

#### Outline

- Decision Trees Regression
- Numerical vs Categorical Attributes
- Pruning

#### Alternatives to Using Stopping Conditions

What is the major issue with pre-specifying a stopping condition?

You may stop too early or stop too late.

How can we fix this issue?

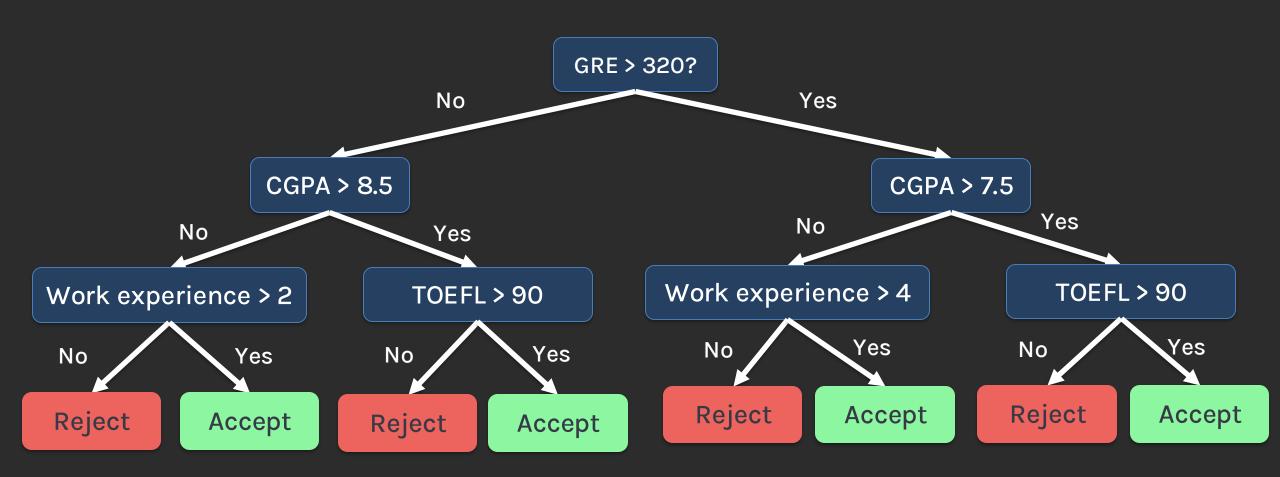
 Choose several stopping criteria (e.g., set minimal Gain(R) at various levels) and cross-validate to decide which one is the best.

What is an alternative approach to this method?

Don't stop. Instead, prune the tree!

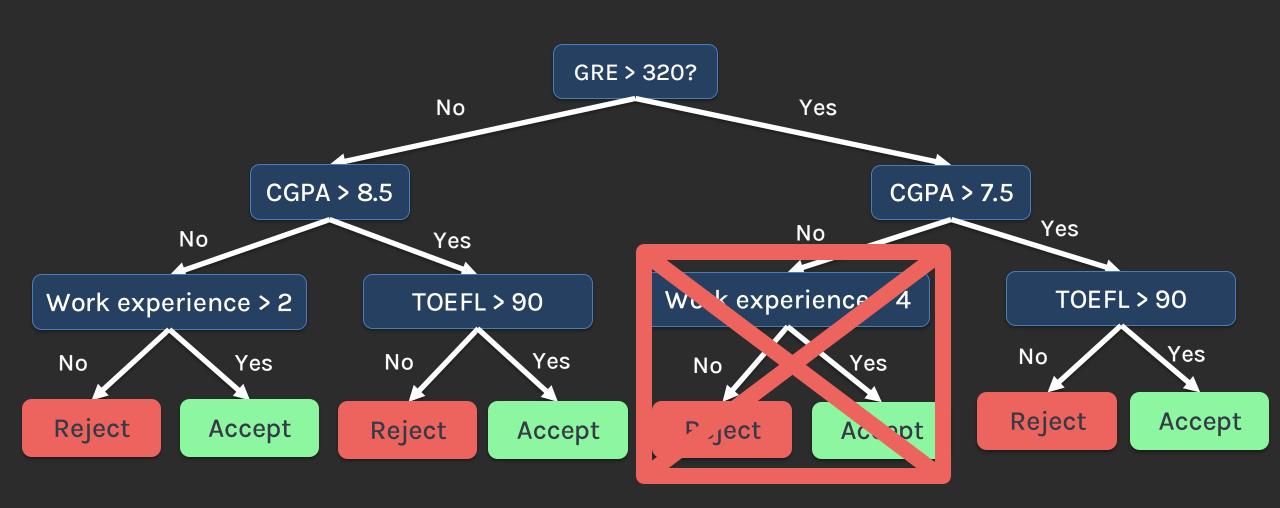
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#### Example: Evaluating Applications to a GRADUATE Program



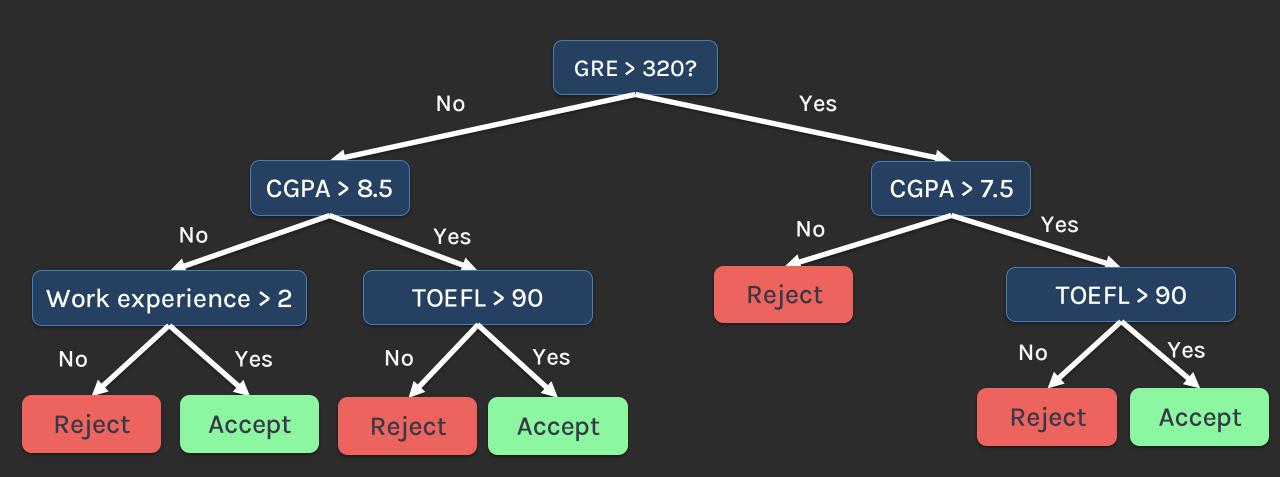
<sup>\*\*</sup> Above representation is only for pedagogical purposes.

#### Example: Evaluating Applications to a GRADUATE Program



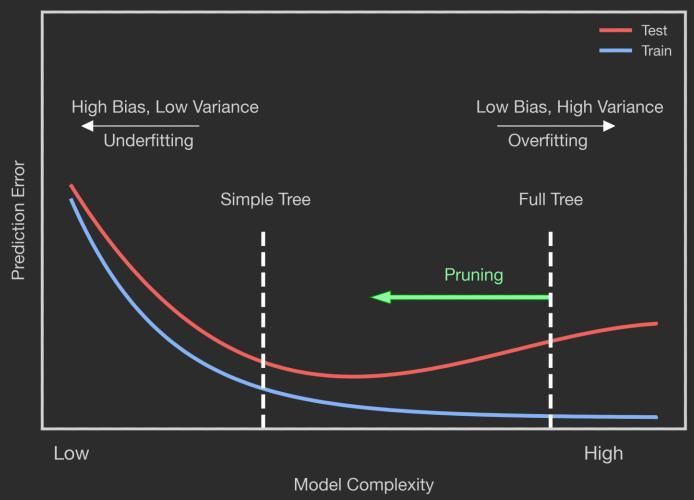
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#### Example: Evaluating Applications to a GRADUATE Program



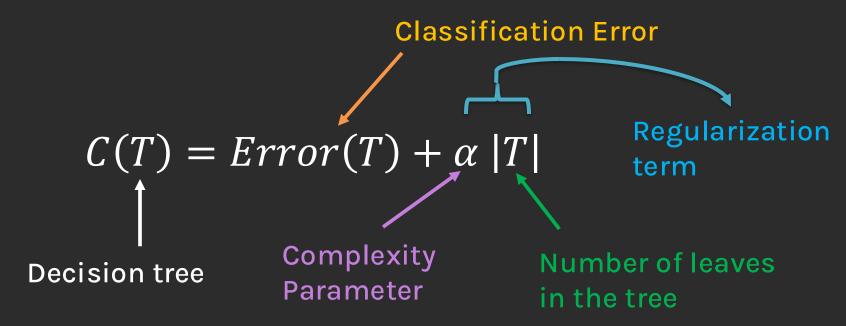
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#### Motivation for Pruning

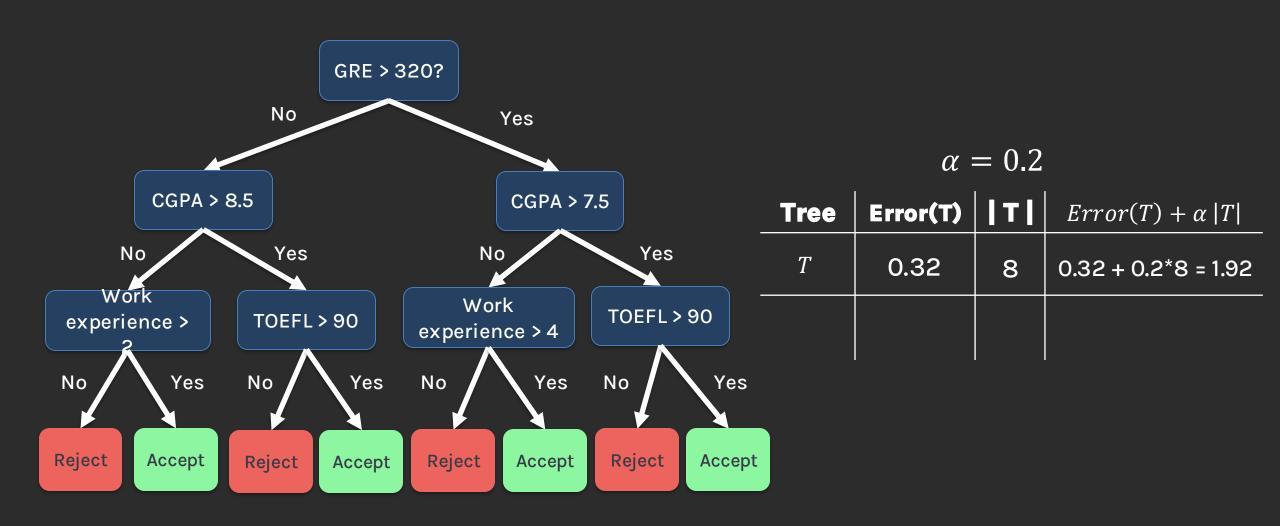


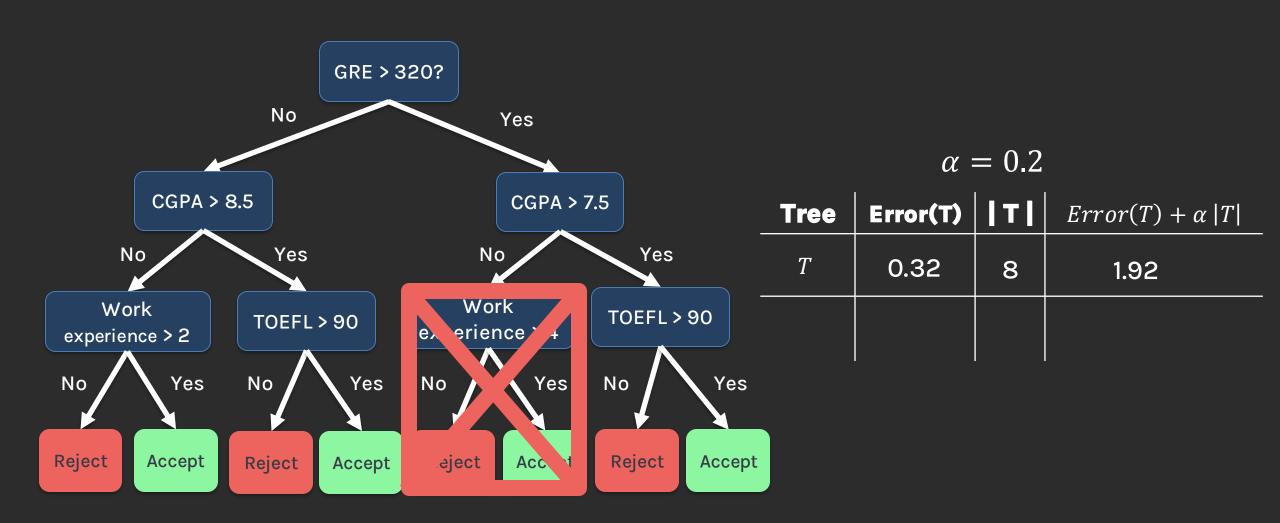
Rather than preventing a complex tree from growing, we can obtain a simpler tree by 'pruning' a complex one.

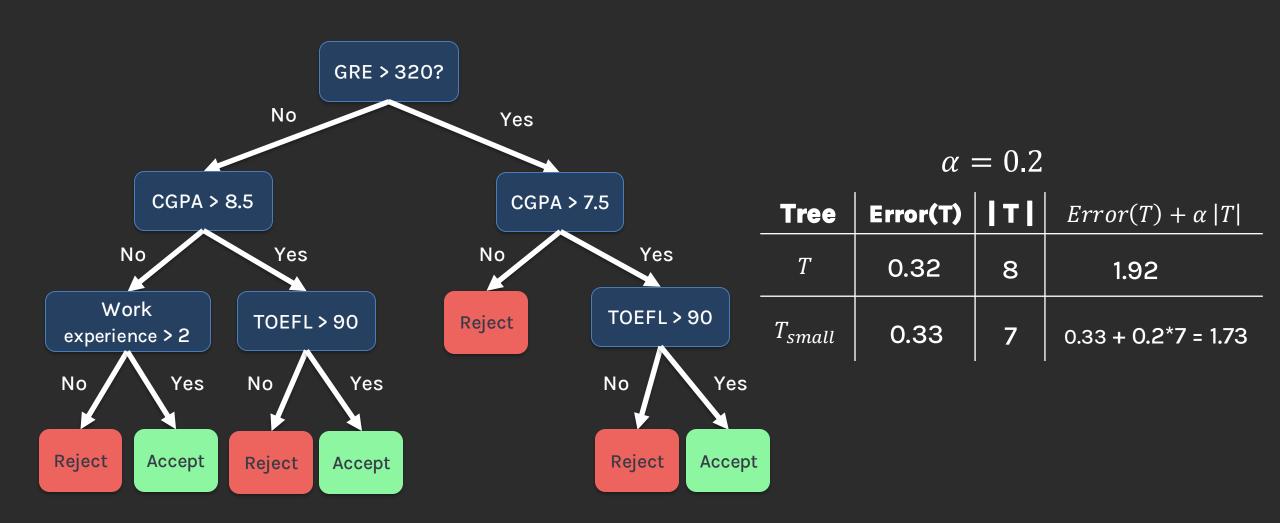
There are many methods of pruning. A common one is the cost complexity pruning:

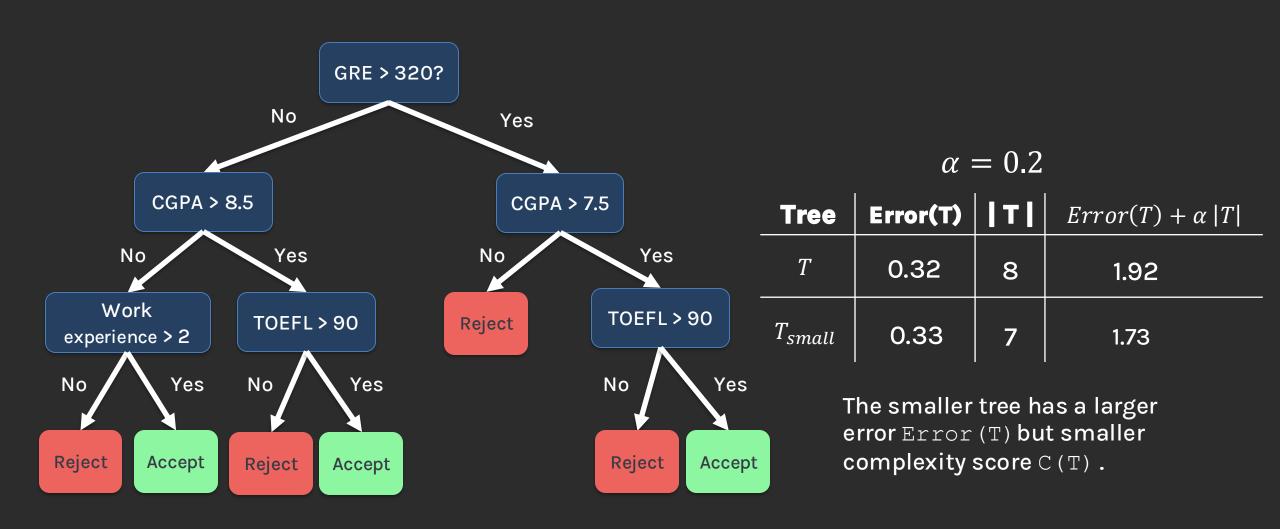


In other words, we add a 'regularization' term!

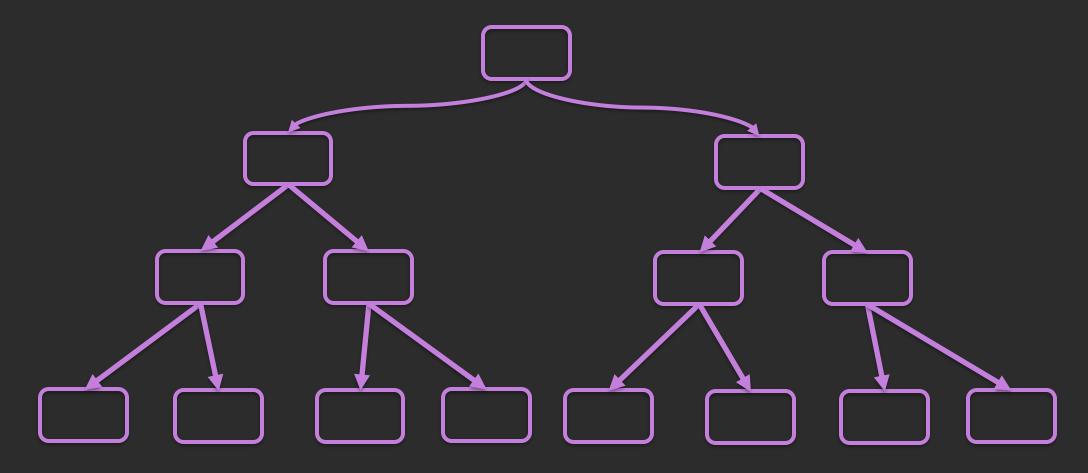






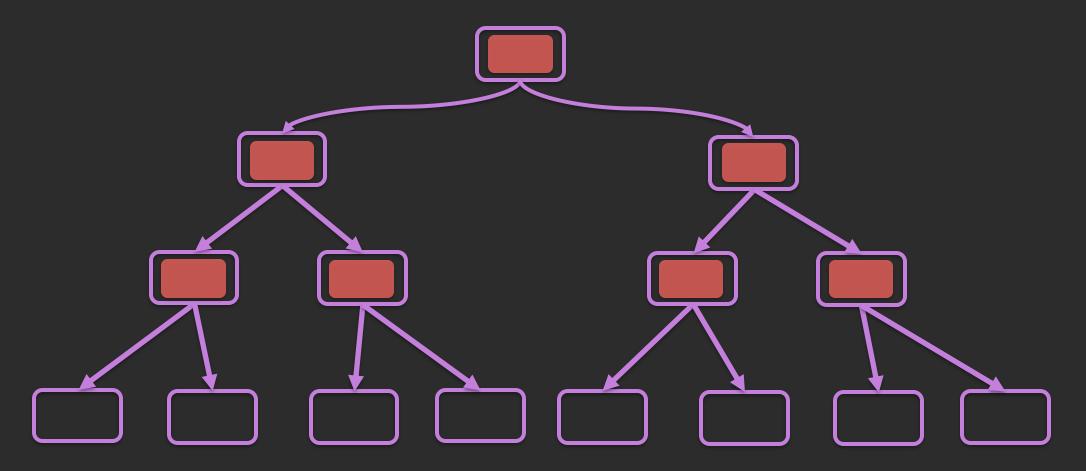


Suppose we have **a full tree**  $T_0$  as shown below.

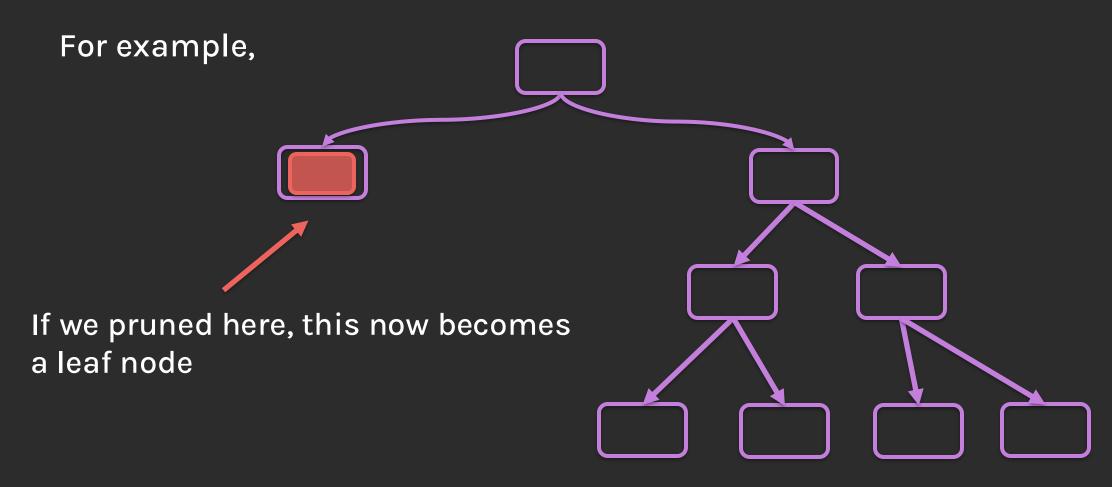


How many possible ways are there to prune this tree?

There are **7** possible pruning locations, which are shown with red rectangles.



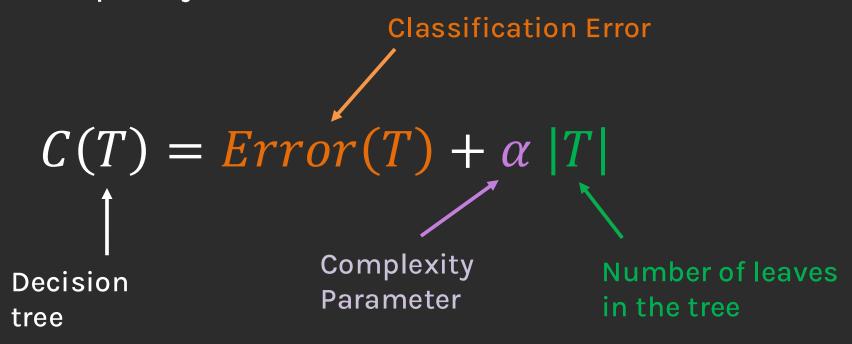
For each of those pruning locations, we will get 7 possible pruned trees,  $m{T}^*$  .



Question: How do we choose the best pruned tree?

We will choose the one that maximizes the difference of **cost complexity score** between a full tree and a pruned tree.

Quick recap: Cost complexity score is



#### Our goal is to maximize $C(T) - C(T^*)$

1. 
$$\underset{T*}{argmax} [C(T) - C(T^*)]$$

2. 
$$\underset{T*}{argmax} [E(T) - E(T^*) + \alpha |T| - \alpha |T^*|]$$

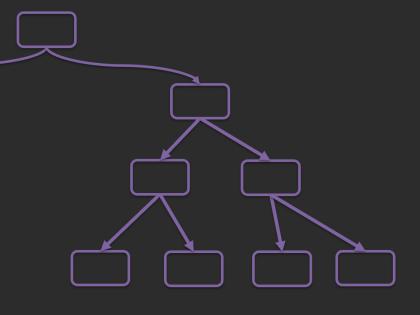
3. 
$$\underset{T*}{argmax} \left[ \frac{E(T) - E(T^*)|}{\alpha |T^*| - \alpha |T|} - 1 \right]$$
 (divide by  $\alpha |T^*| - \alpha |T|$ )

4. 
$$\underset{T*}{argmax} \left[ \frac{E(T) - E(T^*)|}{\alpha |T^*| - \alpha |T|} \right]$$

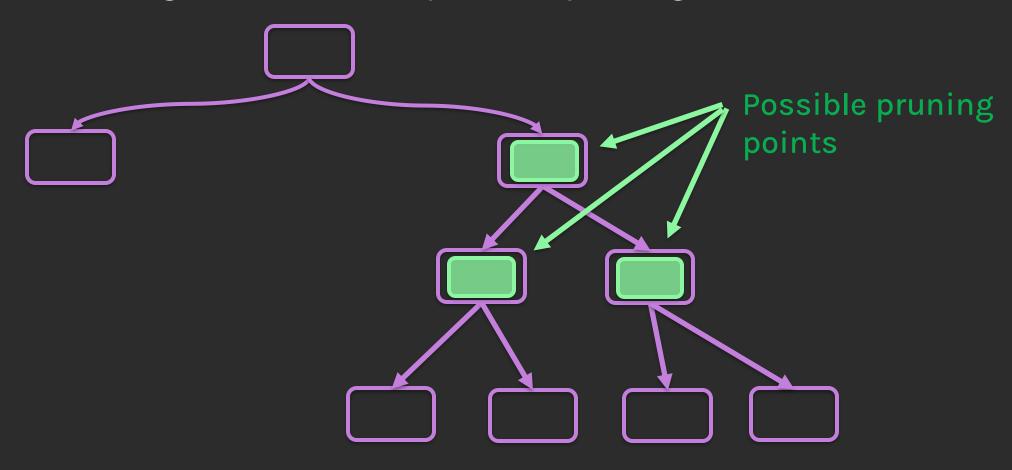
5. 
$$\underset{T*}{argmin} \left[ \frac{E(T) - E(T^*)|}{\alpha |T| - \alpha |T^*|} \right]$$

This will result in a subtree,  $oldsymbol{T^{(1)}}$ 

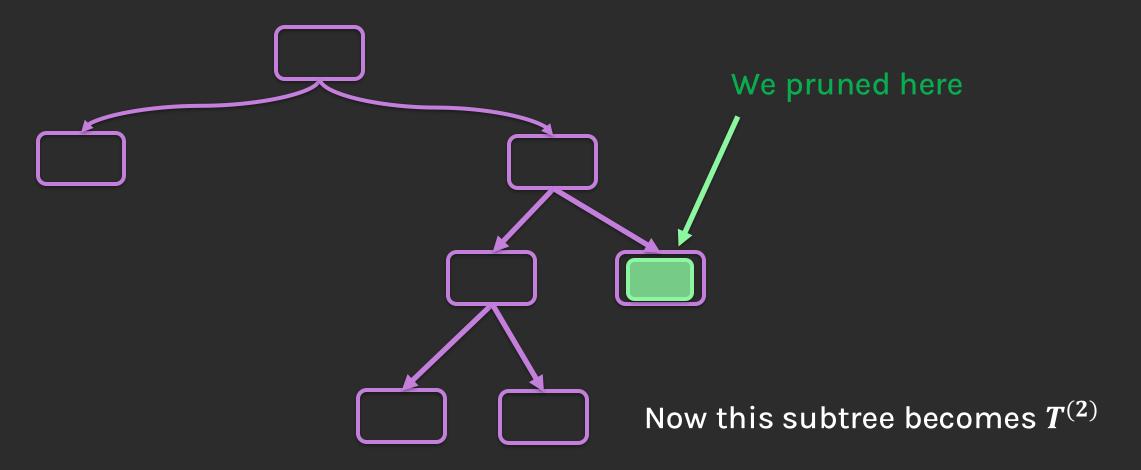
 $T^*$  is the pruned tree where T is the unpruned tree



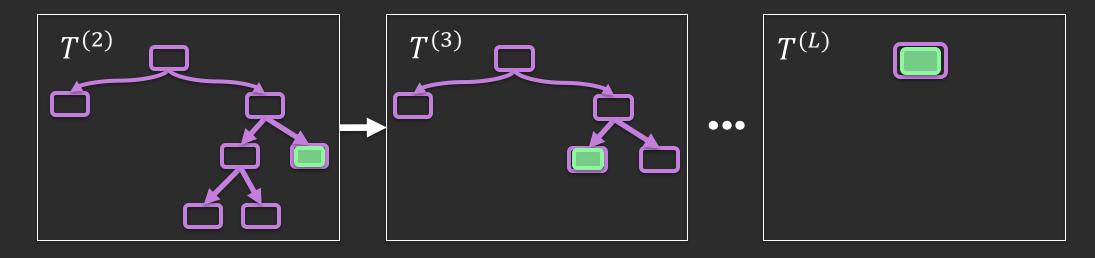
Now, we again consider all possible pruning from  $\overline{T}^{(1)}$ .



We again minimize the ratio of the difference of the  $\frac{argmin}{T*} \left[ \frac{E(T^{(1)}) - E(T^*)}{\alpha |T^{(1)}| - \alpha |T^*|} \right]$  errors **over the difference in the complexity** 



We iterate this pruning process to obtain  $T^{(2)}$ ,  $T^{(3)}$ , ...,  $T^{(L)}$  where  $T^{(L)}$  is the tree containing just the root of  $T^{(0)}$ .



We select the optimal tree  $T^{(i)}$  by cross validation.

This is the  $T^*$  given  $\alpha$ . Finally, we choose **the optimal**  $\alpha$  by cross validation!

#### Summary

#### What is the main drawback of pre-defining stopping criteria for decision tree growth?

Pre-defined stopping criteria may lead to trees that are either too simple (underfitting) or too complex (overfitting) since it's challenging to determine the optimal stopping point beforehand.

# Explain the alternative approach to using stopping conditions for decision tree construction.

Instead of stopping conditions, an alternative approach is to grow a large tree first, then prune it back to find a balanced structure, offering flexibility for optimal complexity.

#### What is the core concept behind pruning in decision trees?

Pruning simplifies a decision tree by removing branches with minimal impact on overall accuracy, enhancing the tree's ability to generalize.

#### Summary

Describe the formula used for calculating the cost complexity of a decision tree. Cost complexity (C(T)) is calculated as: C(T) = Error(T) +  $\alpha$ |T|, where Error(T) is the classification error,  $\alpha$  is the complexity parameter, and |T| is the number of leaves.

In cost-complexity pruning, how does the complexity parameter ( $\alpha$ ) influence the trade-off between tree size and error?

The complexity parameter ( $\alpha$ ) adjusts the penalty for tree size, with higher values favoring smaller trees with potentially higher error and lower values favoring more complex trees with potentially lower error.

How do you determine the best pruned tree from a set of candidate trees generated by pruning?

The best pruned tree is selected by maximizing the difference in cost complexity scores, choosing the tree with the most significant reduction in complexity without a major increase in error.

## Thank you

