exact forms to exact forms. It thus decsends to a linear map, denoted by $F^*: H^p N \to H^p M$, too.

Digression in digression: Pullback of F^* is

$$(F^*\omega)_p(v_1,...,v_n) = \omega_{F(p)}(dF_p(v_1),...,dF_p(v_k)).$$

2.3. Explaination about induced maps etc.

If we have two smooth maps $F, G: M \to N$ and we want to prove that the induced maps are equal $F^* = G^*$. Given a closed p-form ω on N, we need to produce a (p-1)-form η no M such that

$$G^*\omega - F^*\omega = d\eta$$

from this, it will follow that $G^*[\omega] - F^*[\omega] = [d\eta] = 0$, where [] is just taking homotopy equivalence class of given form. The author suggests a way to make it more systematic, by finding an operator h, which transforms closed p-forms on N to (p-1)-forms on M and satisfies

$$d(h\omega) = G^*\omega - F^*\omega.$$

Instead of defining $h\omega$ only when ω is close, it turns out to be far easier to define a map h from the space of all smooth p-forms on N to the space of smooth (p-1)-forms on M, which satisfies:

$$d(h\omega) + h(d\omega) = G^*\omega - F^*\omega,$$

which implies the above equality when ω is closed. (To be completly precise, we define a family of maps, one for each p, which satisfy said equalities on adequate levels.

$$H(\mathcal{M} \times \mathbb{R}_{>})_{dR}^* = H(\mathcal{M})_{dR}^*$$

Chapter 3

Computation

The purpose of this chapter is to present the computation of L_p -cohomologies of Riemannian f-horns.

3.1. Setting

Here we introduce definitions and make the first observations. The setting is largely similar to the setting presented in [Weber], [Youssin], [Cheeger].

Definition 3.1.1 (f-horn). Let \mathcal{M} be a Riemannian manifold. Consider a space $\mathbb{R}_{\geq 0} \times \mathcal{M}$. Define a Riemannian tensor on this product by $dt^2 \oplus f^2(t)g$, where g is the metric on \mathcal{M} . Such a space will be called an f-horn. We will denote it by $c^f \mathcal{M}$.

Definition 3.1.2. By $L_p^k \mathcal{M}$ we will denote the space of *p*-integrable *k*-forms with measurable coefficients.

At first, we will focus our attention on scaling functions from family $f_{\alpha}(x) = e^{\alpha x}$, parametrized by $\alpha \in \mathbb{R}$. The intuition behind such manifolds is best presented graphically, as in the Figure ??.

We can make a simple observation here about differential forms associated with f-horn. The tangent space in the point (t, m) is:

$$T_{(t,m)}(c^f\mathcal{M}) = \mathbb{R} \times T_m\mathcal{M}$$

In terms of differential forms associated with f-horn, it means that $\Lambda^k(\mathbb{R} \times T_m \mathcal{M}) = \Lambda^k(\mathbb{R}) \oplus \Lambda^k(\mathcal{M})$. It can be rephrased in friendlier terms in the following way.

Remark 3.1.1. Every k-form $\omega \in \Lambda^k T(\mathbf{c}^f \mathcal{M})$, and consequently every form in the space of p-integrable forms $L_k^p(\mathbf{c}^f \mathcal{M})$ can be written as $\omega = \eta + \xi \wedge dt$, where both η and ξ do not contain dt. Please note that η is k-form and ξ is k-1 form.

3.2. Norms

Here we define norms of different forms used later in the computation.

For $\omega \in L_p^k \mathcal{M}$ we have the norm:

$$|\omega| = (\int_{\mathcal{M}} |\omega|^p d\mathrm{vol})^{1/p}$$

We have the standard inclusion:

$$i_r: \mathcal{M} \to \mathbf{c}^f \mathcal{M},$$

$$i_r(x) = (x, r).$$

With this in mind, for $\omega = \eta + \xi \wedge dt$ we will write $\omega_r = i_r^*(\omega) = i_r^*(\eta)$.

Definition 3.2.1. We define norm "at the level r" to be:

$$||\omega||_r = ||\omega|_{\mathcal{M}\times\{r\}}|| = f(r)^{n/p-k}||\omega_r||$$

Similarly, when we consider the standard projection operator:

$$\pi: \mathrm{c}^f \mathcal{M} \to \mathcal{M}$$

for $\eta \in L_n^*(c^f \mathcal{M})$ we can write:

$$||\eta||_r := ||\pi^*\eta||_r = f(r)^{n/p-k}||\eta_r||_r$$

As we will be computing cohomologies, we should define the homology operator:

$$I_r: \Omega^*(\mathbf{c}^f \mathcal{M}) \to \Omega^{*-1}(\mathbf{c}^f \mathcal{I})$$

$$I_r(\omega)(x,t) = \int_r^t \xi(x,s)ds$$

Here probably we need some kind of Poincare lemma

The form $I_r\omega$ is smooth for $r \in (0,1)$, but will also consider r = 0 in certain cases. If r > 0 then the homotopy formula holds:

$$\omega - \pi^*(\omega_r) = dI_r\omega + I_r d\omega.$$

This one probably is Poincare lemma in a version suited for our situation. This is a good place to rewrite it here using Bott

Lemma 3.2.1. Let $\alpha(n/p-k) < 0$ Then the form $\pi^*\eta$ is p-integrable for each p-integrable form $\eta \in L_p^k(\mathcal{M})$.

Proof.

$$||\pi^*\eta||^p = \int_{c\mathcal{M}} |\pi^*\eta(x,t)|^p d\text{vol}(c\mathcal{M}) = \int_0^\infty ||\eta||_t^p dt = ||\eta||^p \int_0^\infty f(t)^{n-pk} dt$$

so, if f is given by $f(x) = e^{\alpha}$, the last integral is $||\eta||^p \int_0^{\infty} e^{\alpha(n-pk)} dt$. This integral is convergent if $\alpha(n-pk) < 0$.

The following lemma will also be useful in further computation.

Lemma 3.2.2 (Estimation of $\int \xi$).

Proof.

$$||\int_{t}^{r} \xi_{x} dx|| \leq \int_{t}^{r} ||\xi_{x}|| dx =$$

$$\int_{r}^{t} f(x)^{i-n/p} f(x)^{n/p-i} ||\xi_{x}|| dx \leq$$

$$|\int_{r}^{t} f(x)^{i-n/p} dx|^{1/q} \cdot |\int_{r}^{t} f(x)^{n/p-i} ||\xi_{s}|| ds|^{1/p}$$

Lemma 3.2.3. Let k < (n+1)/p. Then for p-integrable $\omega \in \Omega^k(c^f\mathcal{M})$ the form $I_r\omega$ is integrable.

Proof. For the case k < (n+1)/p = n/p - 1/q + 1 we get from the previous lemma:

$$||I_r\omega|| = \int_0^\infty ||\int_r^t \xi_s ds||dt \le C \int_0^\infty f(t)^{p/q},$$

and for k = (n+1)/p, we get:

$$||I_r\omega|| \le \int_0^1 |t(\log r - \log t)|^{p/q} dt$$

Remark 3.2.1. Based on the above lemma, we get that if k < (n+1)/p then a *p*-integrable closed form is cohomologous to $\pi^*\omega_r$ for almost all r.

$$\omega = dI_0\omega + I_0d\omega$$

Proof. We have $\omega - \pi^*(\omega_r) = dI_r\omega$ and $I_r\omega$ is *p*-integrable. The form ω_r is *p*-integrable for almost all r. So for almost all r the form $dI_r\omega$ is also p-integrable.

Lemma 3.2.4. Let k > (n+1)/p Then $I_0\omega$ is p-integrable for $\omega \in L_p\Omega^k(c^f\mathcal{M})$ and the homotopy formula holds:

$$\omega = dI_0\omega + I_0d\omega$$

Proof. Again, we estimate

$$||I_0\omega|| = \int_0^\infty ||\int_0^t \xi_s ds||_t^p dt \le ...,$$

so this norm is finite. The form $I_0\omega$ may not be smooth. We

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