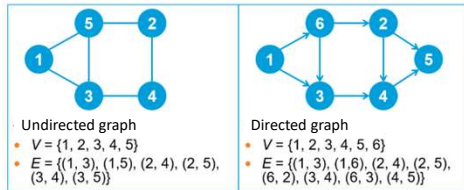


RECALL THE BASIC CONCEPTS OF GRAPHS

- A graph is a structure consisting of nodes (also called vertices) and connections between nodes (also called edges or arcs).
- Graph notation: $G = (V, E)$, where V is a set of nodes and E is a set of edges (arcs)
- $(u, v) \in E$: v is adjacent to u .



RECALL THE BASIC CONCEPTS OF GRAPHS

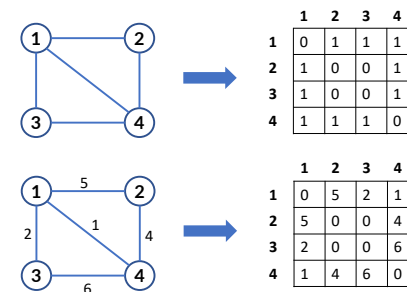
- Given $G = (V, E)$ is a graph
 - The path from vertex s to vertex t on the graph is a sequence of vertices v_1, v_2, \dots, v_k where
 - $s = v_1, t = v_k$
 - $(v_i, v_{i+1}) \in E$
 - A cycle is a path in which the first and last vertices coincide
 - An undirected graph G is called connected if there is always a path between any two vertices of G

GRAPH REPRESENTATION DATA STRUCTURE

- Adjacency matrix, weight matrix
- Adjacency list
- Edge list

GRAPH REPRESENTATION DATA STRUCTURE

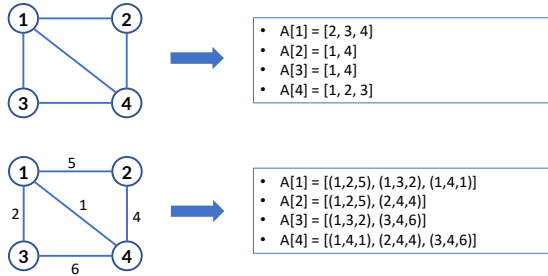
- Adjacency matrix, weight matrix



GRAPH REPRESENTATION DATA STRUCTURE

- Adjacency list

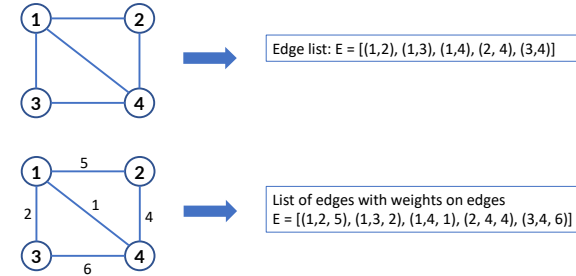
- $A[v]$: list of vertices (or edges/arcs for weighted graphs) adjacent to vertex v



GRAPH REPRESENTATION DATA STRUCTURE

- Edge list

- E : list of edges/arcs of the graph



GRAPH TRAVERSAL

- Traverse the graph in depth: visit the vertices of the graph, each vertex exactly once
- $A[v]$: list of vertices adjacent to v

```
DFS(u, A) { // depth first search from u
    visited[u] = true; // Visit u;
    for v in A[u] do {
        if visited[v] = false then {
            DFS(v, A);
        }
    }
}
```

```
DFS(G = (V, A)) { // depth first search on G
    for v in V do visited[v] = false;
    for v in V do {
        if visited[v] = false then {
            DFS(v, A);
        }
    }
}
```

GRAPH TRAVERSAL

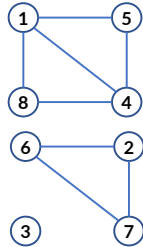
- Traverse the graph breadthwise: visit the vertices of the graph, each vertex exactly once
- $A[v]$: list of vertices adjacent to v

```
BFS(G = (V, A)) { // breadth first search on G
    for v in V do visited[v] = false;
    for v in V do {
        if visited[v] = false then {
            BFS(v, A);
        }
    }
}
```

```
BFS(u, A) { // breadth first search from u
    Q = Empty;
    Q.push(u); visited[u] = true; // visit u
    while Q not empty do {
        v = Q.pop();
        for x in A[v] do
            if visited[x] = false then {
                Q.push(x); visited[x] = true; // visit x
            }
    }
}
```

FIND CONNECTED COMPONENTS

- Description of the problem
 - Given an undirected graph $G = (V, A)$ in it
 - V is the set of vertices
 - A is an adjacency list structure: $A[v]$ is a list of vertices adjacent to v
 - Need to find connected components of G
- Algorithm:
 - Apply depth-first search (or breadth-first search) on G
 - $DFS(u)$ allows visiting all vertices belonging to the same connected component with u



FIND CONNECTED COMPONENTS

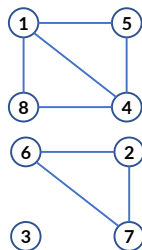
- nbCC: number of connected components of G
- $C[v]$: index (running from 1 to nbCC) of the connected component containing vertex v

```
DFS(u, A) { // DFS from u
    visited[u] = true; // Visit nh u;
    C[u] = nbCC;
    for v in A[u] do {
        if visited[v] = false then {
            DFS(v, A);
        }
    }
}
```

```
DFS(G = (V, A)) { // DFS on G
    for v in V do visited[v] = false;
    nbCC = 0;
    for v in V do {
        if visited[v] = false then {
            nbCC = nbCC + 1;
            DFS(v, A);
        }
    }
}
```

FIND CONNECTED COMPONENTS

- Illustrate with C language
- Data
 - Line 1: contains two positive integers n and m representing the number of vertices and edges, respectively
 - Line $i + 1$ ($i = 1, 2, \dots, m$): contains 2 positive integers u and v which are the 2 endpoints of the i th edge
- Result
 - Write a list of vertices of each connected component found on one line



stdin	stdout
8 8	C[1]: 1 4 5 8
1 4	C[2]: 2 6 7
1 5	C[3]: 3
1 8	
2 6	
2 7	
4 5	
4 8	
6 7	

FIND CONNECTED COMPONENTS

```
#include <stdio.h>
#define N 100001

typedef struct Node{
    int id;
    struct Node* next;
}Node;

int n, m; // #nodes and #edges of G
Node* A[N]; // A[v]: pointer to an adj list
int nbCC; // #connected components
int C[N]; // C[v]: connected component
           //containing v
```

```
Node* makeNode(int id){
    Node* p = (Node*)malloc(sizeof(Node));
    p->id = id; p->next = NULL;
    return p;
}

Node* insert(int id, Node* h){
    Node* p = makeNode(id);
    p->next = h;
    return p;
}
```

FIND CONNECTED COMPONENTS

```
void input(){
    scanf("%d %d",&n,&m);
    for(int v = 1; v <= n; v++){ A[v] = NULL;
    for(int i = 1; i <= m; i++){
        int u,v; scanf("%d%d",&u,&v);
        A[u] = insert(v,A[u]);
        A[v] = insert(u,A[v]);
    }
}
```

```
void DFS(int u){
    C[u] = nbCC;
    for(Node* p = A[u]; p != NULL; p = p->next){
        int v = p->id;
        if(C[v] == -1){
            DFS(v);
        }
    }
}
```

FIND CONNECTED COMPONENTS

```
void DFSG(){
    for(int u = 1; u <= n; u++) C[u] = -1;
    nbCC = 0;
    for(int u = 1; u <= n; u++){
        if(C[u] == -1){
            nbCC = nbCC + 1;
            DFS(u);
        }
    }
}
```

```
void printCC(){
    for(int k = 1; k <= nbCC; k++){
        printf("C[%d]: ",k);
        for(int v = 1; v <= n; v++){
            if(C[v] == k) printf("%d ",v);
        }
        printf("\n");
    }
}
```

FIND CONNECTED COMPONENTS

```
int main(){
    input();
    DFSG();
    printCC();
    return 0;
}
```

CHECK BIPARTITE GRAPHS

- Problem description
 - Given an undirected graph $G = (V, A)$ in it
 - V is the set of vertices
 - A is an adjacency list structure: $A[v]$ is a list of vertices adjacent to v
 - Check if G is a bipartite graph or not?

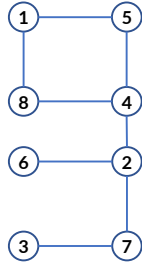
CHECK BIPARTITE GRAPHS

- Data

- Line 1: contains two positive integers n and m representing the number of vertices and edges, respectively
- Line $i + 1$ ($i = 1, 2, \dots, m$): contains 2 positive integers u and v which are the 2 endpoints of the i th edge

- Result

- Write 1 if the graph is bipartite and 0 otherwise



stdin	stdout
8 8	1
1 5	
1 8	
2 4	
2 6	
2 7	
3 7	
4 5	
4 8	

CHECK BIPARTITE GRAPHS

- Algorithm:

- Apply breadth-first search on G
- $d[v]$: level (path length from starting vertex to v in BFS) of vertex v
- BFS(u): visit all vertices with the same connected component with u
 - If the connected component containing u is a bipartite graph, then vertices v with even $d[v]$ will be on the side containing u , and vertices v with odd $d[v]$ will be on the other side.
 - If it is detected that edge (u, v) has $d[u]$ and $d[v]$ with the same parity, then the given graph is not a bipartite graph.

CHECK BIPARTITE GRAPHS - PSEUDOCODE

```

BFS(u) {
    Q = empty queue; Q.push(u); d[u] = 0;
    while Q not empty do {
        v = pop();
        for x in A[v] do {
            if(d[x] > -1){
                if d[v] + d[x] is even then return false;
            }
            else { d[x] = d[v] + 1; Q.push(x); }
        }
    }
    return true;
}

```

```

solve(){
    for u = 1 to n do d[u] = -1;
    for u = 1 to n do if(d[u] = -1){
        if(BFS(u) = false) {
            return false;
        }
    }
    return true;
}

```

CHECK BIPARTITE GRAPHS - COMPLETE CODE

```

#include <stdio.h>
#include <stdlib.h>
#define N 100001
typedef struct Node{
    int id;
    struct Node* next;
}Node;
Node* makeNode(int id){
    Node* p = (Node*)malloc(sizeof(Node));
    p->id = id; p->next = NULL;
    return p;
}

```

```

Node* head;
Node* tail;
void initQueue(){
    head = NULL; tail = NULL;
}
int queueEmpty(){
    return head == NULL && tail == NULL;
}
void push(int id){
    Node* p = makeNode(id);
    if(queueEmpty()){ head = p; tail = p; }
    else { tail->next = p; tail = p; }
}

```

CHECK BIPARTITE GRAPHS – COMPLETE CODE

```
int pop(){
    if(queueEmpty()) return -1;
    int r = head->id; Node* tmp = head;
    head = head->next;
    if(head == NULL) tail = NULL;
    free(tmp);
    return r;
}

Node* add(int id, Node* h){
    Node* p = makeNode(id);
    p->next = h; return p;
}
```

```
int n,m;
Node* A[N];
int d[N]; // d[v] is the level of v
void input(){
    scanf("%d %d", &n, &m);
    for(int v = 1; v <= n; v++) A[v] = NULL;
    for(int i = 1; i <= m; i++){
        int u,v;
        scanf("%d %d", &u, &v);
        A[u] = add(v, A[u]); A[v] = add(u, A[v]);
    }
}
```

CHECK BIPARTITE GRAPHS – COMPLETE CODE

```
int BFS(int u){
    initQueue(); push(u); d[u] = 0;
    while(!queueEmpty()){
        int v = pop();
        for(Node* p = A[v]; p != NULL; p = p->next){
            int x = p->id;
            if(d[x] > -1){ if(d[v] % 2 == d[x] % 2) return 0; }
            else{ d[x] = d[v] + 1; push(x); }
        }
    }
    return 1;
}
```

```
void solve(){
    for(int v = 1; v <= n; v++) d[v] = -1;
    int ans = 1;
    for(int v = 1; v <= n; v++) if(d[v] == -1){
        if(!BFS(v)){ ans = 0; break; }
    }
    printf("%d", ans);
}

int main(){
    input();
    solve();
    return 0;
}
```

HUST

THANK YOU !