# HUST

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### **APPLIED ALGORITHMS**



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Dijkstra algorithm with priority queues

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#### Shortest Path from a source node in a directed graph non-negative weights

- Given a directed graph G = (V, E, A, w) in which
  - V: set of nodes
  - E: set of arcs
  - A[v]: list of adjacent nodes of v
  - w(u, v): non-negative weight of the arc (u, v)
- Given a source node *s* and a destination nodes *t*, find the shortest path from *s* to *t* in *G*
- Dijkstra algorithm
  - d[v]: upper bound of the length of the shortest path from s to v
  - Upper bound improvement
    - If d[v] > d[u] + w(u, v) then
      - update d[v] = d[u] + w(u, v)

```
Dijkstra(G = (V, E, w)) {
  for (v \in V) {
     d(v) = w(s,v);
  S = V \setminus \{s\};// tap cac dinh chua tim duoc duong
               // di ngan nhat
  while(S \neq \{\}) {
    u = select a node \in S having minimum d(u);
    if (u = t) break; // found the shortest path
    S = S \setminus \{u\};
    for (v \in S) {
      if(d(v) > d(u) + w(u,v) {
         d(v) = d(u) + w(u,v);
```

#### Shortest Path from a source node in a directed graph non-negative weights

```
#include<bits/stdc++.h>
using namespace std;
const int N = 1e5+1;
const int INF = 1e9;
struct Arc{
   int node;
   int w;
   Arc(int node, int w){
       node = node; w = w;
};
int n,m;
vector<Arc> A[N];
int s,t;
int d[N]; // d[v] is the distance from s to v
```

```
void solve(){
   for(int v = 1; v <= n; v++) d[v] = INF;
   priority queue<pair<int,int>, vector<pair<int,int> >,
                                       greater<pair<int,int> > > pq;
   d[s] = 0; pq.push(make pair(d[s],s));
   while(!pq.empty()){
       pair<int,int> p = pq.top(); pq.pop();
       int u = p.second;
       if(u == t) break;
       for(int i = 0; i < A[u].size(); i++){
           Arc a = A[u][i]; int v = a.node; int w = a.w;
           if(w + d[u] < d[v])
               d[v] = d[u] + w; pq.push(make pair(d[v],v));
   cout << "Length of the shortest Path from s to t is " << d[t] << endl;</pre>
```





## THANK YOU!