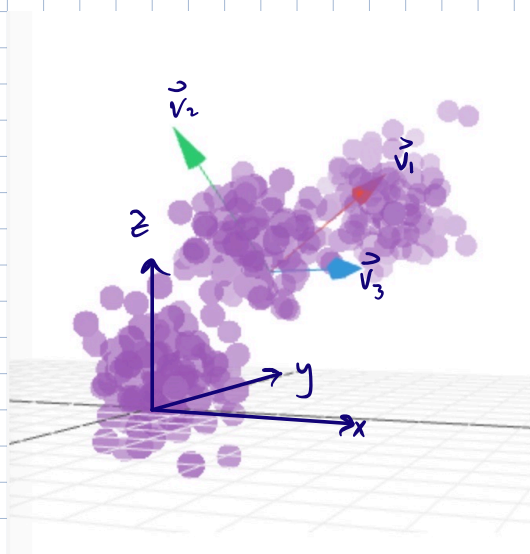


HW 4 due today, 5pm
 3.1: 6, 24, 32, 34, 37, 38
 3.2: 26, 34
 3.3: 30, 38
 Cool exercise but not collected:
 3.3: 90

HW 5 due 2/18
 3.4: 2, 4, 20, 26, 44

Coordinates



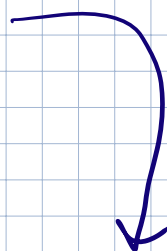
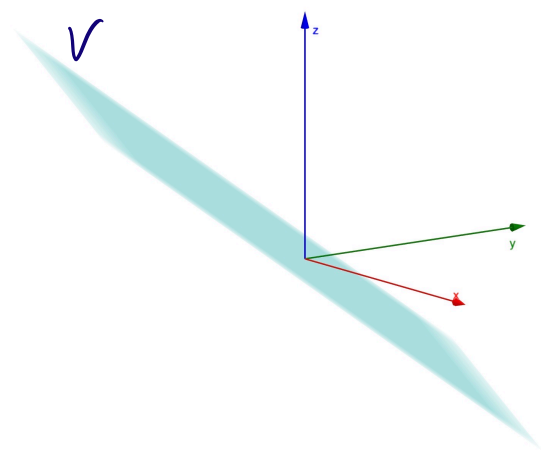
Highly correlated data \mathbb{R}^N

Want to describe using fewer dimensions

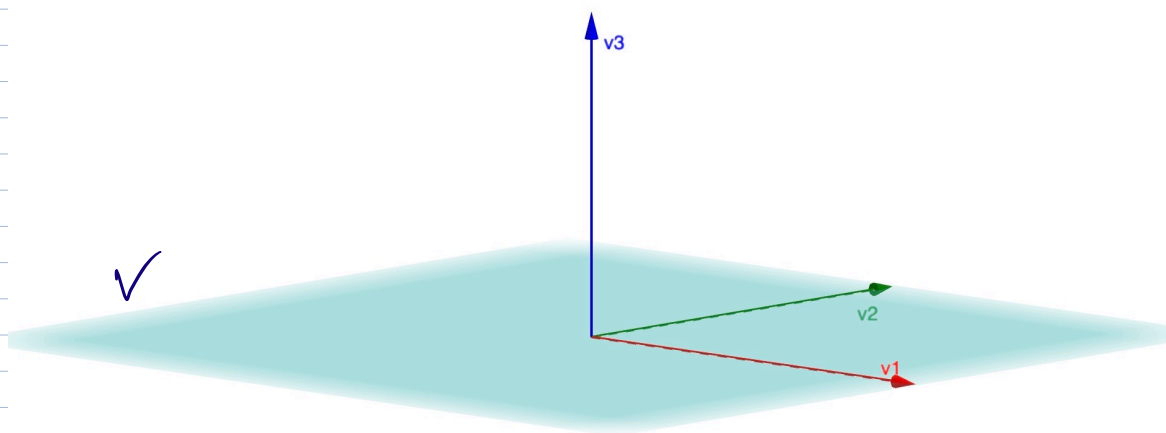
Data in \mathbb{R}^N

$$\vec{v} = \begin{pmatrix} \vdots \\ \vdots \end{pmatrix} \in \text{subspace } V \xrightarrow[\text{with basis } \mathcal{B}]{\text{Coordinates in } \mathcal{B}} [\vec{v}]_{\mathcal{B}} = \begin{pmatrix} \vdots \\ \vdots \end{pmatrix}$$

Eg Data in \mathbb{R}^3 on left has little variation in \vec{v}_3 direction:
 describe data points only using $\{\vec{v}_1, \vec{v}_2\}$



change coordinate system



Lots of examples in §3.4.

Eg Consider a subspace $V = \text{span} \left\{ \underbrace{\begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix}}_{\vec{v}_1}, \underbrace{\begin{pmatrix} 0 \\ 1 \\ 2 \\ 3 \end{pmatrix}}_{\vec{v}_2} \right\}$

Is $\vec{u} = \begin{pmatrix} 2 \\ 5 \\ 4 \\ 3 \end{pmatrix}$ in V ?

$$\left(\begin{array}{cc|c} 1 & 0 & 2 \\ 2 & 1 & 5 \\ 1 & 2 & 4 \\ 0 & 3 & 3 \end{array} \right) \rightarrow \dots \rightarrow \left(\begin{array}{cc|c} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

So, $\vec{u} = 2\vec{v}_1 + \vec{v}_2$

Since $\dim V = 2$, \vec{u} can actually be described by just two numbers!

Def For basis $\mathcal{B} = \{\vec{v}_1, \dots, \vec{v}_m\}$ of subspace V in \mathbb{R}^n , for $\vec{x} \in V$, let c_1, \dots, c_m be the unique scalars such that $\vec{x} = c_1\vec{v}_1 + \dots + c_m\vec{v}_m$.

Then, c_1, \dots, c_m are the \mathcal{B} -coordinates of \vec{x} and

$[\vec{x}]_{\mathcal{B}} = \begin{pmatrix} c_1 \\ \vdots \\ c_m \end{pmatrix}$ is the \mathcal{B} -coordinate vector of \vec{x} .

Eg $\mathcal{B} = \left\{ \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 2 \\ 3 \end{pmatrix} \right\}$, $\vec{u} = \begin{pmatrix} 2 \\ 5 \\ 4 \\ 3 \end{pmatrix}$ then $[\vec{u}]_{\mathcal{B}} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

Note $\vec{x} = \begin{pmatrix} 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_m \\ 1 & & 1 \end{pmatrix} [\vec{x}]_{\mathcal{B}} = \begin{pmatrix} 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_m \\ 1 & & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ \vdots \\ c_m \end{pmatrix} = c_1\vec{v}_1 + \dots + c_m\vec{v}_m$

Eg $\mathcal{B} = \left\{ \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \right\}$ is a basis of \mathbb{R}^3

For $\vec{u} = \begin{pmatrix} 6 \\ 1 \\ 2 \end{pmatrix}$, what is $[\vec{u}]_{\mathcal{B}}$?

Row-reduce $\left(\begin{array}{ccc|c} 2 & 3 & 1 & 6 \\ -1 & 0 & 2 & 1 \\ 0 & -1 & 3 & 2 \end{array}\right) \rightarrow \dots \rightarrow \left(\begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{array}\right)$ so $[\vec{u}]_B = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

Thm B a basis of subspace V of \mathbb{R}^n , then

a) $[\vec{x} + \vec{y}]_B = [\vec{x}]_B + [\vec{y}]_B$ for all \vec{x}, \vec{y} in V

b) $[k\vec{x}]_B = k[\vec{x}]_B$ for all \vec{x} in V and scalars k

Eg $\vec{v} = \begin{pmatrix} 5 \\ -1 \\ -1 \end{pmatrix}$ in \mathbb{R}^3 with basis $B = \left\{ \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \right\}$

$[\vec{v}]_B = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$ and

$[\vec{v} + \vec{u}]_B = \left[\begin{pmatrix} 5 \\ -1 \\ -1 \end{pmatrix} + \begin{pmatrix} 6 \\ 1 \\ 2 \end{pmatrix} \right]_B = \left[\begin{pmatrix} 11 \\ 0 \\ 1 \end{pmatrix} \right]_B = \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = [\vec{v}]_B + [\vec{u}]_B$

check $2 \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} + 2 \begin{pmatrix} 3 \\ 0 \\ -1 \end{pmatrix} + 1 \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 11 \\ 0 \\ 1 \end{pmatrix}$ ✓

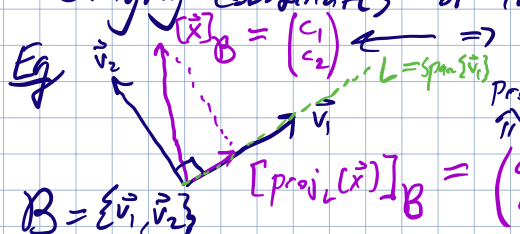
Question If $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a linear transformation and $B = \{\vec{v}_1, \dots, \vec{v}_n\}$ a basis of \mathbb{R}^n ,

What is a matrix B such that $B[\vec{x}]_B = [T(\vec{x})]_B$?

Thm In this situation,

$B = \left(\begin{array}{c} | \\ [T(\vec{v}_1)]_B \\ | \\ \vdots \\ | \\ [T(\vec{v}_n)]_B \\ | \end{array} \right)$ is the unique matrix such that $[T(\vec{x})]_B = B[\vec{x}]_B$

"Changing coordinates of linear transformation"

Eg  $\vec{x} = c_1 \vec{v}_1 + c_2 \vec{v}_2$ so, $\underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}}_B \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} c_1 \\ 0 \end{pmatrix}$

Check $\text{proj}_L(\vec{v}_1) = \vec{v}_1 \Rightarrow [\text{proj}_L(\vec{v}_1)]_B = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ so this gives columns of $B = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$.
 $\text{proj}_L(\vec{v}_2) = \vec{0} \Rightarrow [\text{proj}_L(\vec{v}_2)]_B = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

Diagram For basis $B = \{\vec{v}_1, \dots, \vec{v}_n\}$ of \mathbb{R}^n

$$S = \begin{pmatrix} | & & | \\ \vec{v}_1 & \dots & \vec{v}_n \\ | & & | \end{pmatrix}$$

$$\begin{array}{ccc} \vec{x} & \xrightarrow{A} & T(\vec{x}) \\ \uparrow S & & \uparrow S \\ [\vec{x}]_B & \xrightarrow{B} & [T(\vec{x})]_B \end{array}$$

$$\Rightarrow AS = SB \Leftrightarrow B = S^{-1}AS \text{ \& } A = SBS^{-1}$$

Def Two $n \times n$ matrices are similar if there exists an invertible matrix S such that $AS = SB \Leftrightarrow B = S^{-1}AS$

Eg Is $\underbrace{\begin{pmatrix} 1 & 4 \\ 0 & 1 \end{pmatrix}}_A$ similar to $\underbrace{\begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}}_B$?

Does $\underbrace{\begin{pmatrix} 1 & 4 \\ 0 & 1 \end{pmatrix}}_S \begin{pmatrix} x & y \\ z & t \end{pmatrix} = \begin{pmatrix} x & y \\ z & t \end{pmatrix} \underbrace{\begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}}_B$ for some x, y, z, t ?

$$\begin{pmatrix} x+4z & y+4t \\ z & t \end{pmatrix} = \begin{pmatrix} x+2z & y \\ z+2t & t \end{pmatrix}$$

$$\begin{cases} x+4z = x+2z \\ y+4t = y \\ z = z+2t \\ t = t \end{cases} \Rightarrow \begin{cases} 4z = 2z \\ 4t = 0 \\ 0 = 2t \\ t = t \end{cases} \Rightarrow \begin{cases} t = 0, y = 2z \\ x, y, z \text{ are free} \end{cases}$$

but! $xt - yz \neq 0 \Rightarrow yz \neq 0$

So, $\begin{pmatrix} x & y \\ z & t \end{pmatrix} = \begin{pmatrix} 0 & 2 \\ 1 & 0 \end{pmatrix}$ works and A is therefore similar to B .

Thm A $n \times n$ matrix

- A is similar to itself ($S = Id$)
- A is similar to $B \Leftrightarrow B$ is similar to A (set S to S^{-1})
- A is similar to B and B is similar to $C \Rightarrow A$ is similar to C .