

UNIT 7

Z-TRANSFORM

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□ Contents

1. Definition of Z-transform
2. Region of convergence of Z-transform

□ Learning Objectives

After completing this lesson, you will have a grasp of the following concepts:

- The definition and significance of the Z-transform in signal processing.
- Methods for determining the region of convergence for the Z-transform of discrete-time signals.

1. Definition of Z transform

$$x(n) \xleftrightarrow{Z} X(z)$$

$$X(z) \equiv Z\{x(n)\}$$

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

$$X(z) = \cdots + x(-2)z^2 + x(-1)z + x(0) + x(1)z^{-1} + x(2)z^{-2} + \cdots$$

- The Z-transform exists only for values of Z that make the series converge.
- The region of convergence (ROC) of X(z) is the set of values of Z for which X(z) has finite values.

Example

- Compute the Z-transform and the region of convergence for the following signal:

$$x_1(n) = \{1, 2, 5, 7, 0, 1\}$$

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

$$X_1(z) = 1 + 2z^{-1} + 5z^{-2} + 7z^{-3} + z^{-5}$$

ROC is the Z plane except $z = 0$

Example

- Compute the Z-transform and the region of convergence for the following signal:

$$x_2(n) = \left(\frac{1}{2}\right)^n u(n)$$

$$X_2(z) = \sum_{n=0}^{\infty} \left(\frac{1}{2}\right)^n z^{-n} = \sum_{n=0}^{\infty} \left(\frac{1}{2z}\right)^n$$

$$1 + A + A^2 + A^3 + \dots = \frac{1}{1 - A}, |A| < 1$$



$$X(z) = \frac{1}{1 - \frac{1}{2z}} = \frac{1}{1 - \frac{1}{2}z^{-1}} = \frac{z}{z - \frac{1}{2}} \quad \text{ROC: } |z| > \frac{1}{2}$$

Observation

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

- The Z-transform is simply an alternative representation of a signal..
- The coefficient of z^{-n} in the transform is the value of the signal at time n .
- The exponent of Z contains information about the time needed to determine the samples of the signal.
- With the Z-transform, we can represent signals with infinite duration in the time domain by a finite form in the Z domain.

2. Region of convergence of the Z transform

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

- Region of Convergence – ROC is the range of values of for which the geometric series in the definition of the Z-transform converges.
- The Cauchy criterion is commonly used to determine the ROC. Specifically, a series of the form:

$$\sum_{n=0}^{\infty} u_n = u_0 + u_1 + u_2 + \dots$$

converges if the condition $\lim_{n \rightarrow \infty} |u_n|^{1/n} < 1$ is satisfied.

Determine ROC

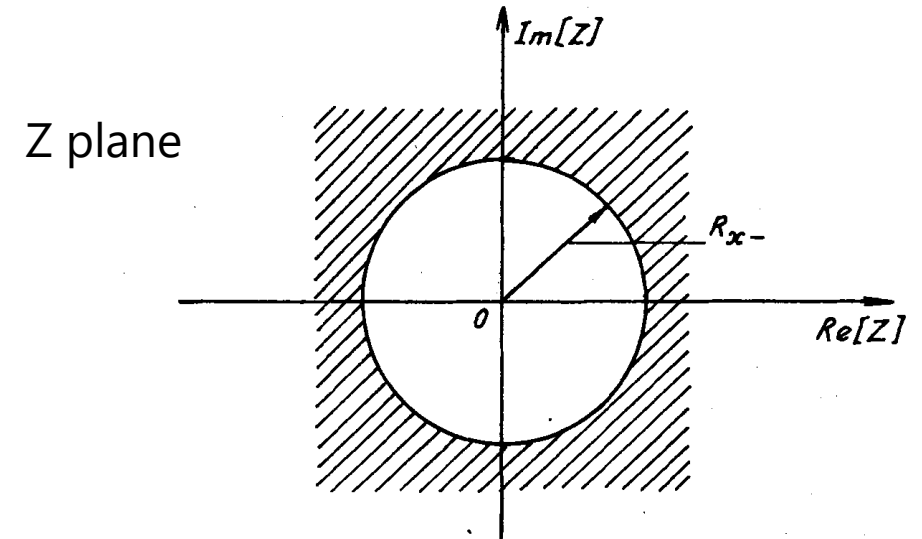
$$X(z) = X_1(z) + X_2(z) = \sum_{n=-\infty}^{-1} x(n)z^{-n} + \sum_{n=0}^{\infty} x(n)z^{-n}$$

- Applying Cauchy criterion we obtain

$$\lim_{n \rightarrow \infty} |x(n)z^{-n}|^{1/n} < 1 \Rightarrow \lim_{n \rightarrow \infty} |x(n)|^{1/n} |z^{-1}| < 1$$

- Assuming $\lim_{n \rightarrow \infty} |x(n)|^{1/n} = R_{x-}$
- $X_2(z)$ converge if z satisfies

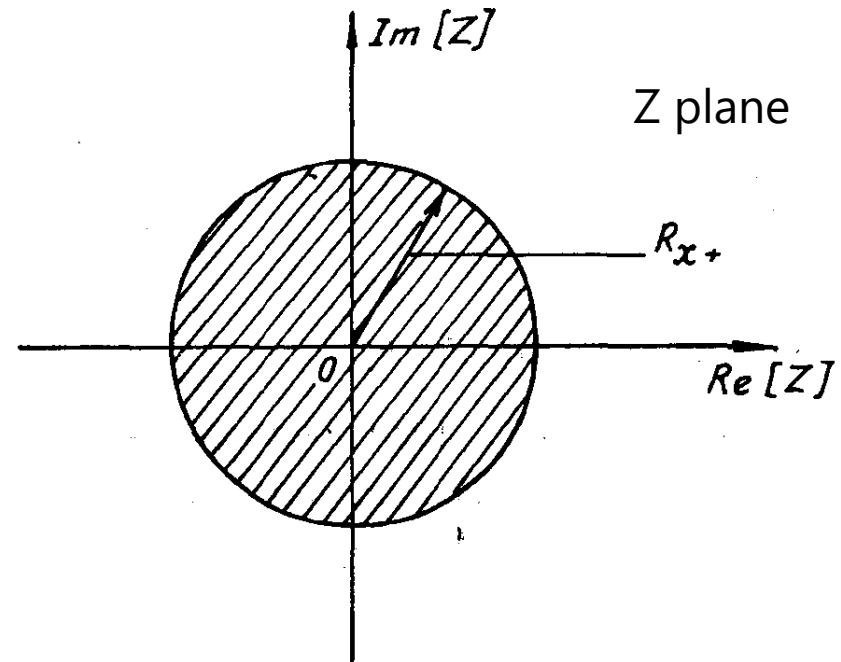
$$|z| > R_{x-}$$



ROC of $X_1(Z) = \sum_{n=-\infty}^{-1} x(n)z^{-n}$

- Non-causal signal
- $X_1(z)$ converge if z satisfies $|z| < R_{x+}$, where

$$R_{x+} = \frac{1}{\lim_{n \rightarrow \infty} |x(-n)|^{1/n}}$$



ROC of Z transform

- In the general case, ROC of Z transform is

$$0 \leq R_{x-} < |z| < R_{x+} \leq \infty$$

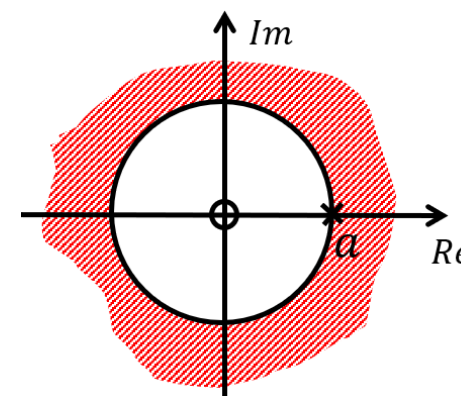
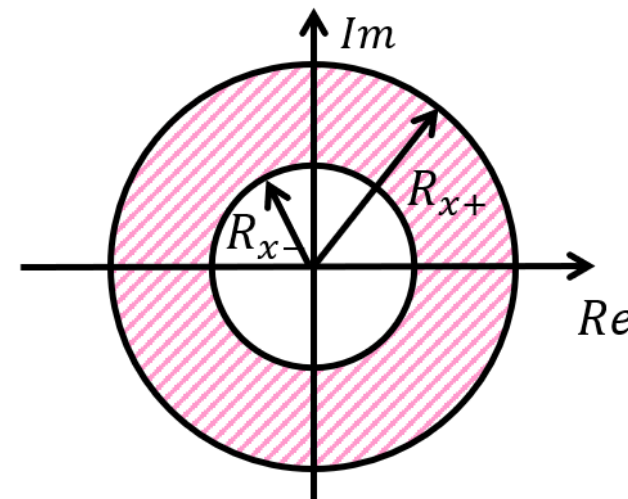
- Example: Given the signal $x(n) = a^n u(n)$, determine the Z transform and its ROC.

$$X(z) = \sum_{n=0}^{\infty} a^n z^{-n} = \sum_{n=0}^{\infty} (az^{-1})^n = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

- ROC: $|z| > |a|$, $R_{x-} = |a|$, $R_{x+} = \infty$
- Zero point: $z = 0$
- Pole point: $z = a$
- ROC excludes pole

$$R_{x-} = \lim_{n \rightarrow \infty} \frac{|x(n)|^{1/n}}{1}$$

$$R_{x+} = \frac{1}{\lim_{n \rightarrow \infty} |x(-n)|^{1/n}}$$



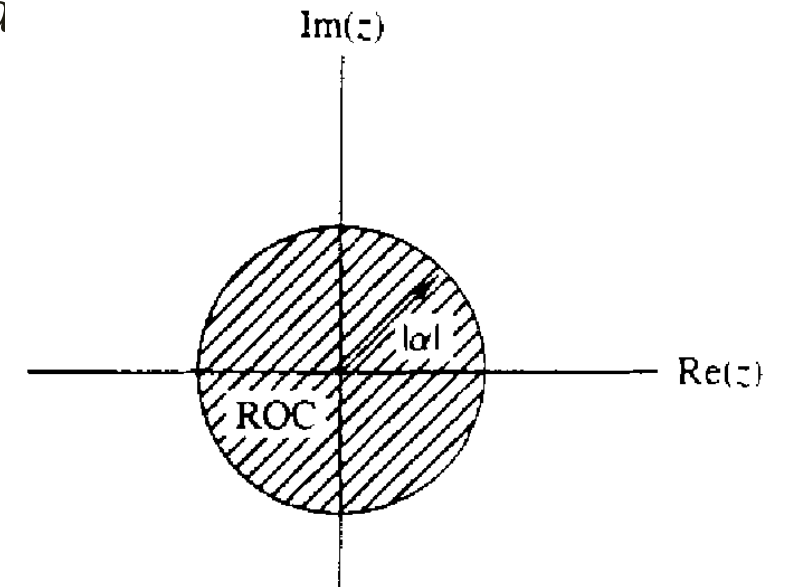
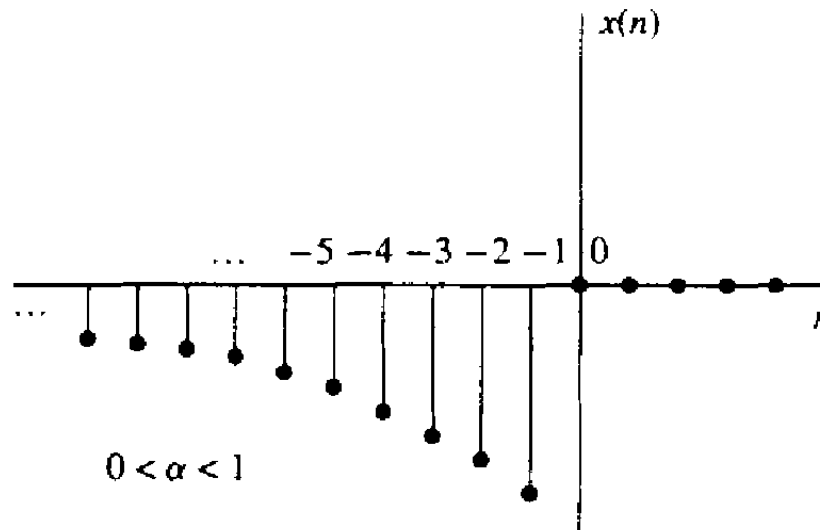
Example

- Determine Z-transform of the following signal

$$x(n) = -\alpha^n u(-n - 1) = \begin{cases} 0 & n \geq 0 \\ -\alpha^n & n \leq -1 \end{cases}$$

$$\text{ROC: } |z| < |\alpha|$$

$$x(n) = -\alpha^n u(-n - 1) \xleftrightarrow{Z} X(z) = \frac{1}{1 - \alpha z^{-1}} = \frac{Z}{Z - \alpha}$$



Observation

- The causal signal $\alpha^n u(n)$ and the anti-causal signal $-\alpha^n u(-n-1)$ have the same Z-transform expression.
- Therefore, the Z-transform expression alone is not sufficient to determine the signals in the time domain.

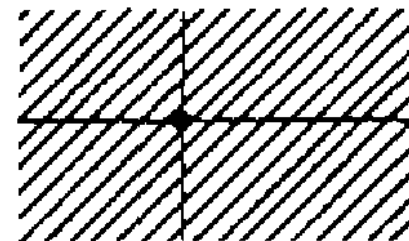
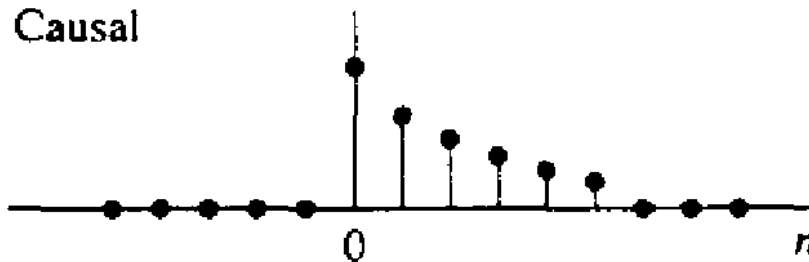


A discrete-time signal $x(n)$ is uniquely defined by two components:

- ❖ $X(z)$
- ❖ its region of convergence (ROC)

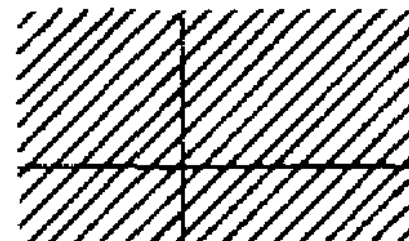
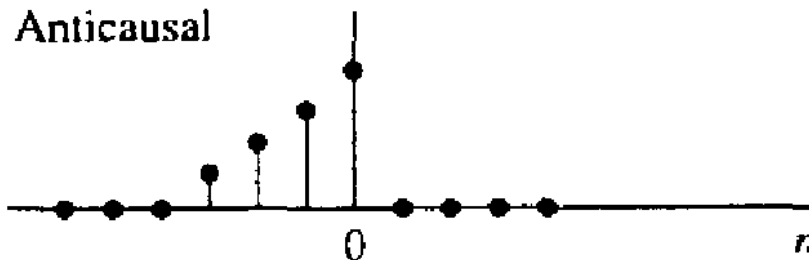
Summary: Finite-length signal

Causal



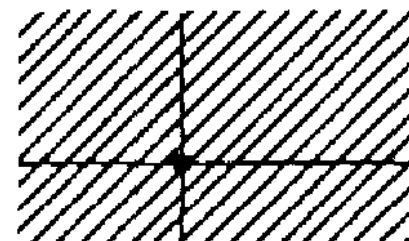
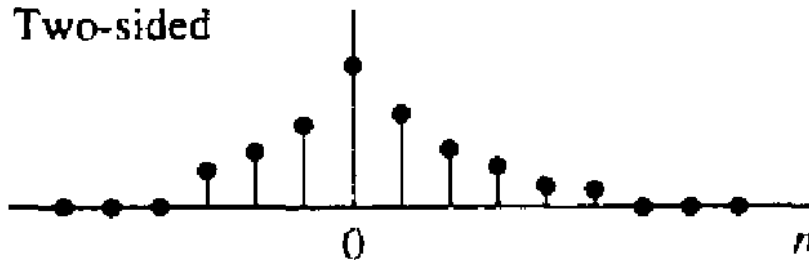
Entire z -plane
except $z = 0$

Anticausal



Entire z -plane
except $z = \infty$

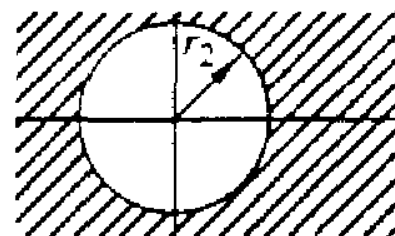
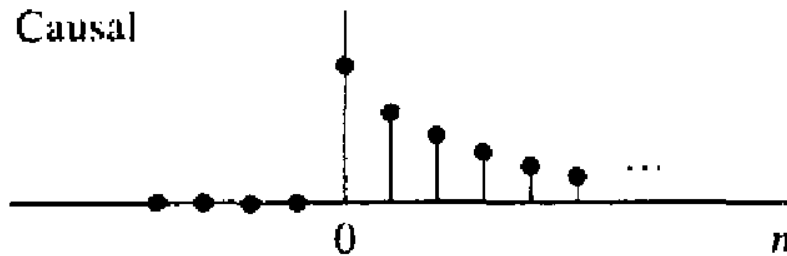
Two-sided



Entire z -plane
except $z = 0$
and $z = \infty$

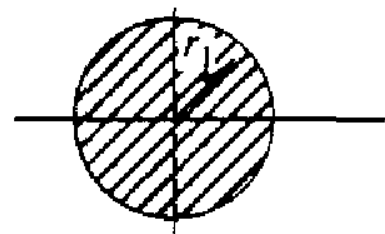
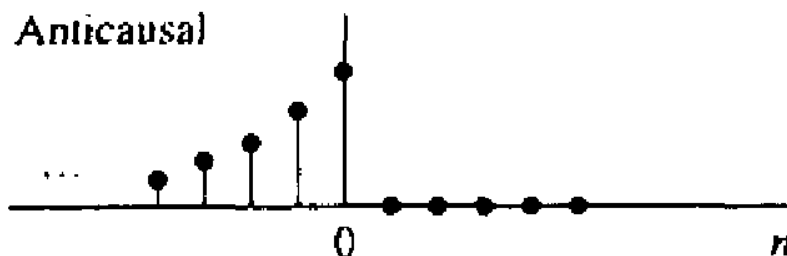
Summary: Infinite-length signal

Causal



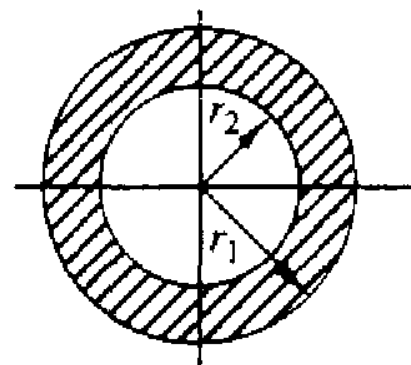
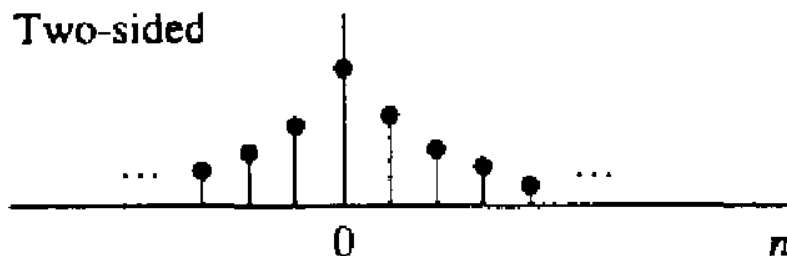
$$|z| > r_2$$

Anticausal



$$|z| < r_1$$

Two-sided



$$r_2 < |z| < r_1$$

4. Summary

- The Z-transform allows for the representation of a signal in the complex domain. An important advantage of the Z-transform is that it allows for the representation of infinite-length signals as finite-length forms.
- The region of convergence (ROC) of the Z-transform is the range of values of Z for which the infinite power series in the Z-transform definition converges. Together with the Z-transform expression, the ROC uniquely determines the corresponding discrete-time signal $x(n)$ in the time domain.

5. Assignment

- Assignment 1

□ Determine Z-transform and its ROC of the following signals:

a. $x_1(n) = \{1, 2, 5, 7, 0, 1\}$
 ↑

b. $x_2(n) = \delta(n)$

c. $x_3(n) = \delta(n - k), \quad k > 0$

d. $x_4(n) = \delta(n + k), \quad k > 0$

Homework

- Assignment 2

- Determine Z-transform and its ROC of the following signals:

- a. $x(n) = (\cos \omega_0 n)u(n)$

- b. $x(n) = (\sin \omega_0 n)u(n)$

- c. $x(n) = (3^{n+1} - 1)u(n)$

- d. $x(n) = 2^{-n}u(n) + 3^{n+1}u(n)$

Homework

- Assignment 3
 - Calculate the Z-transform and ROC of the following signals. Then comment on the changes in the ROC:
 - a. $x(n) = 2^n u(n)$
 - b. $y_1(n) = 3^n x(n)$
 - c. $y_2(n) = \left(\frac{1}{3}\right)^n x(n)$
 - d. $y_3(n) = e^{j\pi n/2} x(n)$

Homework

- Assignment 4
 - Calculate the Z-transform and ROC of the following signals:
 - a. $x(n) = a^n(\cos \omega_0 n)u(n)$
 - b. $x(n) = a^n(\sin \omega_0 n)u(n)$
 - c. Ramp signal $u_r(n)$

The next unit 8

PROPERTIES OF THE Z-TRANSFORM

References:

- ***Nguyễn Quốc Trung (2008), Xử lý tín hiệu và lọc số, Tập 1, Nhà xuất bản Khoa học và Kỹ thuật, Chương 1 Tín hiệu và hệ thống rời rạc.***
- ***J.G. Proakis, D.G. Manolakis (2007), Digital Signal Processing, Principles, Algorithms, and Applications, 4th Ed, Prentice Hall, Chapter 1 Introduction.***



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