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# $L_p$ -cohomologies of Riemannian f-horns.

Praca licencjacka na kierunku MATEMATYKA

> Praca wykonana pod kierunkiem dra hab. Andrzeja Webera Instytut Matematyki

### Oświadczenie kierującego pracą

Potwierdzam, że niniejsza praca została przygotowana pod moim kierunkiem i kwalifikuje się do przedstawienia jej w postępowaniu o nadanie tytułu zawodowego.

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Świadom odpowiedzialności prawnej oświadczam, że niniejsza praca dyplomowa została napisana przeze mnie samodzielnie i nie zawiera treści uzyskanych w sposób niezgodny z obowiązującymi przepisami.

Oświadczam również, że przedstawiona praca nie była wcześniej przedmiotem procedur związanych z uzyskaniem tytułu zawodowego w wyższej uczelni.

Oświadczam ponadto, że niniejsza wersja pracy jest identyczna z załączoną wersją elektroniczną.

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Podpis autora (autorów) pracy

#### Abstract

In this thesis  $L_p$ -cohomologies of Riemannian f-horn are calculated.

#### Słowa kluczowe

kohomologie de Rhama, topologia różniczkowa

### Dziedzina pracy (kody wg programu Socrates-Erasmus)

- 11.0 Matematyka, Informatyka:
- 11.1 Matematyka

### Klasyfikacja tematyczna

14 Algebraic Geometry14F (Co)homology theory14F40 de Rham cohomology

### Tytuł pracy w języku angielskim

An implementation of a difference blabalizer based on the theory of  $\sigma$  –  $\rho$  phetors

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## Chapter 1

# Introduction

In [Weber] the author considers a cone over Riemannian pseudomanifold. The cone is given a metric of the form  $dt \otimes dt \oplus t^2g$  and g is the metric on the nonsingular part of the original pseudomanifold. In the mentioned work,  $L_p$  cohomology of this space is presented.

This line of research can be traced back to Cheeger [Cheeger]. A similar approach was presented by Youssin [Youssin], where f-horns were considered.

We present a slight modification of this notions, by considering manifolds where the Riemannian metric is of the for

### Chapter 2

### **Preliminaries**

### 2.1. Vector spaces and tensors

Let us recall some basic facts about behaviour of norm when scaling tensors. If we consider a finite-dimensional vector space V with a given metric  $||\cdot||$  and define a new metric  $||x||_r = r||x||$ . Then in the space  $(V, ||\cdot||_r)^*$  dual to  $(V, |||\cdot|||)$ , the normed is scaled by the factor  $\frac{1}{r}$ , that is for any  $\varphi \in V^*$  we get  $||\varphi||_r = \frac{1}{r}||\varphi||$ .

We will make a simple observation that we will later use in the computations. We consider a Riemannian manifold M and tagent  $T_x$ M and cotangent  $T_x^*$ M spaces in the point x. Let the bases of these spaces be  $e_1, e_2, ..., e_n$  and dual  $e_1^*, e_2^*, ..., e_n^*$ . The volume form of this manifold is dvol  $= \pm e_1^* \wedge e_2^* \wedge ... \wedge e_n^*$ .

We now want to compute how forms from  $\Lambda(\mathcal{M})$  are scaled with respect to such a change in the norm. Suppose we are considering space of k-forms on  $\mathbb{M}$  at some arbitrary point. Then every k-form can be locally expressed in a basis consisting of products of covectors belonging to basis dual to the standard basis. That is every k-form in the point x using some local coordinates  $(x_1, x_2, ...x_n)$  can be written  $\sum_{I \in I} a_I dx_i$ , where I is the set of k-indices of form  $(i_1, i_2, ..., i_k)$ , with  $i_1, i_2, ... \in \{1, 2, ..., n\}$ . (following Einstein convention). Let us see how

basis vector is scaled:

$$\begin{split} ||dx_{i_1} \wedge dx_{i_2} \wedge \ldots \wedge dx_{i_k}||_t &= ||dx_{i_1}||_t \cdot ||dx_{i_2}||_t \cdot \ldots \cdot ||dx_{i_k}||_t = \\ & \frac{1}{t} ||dx_{i_1}|| \cdot \frac{1}{t} ||dx_{i_2}||_t \cdot \ldots \cdot \frac{1}{t} ||dx_{i_k}||_t = \frac{1}{t^k} ||dx_{i_1} \wedge dx_{i_2} \wedge \ldots \wedge dx_{i_k}||_t = \\ & \frac{1}{t^k} ||dx_{i_1} + \frac{1}{t^k} ||dx_{i_2} + \frac{1}{t^k} ||dx_{i_2} + \frac{1}{t^k} ||dx_{i_1} + \frac{1}{t^k} ||dx_{i_2} + \frac{1}{t^k} |$$

This means that any k form is scaled by  $1/t^k$  when metric is scaled by a factor of t. This applies also to the volume form, so we obtain:

$$d\text{vol}_t = \frac{1}{t^n}d\text{vol}$$

#### 2.2. Differential forms

**Riemannian metric** is a smooth symmetric covariant 2-tensor field on manifold  $\mathcal{M}$  that is positive definite at each point. (attaching a field of linear functions that takes two variables to every point of the manifold).

Consulting page 328 of Lee gives us that in any smooth local coordinates  $(x^i)$ , Riemannian metric can be written as:

$$g = g_{ij}dx^i \otimes dx^j = g_{ij}dx^i dx^j$$

where  $g_{ij}$  is a positive definite matrix of smooth functions.

The simplest example of Riemannian metric is *Euclidean metric* on  $\mathbb{R}^n$  given in standard coordinates by

$$g = \delta_{ij} dx^i dx^j$$
.

Citing prof. Lee, it is common to abbreviate the symmetric product of a tensor  $\alpha$  with itself by  $\alpha^2$ , so the Euclidean metric can also be written as

$$g = (dx^1)^2 + \dots + (dx^n)^2$$
,

so now it is way easier to understand what exactly is meant by  $dt \otimes dt + f^2g$ , which should be the same as  $dt^2 + f^2g$ .

**Induced map** For any smooth map  $F: M \to N$  between two smooth manifolds with or without boundary, the pullback  $F^*: \Omega^p N \to \Omega^p M$  carries closed forms to closed forms and exact forms to exact forms. It thus decsends to a linear map, denoted by  $F^*: H^p N \to H^p M$ , too.

Digression in digression: Pullback of  $F^*$  is

$$(F^*\omega)_p(v_1,...,v_n) = \omega_{F(p)}(dF_p(v_1),...,dF_p(v_k)).$$

### 2.3. Explaination about induced maps etc.

If we have two smooth maps  $F, G: M \to N$  and we want to prove that the induced maps are equal  $F^* = G^*$ . Given a closed p-form  $\omega$  on N, we need to produce a (p-1)-form  $\eta$  no M such that

$$G^*\omega - F^*\omega = d\eta$$

from this, it will follow that  $G^*[\omega] - F^*[\omega] = [d\eta] = 0$ , where [] is just taking homotopy equivalence class of given form. The author suggests a way to make it more systematic, by finding an operator h, which transforms closed p-forms on N to (p-1)-forms on M and satisfies

$$d(h\omega) = G^*\omega - F^*\omega.$$

Instead of defining  $h\omega$  only when  $\omega$  is close, it turns out to be far easier to define a map h from the space of all smooth p-forms on N to the space of smooth (p-1)-forms on M, which satisfies:

$$d(h\omega) + h(d\omega) = G^*\omega - F^*\omega,$$

which implies the above equality when  $\omega$  is closed. (To be completly precise, we define a family of maps, one for each p, which satisfy said equalities on adequate levels.

$$H(\mathcal{M} \times \mathbb{R}_{>})_{dR}^* = H(\mathcal{M})_{dR}^*$$

### Chapter 3

# Computation

The purpose of this chapter is to present the computation of  $L_p$ -cohomologies of Riemannian f-horns.

### 3.1. Setting

Here we introduce definitions and make the first observations. The setting is largely similar to the setting presented in [Weber], [Youssin], [Cheeger].

**Definition 3.1.1** (f-horn). Let  $\mathcal{M}$  be a Riemannian manifold. Consider a space  $\mathbb{R}_{\geq 0} \times \mathcal{M}$ . Define a Riemannian tensor on this product by  $dt^2 \oplus f^2(t)g$ , where g is the metric on  $\mathcal{M}$ . Such a space will be called an f-horn. We will denote it by  $c^f \mathcal{M}$ .

Remark 3.1.1. This terminology is present in works of Cheeger.

At first, we will focus our attention on scaling functions from family  $f_{\alpha}(x) = e^{\alpha x}$ , parametrized by  $\alpha \in \mathbb{R}$ . The intuition behind such manifolds is best presented graphically, as in the Figure ??.

We can make a simple observation here about differential forms associated with f-horn. The tangent space in the point (t, m) is:

$$T_{(t,m)}(c^f\mathcal{M}) = \mathbb{R} \times T_m\mathcal{M}$$

In terms of differential forms associated with f-horn, it means that  $\Lambda^k(\mathbb{R} \times T_m \mathcal{M}) = \Lambda^k(\mathbb{R}) \oplus \Lambda^k(\mathcal{M})$ . It can be rephrased in friendlier terms in the following way.

**Remark 3.1.2.** Every k-form  $\omega \in \Lambda^k T(c^f \mathcal{M})$ , and consequently every form in the space of p integrable forms  $L_k^p(c^f \mathcal{M})$  can be written as  $\omega = \eta + \xi \wedge dt$ , where both  $\eta$  and  $\xi$  do not contain dt. Please note that  $\eta$  is k-form and  $\xi$  is k-1 form.

Remark 3.1.3 (Norms of forms). We have the standard inclusion:

$$i_r: \mathcal{M} \to \mathbf{c}^f \mathcal{M},$$

$$i_r(x) = (x, r).$$

With this in mind, we will write  $\omega_r = i_r^*(\omega) = i_r^*(\eta)$ . Further, let us denote  $||\omega|_{\mathcal{M}\times\{r\}}|| = f(r)^{n/p-k}||\omega_r||$  as  $||\omega||_r$ . Moreover, if

$$\pi: \mathbf{c}^f \mathcal{M} \to \mathcal{M}$$

is the projection, we establish that for  $\eta \in L_p^*(\mathbf{c}^f \mathcal{M})$  we can write  $||\eta||_r := ||\pi^*\eta||_r = f(r)^{n/p-k}||\eta_r||$ .

As we are computing cohomologies, we should define the homology operator. Let

$$I_r: \Omega^*(\mathbf{c}^f \mathcal{M}) \to \Omega^{*-1}(\mathbf{c}^f \mathcal{I})$$

$$I_r(\omega)(x,t) = \int_x^t \xi(x,s)ds$$

The form  $I_r\omega$  is smooth for  $r \in (0,1)$ , but will also consider r = 0 in certain cases. If r > 0 then the homotopy formula holds:

$$\omega - \pi^*(\omega_r) = dI_r\omega + I_r d\omega.$$

This one probably is Poincare lemma in a version suited for our situation. This is a good place to rewrite it here using Bott

**Lemma 3.1.1.** Let k < (n+1)/p Then the form  $\pi^*$  is p-integrable for each p-integrable form  $\eta \in L^k_p(\mathcal{M})$ .

Proof.

$$||\pi^*\eta||^p = \int_{c\mathcal{M}} |\pi^*\eta(x,t)|^p d\text{vol}(c\mathcal{M}) = \int_0^\infty ||\eta||_t^p dt = ||\eta||^p \int_0^\infty f(t)^{n-pk} dt$$

so, if f is given by  $f(x) = e^{\alpha}$ , the last integral is  $||\eta||^p \int_0^{\infty} e^{\alpha(n-pk)} dt$ . This integral is convergent if  $\alpha(n-pk) < 0$ .

The following lemma will be useful in further computation.

**Lemma 3.1.2** (Estimation of  $\int \xi$ ). blabla bla

Proof.

$$||\int_{t}^{r} \xi_{x} dx|| \leq \int_{t}^{r} ||\xi_{x}|| dx =$$

$$\int_{r}^{t} f(x)^{i-n/p} f(x)^{n/p-i} ||\xi_{x}|| dx \leq$$

$$|\int_{r}^{t} f(x)^{i-n/p} dx|^{1/q} \cdot |\int_{r}^{t} f(x)^{n/p-i} ||\xi_{s}|| ds|^{1/p}$$

**Lemma 3.1.3.** Let k < (n+1)/p. Then for p-integrable  $\omega \in \Omega^k(\mathbf{c}^f \mathcal{M})$  the form  $I_r\omega$  is integrable.

*Proof.* For the case k < (n+1)/p = n/p - 1/q + 1 we get from the previous lemma:

$$||I_r\omega|| = \int_0^\infty ||\int_r^t \xi_s ds||dt \le C \int_0^\infty f(t)^{p/q},$$

and for k = (n+1)/p, we get:

$$||I_r\omega|| \le \int_0^1 |t(\log r - \log t)|^{p/q} dt$$

**Remark 3.1.4.** Based on the above lemma, we get that if k < (n+1)/p then a *p*-integrable closed form is cohomologous to  $\pi^*\omega_r$  for almost all r.

$$\omega = dI_0\omega + I_0d\omega$$

*Proof.* We have  $\omega - \pi^*(\omega_r) = dI_r\omega$  and  $I_r\omega$  is *p*-integrable. The form  $\omega_r$  is *p*-integrable for almost all r. So for almost all r the form  $dI_r\omega$  is also p-integrable.

**Lemma 3.1.4.** Let k > (n+1)/p Then  $I_0\omega$  is p-integrable for  $\omega \in L_p\Omega^k(\mathbf{c}^f\mathcal{M})$  and the homotopy formula holds:

$$\omega = dI_0\omega + I_0d\omega$$

Proof. Again, we estimate

$$||I_0\omega|| = \int_0^\infty ||\int_0^t \xi_s ds||_t^p dt \le ...,$$

so this norm is finite. The form  $I_0\omega$  may not be smooth. We

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