

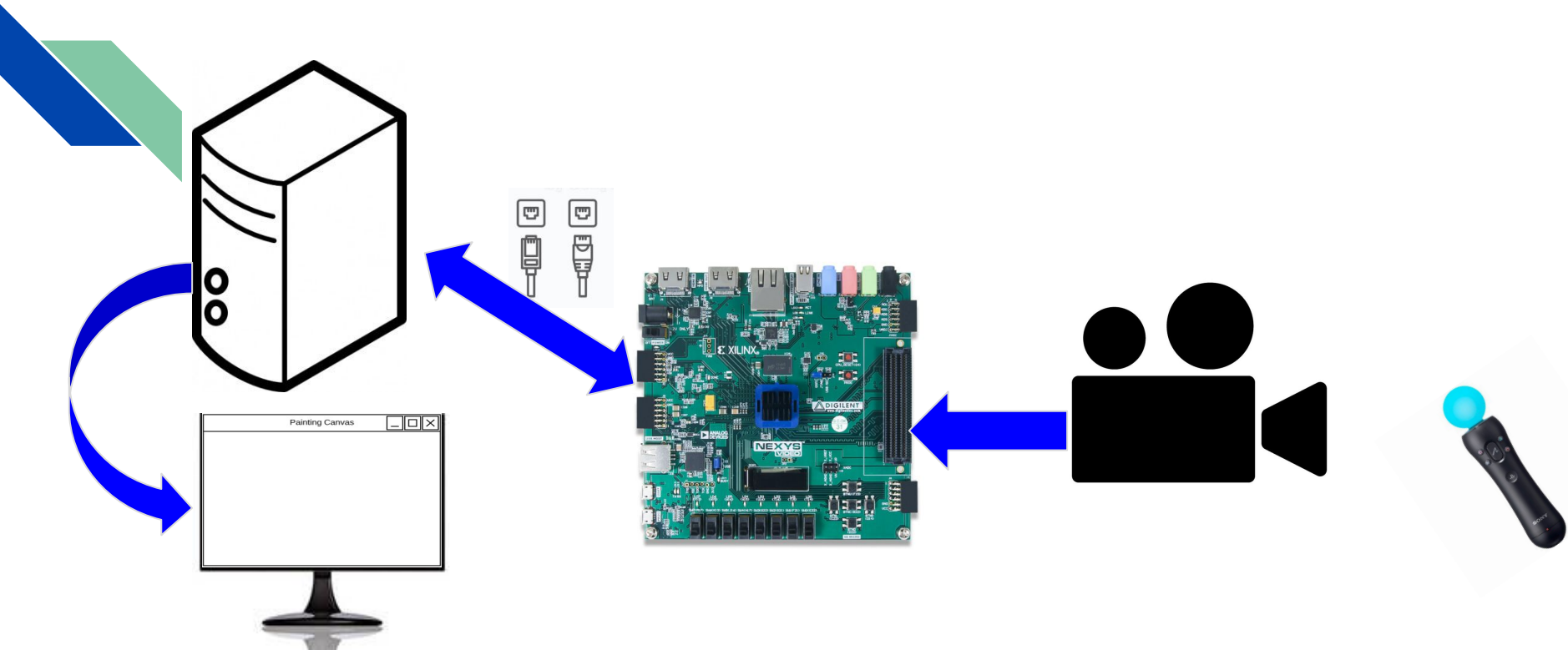


IoT Air Draw

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INTRODUCTION





OUTPUT

PROCESS

INPUT



Goals - Custom IP

Fast processing speed at 30HZ on HD video

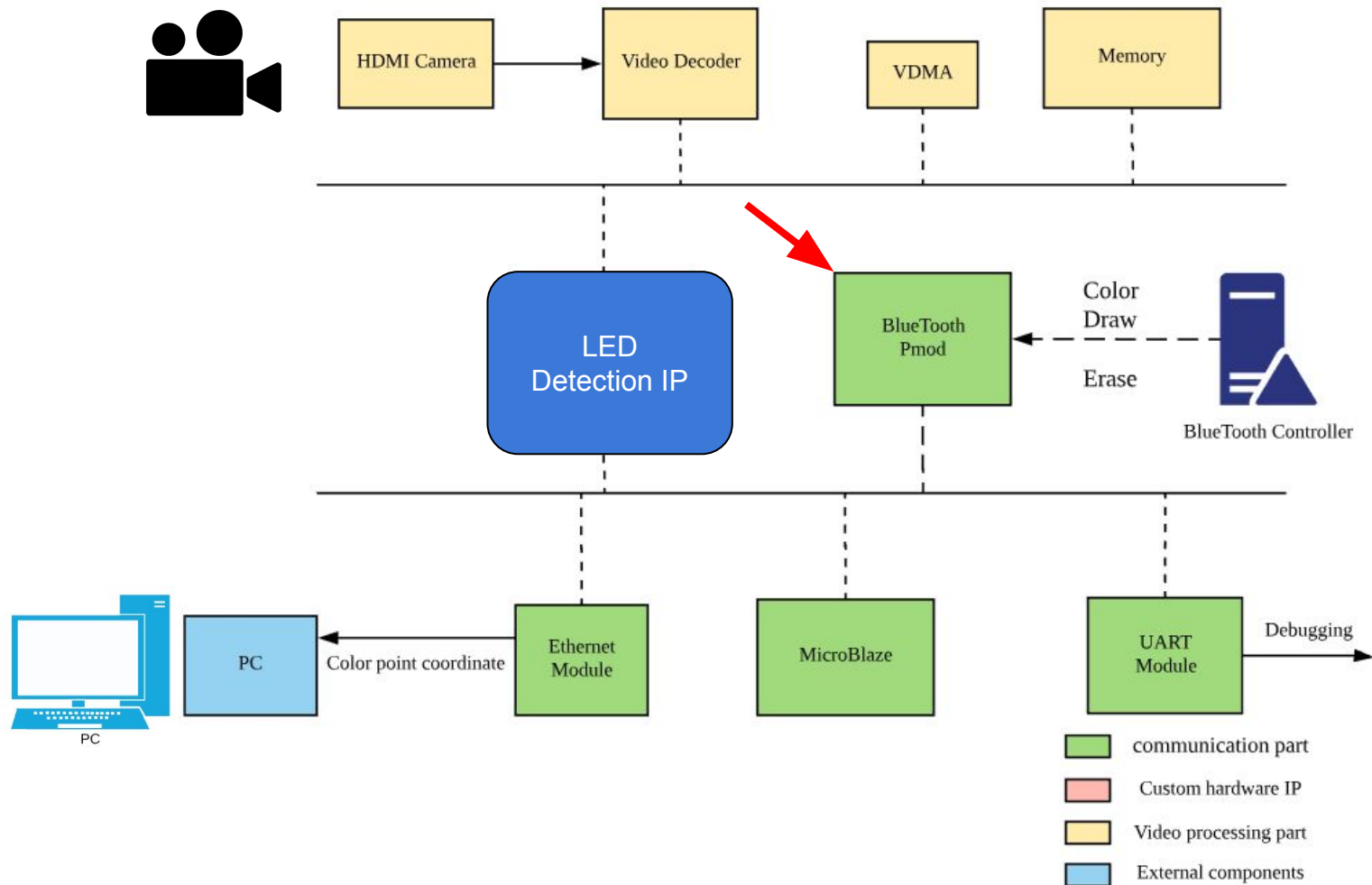
Simple algorithm with high detection accuracy

Multi color detection

Capability of detecting size of LED (using bounding box)

Final SYSTEM Block Diagram





Change in Plan

- Moved away from custom IP interrupt
 - Turned out not necessary
 - Conflict in interrupt
- Used Bluetooth
 - Allow remote control
 - Adding more usability



Code Blocks - Hardware

- ❖ Borrowed
 - Initial video setup
 - Some VDMA functions in sdk
- ❖ Created (own IP)
 - LED detecting IP
 - External Bluetooth controller
 - SDK code integrating ethernet and video



Code Blocks - Software

- ❖ Borrowed
 - Python OpenGL
 - Python library for filtering
- ❖ Created (own IP)
 - State machine for drawing
 - Data structure to store points in mem



Design Process



Work Distribution

Nafis

- Software frontend & external controller
- Integration of Ethernet and video in SDK
- Bluetooth module

Haiqi

- Ethernet and video path setup
- Custom IP testing environment setup

Mariko

- Implemented Custom LED detecting IP (HLS)
- Investigated and experimented prototype algorithm in software



Design Steps

Initial Phase

- ❖ Basic Ethernet and Video path setup
- ❖ Algorithm investigation & Prototyping

Development

- ❖ Implemented & tested custom IP in hardware
- ❖ Integrated custom IP into data path



Design Steps (cont'd)

Integration (Mid project Demo)

- ❖ Integrated Video and Ethernet in SDK
- ❖ Integrated with Software server and Bluetooth

Optimization

- ❖ Increased detection accuracy
- ❖ Software side improvements



Lesson and Learned

- ❖ Hardware is fast(er than python)
- ❖ Vivado is VERY slow :'(
- ❖ Be aware of License access
- ❖ Xilinx software is buggy



Q&A

