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X_{i} = \frac{\det(A_{\overline{b},i})}{\det(A_{i})} \qquad X_{2} = \frac{\det(A_{\overline{b},2})}{\det(A_{i})}
             Then ((raner's Rule) For an invertible nxn matrix A, the system A\vec{x} = \vec{b}

Satisfies

X<sub>i</sub> = A_{bi}

Let (A)

Where A_{bi} is "replace column; by \vec{b}."

Pf tet (A<sub>bi</sub>) = A_{bi}

A_
                                                                                                                                                                                                                                                                                                                                                                                                                                     = \det \begin{pmatrix} \overrightarrow{v}_1 \cdots (\overrightarrow{x_i}\overrightarrow{w_i} + \cdots + \overrightarrow{x_n}\overrightarrow{w_n}) & \cdots & \overrightarrow{w_n} \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}
= \det \begin{pmatrix} \overrightarrow{v}_1 \cdots \overrightarrow{v}_i\overrightarrow{w}_i & \cdots & \overrightarrow{w_n} \\ 1 & 1 & 1 \end{pmatrix}
Eq. (x_1 + 2x_2 = 5)
(3x_1 + 4x_2 = 7)
(
                                                                                                                                                                                                                                                                                               X_{2} = \frac{\text{def } 15}{(37)} = \frac{1.7 - 5.3}{1.4 - 2.3} = 4
\text{def } 12
\text{def } 12
\text{def } 1
  Computing At with Comer's Rule
               For A'' = \begin{pmatrix} m_1 & m_1 \\ \vdots & \vdots \\ m_n & m_n \end{pmatrix} Consider A \begin{pmatrix} m_1 \\ \vdots \\ m_n \end{pmatrix} = \vec{e}_j
                Craver's Rule = 2 Mij = Jet Aēji
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By cofactor expansion on column is det A = (-1)^{itj} Jet(A_i)

= \sum_{ij} (-1)^{itj} Jet(A_i)

Def For invertible nown matrix A, the classical adjoint is the view matrix A adj(A) = (-1)^{itj} Jet(A_{ji}).
                     Then For invertible own matrix A, A = I adi(A).
           detA = 6
                                                                                                                                                                                                                                                                                                                                                                                                  = \begin{pmatrix} 5 \cdot 1 - 6 \cdot 2 & -(2 \cdot 1 - 3 \cdot 2) & 2 \cdot 6 - 3 \cdot 5 \\ -(4 \cdot 1 - 6 \cdot 1) & 1 \cdot 1 - 3 \cdot 1 & -(1 \cdot 6 - 3 \cdot 4) \\ 4 \cdot 2 - 5 \cdot 1 & -(1 \cdot 2 - 2 \cdot 1) & 1 \cdot 5 - 2 \cdot 4 \end{pmatrix}
                                                                                                                                                                                                                                                                                                                                                                        = \begin{pmatrix} -7 & 4 & -3 \\ 2 & -2 & 6 \\ 3 & 0 & 3 \end{pmatrix}
                                                                                 Determinant of a linear transformation between linear spaces 

Eg D: P_2 \longrightarrow P_2 What is let (D)? What let (D) = 0.

D(f) = f'
                                                                 D(f) = f'
                                                                 For \mathcal{B} = \{1, x, x^2\}, the \mathcal{B}-matrix \mathcal{D}
is \mathcal{B} = \{[D(1)]_{\mathcal{B}} [D(X)]_{\mathcal{B}} [D(X^2)]_{\mathcal{B}}
                                                                                                                                                                                               = \left( \begin{bmatrix} 0 \\ 0 \end{bmatrix} & \begin{bmatrix} 1 \\ 1 \end{bmatrix} & \begin{bmatrix} 2x \\ 2x \end{bmatrix} & \begin{bmatrix} 2x \\ 1 \end{bmatrix} & \begin{bmatrix} 2x \\ 2x \end{bmatrix} & 
                                                                                                                                                                                                           = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix} \quad \text{and} \quad \text{Jet } B = 0
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Def For a linear transformation T: V -> V for V a finite-dinersion 4 linear space, Let T = Jet B for B the B-matrix of T for some basis B of V. Note (a) Let T is independent of Choice of B (b) let T = 0 if and only if T: V->V is an isomorphism (v is finite directional)