Calculating π on Pi Day

Author: Eric Silberstein

Claps: 430

Date: Mar 14

Happy Pi Day! I posted to our data science channel asking for smart, dumb, serious, funny, creative, or boring ways to estimate π. Here's what came back:

Vinicius Aurichio

```
(6*sum(1/n**2 for n in range(1, 1001)))**(0.5)
=> 3.1406380562059946
```

Computing the sum of the inverse of the square of all natural numbers is known as the <u>Basel</u> <u>problem</u>. The exact result is $pi\hat{A}^2/6$ and can be obtained in a variety of ways (<u>this</u> is my favorite). We can approximate pi by computing a partial sum and solving for pi from it.

Eric Silberstein

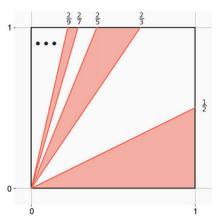
```
import numpy as np
delta = 1e-9
4 * delta * np.sum((1 - np.arange(0, 1, delta) ** 2) ** 0.5)
=> 3.1415926555897618
```

Center a circle of radius one at the origin. Calculate the area of the quarter of the circle in the top right quadrant by summing the area of lots of rectangles of width delta and height calculated using the pythagorean theorem. That area should be pi/4.

Tom Dinitz

```
import numpy as np
n = 100_000_000
5 - 4 * np.mean(np.round(np.random.rand(n)/np.random.rand(n)) % 2 == 0)
=> 3.14152348
```

Take a random point in the positive 1x1 square, and round the ratio of its coordinates. The probability that you get an even number is $\frac{5-\pi}{4}$. To compute this, note that we must have either $0 \le \frac{y}{x} \le \frac{1}{2}$, or $2n - \frac{1}{2} \le \frac{y}{x} \le 2n + \frac{1}{2}$, for some n >= 1. In other words, our point has to be between the x-axis and $y = \frac{1}{2}x$, or between the lines $y = (2n - \frac{1}{2})x$ and $y = (2n + \frac{1}{2})x$:



This latter category corresponds to triangles with height 1 whose bases stretch between $\frac{2}{4n+1}$ and $\frac{2}{4n-1}$. The area of these triangles can be summed using the Leibniz formula for pi/4:

$$\frac{1}{2}\left(\left(\frac{2}{3} - \frac{2}{5}\right) + \left(\frac{2}{7} - \frac{2}{9}\right) + \dots\right) = \left(\frac{1}{3} - \frac{1}{5}\right) + \left(\frac{1}{7} - \frac{1}{9}\right) + \dots = 1 - \frac{\pi}{4}$$

Thus, adding in the triangle between the x-axis and $y = \frac{1}{2}x$, we get the total area (i.e. the probability we were after): $\frac{1}{4} + (1 - \frac{\pi}{4}) = \frac{5-\pi}{4}$.

Sofiane Hadji

```
M = 1_000_000
2 * np.product([4 * (k**2) / (4 * (k**2)-1) for k in range(1,M)])
=> 3.1415918681913633
```

This approximation comes from the Wallis integrals

 $I_n = \int_0^{\pi/2} \sin^n x \, dx$, a family of integrals which follows the following recurrence relation:

- $\bullet \quad I_0 = \pi/2$
- \bullet $I_1 = 1$
- $I_n = \frac{n-1}{n}I_{n-2}$ for $n \ge 2$ (proof by integration by parts)

We can then compute the value of the integral for odd and even values of n:

$$I_{2n} = \pi \prod_{p=1}^{n} \frac{2p-1}{2p}$$
 and $I_{2n+1} = 2 \prod_{p=1}^{n} \frac{2p}{2p+1}$.

 (I_n) is a decreasing sequence (check $I_n - I_{n+1}$), so we can write $I_{2n+1} \leq I_{2n} \leq I_{2n-1}$

and
$$1 \le \frac{I_{2n}}{I_{2n+1}} \le \frac{I_{2n-1}}{I_{2n+1}} = \frac{2n+1}{2n}$$

Therefore $\lim_{n \to +\infty} \frac{I_{2n}}{I_{2n+1}} = 1$. Rewriting this quotient, we end up with

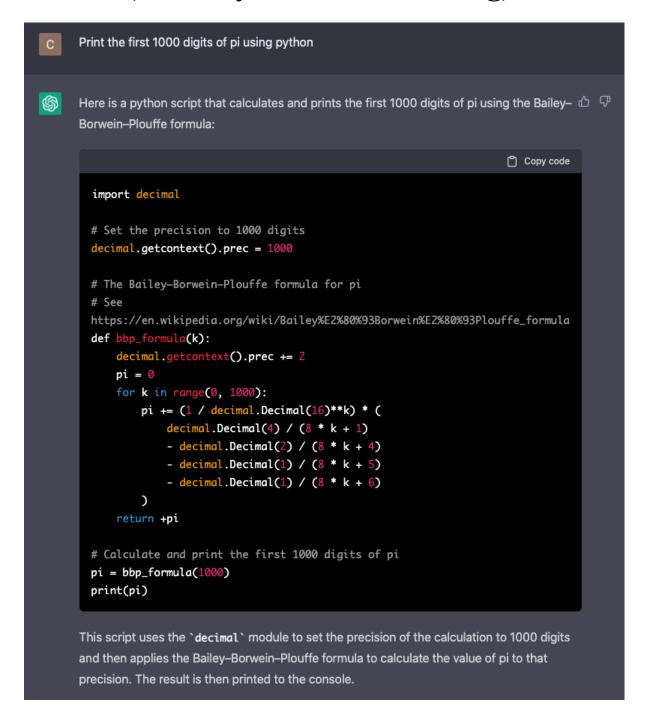
$$\lim_{n \to +\infty} \prod_{p=1}^{n} \frac{4p^{2}}{4p^{2}-1} = \frac{\pi}{2}$$

Eric Silberstein

```
import numpy as np
n = 100_000_000
4 * np.sum((np.random.rand(n) ** 2 + np.random.rand(n) ** 2) ** 0.5 < 1) /
=> 3.14188724
```

Throw darts at the 1x1 square in the positive-X, positive-Y quadrant sitting at the origin. Use the pythagorean theorem to see how many land within the circle of radius one centered at the origin. Since the area of that fourth of the circle is pi/4, and the area of the square is 1, the ratio of darts in the circle to all darts should be pi/4.

ChatGPT (courtesy of Conor Dowling)



It prints 1002 digits and the last 2 are wrong but in fairness I only asked for 1000.

Tristan Mills

```
m1 = 1.0

m2 = 10_000_000_000

m_sum = (m1 + m2)

mu = (m1 - m2)/m_sum

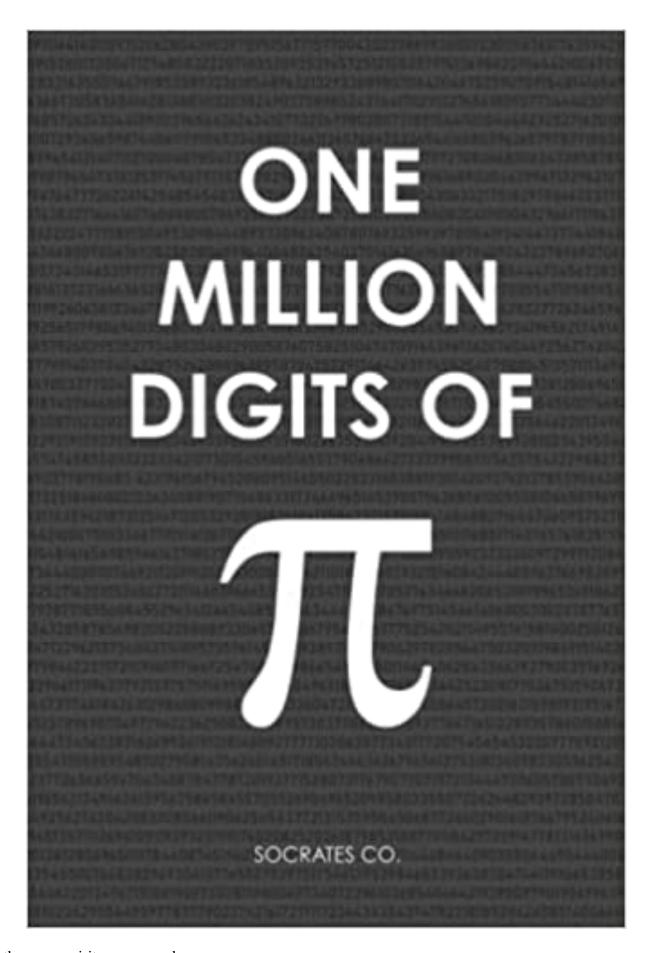
V1, v2 = 0., 1.
```

```
collisions = 0
while not (v1 <= 0 and v2 < 0 and abs(v1) <= abs(v2)):
    collisions += 1
    if collisions % 2:
        v1, v2 = mu * v1 + 2*m2/m_sum*v2, -mu * v2 + 2*m1/m_sum*v1
    else:
        v1 = -v1
print(collisions)
=> 314159
```

The above script simulates two blocks sliding on an infinite frictionless plane. The first mass is at rest, and the second is moving towards mass and is ten-billion times as massive. They experience perfect elastic collisions between themselves. On the far side of block one is a wall against which block one will also bounce against elastically. (Momentum and kinetic energy are conserved.) By counting the number of collisions between the blocks, but also block one against the wall as block 2's momentum is slowly turned around, we "count� pi without its decimal places. (You can increase the mass difference between the masses, but it needs to be 100^n where n is a positive integer. Also, some major shortcuts have been taken to shorten the script.)

Christina Dedrick

Lookup table. Store the value of π in some type of memory. Ask for it when needed. Consider buying this book if you find yourself without a computer. A printout of the first 10 digits kept in your wallet will also get you pretty far.



In the same spirit, you can ask someone.

Achu Balasubramanian

```
def calculate_pi(n, i=1):
    return n if i == n else (2 * i - 1) + (i ** 2 / calculate_pi(n, i +1))
4 / calculate_pi(24)
=> 3.141592653589793
```

(I chose n=24 since it was the smallest n where 4/calculate_pi(n) == math.pi returned True). There are some other fun continued fractions (I chose to implement the right-most one):

$$\pi = 3 + \frac{1^{2}}{6 + \frac{3^{2}}{6 + \frac{5^{2}}{6 + \frac{7^{2}}{6 + \frac{9^{2}}{6 + \cdots}}}}} = \frac{4}{1 + \frac{1^{2}}{2 + \frac{3^{2}}{2 + \frac{5^{2}}{2 + \frac{7^{2}}{2 + \cdots}}}}} = \frac{4}{1 + \frac{1^{2}}{3 + \frac{1^{2}}{3 + \frac{2^{2}}{5 + \frac{3^{2}}{4^{2}}}}}} = \frac{4}{1 + \frac{1^{2}}{3 + \frac{2^{2}}{3 + \frac{2^{2}}{5 + \frac{3^{2}}{4^{2}}}}}} = \frac{4}{1 + \frac{1^{2}}{3 + \frac{2^{2}}{5 + \frac{3^{2}}{4^{2}}}}} = \frac{4}{1 + \frac{1^{2}}{3 + \frac{2^{2}}{5 + \frac{3^{2}}{5 + \frac{3^{2}}{5$$

Side note: Ramanujan's Pi approximation is probably my favorite because of just how crazy it is:

$$rac{1}{\pi} = rac{2\sqrt{2}}{99^2} \sum_{k=0}^{\infty} rac{(4k)!}{k!^4} rac{26390k + 1103}{396^{4k}}$$

Charlie Natoli

```
In [2]:
         1 import numpy as np
         2 import time
         3 import pandas as pd
         4 from PIL import Image, ImageDraw
In [4]:
        1 # create an image of a circle
         2 n = 200
         3 im = Image.new(mode="RGB", size=(n, n))
         4 draw = ImageDraw.Draw(im)
         5 draw.pieslice(xy=((0,0),(n,n)), fill='red', start=0,end=360)
Out[4]:
In [6]: 1 # count up how many pixels there are of each color
         pixel_color_counts = pd.array(im.getdata()).value_counts()
         3 pixel_color_counts
Out[6]: (0, 0, 0)
(255, 0, 0)
                        8349
                       31651
        dtype: int64
         1 \# the ratio of a circle's area to a square bounding it is pi / 4.
In [7]:
         2 # We can compare the number of pixels in the circle's color (circle area)
                 to the number of pixels overall (bounding square area) to appoximate pi
         4 circle_body_color = max(pixel_color_counts)
         5 total_pixels = sum(pixel_color_counts)
         6 4 * circle_body_color / total_pixels
Out[7]: 3.1651
```

```
1 # does it seem to converge on pi if we use larger and larger images? Yes.
   # does it scale well? No! Very slow and O(N^2).
   def approx_pi_from_image(n):
        im = Image.new(mode="RGB", size=(n, n))
 7
        draw = ImageDraw.Draw(im)
 8
        draw.pieslice(xy=((0,0),(n,n)), fill='red', start=0,end=360)
 9
10
        pixel_color_counts = pd.array(im.getdata()).value_counts()
11
12
        circle body color = max(pixel color counts)
13
        total_pixels = sum(pixel_color_counts)
14
15
       return 4 * circle_body_color / total_pixels
16
17 for n in [100, 1000, 10000, 20000]:
18
       start = time.time()
19
        pi = approx_pi_from_image(n)
       time_elapsed = time.time() - start
20
        print(f'n: {n}, pi; {pi}, seconds elapsed: {time_elapsed:.3f}')
21
n: 100, pi; 3.19, seconds elapsed: 0.011
n: 1000, pi; 3.146924, seconds elapsed: 1.046
n: 10000, pi; 3.14215148, seconds elapsed: 101.743
```

n: 20000, pi; 3.14187167, seconds elapsed: 400.441

Nick Hartmann

```
from getch import getch
from mpmath import mp, pi
mp.dps = 1000
starting prompt = "Guess the digits of pi! What comes next after 3.14"
starting digit = 4
current_prompt = starting prompt
current digit = starting digit
high score = 0
while True:
    print(current prompt)
    target digit = str(pi)[current digit]
    guessed digit = getch()
    if guessed digit == target digit:
        current prompt += quessed digit
        current digit += 1
    else:
        if current digit > high score:
            high score = current digit
        print(f"""
              Incorrect! The next digit was {target digit}.
              You guessed {current digit-2} digits after the decimal point
              Your high score is {high score-2}.
```

Press 'y' to play again or any other key to exit

```
""")
if getch().lower() == "y":
    current_prompt = starting_prompt
    current_digit = starting_digit
else:
    break
```

The "guess and check� method. Run the code. You'll be asked to enter the digits of pi one by one. If you make a mistake, you'll be sent back to the beginning, but python will tell you what the correct digit was, and you can try again. Your high score will be tracked.

Wayne Coburn

Watch this:

Michael Lawson

```
import numpy as np
from math import pi
from sklearn.linear model import LinearRegression
MAX RADIUS = 100
MIN RADIUS = 0.1
NUM CIRCLES TO MEASURE = 200
# set random number seed for replicability
np.random.seed(seed=314)
# calculate the true values of radius-squared and area
radii = np.random.uniform(low=MIN RADIUS, high=MAX RADIUS, size=NUM CIRCLE
radii_squared = np.square(radii)
areas = pi * radii squared
# add Gaussian noise to areas (simulating measurement area)
areas with measurement error = areas + np.random.normal(loc=0, scale=15)
# fit linear regression to find value of pi
radii squared preprocessed array = radii squared.reshape(-1, 1)
linear model = LinearRegression()
linear model.fit (X=radii squared preprocessed array, y=areas with measurem
pi derived = linear model.coef
print ("The value of pi, calculated via linear regression assuming Gaussian
```

=> The value of pi, calculated via linear regression assuming Gaussian err

Motivation: Sometimes we have to deal with measurement error in real data. Suppose you have a bunch of circles of different radii, each of which you know, but you don't know each circle's area. You're able to measure these circles' area, but your area-measuring tool has measurement error. Based on previous times you've used the tool, you're reasonably confident this measurement error is mean-zero and near Gaussian. In this situation, linear

regression is a great approach to estimate pi â€" it can help you estimate the coefficient between radius-squared and area, after accounting for noise!

Michael Lawson

```
from math import pi

def point_estimator_of_real_number(num):
    return 3

estimated_pi = point_estimator_of_real_number(pi)

print("The value of pi estimated by the Lawsonian 3-Estimator is", estimated by the value of pi estimated by the Lawsonian 3-Estimator is 3
```

This method of calculating pi hearkens back to one of the most important lessons I learned in inferential statistics. Early in that class, our professor, Michael Kosorok, asked us to define an estimator. He let us throw out definitions for a few minutes, then walked to the board and wrote out a simple function: $\hat{a} \in \mathfrak{C}(X) = 3\hat{a} \in \mathfrak{A}$ it the function T of the data X always takes the value 3. This, he explained, is an estimator $\hat{a} \in \mathfrak{C}^{TM}$ a function of the data that returns a well-defined value. It $\hat{a} \in \mathfrak{C}^{TM}$ is just that most of the time, it $\hat{a} \in \mathfrak{C}^{TM}$ a very bad estimator. Inferential statistics exists precisely because, unless you understand the properties that make a statistical estimator well-behaved, it might just be the Kosorok 3-Estimator under the hood for all you know.

Iâ€TMve applied that idea to this particular estimation problem. And hey, what do you know â€" the Lawsonian 3-Estimator is actually pretty good at calculating pi!

Just don't ask it to calculate 2*pi.

David Lustig

One of my favorite ways to approximate pi comes from Buffon's needle problem. As an abridged history we can imagine that Buffon is frantically dropping needles (or matches or a baguette or something one dimensional) of length (*l*) on a floor with parallel lines a set width apart (t) and he wants to estimate the probability of the needle crossing a line. He runs out of patience and instead decides to publish a paper posing this question and a solution using integral geometry instead. The <u>proof</u> is of medium length and uses some sensible math so we take his word that the solution to this problem is:

```
p = 2/\ddot{I} \in *1/t
```

Unlike Buffon we have computers that never get bored of dropping matches, so we can simulate as follows:

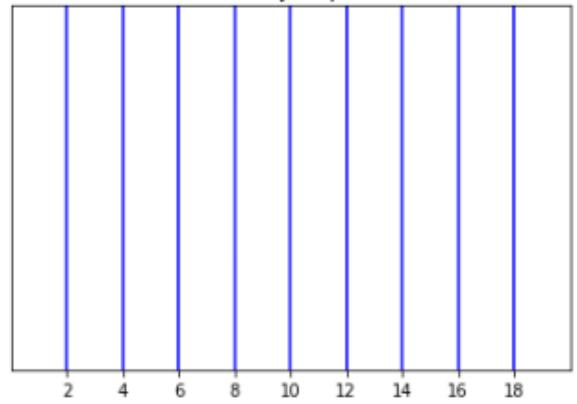
A) Import packages and make a "floor:�

```
import cmath
import math
import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
```

```
from IPython.display import display

fig = plt.figure()
ax = plt.subplot()
ax.set_ylim([0, 20])
ax.set_xlim([0, 20])
for i in range(2, 20, 2):
    plt.axvline(x=i, color='blue')
ax.set_xticks(range(2, 20, 2))
ax.set_yticks([])
plt.title('A beautifully striped floor')
```

A beautifully striped floor



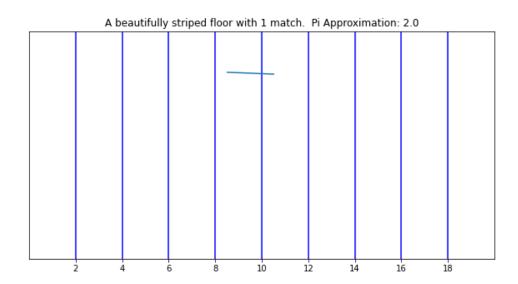
B) Drop matches at random and check if they cross a line:

```
def drop_match(x_bounds, y_bounds, match_length, ax):
    x_start = np.random.uniform(x_bounds[0], x_bounds[1])
    y_start = np.random.uniform(y_bounds[0], y_bounds[1])
    pt = cmath.rect(match_length, math.radians(np.random.uniform(0, 360)))
    x_end = pt.real + x_start
    y_end = pt.imag + y_start
    ax.plot([x_start, x_end], [y_start, y_end])
    return [x_start, x_end]

def check_match(xcoords, lines):
    inside = 0
    for line in lines:
        if min(xcoords) < line and max(xcoords) > line:
            inside = 1
```

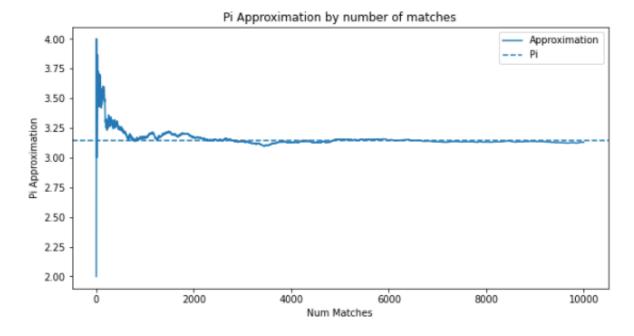
return inside

```
fig = plt.figure(figsize=(10,5))
fig.set facecolor('white')
ax = plt.subplot()
ax.set ylim([0, 20])
ax.set xlim([0, 20])
for i in range (2, 20, 2):
    plt.axvline(x=i, color='blue')
ax.set xticks(range(2, 20, 2))
ax.set yticks([])
match counter = 0
match cross line counter = 0
pi approximations = []
for i in range(10000):
    coords = drop match([2, 18], [2,18], 2, ax)
    match counter += 1
    match cross line counter += check match(coords, range(2, 20, 2))
    pi approx = 2/(match cross line counter/match counter)
    pi approximations.append(pi approx)
plt.title(f'A beautifully striped floor with {match counter} matches.
                                                                         Ρi
display(fig)
```

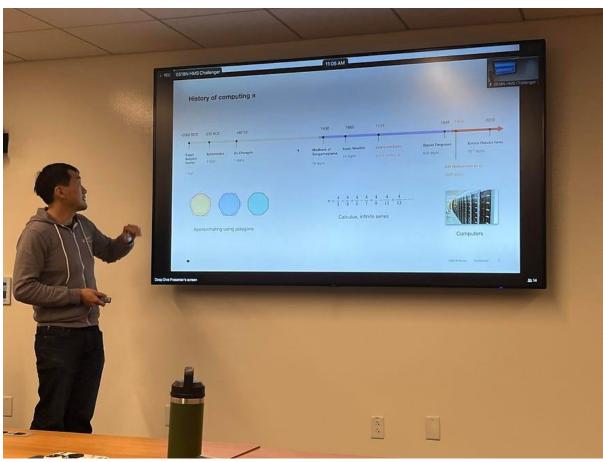


C) Look at how cool it is that our approximation approaches pi:

```
fig = plt.figure(figsize=(10,5))
sns.lineplot(x=range(len(pi_approximations)), y=pi_approximations)
plt.xlabel('Num Matches')
plt.ylabel('Pi Approximation')
plt.axhline(np.pi, linestyle = '--')
plt.title('Pi Approximation by number of matches')
plt.legend(['Approximation', 'Pi'])
```



After 10,000 match drops we have $\ddot{l}\in \hat{a}\%^{\hat{}}$ 3.1308703819661865



Dave Xiao talking about Pi and Data Science on Pi Day