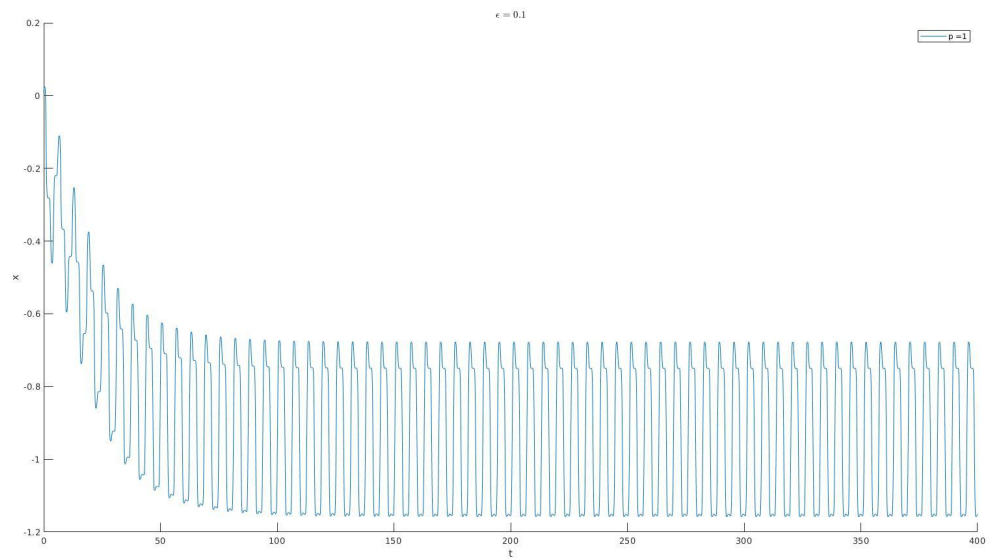


Name : Sudhanshu Mishra  
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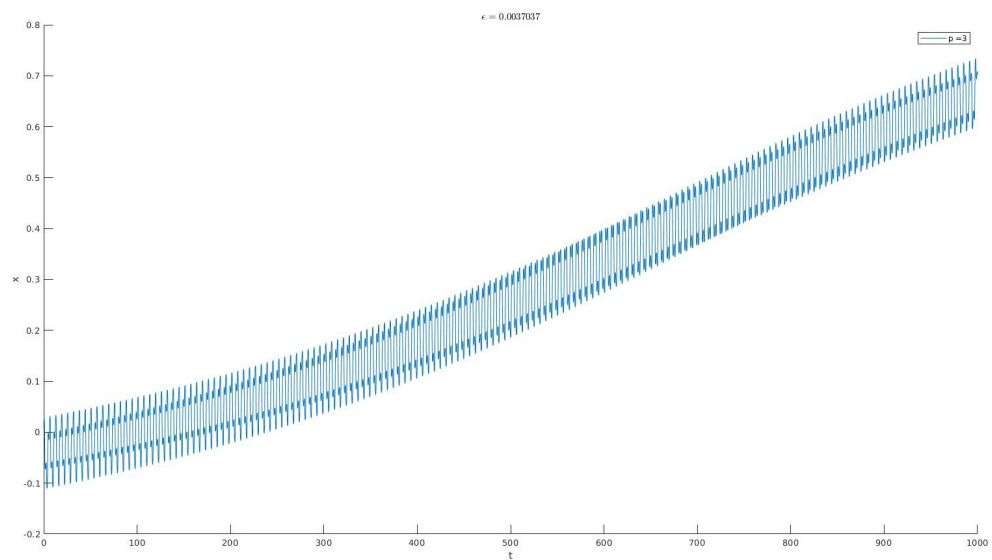
Q1.  
Numerical Simulation where avg value stabilizes.

P = 1



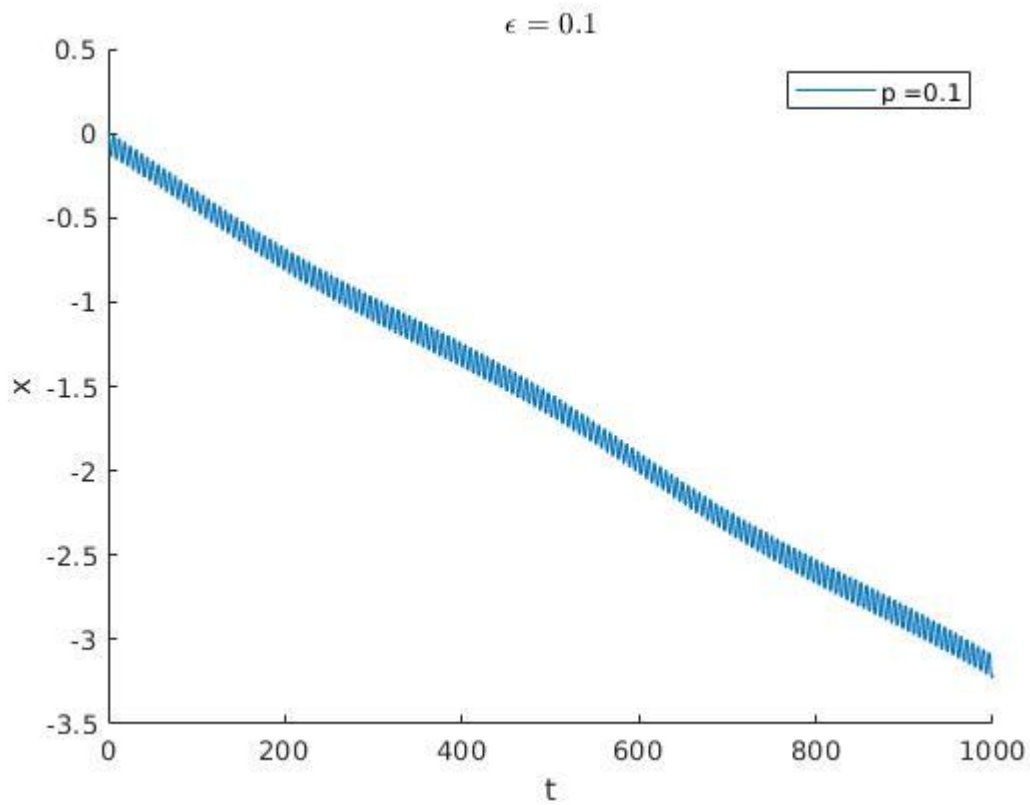
Numerical Simulation where it grows without bound

P = 3



Numerical Simulation where it grows negatively without bound

P = 0.1



After applying MMS : The avgd eqn is

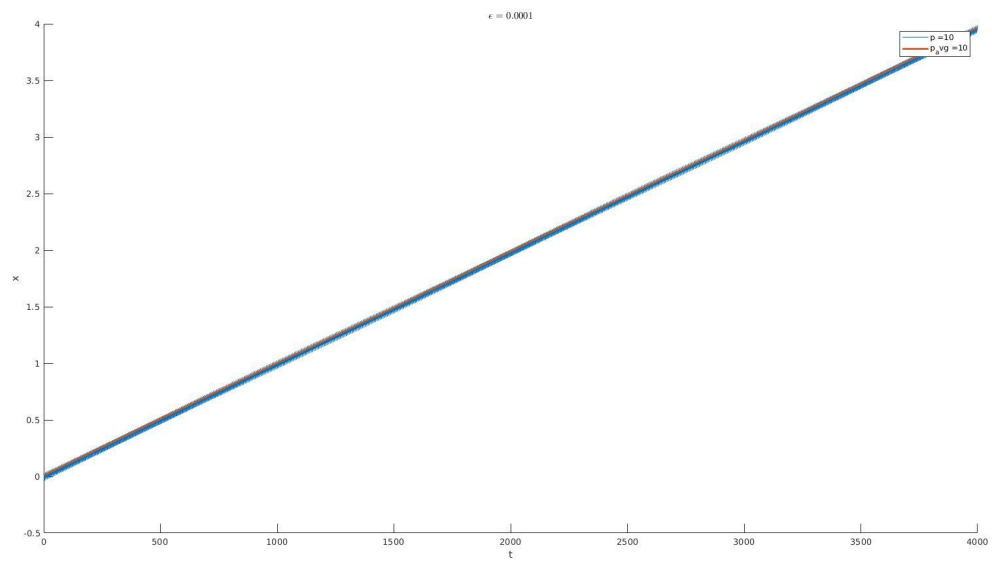
$$rep_{eq} = \frac{d}{dT_2} X(T_2) + \frac{(-15792 p^3 - 5880 p) \sin(X(T_2)) \cos(X(T_2))^3}{1680} + \frac{(7896 p^3 + 2940 p) \sin(X(T_2)) \cos(X(T_2))}{1680} - \frac{5 p^6}{48} + \frac{303 p^4}{560} - \frac{3 p^2}{80} + \frac{5}{16}$$

Choosing epsilon = 0.1/p<sup>3</sup>

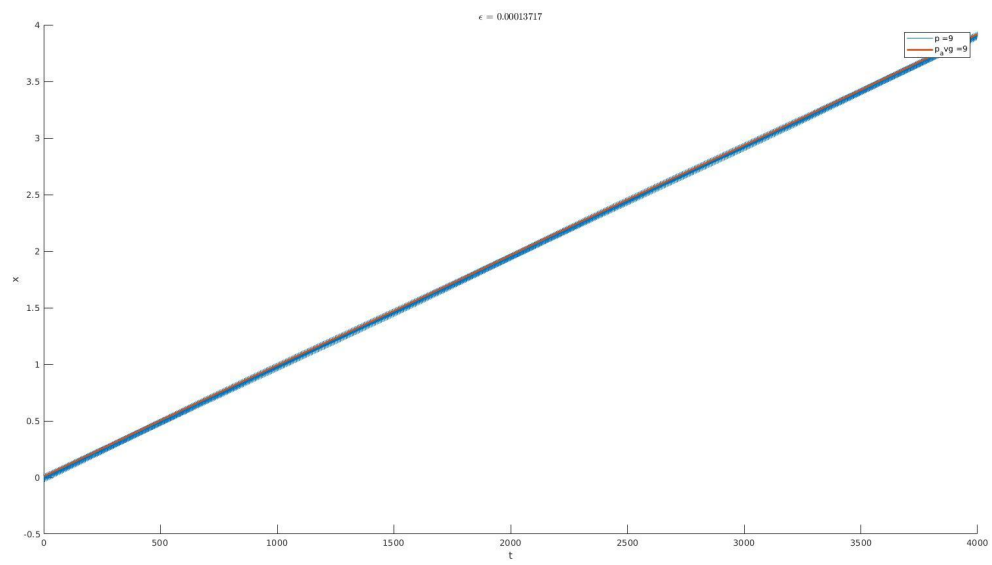
For different values of p:

P ranging from 1 to 10 :

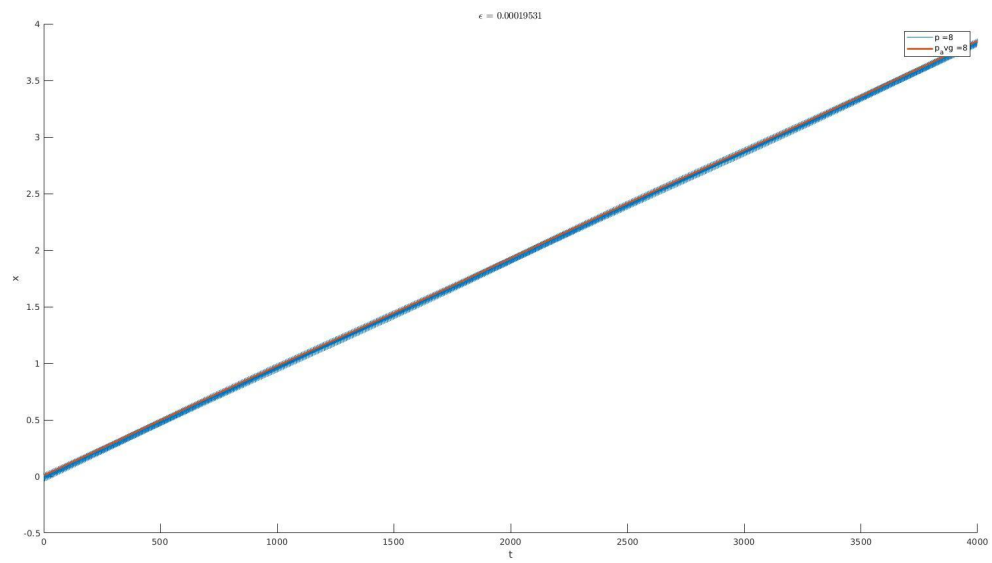
P = 10



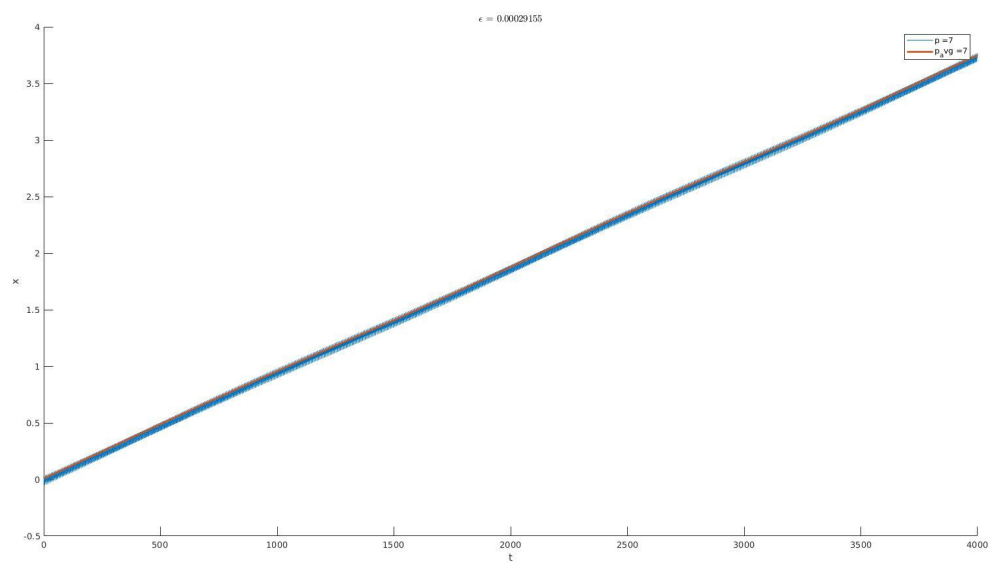
P = 9



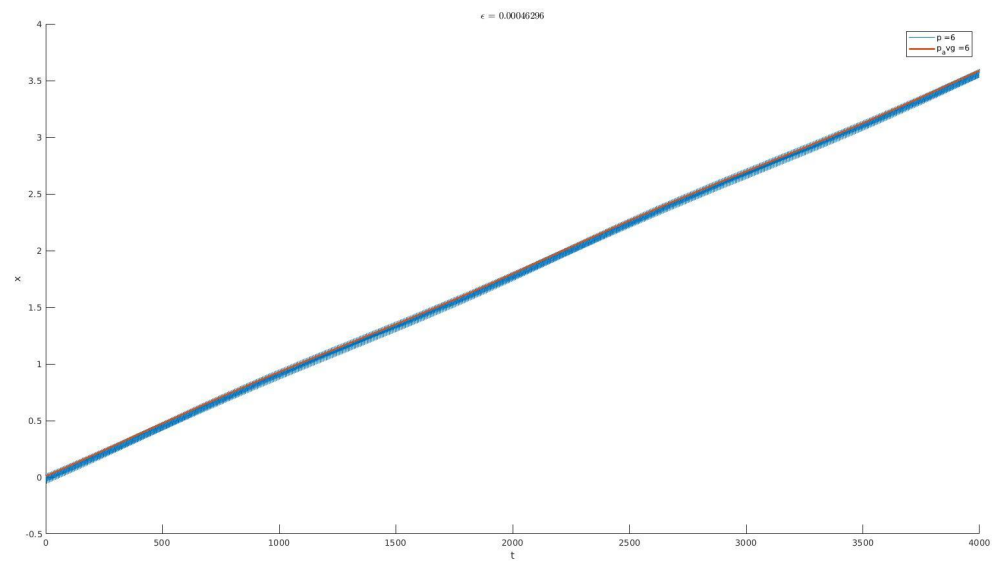
P = 8



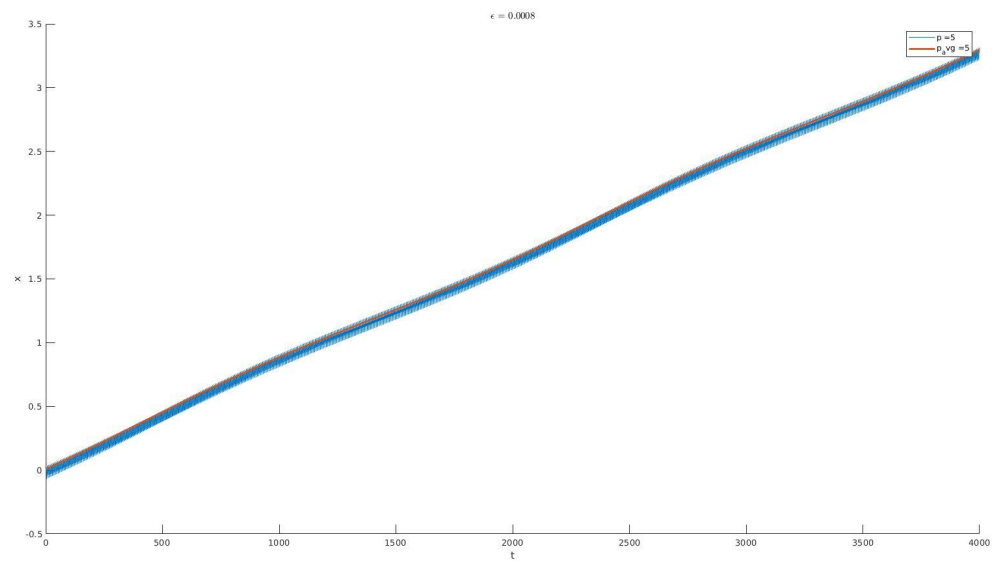
$P = 7$



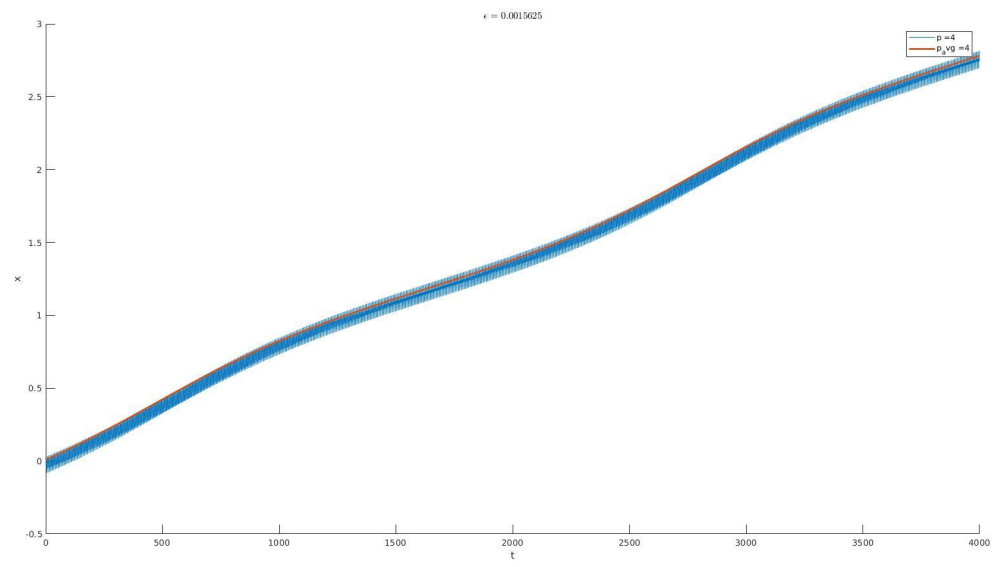
$P = 6$



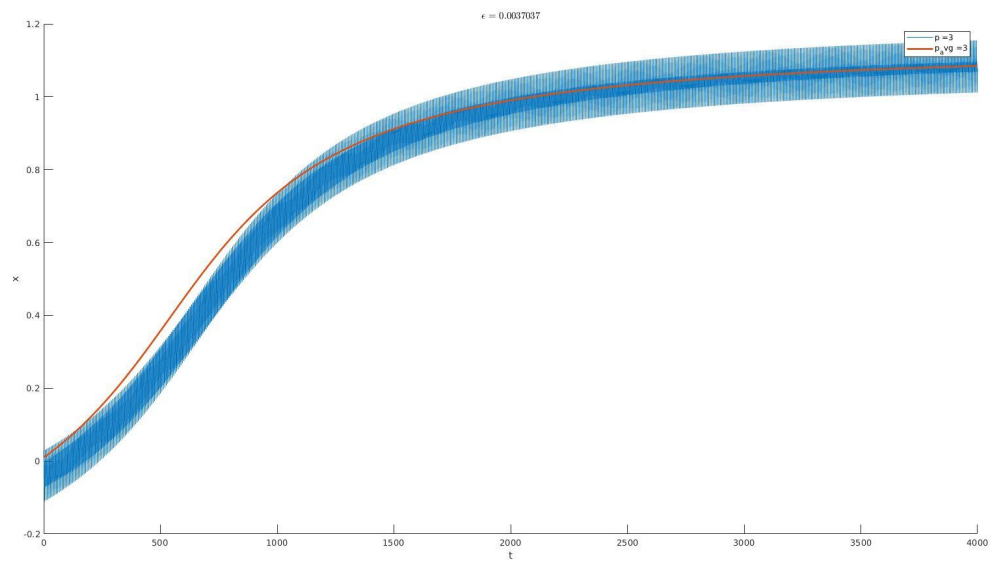
$P = 5$



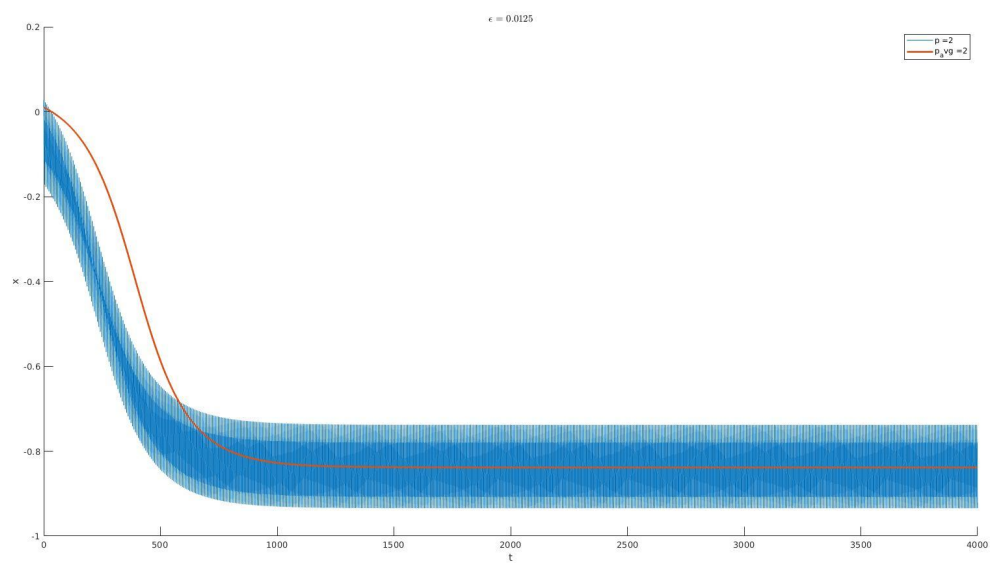
$P = 4$



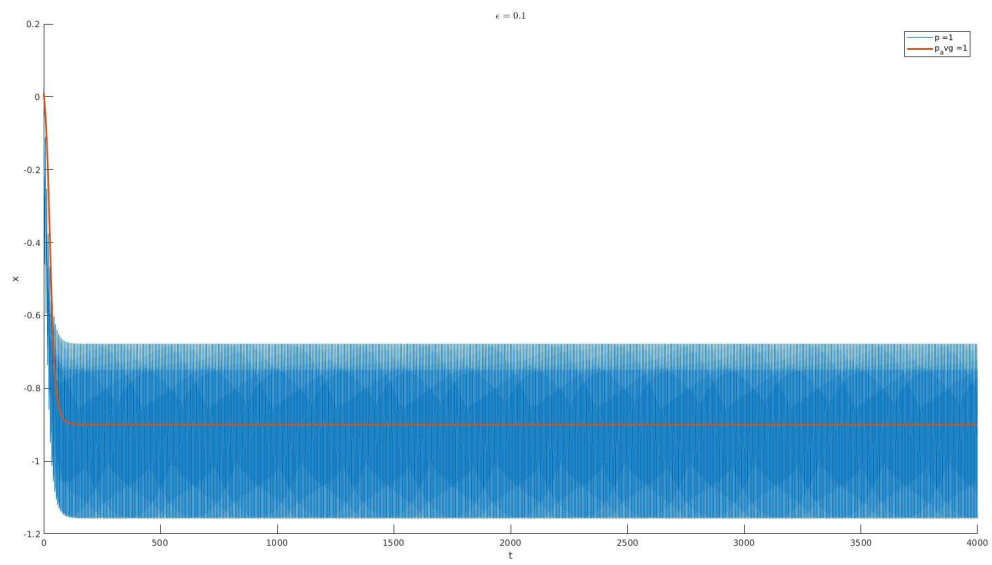
$P = 3$



$P = 2$

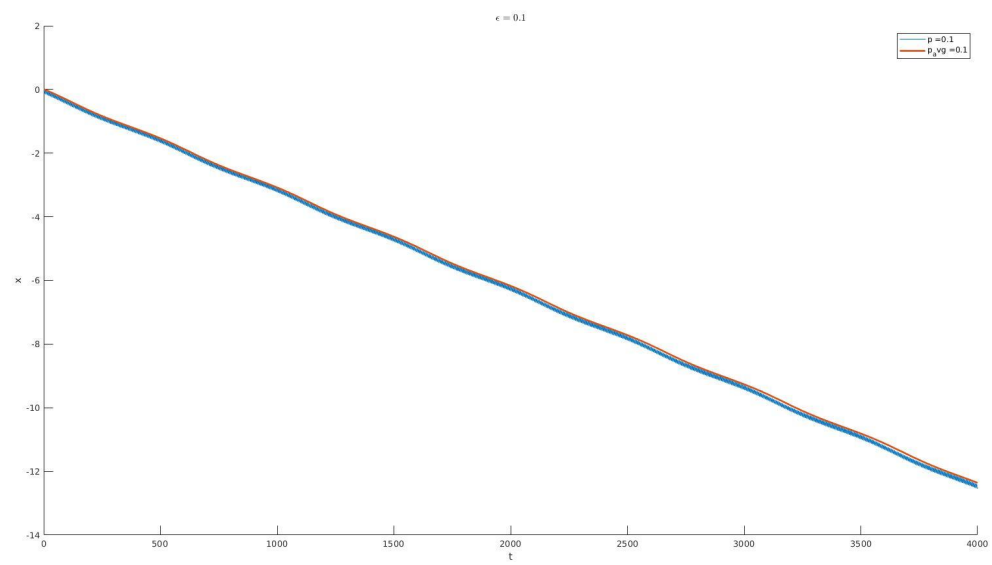


P = 1



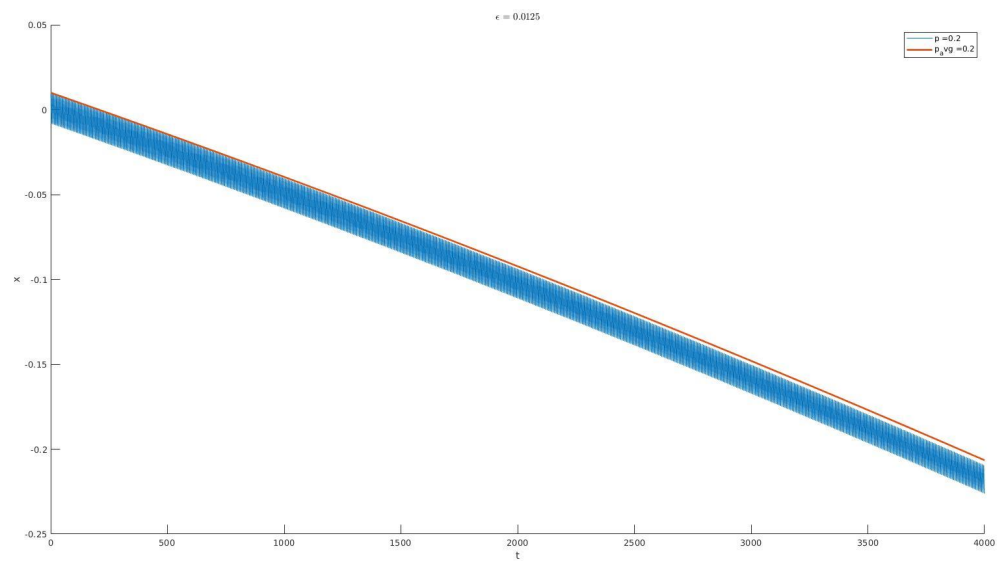
Different values of P ranging from 0.1 to 0.9  
Choosing epsilon =  $0.0001/p^3$

P = 0.1

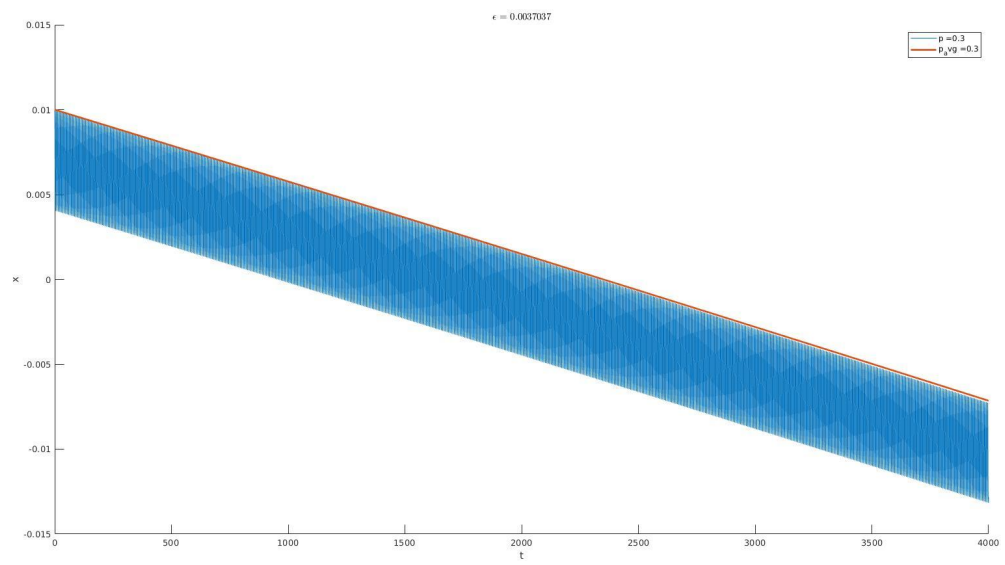




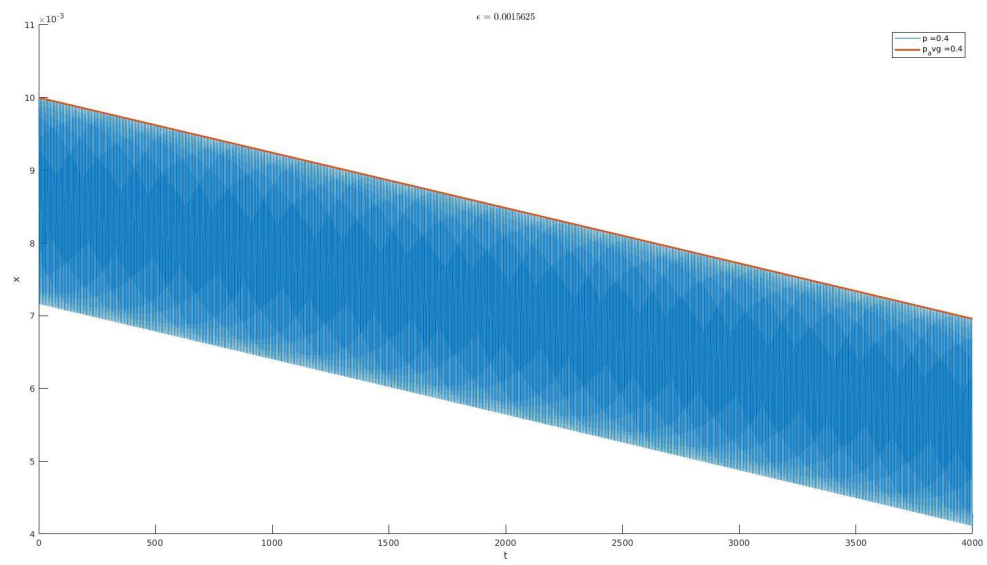
P = 0.2



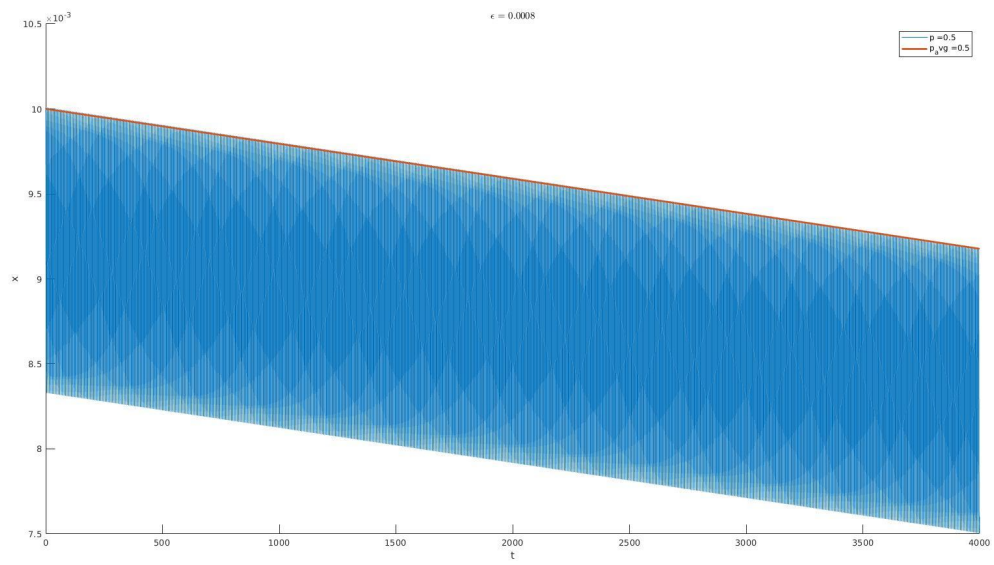
P = 0.3



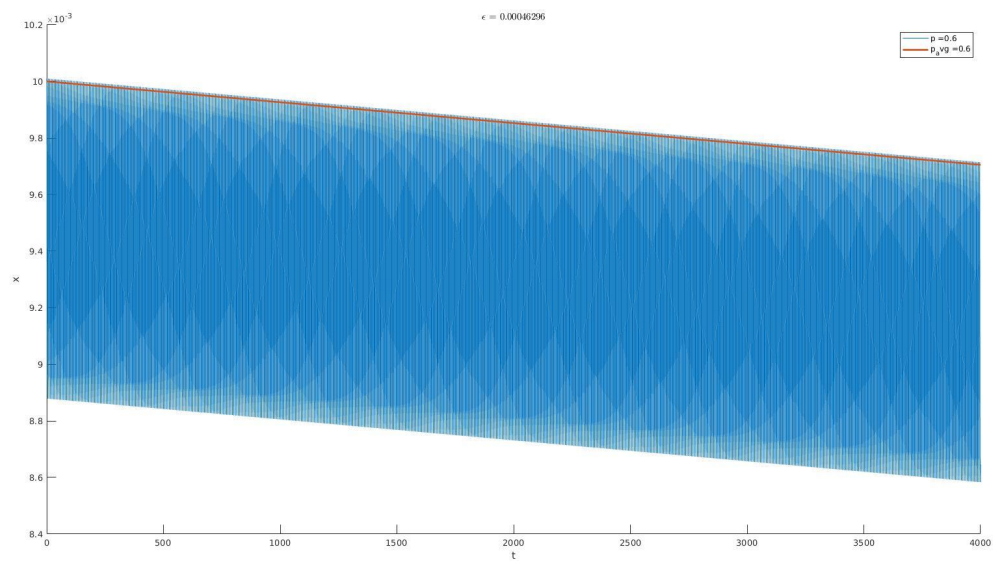
P = 0.4



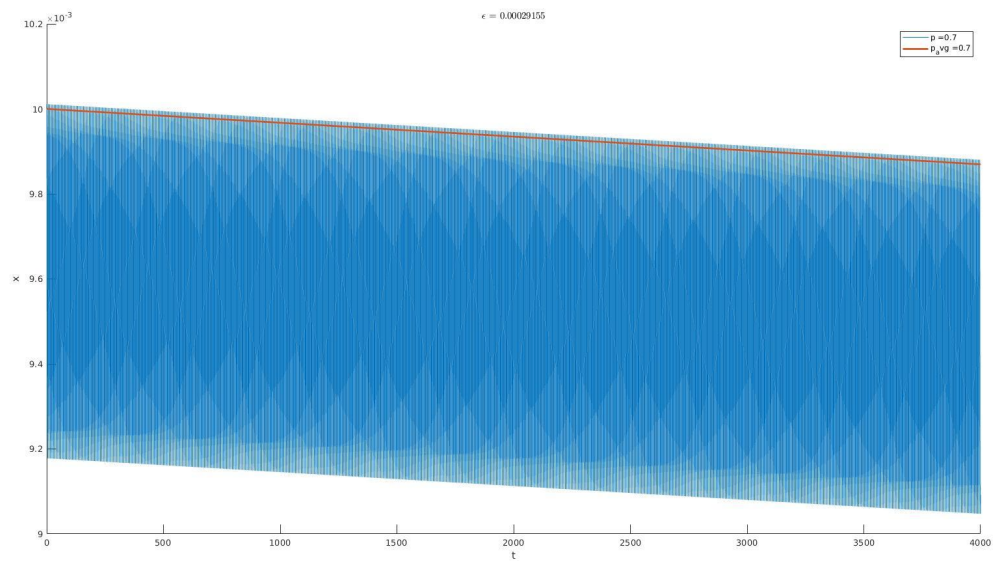
P = 0.5



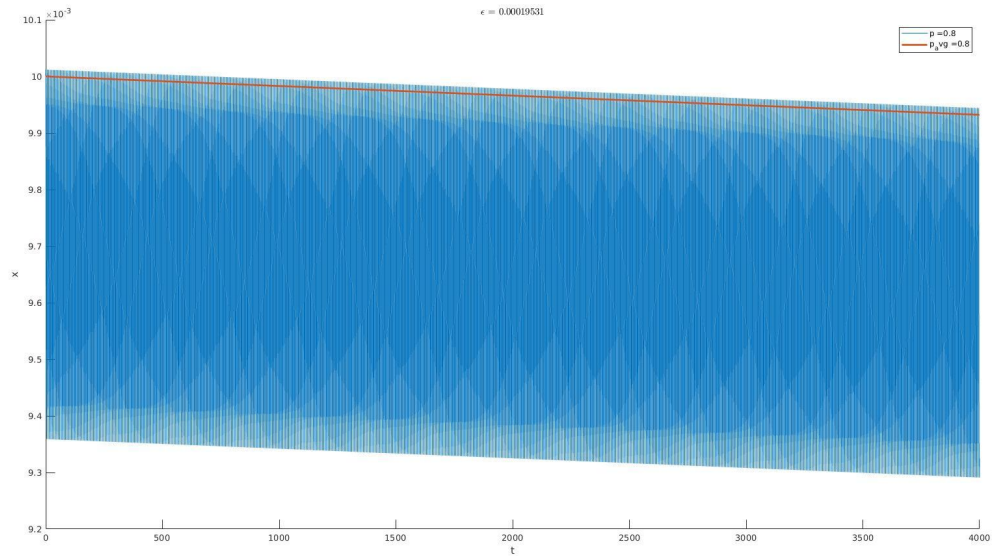
P = 0.6



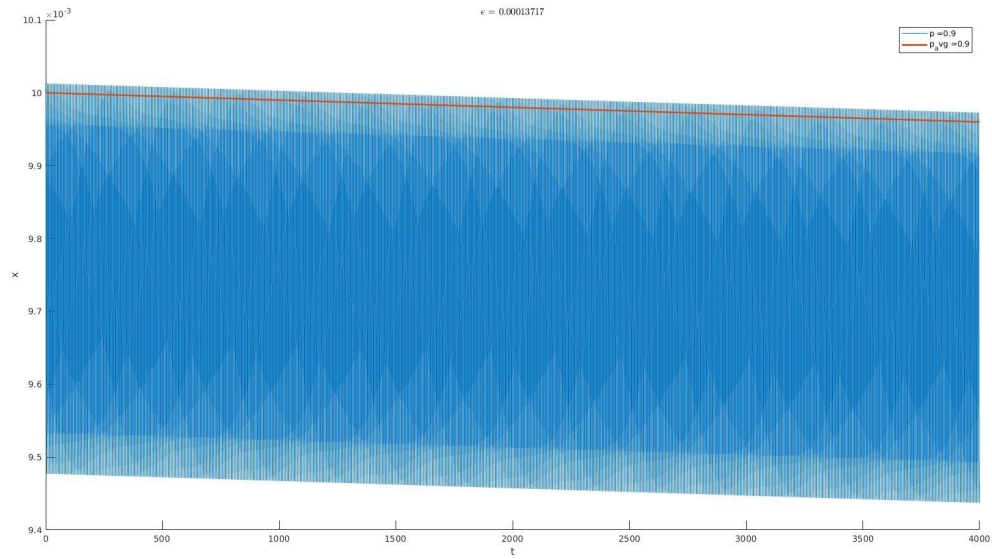
P = 0.7



P=0.8



P = 0.9



Discussion: The MMS avgd solution matches the numerical solution (in blue) for most cases. There is significant mismatch for  $P = 3$  and  $P = 2$  cases. For other  $P > 1$  cases, the solution is a good averaged version of the original curve. For  $P < 1$  cases, the averaged curve is able to follow the original solution, but it does not follow the mean value, rather it follows the peaks of the curve.

Maple Code Below:

sun 21:17 • /home/sudhanshu/Desktop/ME627/MMS\_2nd\_Order\_2mw\* - [Server 5] - Maple 2018

File Edit View Insert Format Table Drawing Plot Tools Window Help

Workbook: Start.mw X MMS\_2nd\_Order.X [Untitled 3] X MMS\_2nd\_Order\_2.X

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av1 := simplify(
$$\frac{(-15792 p^2 - 5880 p) \sin(AA(T_2)) \cos(AA(T_2))^3 - (7896 p^3 + 2940 p) \sin(AA(T_2)) \cos(AA(T_2))}{8 p^4} + 5 p^6 - 303 p^4 + 3 p^2 - 5$$
) (14)

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sun 21:17 • /home/sudhanshu/Desktop/ME627/MMS\_2nd\_Order\_2mw\* - [Server 5] - Maple 2018

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Workbook: Start.mw X MMS\_2nd\_Order.X [Untitled 3] X MMS\_2nd\_Order\_2.X

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restart;

de := xdot + epsilon (sin(T[0] + x) - p cos(3 T[0] - x))^3;

N := 2; ts := seq(T[k], k = 0..N);

xs := add(X[k](ts) e^k, k = 0..N);

xs := add(diff(xs, T[k]) e^k, k = 0..N);

de := subs(xdot = xs, de);

de := convert(taylor(de, epsilon, N+1), polynomial);

de := 
$$\frac{6}{\epsilon^0} X_0(T_0, T_1, T_2) + \left( \frac{6}{\epsilon^1} X_1(T_0, T_1, T_2) + \frac{6}{\epsilon^2} X_2(T_0, T_1, T_2) + \left( \sin(T_0 + X_0(T_0, T_1, T_2)) - p \cos(3 T_0 - X_0(T_0, T_1, T_2)) \right)^3 \right) e + \left( \frac{6}{\epsilon^3} X_3(T_0, T_1, T_2) + \frac{6}{\epsilon^4} X_4(T_0, T_1, T_2) + \frac{6}{\epsilon^5} X_5(T_0, T_1, T_2) + 3 \left( \sin(T_0 + X_0(T_0, T_1, T_2)) - p \cos(3 T_0 - X_0(T_0, T_1, T_2)) \right)^2 \left( \cos(T_0 + X_0(T_0, T_1, T_2)) X_0(T_0, T_1, T_2) - p \sin(3 T_0 - X_0(T_0, T_1, T_2)) X_1(T_0, T_1, T_2) \right) \right) e^2$$
 (5)

coeff(de, epsilon, 0);

temp := 
$$\frac{6}{\epsilon^0} X_0(T_0, T_1, T_2) = A(T[1], T[2]);$$

temp := 
$$X_0(T_0, T_1, T_2) = A(T_1, T_2)$$
 (7)

xs := subs(temp, xs);

xs := 
$$A(T_1, T_2) + X_1(T_0, T_1, T_2) e + X_2(T_0, T_1, T_2) e^2$$
 (8)

de := collect(expand(subst(temp, de)), epsilon);

temp := coeff(de, epsilon, 1);

temp1 := combine(expand(subst(X\_1(T\_0, T\_1, T\_2) = 0, 
$$\frac{6}{\epsilon^1} A(T_1, T_2) = 0, temp$$
)), trig);

temp1 := 
$$-\frac{3 p^2 \sin(5 T_0 - 3 A(T_1, T_2))}{4} + \frac{3 p^2 \sin(T_0 + A(T_1, T_2))}{2} + \frac{3 p^2 \sin(7 T_0 - A(T_1, T_2))}{4} + \frac{3 p \cos(T_0 - 3 A(T_1, T_2))}{4} + \frac{3 p \cos(5 T_0 + A(T_1, T_2))}{4} - \frac{3 p^3 \cos(3 T_0 - A(T_1, T_2))}{4} - \frac{p^3 \cos(9 T_0 - 3 A(T_1, T_2))}{4} - \frac{\sin(3 T_0 + 3 A(T_1, T_2))}{4} + \frac{3 \sin(T_0 + A(T_1, T_2))}{4} - \frac{3 p \cos(3 T_0 - A(T_1, T_2))}{2}$$
 (9)

av1 := combine(integrate(temp1, T[0] = 0..8 Pi));

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Activities Java-lang-Threat sun 21:17:52

/home/sudhanshu/Desktop/ME627/MMS\_2nd\_Order\_2.mw - [Server 5] - Maple 2018

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Workbook Palettes

Start.mw X MMS\_2nd\_Order\_2 X [Untitled (3)] X MMS\_2nd\_Order\_2 X

Text Math Drawing Plot Animation Hide

2D Input

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$$\begin{aligned}
 &+ 336 p^3 \cos(AA(T_2))^2 \cos(T_0)^8 \sin(AA(T_2)) \sin(T_0) - 180 p^3 \cos(AA(T_2))^2 \cos(T_0)^8 \sin(AA(T_2)) \sin(T_0) - 192 p^3 \cos(AA(T_2)) \cos(T_0)^7 \sin(AA(T_2))^2 \sin(T_0)^2 \\
 &+ 240 p^3 \cos(AA(T_2)) \cos(T_0)^5 \sin(AA(T_2))^2 \sin(T_0)^2 + 9 p^3 \cos(AA(T_2)) \cos(T_0) \sin(AA(T_2))^2 \sin(T_0)^2 + 48 \cos(T_0)^7 \sin(AA(T_2))^2 \cos(T_0)^2 \sin(AA(T_2))^2 \\
 &- 72 \cos(T_0)^5 \sin(AA(T_2))^2 \cos(T_0)^2 \sin(AA(T_2))^2 \\
 &+ 27 \cos(T_0)^7 \sin(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \\
 &+ 3 \cos(T_0)^7 \sin(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \cos(AA(T_2))^2 \\
 &+ 48 p^3 \cos(AA(T_2))^2 \sin(T_0)^3 \cos(T_0)^4 + 3 \sin(T_0) \cos(AA(T_2)) \cos(T_0)^3 \sin(AA(T_2))^2 + 48 \sin(T_0) \cos(AA(T_2))^2 \cos(T_0)^3 \sin(AA(T_2))^2 - 72 \sin(T_0) \cos(AA(T_2))^2 \cos(T_0)^3 \sin(AA(T_2))^2 \\
 &+ 3 \sin(T_0)^3 \cos(AA(T_2))^2 \cos(T_0)^3 \sin(AA(T_2))^2 + 3 \sin(T_0)^2 \cos(AA(T_2))^2 \cos(T_0)^3 \sin(AA(T_2))^2 - 12 \sin(T_0)^2 \cos(AA(T_2))^2 \cos(T_0)^3 \sin(AA(T_2))^2 + 9 \sin(T_0)^2 \cos(AA(T_2))^2 \cos(T_0)^3 \sin(AA(T_2))^2 \\
 &+ \frac{e}{e T_0} X_0(T_0, T_2)
 \end{aligned}$$

$$\begin{aligned}
 &\text{temp2} := \text{integrate}(\text{temp1}, T[0]): \\
 &\text{temp3} := X_0(T_0, T_2) = \text{temp2} \\
 &x := \text{subs}(\text{temp3}, x) \\
 &\text{dea} := \text{collect}(\text{expand}(\text{subs}(\text{temp3}, \text{dea})), \text{epsilon}) \\
 &\text{temp1} := \text{coeff}(\text{dea}, \text{epsilon}, 2) \\
 &\text{temp1} := \text{expand}\left(\text{subs}\left(\frac{d}{dT_2}, AA(T_2) = 0, X_0(T_0, T_2, T_2) = 0, \text{temp}\right)\right) \\
 &\text{av2} := \text{simplify}\left(\frac{\text{integrate}(\text{temp1}, T[0] = 0.8 P)}{8 P}\right) \\
 &\text{av2} = \frac{(-15792 p^3 - 5880 p) \sin(AA(T_2)) \cos(AA(T_2))^3}{1680} - \frac{(7896 p^3 + 2940 p) \sin(AA(T_2)) \cos(AA(T_2))}{1680} + \frac{5 p^6}{48} - \frac{303 p^4}{560} + \frac{3 p^2}{80} - \frac{5}{16}
 \end{aligned}$$

$$\text{finalaq} = \frac{d}{dT_2} AA(T_2) - \text{av2}$$

$$\text{finalaq} = \frac{d}{dT_2} AA(T_2) + \frac{(-15792 p^3 - 5880 p) \sin(AA(T_2)) \cos(AA(T_2))^3}{1680} + \frac{(7896 p^3 + 2940 p) \sin(AA(T_2)) \cos(AA(T_2))}{1680} - \frac{5 p^6}{48} + \frac{303 p^4}{560} - \frac{3 p^2}{80} + \frac{5}{16}$$

$$\text{subsp} = 3, \text{finalaq}, \frac{d}{dT_2} AA(T_2) - \frac{2643 \cos(AA(T_2))^3 \sin(AA(T_2))}{10} + \frac{2643 \cos(AA(T_2)) \sin(AA(T_2))}{20} - \frac{4499}{140}$$

$$\text{repreq} = \text{subs}(AA(T[2]) = X1, \text{finalaq}), \frac{e}{e T_2} X1 + \frac{(-15792 p^3 - 5880 p) \sin(X1) \cos(X1)^3}{1680} + \frac{(7896 p^3 + 2940 p) \sin(X1) \cos(X1)}{1680} - \frac{5 p^6}{48} + \frac{303 p^4}{560} - \frac{3 p^2}{80} + \frac{5}{16}$$

$$\text{subsp} = 1, \text{repreq}, \frac{299}{420} - \frac{129 \sin(X1) \cos(X1)^3}{10} + \frac{129 \sin(X1) \cos(X1)}{20}$$

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Q2.

Problem 2.

$$\ddot{x} + \varepsilon c \dot{x} + (1 + \varepsilon \cos(2t))x = 0 \quad 0 < \varepsilon < 1$$

$$\begin{cases} x_1 = x \\ x_2 = \dot{x} \end{cases}$$

$$\begin{aligned} \dot{x}_1 &= x_2 \\ \dot{x}_2 &= -\varepsilon c x_2 - x_1 (1 + \varepsilon \cos(2t)) \end{aligned}$$

$$\begin{aligned} \dot{x}_1 &= x_2 \\ \dot{x}_2 &= -\varepsilon c x_2 - x_1 (1 + \varepsilon \cos(2t)) \end{aligned}$$

$$\ddot{x} + x = -\varepsilon c \dot{x} - \varepsilon \cos(2t)x$$

$$\boxed{\ddot{x} + x = -\varepsilon (c \dot{x} + \cos(2t)x)}$$

$\downarrow$   
 $f(x, \dot{x})$

$$\begin{aligned} x_1 &= x \\ x_2 &= \dot{x} \end{aligned}$$

$$\begin{aligned} \dot{x}_2 &= -x_1 - \varepsilon (c x_2 + \cos(2t)x_1) \rightarrow (1) \\ \dot{x}_1 &= x_2 \rightarrow (2) \end{aligned}$$



$$x_1 = A \cos(t + \phi)$$

$$x_2 = -A \sin(t + \phi)$$

$$\dot{x}_1 = \dot{x}_2$$

~~$$-A \sin(t + \phi) = -A \sin(t + \phi)$$~~

$$\dot{x}_1 = \dot{A} \cos(t + \phi) - A \sin(t + \phi) \cdot (1 + \dot{\phi})$$



In ②  $\dot{x}_1 = \dot{x}_2$

$$\dot{A} \cos(t + \phi) - A \sin(t + \phi) \cdot (1 + \dot{\phi}) = -A \sin(t + \phi)$$

for brevity  $\cos(t + \phi) = c$   
 $\sin(t + \phi) = s$

$$\Rightarrow \text{~~the~~}$$

$$\dot{A}c - \cancel{As} - A\dot{s} = \cancel{-As}$$

$$\Rightarrow \boxed{\dot{A}c - A\dot{s} = 0} \rightarrow \textcircled{3}$$

In ①

$$\dot{x}_2 = -\dot{A}s - Ac(1 + \dot{\phi})$$

$$= -Ac + \varepsilon f$$

$$\Rightarrow \textcircled{4} \quad -\dot{A}s - Ac\dot{\phi} = \varepsilon f \rightarrow \textcircled{4}$$



... (3)

$$\dot{A}c - As\dot{\phi} = 0 \quad \times \quad c$$

(4)

~~$\dot{A}c - As\dot{\phi} = 0$~~

$$(4) \quad \dot{A}s + Ac\dot{\phi} = -\varepsilon f \quad \times \quad s$$

$\therefore$  Adding  $c \times (3) + s \times (4)$

$$\hookrightarrow \dot{A} = -\varepsilon f \sin(t+\phi) \quad (5)$$

~~But~~ Adding  $(4) \times c + (3) \times (-s)$

$$A\dot{\phi} = -\varepsilon f \cos(t+\phi)$$

$$\dot{\phi} = -\frac{\varepsilon f}{A} \cos(t+\phi) \rightarrow (6)$$

$$\begin{aligned} \dot{A} &= -\varepsilon f \sin(t+\phi) && \rightarrow (5) \\ \dot{\phi} &= -\frac{\varepsilon f}{A} \cos(t+\phi) && \rightarrow (6) \end{aligned}$$

Now sys. is in Lagrange Standard form.

$$\dot{f} = -\overset{\text{damping const. } c}{c}x_2 - \cos(2t)x_1$$

$$x_1 = \overset{\text{not } \cos(t+\phi)}{AC}$$

$$x_2 = -AS$$

$$\therefore \dot{f} = -c(-A \sin(t+\phi)) - \cos 2t (A \cos(t+\phi))$$

$$\dot{f} = Ac \sin(t+\phi) - A \cos(t+\phi) \cos 2t$$

Finally the diff. Eqn becomes.

$$\begin{aligned} \textcircled{5} \quad \ddot{A} &= -\varepsilon(\sin(t+\phi)) \left[ \overset{\textcircled{7}}{Ac \sin(t+\phi) - A \cos(t+\phi) \cos 2t} \right] \\ \ddot{\phi} &= -\varepsilon(\cos(t+\phi)) \left[ \overset{\textcircled{8}}{c \sin(t+\phi) - \cos(t+\phi) \cos 2t} \right] \end{aligned}$$

Apply MMS first order

So given Eqn is in Lag. form.

i.e.  $\dot{x} = -\varepsilon f' \rightarrow \textcircled{9}$

where  $s'$  can be seen from above.

std. form.

$$\begin{Bmatrix} A \\ \phi \end{Bmatrix}$$

Here  $x$  is a vector

So assume

$$x = X(T_0, T_1) \quad \text{assuming 1st order}$$

$$T_0 = t \quad T_1 = \epsilon t$$

$$\dot{x} = \frac{\partial X}{\partial T_0}(1) + \frac{\partial X}{\partial T_1}(\epsilon)$$

↳ 9+10 case

$$\text{also we take } x = X_0(T_0, T_1) + \epsilon X_1(T_0, T_1)$$

$$\therefore \dot{x} = \frac{\partial X_0}{\partial T_0} + \epsilon \frac{\partial X_1}{\partial T_0} + \epsilon \frac{\partial X_0}{\partial T_1} + \epsilon^2 \frac{\partial X_1}{\partial T_1}$$

↳ ⑩ ⑩

Putting  $\dot{x}$  in ⑨

we get

$$\frac{\partial X_0}{\partial T_0} + \epsilon \left( \frac{\partial X_1}{\partial T_0} + \frac{\partial X_0}{\partial T_1} \right) + \epsilon^2 \left( \frac{\partial X_1}{\partial T_1} \right) = -\epsilon f'$$

$$\therefore \frac{\partial X_0}{\partial T_0} = 0 \Rightarrow X = A(T_1)$$

$$\therefore \frac{\partial X_1}{\partial T_0} + \frac{\partial A}{\partial T_1} = -\epsilon f'$$



Now

$$\frac{\partial X_1}{\partial T_0} = - \frac{\partial A}{\partial T_1} - \epsilon f'$$

$\swarrow f(T_1)$   
 $\searrow f(T_0, x)$   
 $\Downarrow$   
 $f(T_0, x)$

Now let's evaluate

To avg of  $f$

$f$  here is a vector

where  $f_1 = \sin(t+\phi) [A \cos(t+\phi) \cos(2t)]$   
 $f_2 = \cos(t+\phi) [A \sin(t+\phi) - A \cos(t+\phi) \cos(2t)]$

To avg of  $f_1$  keeping  $A, \phi$  const.

$$\begin{aligned} \sin^2(t+\phi) &= \frac{1}{2} \\ \frac{1}{2} \cdot 2 \sin(t+\phi) \cos(t+\phi) \cos(2t) &= \frac{1}{2} \sin(2t+2\phi) \cos(2t) \\ &= \frac{1}{4} (\sin(\frac{4}{2}t + 2\phi) + \sin(2\phi)) \end{aligned}$$

The avg becomes  $= \frac{1}{4} \sin(2\phi)$

$$\sin(t+\phi)\cos(t+\phi) = \frac{1}{2}\sin(2t+\phi) = 0$$

$$\cos(t+\phi)^2 \cos(2t) = \frac{\cos(2\phi)}{4}$$

To avging

$$\frac{\partial X_1}{\partial T_0} = -\frac{\partial A}{\partial T_1} - \epsilon \begin{bmatrix} Ac(y_2) - \frac{A}{4}\sin(2\phi) \\ 0 - \frac{\cos(2\phi)}{4} \end{bmatrix} = 0$$

~~We get~~

$$\text{We choose A s.t. } \frac{\partial X_1}{\partial T_0} = 0$$

i.e we remove secular terms.

Using <sup>MM1</sup> Avgd Eqn is

$$\frac{\partial A}{\partial t} = -\epsilon \begin{bmatrix} \frac{Ac}{2} - \frac{A}{4}\sin 2\phi \\ -\frac{\cos(2\phi)}{4} \end{bmatrix}$$

$$\therefore \begin{bmatrix} \frac{\partial A}{\partial t} \\ \frac{\partial \phi}{\partial t} \end{bmatrix} = -\epsilon \begin{bmatrix} \frac{Ac}{2} - \frac{A}{4}\sin 2\phi \\ -\frac{\cos(2\phi)}{4} \end{bmatrix}$$

Now Eq. pts

$$A \cdot (2c - \sin 2\phi) = 0$$

$$2c = \sin 2\phi$$

$$\boxed{\phi = \frac{1}{2} \sin^{-1}(2c) + k\pi}$$

Now finding Eq. pts.

$$\frac{A}{4} (2c - \sin(2\phi)) = 0$$

$$\Rightarrow A = 0 \quad \text{or} \quad \sin 2\phi = 2c$$

$$\Rightarrow \phi = \frac{1}{2} \sin^{-1}(2c) + k\pi$$

$$\hookrightarrow \phi = \frac{\sin^{-1}(2c)}{2}, \frac{\sin^{-1}(2c)}{2} + \pi, \dots$$

$$\text{also } \cos(2\phi) = 0$$

$$\Rightarrow 2\phi = (2k+1)\pi/2$$

$$k \in \mathbb{Z}$$

$$\Rightarrow \phi = \frac{(2k+1)\pi}{4}$$

$$\hookrightarrow \phi \in \left\{ \dots, -\pi/4, -\pi/4, \pi/4, 3\pi/4, 5\pi/4, \dots \right\}$$

$$\begin{aligned} \frac{1}{2} \sin^{-1}(2c) &= \pi/4 \\ \sin^{-1}(2c) &= \pi/2 \\ c &= 1/2 \end{aligned}$$

$$\begin{aligned} \frac{1}{2} \sin^{-1}(2c) &= -\pi/4 \\ c &= -1/2 \end{aligned}$$



~~for  $c = 1/2$~~

Now linearizing around eq. pt.

Jacobian

$$\text{Matrix} = \begin{bmatrix} -\frac{c}{2} + \frac{\sin 2\phi}{4} & \frac{A \cos(2\phi) \cdot 2}{4} \\ 0 & \frac{1}{4} (-\sin 2\phi) \cdot 2 \end{bmatrix}$$

~~for  $c = 1/2$  Eq. pt  $\phi = 0$~~

for Eq. pts corresponding to  $A=0$   $\therefore$ , the Eq. pt has no dependence on  $c$ .

$\therefore$  Second set of Eq. pts must be chosen.

Now for  $|c| > 1/2$  Eqn pts correspond to  $A=0$  case

$$\phi = \frac{(2k+1)\pi}{4} = \frac{1}{2} \sin^{-1}(2c) + k\pi$$

$$\frac{1}{2} \sin^{-1}(2c) = \frac{\pi}{4}$$

$$2c = 1 \quad c = 1/2$$

$$\frac{1}{2} \sin^{-1}(2c) + \pi = \frac{\pi}{4}$$

$$\frac{1}{2} \sin^{-1}(2c) = \frac{5\pi}{4}$$

~~$\sin^{-1}$~~

$$\sin^{-1}(2c) - 2k\pi = (2k+1)\frac{\pi}{4}$$

$$\Rightarrow 2c = \sin\left((2k+1)\frac{\pi}{4}\right)$$

$$c = \frac{1}{2} \sin\left((2k+1)\frac{\pi}{4}\right)$$

$$c = \frac{1}{2}, -\frac{1}{2}$$

for  $c = \frac{1}{2}, \phi = \pi/2$

Jacobian Matrix = 
$$\begin{bmatrix} -\frac{1}{4} + 0 & \frac{A(-1)}{2} \\ 0 & -\frac{1}{2}(0) \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{1}{4} & -\frac{A}{2} \\ 0 & 0 \end{bmatrix}$$

$$-\frac{1}{4} - \lambda$$

$$\lambda \quad \lambda(\lambda + \frac{1}{4}) = 0$$

$$[\lambda = -\frac{1}{4}, 0]$$

for  $c = -\frac{1}{2}, \phi = -\pi/2$

$$[\lambda = \frac{1}{4}, 0]$$

for  $c = \frac{1}{2}$   
the eqn is stable around eq  
pts.



for Eq.pts  $A=0$  and  $\phi = (2k+1)\frac{\pi}{4}$

Jacobian Matrix: 
$$\begin{bmatrix} -\frac{c}{2} + \frac{\sin(2\phi)}{4} & \frac{A}{4} \cos(2\phi) \cdot 2 \\ 0 & -\frac{1}{2} (\sin 2\phi) \end{bmatrix} = H$$

for the Eq.pts.  $A=0$   $\phi = (2k+1)\frac{\pi}{4}$

$$H = \begin{bmatrix} -c/2 + 1/4 (\pm 1) & 0 \\ 0 & -1/2 (\pm 1) \end{bmatrix}$$

Eigen values.

$$-\frac{1}{2} (\pm 1), \quad -\frac{c}{2} \pm \frac{1}{4}$$

for  $\phi = \pi/4$

$$\lambda = -\frac{c}{2} + 1, \quad -1/2$$

for st.  $-\frac{c}{2} + 1/4 < 0$

$$+\frac{c}{2} > \frac{1}{2} \Rightarrow c/2 > 1/4$$

$$\boxed{c > 1/2}$$

for  $\phi = -\pi/4$

$$\lambda = +1/2, \quad -\frac{c}{2} - 1/4$$

$$-\frac{c}{2} - 1/4 > 0 \Rightarrow c/2 > -1/4$$

$c > -1/2$  but second e.v. is neg. so unstable

Thus,  $c = 0.5$  is the minimum value for stability