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Document Revision History

| Revision | Date | Description |
|----------|--------------|---------------------------------------|
| 1.0 | 30 June 2017 | Initial release |
| 1.1 | 30 Oct 2017 | Correct the number of LED |
| | | 2. Add description for LED |
| | | 3. Add jumpers setting at chapter 2.4 |

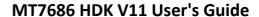
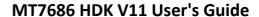




Table of Contents

| 1. | Intro | duction | 4 |
|----|-------|---|----|
| 2. | Get s | started with the HDK | 5 |
| | 2.1. | Configuring the MT7686 HDK | 5 |
| | 2.2. | Installing the MT7686 HDK drivers on Microsoft Windows | 6 |
| | 2.3. | Configuring the HDK flash mode | 7 |
| | 2.4. | Downloading the image using the MT7686 HDK as a removable storage | 8 |
| 3. | Hard | ware Features | 9 |
| 4. | Hard | ware Feature Configuration | 10 |
| | 4.1. | Microcontroller | 10 |
| | 4.2. | Power supply | 10 |
| | 4.3. | LEDs | |
| | 4.4. | Buttons | |
| | 4.5. | Extension connectors | 13 |
| | 4.6. | RTC | |
| | 4.7. | RF connections | |
| | 4.8. | CMSIS-DAP firmware update procedure | 19 |
| 5. | Sche | matics (V11) | 20 |





Lists of Tables and Figures

| Table 1. Jumper settings for system power input through USB connection | 10 |
|--|----|
| Table 2. System power input from AA or AAA battery jumpers | 11 |
| Table 3. GPIO pins to activate the LEDS | 12 |
| Table 4. GPIO pin-out extension connectors | 13 |
| Table 5. GPIO pin multi-function definition | 13 |
| | |
| Figure 1. Front view of MT7686 HDK | 4 |
| Figure 2. Jumpers and connectors on the MT7686 HDK | 5 |
| Figure 3. COM port associated with the MT7686 HDK | 7 |
| Figure 4. New removable storage detected | 8 |
| Figure 5. Power up the HDK using an AA or AAA Battery (J2001) | 11 |
| Figure 6. On-board LEDs | |
| Figure 7. Locations of I2C pull-up resistors | 18 |
| Figure 8. Location of the components C17 and C18 | |



1. Introduction

MediaTek LinkIt™ for real-time operating system (RTOS) is a low-cost and easy to use Internet of Things (IoT) development platform to design, prototype, evaluate and implement IoT projects. The platform supports MT7686 hardware development kit (HDK). This user manual provides required knowledge on features of the HDK, including the pins, communication interfaces, core microcontroller unit (MCU) description, the networking capabilities and how to use them through the host driver.

The HDK includes MediaTek MT7686 chipset based on ARM Cortex-M4 with floating point unit in QFN48 package. It enables rich connectivity features, communication with cloud services and real-time control. The MT7686 HDK supports ARM mbed IoT Device Platform for more convenient debugging and binary code download operations.

The following features are available:

- Mass storage device (MSD) programmer.
 - o The MT7686 HDK has three binary files for bootloader, Wi-Fi connectivity and FreeRTOS. The MSD programmer enables to update the FreeRTOS binary file only.
- Coresight Debug Access Port (<u>CMSIS-DAP</u>) debug interface.
 - A firmware debug interface similar to <u>ST-link</u> or <u>J-link</u>. It enables debugging a target project or downloading a binary to the flash storage of the device.
- Virtual Serial Port.
 - o Supports UART functionality, such as transferring log information from the HDK.

These features are used to download and debug a project on MT7686 HDK.

The front view of the HDK including a stamp module and main board is shown in Figure 1. MT7682 and MT7686 use the same HDK main board.

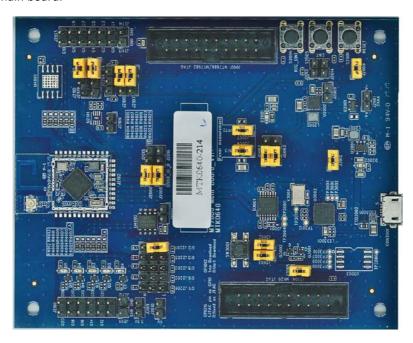


Figure 1. Front view of MT7686 HDK



2. Get started with the HDK

Before commencing the application development, you need to configure the development platform.

2.1. Configuring the MT7686 HDK

MT7686 HDK includes a main board (MT7686 Main Board_V11) and a MT7686 stamp module. The MT7686 stamp module is mounted on the main board. The top view of the main board is shown in Figure 2.

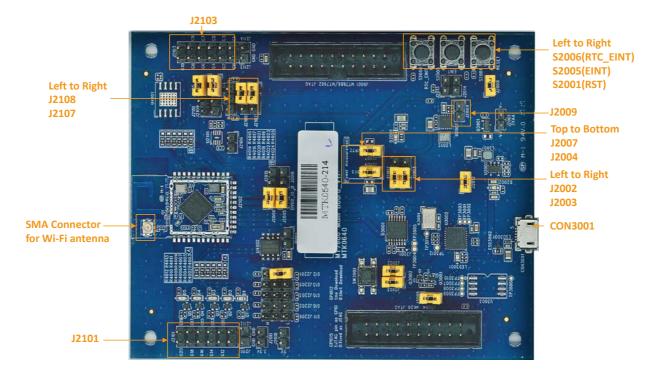


Figure 2. Jumpers and connectors on the MT7686 HDK

The description of pins (Figure 2) and their functionality is provided below.

- 1) **CON3001** is a USB connector to debug through UART, transmit and receive a signal and supply power from the PC. The USB connectivity with the PC is supported by the on-board MK20DX128VFM5.
 - a) Set the jumpers **J2002** pin 1 and pin 2, **J2003** pin 1 and pin 2, **J2004** and **J2007** on, if the board is powered by a USB connector.
- 2) **\$2005** enables the external interrupt (configured at **GPIO0**), see section 4.4, "Buttons", for more details.
- 3) Press **\$2001** to reset the system.
- **Wi-Fi Antenna** is a PCB antenna. MT7686 stamp module is by default connected to the PCB antenna to transmit and receive RF signals.

The default configuration of the MT7686 HDK supports the following functionality:

- 1) Power supply. Attach a micro-USB connector to the **CON3001**.
- 2) Supports RTC interrupt.



- 3) Clock source 32.768kHz source crystal clock for the RTC mode or external clock operating on 32.768 kHz.
- 4) XTAL at 26MHz.
- 5) Supports RTC mode.

The hardware settings of the stamp module are shown below:

- 1) XTAL at 26MHz.
- 2) Clock source 32.768kHz source crystal clock for the RTC mode or external clock operating at 32.768kHz.
- 3) Supports RTC mode.

2.2. Installing the MT7686 HDK drivers on Microsoft Windows

To configure the MT7686 HDK:

- 1) Connect the HDK to the computer using a micro-USB cable.
- 2) Download and install mbed Windows serial port driver from here. Open Windows **Control Panel** then click **System** and:
 - On Windows 7 and 8, click Device Manager.
- 3) In **Device Manager**, navigate to **Ports (COM & LPT)** (see Figure 3).
- 4) A new COM device should appear under Ports (COM & LPT) in Device Manager, as shown in Figure 3. Note the COMx port number of the serial communication port, this information is needed to send command and receive logs from the COM port. Virtual COM port is connected to the board through the UARTO of the MT7686, see section 4.5, "Extension connectors". The mbed Serial Port (UARTO) is applied to flash the board and log the outputs.



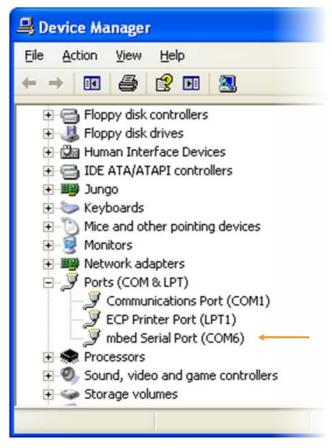


Figure 3. COM port associated with the MT7686 HDK

2.3. Configuring the HDK flash mode

The MT7686 HDK is embedded with 4MB flash memory. The boot options are either from the Flash memory or from the UART port.

To update the firmware on the MT7686 HDK:

- 1) Set the jumpers **J2002** pin 1 and pin 2, **J2003** pin 1 and pin 2, **J2004** and **J2007** on.
- 2) To enable the chipset to UART download mode, set the jumper **J2201** pin 2 and pin 3 on.
- In this mode, if the power is on, the board will load ROM code and start the **ATE Daemon** or **Firmware Upgrade Daemon** according to the MT7686 Flash Tool's behavior on the PC. A message is sent to the **UART0** port of the chipset and the code is uploaded to the embedded flash memory through **UART0**.
- 3) Connect the board to the computer using a micro-USB cable.

The development board should now be connected to the PC, as shown in Figure 2.

To run the project on the MT7686 HDK:

- 1) Set the jumpers **J2002** pin 1 and pin 2, **J2003** pin 1 and pin 2, **J2004** and **J2007** on.
- 2) Remove J2201 jumper, to set the board into a flash mode.
- In this mode, if the power is on, the board will load firmware from the Flash and reboot.
- 3) Connect the board to a computer using a micro-USB cable.





The development board should now be connected to the PC, as shown in Figure 4.

2.4. Downloading the image using the MT7686 HDK as a removable storage

To update the FreeRTOS binary only (example project binary: mt7686_iot_sdk.bin), use the HDK as a mass storage device according to the following steps:

- 1) Set the jumpers J2107 pin 2 and pin 3, J2108 pin 2 and pin 3 on.
- 2) Power up the board with a micro-USB cable.
- 3) Navigate to **Computer** on your PC to check if a new mass storage named **MT7686** is available under **Removable Disk**, as shown in Figure 4.
- 4) Open the **MT7686** removable storage, then drag and drop the binary mt7686_iot_sdk.bin to complete downloading the image.

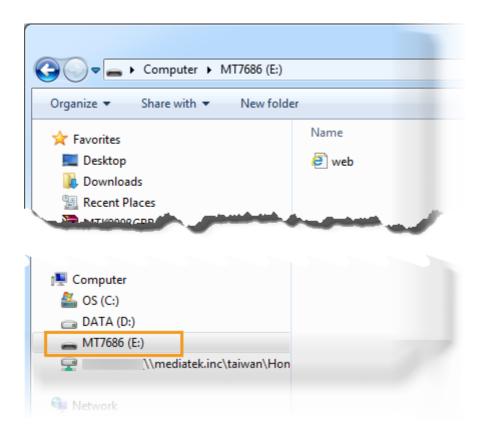


Figure 4. New removable storage detected



3. Hardware Features

This section provides the main supported features of the MT7686 HDK. The detailed description of the features is provided in the upcoming sections.

- IEEE 802.11bgn Wireless Connectivity Single Chip with QFN68 package.
- The IOs on MT7686 HDK are 3.3V compatible. MT7686 chip IO can support 3.3V, 2.8V and 1.8V.
- Support for <u>FreeRTOS</u>.
- Flexible on-board power supply
 - o <u>USB</u> with power (V_{Bus} , 5V).
 - External V_{IN} (1.8~3.63V).
- Eight LEDs
 - o Power LEDs (**D2001**, **D2002**)
 - User LEDs (D1, D2, D3, D4, D5).
 - UART communication LEDs(LED3001)
- Three push buttons
 - System Reset.
 - Real Time Clock (RTC) Interrupt.
 - External Interrupt.
- XTAL (Crystal Oscillator)
 - o 26MHz source clock support with low power consumption in idle mode.
 - o 32.768kHz clock for the RTC mode or external 32.768kHz mode.
- USB re-enumeration capability: two different interfaces supported on the same USB.
 - o CMSIS-DAP USB.
 - o Virtual COM port UART through USB on PC.
- On-board chip antenna with <u>U.FL</u> for conducted testing.
- Micro USB connector for power and debug connections.
- Headers for current measurement.



4. Hardware Feature Configuration

4.1. Microcontroller

MT7686 features an ARM Cortex-M4 with floating point processor, which is the most energy efficient ARM processor available.

MT7686 provides low power consumption embedded architecture and it's optimized for various types of applications in home automation, smart grid, handheld devices, personal medical devices and industrial control that have lower data rates, and transmit or receive data on an infrequent basis.

4.2. Power supply

MT7686 HDK supports two types of power supply.

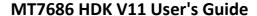
1) Power up with a micro-USB connector.

An on-board switching regulator provides voltage of 3.3V for the MT7686 HDK based on MT7686F, if the power is supplied from an on-board micro-USB connector **CON3001** (Figure 2). This supply can be isolated from the switching regulator using the jumpers. Note, that the jumpers **J2002** pin 1 and pin 2, **J2003** pin 1 and pin 2, **J2004** and **J2007** are required to be set on. More details on the jumpers can be found in Table 1.

| Jumper | Usage | Comments |
|------------|---------------------------------|---|
| J2002(1-2) | 3.3V power supply | Use micro-USB connector supporting 3.3V power source. |
| J2004 | Current measurement | Measures the current flow in MT7686F. |
| J2003(1-2) | AVDD33_VRTC power supply | Use micro-USB connector supporting RTC 3V3 power. |
| J2007 | Current measurement in RTC mode | Measures the current flow in RTC mode for MT7686. |

Table 1. Jumper settings for system power input through USB connection

- 2) Power up using an AA or AAA battery.
- Connect an external AA battery to battery pin header (J2001) to supply power to the system, as shown in Figure 5. When using an AA battery, plug the USB to micro-USB connector CON3001 (Figure 2). Note, that the jumpers J2002 pin 2 and pin 3, J2003 pin 2 and pin 3, J2004, J2007, and J2009 are required to be set on. More details on the jumpers can be found in Table 2.





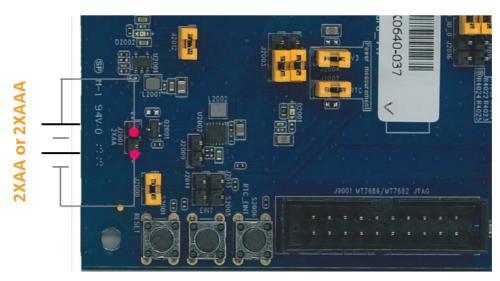


Figure 5. Power up the HDK using an AA or AAA Battery (J2001)

Table 2. System power input from AA or AAA battery jumpers

| Jumper | Usage | Comments |
|------------|---------------------------------|---|
| J2002(2-3) | 3.3V power supply | Use AA or AAA battery source supporting 3.3V power. |
| J2004 | Current measurement | Measures the current flow in MT7686. |
| J2003(2-3) | AVDD33_VRTC power supply | Use AA or AAA battery source supporting RTC 3V3 power. |
| J2007 | Current measurement in RTC mode | Measures the current flow in RTC mode for MT7686. |
| J2009 | Enables booster | Connects MT7686 EXT_PWR_EN (pin 21) to booster enabling pin |

4.3. LEDs

The MT7686 HDK has onboard LEDs associated with different functionalities of the board (Figure 6).

- 1) **D2002** indicates the power rail 5V is on.
- 2) **D2001** indicates the power rail 3.3V is on.
- 3) Blinking **LED3001** indicates communication between MK20 UART and MT7682 UARTO.
- 4) **D1**, **D2**, **D3**, **D4**, and **D5** are LEDs assigned for user interaction. All LEDs are high active (Figure 6).



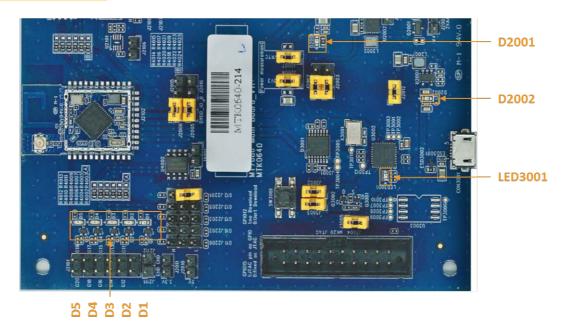


Figure 6. On-board LEDs

GPIO pins to activate the LEDs are shown in Table 3.

Table 3. GPIO pins to activate the LEDS

| LED | GPIO |
|-----|--------|
| D1 | GPIO11 |
| D2 | GPIO12 |
| D3 | GPIO13 |
| D4 | GPIO14 |
| D5 | GPIO15 |

4.4. Buttons

The MT7686 HDK is equipped with buttons with the following functionality. The push buttons are shown in Figure 2.

- 1) System reset button (**S2001**) resets the MT7686 HDK.
- 2) External interrupt button (**\$2005**). Users can configure GPIO0 as an external interrupt pin. Press the button to wake up the system from the sleep mode.
- 3) RTC interrupt button (\$2006). When the system is in RTC mode, push the button to wake up the system.
- 4) CMSIS-DAP Firmware update button (**SW3001**). Press the button to enter upload mode and upload the latest CMSIS-DAP Firmware to MK20.





4.5. Extension connectors

The MT7686 HDK provides similar pin-out extension connectors (**J2101** and **J2103**) for various sensor and device connectivity, as shown in Figure 2 and described in Table 4.

The board has 21 GPIOs multiplexed with other interfaces. Depending on the use case, user can configure each I/O functionality.

Table 4. GPIO pin-out extension connectors

| Connector Pin Number | Signal Name | Connector Pin Number | Signal Name |
|-------------------------|-------------|-------------------------|-------------|
| J2101.1 | GPIO20 | J2103.1 | GPIO1 |
| J2101.2 | GPIO19 | J2103.2 | GPIO0 |
| J2101.3 | GPIO18 | J2103.3 | GPIO3 |
| J2101.4 | GPIO17 | J2103.4 | GPIO2 |
| J2101.5 | GPIO16 | J2103.5 | GPIO5 |
| J2101.6 | GPIO15 | J2103.6 | GPIO4 |
| J2101.7 | GPIO14 | J2103.7 | GPIO7 |
| J2101.8 | GPIO13 | J2103.8 | GPIO6 |
| J2101.9 | GPIO12 | J2103.9 | GPIO9 |
| J2101.10 | GPIO11 | J2103.10 | GPIO8 |
| J2101.11 | X ** | J2103.11 | х |
| J2101.12 | RTC_EINT | J2103.12 | GPIO10 |

Table 5. GPIO pin multi-function definition

| Pin alias | Name | Description |
|-----------|---------------|--|
| GPIO0 | GPI00 | General purpose input, output |
| | EINT0 | External interrupt |
| | U1RTS | UART RTS |
| | SCL1 | I2C CLK |
| | I2S_RX | I2S RX |
| | JTDI | JTAG Debug port |
| | WIFI_ANT_SEL0 | External frontend control |
| | BT_PRI1 | Wi-Fi and Bluetooth coexistence control signal |
| | PWM0 | Pulse-width-modulated output |
| GPIO1 | GPIO1 | General purpose input, output |
| | EINT1 | External interrupt |
| | U1CTS | UART CTS |
| | SDA1 | I2C Data |
| | I2S_TX | I2S TX |



| | JTMS | JTAG Debug port |
|-------|---------------|--|
| | WIFI_ANT_SEL1 | External frontend control |
| | BT_PRI3 | Wi-Fi and Bluetooth coexistence control signal |
| | PWM1 | Pulse-width-modulated output |
| GPIO2 | GPIO2 | General purpose input, output |
| | EINT2 | External interrupt |
| | URXD1 | UART RX |
| | PWM0 | Pulse-width-modulated output |
| | I2S_WS | I2S WS |
| | JTCK | JTAG Debug port |
| | CLKO0 | Clock out port |
| | BT_PRIO | Wi-Fi and Bluetooth coexistence control signal |
| | WIFI_ANT_SEL4 | External frontend control |
| GPIO3 | GPIO3 | General purpose input, output |
| | EINT3 | External interrupt |
| | UTXD1 | UART TX |
| | PWM1 | Pulse-width-modulated output |
| | I2S_CK | I2S bit clock |
| | JTRST_B | JTAG Debug port |
| | WIFI_ANT_SEL2 | External frontend control |
| | I2S_CK | I2S bit clock |
| GPIO4 | GPIO4 | General purpose input, output |
| | SPISLV_A_SIO2 | SPI slave SIO2 |
| | SPIMST_A_SIO2 | SPI master SIO2 |
| | EINT4 | External interrupt |
| | I2S_MCK | I2S MCLK |
| | JTDO | JTAG Debug port |
| | WIFI_ANT_SEL3 | External frontend control |
| | I2S_MCK | 12S MCLK |
| GPIO5 | GPIO5 | General purpose input, output |
| | SPISLV_A_SIO3 | SPI slave SIO3 |
| | SPIMST_A_SIO3 | SPI master SIO3 |
| | EINT5 | External interrupt |
| | URXD0 | UART RX |
| | WIFI_ANT_SEL0 | External frontend control |
| | TDM_RX | TDM RX |
| | SCLO | I2C CLK |
| | PMU_RGU_RSTB | PMU Control Signal |



| GPIO6 | GPIO6 | General purpose input, output |
|--------|---------------|--|
| | SPISLV_A_CS | SPI slave CS |
| | SPIMST_A_CS | SPI master CS |
| | EINT6 | External interrupt |
| | UTXD0 | UART TX |
| | WIFI_ANT_SEL1 | External frontend control |
| | TDM_TX | TDM TX |
| | SDA0 | I2C DATA |
| GPIO7 | GPIO7 | General purpose input, output |
| | SPISLV_A_SCK | SPI slave CLOCK |
| | SPIMST_A_SCK | SPI master CLOCK |
| | EINT7 | External interrupt |
| | CLKO1 | Clock out port |
| | WIFI_ANT_SEL2 | External frontend control |
| | TDM_WS | TDM WS |
| | BT_PRI3 | Wi-Fi and Bluetooth coexistence control signal |
| GPIO8 | GPIO8 | General purpose input, output |
| | SPISLV_A_SIO0 | SPI slave SIO0 |
| | SPIMST_A_SIO0 | SPI master SIO0 |
| | EINT8 | External interrupt |
| | SCL0 | I2C CLK |
| | UORTS | UART RTS |
| | TDM_CK | TDM CK |
| | BT_PRIO | Wi-Fi and Bluetooth coexistence control signal |
| GPIO9 | GPIO9 | General purpose input, output |
| | SPISLV_A_SIO1 | SPI slave SIO1 |
| | SPIMST_A_SIO1 | SPI master SIO1 |
| | EINT9 | External interrupt |
| | SDA0 | I2C DATA |
| | UOCTS | UART CTS |
| | TDM_MCLK | TDM MCLK |
| | WIFI_ANT_SEL3 | External frontend control |
| | BT_PRI1 | Wi-Fi and Bluetooth coexistence control signal |
| GPIO10 | GPIO10 | General purpose input, output |
| | EINT10 | External interrupt |
| | U2CTS | UART CTS |
| | PWM2 | Pulse-width-modulated output |



| | PMU_RGU_RSTB | PMU Control Signal |
|--------|----------------|-------------------------------|
| | PMU_GOTO_SLEEP | PMU Control Signal |
| | WIFI_ANT_SEL4 | External frontend control |
| | SDA0 | I2C DATA |
| GPIO11 | GPIO11 | General purpose input, output |
| | EINT11 | External interrupt |
| | PWM3 | Pulse-width-modulated output |
| | URXD2 | UART RX |
| | MA_MC0_CK | SDIO master clock |
| | SLV_MC0_CK | SDIO slave clock |
| | CLKO2 | Clock out port |
| | WIFI_ANT_SEL0 | External frontend control |
| | I2S_RX | I2S RX |
| GPIO12 | GPIO12 | General purpose input, output |
| | SPISLV_B_SIO3 | SPI slave SIO3 |
| | SPIMST_B_SIO3 | SPI master SIO3 |
| | UTXD2 | UART TX |
| | MA_MC0_CM0 | SDIO master command |
| | SLV_MC0_CM0 | SDIO slave command |
| | EINT12 | External interrupt |
| | WIFI_ANT_SEL1 | External frontend control |
| | I2S_TX | I2S TX |
| GPIO13 | GPIO13 | General purpose input, output |
| | SPISLV_B_SIO2 | SPI slave SIO2 |
| | SPIMST_B_SIO2 | SPI master SIO2 |
| | U2RTS | UART RTS |
| | MA_MC0_DA0 | SDIO mater Data0 |
| | SLV_MC0_DA0 | SDIO slave Data0 |
| | CLKO4 | Clock out port |
| | EINT13 | External interrupt |
| | I2S_WS | 12S WS |
| GPIO14 | GPIO14 | General purpose input, output |
| | SPISLV_B_SIO1 | SPI slave SIO1 |
| | SPIMST_B_SIO1 | SPI master SIO1 |
| | TDM_RX | TDM RX |
| | MA_MC0_DA1 | SDIO master Data1 |
| | SLV_MC0_DA1 | SDIO slave Data1 |
| | PWM4 | Pulse-width-modulated output |
| | EINT14 | External interrupt |
| | CLKO4 | Clock out port |



| GPIO15 | GPIO15 | General purpose input, output |
|--------|----------------------|--|
| | SPISLV_B_SIO0 | SPI slave SIO0 |
| | SPIMST_B_SIO0 | SPI master SIO0 |
| | TDM_TX | TDM TX |
| | MA_MC0_DA2 | SDIO mater Data2 |
| | SLV_MC0_DA2 | SDIO slave Data2 |
| | SCL1 | I2C Clock |
| | EINT15 | External interrupt |
| | PWM3 | Pulse-width-modulated output |
| GPIO16 | GPIO16 | General purpose input, output |
| | SPISLV_B_SCK | SPI slave clock |
| | SPIMST_B_SCK | SPI master clock |
| | TDM_WS | TDM WS |
| | MA_MC0_DA3 | SDIO master Data3 |
| | SLV_MC0_DA3 | SDIO slave Data3 |
| | SDA1 | I2C data |
| | EINT16 | External interrupt |
| GPIO17 | GPIO17 | General purpose input, output |
| | SPISLV_B_CS | SPI slave CS |
| | SPIMST_B_CS | SPI master CS |
| | TDM_CK | TDM CK |
| | CLKO3 | Clock out port |
| | AUXADC0 | AUX ADC |
| | EINT17 | External interrupt |
| | BT_PRIO | Wi-Fi and Bluetooth coexistence control signal |
| GPIO18 | GPIO18 | General purpose input, output |
| | PMU_GOTO_SLEEP | PMU Control Signal |
| | TDM_MCLK | TDM MCLK |
| | CLKO4 | Clock out port |
| | SDA1 | I2C data |
| | ZCV (SW set AUXADC1) | AUX ADC |
| | EINT18 | External interrupt |
| | CLKO3 | Clock out port |
| | PMU_RGU_RSTB | PMU Control Signal |
| GPIO19 | GPIO19 | General purpose input, output |
| | URXD0 | UART RX |
| | EINT19 | External interrupt |
| | SCL1 | I2C Clock |
| | PWM5 | Pulse-width-modulated output |

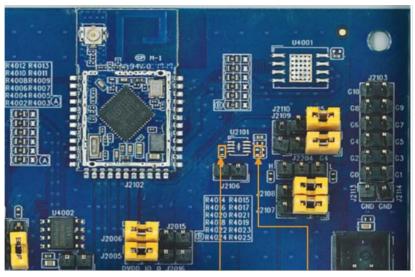


| | AUXADC2 | AUX ADC |
|--------|---------|-------------------------------|
| GPIO20 | GPIO19 | General purpose input, output |
| | UTXD0 | UART TX |
| | EINT20 | External interrupt |
| | AUXADC3 | AUX ADC |

Note, to use the GPIO8 and GPIO9 pins as I2CO, add pull-up resistors on the HDK or on the I2CO daughterboard.



To add pull-up resistors on the HDK, refer to the resistor locations in Figure 7. The location of R2101 is for adding the pull-up resistor for I2CO_SDA (GPIO9). The location of R2102 is for adding the pull-up resistor for I2CO_CLK (GPIO8).



R2101 R2102

Figure 7. Locations of I2C pull-up resistors

4.6. RTC

The MT7686 HDK features an RTC module. The clock source operates at 32.768kHz crystal oscillator or an external clock source. The RTC has built-in accurate timer to wake up the system when the user-defined timer expires. The RTC uses a different power source from the Power Management Unit (PMU). In retention mode, the PMU is turned off while the RTC module remains powered on. The RTC module only consumes $3\mu A$ in retention mode. The RTC has a dedicated PMU control pin EXT_PWR_EN (pin 21) used to turn the power on when the RTC timer expires and turn the power off when it intends to enter the hibernate mode.

4.7. RF connections

By default, the board ships with RF signals routed to the on-board circuit antenna. An on-board U.FL, a conductive test component, (I-PEX) connector enables to test the signals using a compatible cable. If a user wants to perform the testing, the user needs to solder the capacitor from the location **C17** to **C18**.



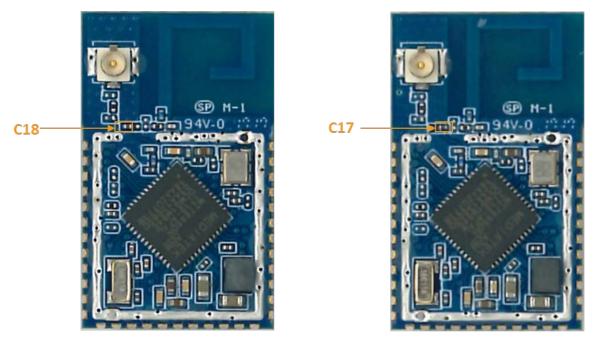


Figure 8. Location of the components C17 and C18

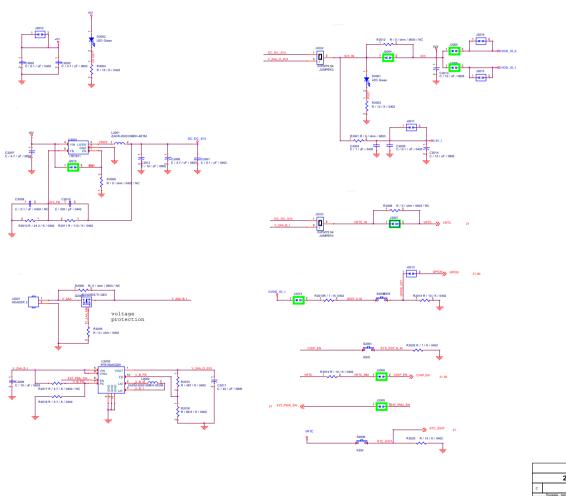
4.8. CMSIS-DAP firmware update procedure

The latest firmware from OpenSDA platform can be downloaded from the mbed official website. To update the binary firmware of CMSIS-DAP, press and hold the **SW3001**, then plug-in the USB cable to **CON3001**, release the button **SW3001** once the mass storage is shown, and then drag and drop in the binary code. After the mass storage disappears, keep the power connected for 10 seconds, and then reboot the system again to finish the firmware update.

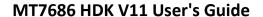


5. Schematics (V11)

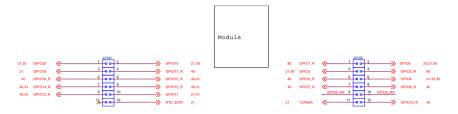
Main board schematic-1

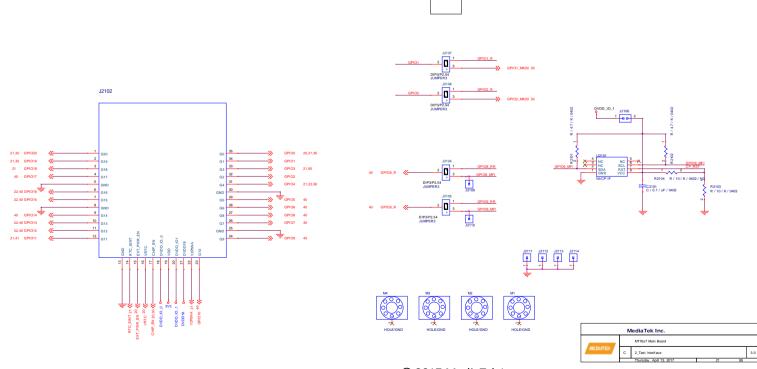




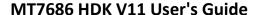






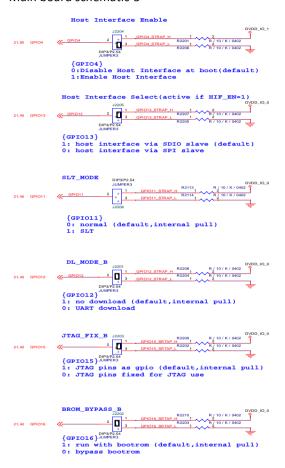


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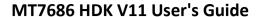




Main board schematic-3

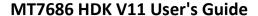




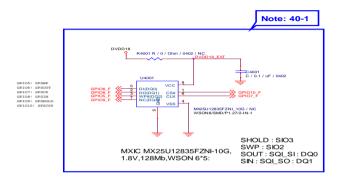




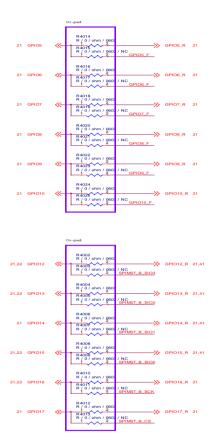
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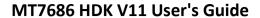






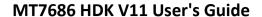






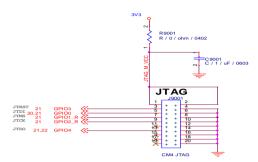








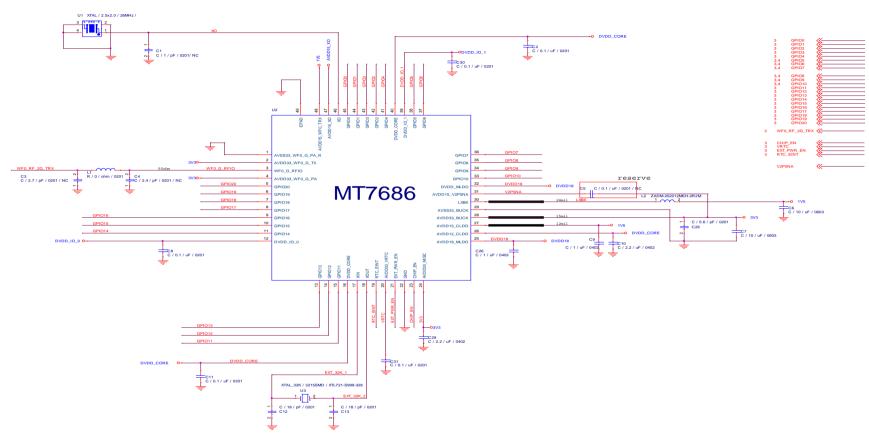
Main board schematic-7



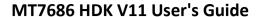




MT7686_STAMP_MODULE_V10 schematic-1

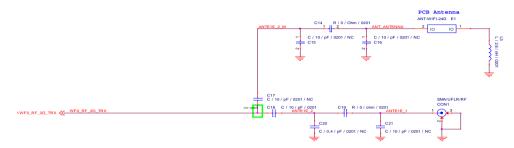


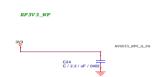
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|-----|---------------------|-----------|-----------------------------|-------|---|----|---|------------|--|
| | COMPRESSED IMAGE | Title | MT7686 Stamp Module | | | | | | |
| | | Size C | Document Number 10_BB_RF | | | | | Rev 0.1 | |
| - 1 | | Date: | Friday, January 13, 2017 | Sheet | 1 | of | 4 | | |

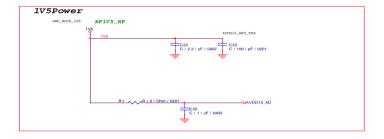




MT7686_STAMP_MODULE_V10 schematic-2















MT7686_STAMP_MODULE_V10 schematic-3

Strap Pin

