

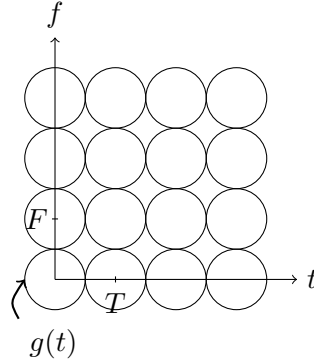
Harmonic Analysis

Weyl-Heisenberg frames

There are two important classes of highly structured frames that have been studied extensively, namely Weyl-Heisenberg (Gabor) frames and wavelets. We will start with Weyl-Heisenberg frames.

1 Motivation

There are many applications where a localized time-frequency representation of a signal $x(t) \in \mathcal{L}^2(\mathbb{R})$ is needed. In 1946, Gabor formulated an approach to decompose signals in terms of elementary signals. He partitioned the time-frequency plane into non-overlapping rectangles and intended to find a collection of elementary signals with small corresponding areas in the time-frequency plane:



We consider modulated and translated versions of a so called window function $g(t)$, i.e.,

$$g_{m,n}(t) = e^{i2\pi n F t} g(t - mT)$$

where $m, n \in \mathbb{Z}$ and $T, F > 0$ are fixed time and frequency parameters. $\{g_{m,n}(t)\}_{m,n \in \mathbb{Z}}$ is called a Weyl-Heisenberg system.

The following discussion is primarily concerned with the question for what choices of $g(t)$ and T and F a Weyl-Heisenberg system is a frame.

For convenience, we define the *Weyl operator* $W_{m,n}^{(T,F)}$ as

$$\left(W_{m,n}^{(T,F)} g\right)(t) = g_{m,n}(t) = e^{i2\pi n F t} g(t - mT).$$

Example 1.1: Consider the Fourier series. The Fourier series is a signal expansion in the functions $e^{i2\pi n \frac{t}{T}}$. It is convenient to normalize these functions, thus we define

$$\phi_n(t) = \begin{cases} \sqrt{1/T} e^{i2\pi n \frac{t}{T}} & \text{for } 0 \leq t \leq T \\ 0 & \text{otherwise.} \end{cases}$$

Setting

$$g(t) = \begin{cases} \sqrt{1/T} & \text{for } 0 \leq t \leq T \\ 0 & \text{otherwise,} \end{cases}$$

we can write $\phi_n(t) = W_{0,n}^{(T, \frac{1}{T})} g(t)$. The set

$$\left\{ \left(W_{0,n}^{(T, \frac{1}{T})} g \right)(t) = \phi_n(t) \right\}_{n \in \mathbb{Z}}$$

is an ONB for $\mathcal{L}^2([0, T])$. Thus $\mathcal{L}^2([Tm, T(m+1)])$ has the ONB

$$\left\{ \left(W_{m,n}^{(T, \frac{1}{T})} g \right)(t) = \phi_n(t - mT) \right\}_{n \in \mathbb{Z}}.$$

Putting these bases together, we obtain that $\mathcal{L}^2(\mathbb{R})$ has the ONB

$$\left\{ \left(W_{m,n}^{(T, \frac{1}{T})} g \right)(t) \right\}_{m,n \in \mathbb{Z}}. \quad (1.1)$$

Thus (1.1) is a frame for $\mathcal{L}^2(\mathbb{R})$. Note that $g(t)$ has finite support, thus its support in the frequency domain is infinite.

Definition 1.1: When the set of functions $\left\{ g_{m,n}(t) = \left(W_{m,n}^{(T,F)} g \right)(t) \right\}$ with $m, n \in \mathbb{Z}$ and $T, F > 0$ is a frame for \mathcal{L}^2 , it is called a *Weyl-Heisenberg* frame.

Proposition 1.1. The Weyl-operator $W_{m,n}^{(T,F)}$ satisfies the following properties

- i. $W_{m,n} W_{k,l} = e^{-i2\pi(mT)(lF)} W_{m+k, n+l}$ (Composition)
- ii. $W_{m,n}^* = e^{-i2\pi mnTF} W_{-m, -n}$ (Adjoint) linearity!
- iii. $W_{m,n} W_{m,n}^* = W_{m,n}^* W_{m,n} = \mathbb{I}$ (Unitarity)

Proof. We prove the three properties separately.

i. Note that

$$\begin{aligned} (W_{m,n} W_{k,l} x)(t) &= W_{m,n} \left[e^{i2\pi l F t} x(t - kT) \right] \\ &= e^{i2\pi n F t} e^{i2\pi l F (t - mT)} x(t - (m+k)T) \\ &= e^{-i2\pi l m F T} (W_{m+k, n+l} x)(t). \end{aligned}$$

ii. By straightforward calculation

$$\begin{aligned} \langle W_{m,n} x, y \rangle &= \int_{-\infty}^{\infty} e^{i2\pi n F t} x(\underbrace{t - mT}_{t'}) \overline{y(t)} dt \\ &= \int_{-\infty}^{\infty} e^{i2\pi n F (t' + mT)} x(t') \overline{y(t' + mT)} dt' \\ &= \int_{-\infty}^{\infty} x(t') \overline{e^{-i2\pi n F (t' + mT)} y(t' + mT)} dt' \\ &= \langle x, e^{-i2\pi n m F T} W_{-m, -n} y \rangle, \end{aligned}$$

where the second equality follows from the substitution $t = t' + mT$. Hence, the adjoint operator of $W_{m,n}$ is given by $W_{m,n}^* = e^{-i2\pi m n T F} W_{-m, -n}$.

iii. Verify that

$$W_{m,n} W_{m,n}^* \stackrel{\text{ii.}}{=} W_{m,n} W_{-m, -n} e^{-i2\pi m n T F} \stackrel{\text{i.}}{=} \mathbb{I}.$$

Analogously, we find that

$$W_{m,n}^* W_{m,n} = \mathbb{I}.$$

□

Definition 1.2: The *frame operator* is defined as

$$(\mathbb{S}x)(t) = \sum_m \sum_n \langle x, g_{m,n} \rangle g_{m,n}(t).$$

Lemma 1.1. The frame operator \mathbb{S} and its inverse \mathbb{S}^{-1} commute with the Weyl operator $W_{m,n}$, i.e.,

$$\begin{aligned} W_{m,n}\mathbb{S} &= \mathbb{S}W_{m,n} \\ W_{m,n}\mathbb{S}^{-1} &= \mathbb{S}^{-1}W_{m,n}. \end{aligned}$$

Proof. Notice that the second property follows from the first by left- and right-multiplication with \mathbb{S}^{-1} . Hence, it suffices to prove the first identity. We find that

$$\begin{aligned} (W_{m,n}\mathbb{S}x)(t) &= W_{m,n} \sum_{k,l} \langle x, W_{k,l}g \rangle (W_{k,l}g)(t) \\ &= \sum_{k,l} \langle x, W_{k,l}g \rangle (W_{m,n}W_{k,l}g)(t) \\ &= \sum_{k,l} \langle x, W_{k,l}g \rangle e^{-i2\pi mTlF} (W_{m+k,n+l}g)(t) = (*), \end{aligned}$$

where used Proposition 1.1, i. to come from the second to the third equality. On the other hand, we have

$$\begin{aligned} (\mathbb{S}W_{m,n}x)(t) &= \sum_{k,l} \langle W_{m,n}x, W_{k,l}g \rangle (W_{k,l}g)(t) \\ &= \sum_{k,l} \langle x, W_{m,n}^* W_{k,l}g \rangle (W_{k,l}g)(t) \\ &= \sum_{k,l} e^{i2\pi(n-l)mTF} \left\langle x, W_{\underbrace{k-m}_{k'}} \underbrace{l-n}_{l'} g \right\rangle (W_{k,l}g)(t) \\ &= \sum_{k',l'} \langle x, W_{k',l'}g \rangle e^{-i2\pi mTl'F} (W_{m+k',n+l'}g)(t) = (*) \end{aligned}$$

implying that $W_{m,n}\mathbb{S} = \mathbb{S}W_{m,n}$. □

Proposition 1.2. Let $\{g_{m,n}(t) = (W_{m,n}g)(t)\}$ be a Weyl-Heisenberg frame. Then, the dual frame is again a Weyl-Heisenberg frame, i.e.,

$$\tilde{g}_{m,n}(t) = (W_{m,n}\tilde{g})(t)$$

with $\tilde{g}(t) = (\mathbb{S}^{-1}g)(t)$.

Proof.

$$\tilde{g}_{m,n}(t) = (\mathbb{S}^{-1}g_{m,n})(t) = (W_{m,n}\mathbb{S}^{-1}g)(t) = (W_{m,n}\tilde{g})(t).$$

□

2 Zak Transform

To answer for which T and F the family $\{g_{m,n}(t)\}$ is a frame, we need to study a new tool.

Definition 2.1: The Zak transform (ZT) of a signal $x(t)$ is defined as

$$(\mathbb{Z}^{T,F}x)(t, f) = \sum_{k=-\infty}^{\infty} x(t + kT) e^{-i2\pi k \frac{f}{F}}.$$

We sometimes use the shorthand notations $(\mathbb{Z}_x)(t, f)$ or $\mathbb{Z}_x(t, f)$.

Proposition 2.1. The Zak transform exhibits the following properties (see [?, Sec. 8.3] for the assumptions on the signals)

i Frequency-Domain Expression

$$\mathbb{Z}_x(t, f) = \frac{1}{T} e^{i2\pi \frac{f}{R} t} \sum_{k=-\infty}^{\infty} \hat{x}\left(\frac{f + kF}{R}\right) e^{i2\pi k \frac{t}{T}}$$

where $\hat{x}(f) = \int_{\mathbb{R}} e^{-i2\pi f t} dt$ is the Fourier transform of the signal $x(t)$.

ii Periodicity

$\mathbb{Z}_x(t, f)$ is periodic in the frequency variable and quasi-periodic in the time variable, i.e.,

$$\begin{aligned} \mathbb{Z}_x(t + T, f) &= e^{i2\pi \frac{f}{F}} \mathbb{Z}_x(t, f) \\ \mathbb{Z}_x(t, f + F) &= \mathbb{Z}_x(t, f). \end{aligned}$$

iii Symmetry Properties

$$\begin{aligned} \mathbb{Z}_{x^-}(t, f) &= \mathbb{Z}_x(-t, -f) \\ \mathbb{Z}_{\bar{x}}(t, f) &= \overline{\mathbb{Z}_x(t, -f)}, \end{aligned}$$

where x^- denotes $x(-t)$.

iv Scaling

$$\begin{aligned} \tilde{x}(t) &\triangleq x(at) \\ \mathbb{Z}_{\tilde{x}}^{(T,F)}(t, f) &= \mathbb{Z}_x^{(aT,F)}(at, f) = \mathbb{Z}_x^{(aT, \frac{F}{a})}\left(at, \frac{f}{a}\right). \end{aligned}$$

v Shift Properties

$$\begin{aligned} \tilde{x}(t) &\triangleq x(t - \tau) \quad \Rightarrow \mathbb{Z}_{\tilde{x}}(t, f) = \mathbb{Z}_x(t - \tau, f) \\ \tilde{x}(t) &\triangleq x(t) e^{i2\pi \nu t} \quad \Rightarrow \mathbb{Z}_{\tilde{x}}(t, f) = e^{i2\pi \nu t} \mathbb{Z}_x(t, f - \nu \mathbf{R}). \end{aligned}$$

vi Marginal Properties (inverse transforms)

$$\begin{aligned} a. \quad x(t) &= \frac{1}{F} \int_0^F \mathbb{Z}_x(t, f) df \\ b. \quad \hat{x}(f) &= \int_0^T e^{-i2\pi f t} \mathbb{Z}_x(t, f) dt \end{aligned}$$

vii Inner Product

$$\frac{1}{F} \langle \mathbb{Z}_x, \mathbb{Z}_y \rangle \triangleq \frac{1}{F} \int_0^T \int_0^F \mathbb{Z}_x(t, f) \overline{\mathbb{Z}_y(t, f)} dt df = \langle x, y \rangle$$

viii Norm

$$\frac{1}{F} \|\mathbb{Z}_x\|^2 = \|x\|^2.$$

ix Multiplication Property

$$\begin{aligned}\tilde{x}(t) &= x(t) y(t) \\ \mathbb{Z}_{\tilde{x}}(t, f) &= \frac{1}{F} \int_0^F \mathbb{Z}_x(t, f - \nu) \mathbb{Z}_y(t, \nu) d\nu.\end{aligned}$$

x Convolution Property

$$\begin{aligned}\tilde{x}(t) &= x(t) \star y(t) = \int_{-\infty}^{\infty} x(t - \tau) y(\tau) d\tau \\ \mathbb{Z}_{\tilde{x}}(t, f) &= \int_0^T \mathbb{Z}_x(t - \tau, f) \mathbb{Z}_y(\tau, f) d\tau.\end{aligned}$$

xi Product of Two Zak Transforms

$$\mathbb{Z}_x(t, f) \overline{\mathbb{Z}_y(t, f)} = F \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} \left\langle x, \tilde{y}^{(mT, \frac{n}{T})} \right\rangle e^{-i2\pi m \frac{f}{F}} e^{i2\pi n \frac{t}{T}}$$

$$\text{where } \tilde{y}^{(mT, \frac{n}{T})}(t) = y(t - mT) e^{i2\pi n \frac{t}{T}}.$$

xii Cascading the Zak Transform Operator with the Weyl Operator: For integer $N = TF$, we have

$$(\mathbb{Z}W_{m,n}g)(t, f) = e^{i2\pi(nFt - m\frac{f}{F})} \mathbb{Z}_g(t, f)$$

Proof. In the following, we prove the above properties separately.

i. Recall the Poisson summation formula

$$\sum_{k=-\infty}^{\infty} y(t + kT) = \frac{1}{T} \sum_{k=-\infty}^{\infty} \hat{y}\left(\frac{k}{T}\right) e^{i2\pi k \frac{t}{T}}.$$

Substituting $y(t) = x(t) e^{-i2\pi \tilde{f}t} \circ \bullet \hat{y}(f) = \hat{x}\left(f + \tilde{f}\right)$ into the Poisson summation formula yields

$$\begin{aligned}\sum_{k=-\infty}^{\infty} x(t + kT) e^{-i2\pi \tilde{f}(t+kT)} &= \frac{1}{T} \sum_{k=-\infty}^{\infty} \hat{x}\left(\tilde{f} + \frac{k}{T}\right) e^{i2\pi k \frac{t}{T}} \\ \Rightarrow \sum_{k=-\infty}^{\infty} x(t + kT) e^{-i2\pi \tilde{f}kT} &= \frac{1}{T} e^{i2\pi \tilde{f}t} \sum_{k=-\infty}^{\infty} \hat{x}\left(\tilde{f} + \frac{k}{T}\right) e^{i2\pi k \frac{t}{T}}.\end{aligned}$$

Setting $f = \tilde{f}R = \tilde{f}TF$ gives the result.

ii. - v. Follows directly from the definition.

vi. The proofs of both properties are based on the same idea.

a. Using the definition and swapping integration and summation yields

$$\begin{aligned}\frac{1}{F} \int_0^F \mathbb{Z}_x(t, f) df &= \frac{1}{F} \int_0^F \sum_{k=-\infty}^{\infty} x(t + kT) e^{-i2\pi k \frac{f}{F}} df \\ &= \frac{1}{F} \sum_{k=-\infty}^{\infty} x(t + kT) \underbrace{\left[\int_0^F e^{-i2\pi k \frac{f}{F}} df \right]}_{F\delta[k]} = x(t).\end{aligned}$$

b. Use the same idea but exploit property i. and express \mathbb{Z}_x through $\hat{x}(f)$.

vii. Direct calculation yields

$$\begin{aligned}&\int_0^T \int_0^F \mathbb{Z}_x(t, f) \overline{\mathbb{Z}_y(t, f)} dt df \\ &= \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \int_0^T \int_0^F x(t + kT) \overline{y(t + lT)} e^{i2\pi(l-k)\frac{f}{F}} dt df \\ &= F \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta[l - k] \int_0^T x(t + kT) \overline{y(t + lT)} dt \\ &= F \sum_{k=-\infty}^{\infty} \int_{kT}^{(k+1)T} x(t) \overline{y(t)} dt \\ &= F \int_{-\infty}^{\infty} x(t) \overline{y(t)} dt.\end{aligned}$$

viii. Substitute $y(t) = x(t)$ into the expression for the inner product given in vii.

ix. Note that $\tilde{x}(t) = x(t) y(t) \circ \bullet \hat{\tilde{x}} = \hat{x}(f) \star \hat{y}(f) = \int_{-\infty}^{\infty} \hat{x}(f - \nu) \hat{y}(\nu) d\nu$. It follows that

$$\begin{aligned}
& \mathbb{Z}_{\tilde{x}}(t, f) \\
&= \frac{1}{T} e^{i2\pi \frac{f}{R} t} \sum_{k=-\infty}^{\infty} \left[\int_{-\infty}^{\infty} \hat{x}\left(\frac{f + kF}{R} - \nu\right) \hat{y}(\nu) d\nu \right] e^{i2\pi k \frac{t}{T}} \\
&= \frac{1}{T} e^{i2\pi \frac{f}{R} t} \sum_{k=-\infty}^{\infty} e^{i2\pi k \frac{t}{T}} \sum_{l=-\infty}^{\infty} \int_{l\frac{F}{R}}^{(l+1)\frac{F}{R}} \hat{x}\left(\frac{f + kF}{R} - \nu\right) \hat{y}(\nu) d\nu \\
&= \frac{1}{T} e^{i2\pi \frac{f}{R} t} \sum_{k=-\infty}^{\infty} e^{i2\pi k \frac{t}{T}} \sum_{l=-\infty}^{\infty} \int_0^{\frac{F}{R}} \hat{x}\left(\frac{f + kF - lF}{R} - \nu\right) \hat{y}\left(\nu + l\frac{F}{R}\right) d\nu \\
&\stackrel{k'=k-l}{=} \frac{1}{T} e^{i2\pi \frac{f}{R} t} \sum_{k'=-\infty}^{\infty} e^{i2\pi k' \frac{t}{T}} \sum_{l=-\infty}^{\infty} e^{i2\pi l \frac{t}{T}} \int_0^{\frac{F}{R}} \hat{x}\left(\frac{f + k'F}{R} - \nu\right) \hat{y}\left(\nu + l\frac{F}{R}\right) d\nu \\
&= T \int_0^{\frac{F}{R}} \underbrace{\frac{1}{T} e^{i2\pi(\frac{f}{R}-\nu)t} \sum_{k=-\infty}^{\infty} \hat{x}\left(\frac{f + kF}{R} - \nu\right) e^{i2\pi k \frac{t}{T}}}_{\mathbb{Z}_x(t, f - \nu R)} \times \\
&\quad \underbrace{\frac{1}{T} e^{i2\pi \nu t} \sum_{l=-\infty}^{\infty} \hat{y}\left(\nu + l\frac{F}{R}\right) e^{i2\pi l \frac{t}{T}} d\nu}_{\mathbb{Z}_y(t, \nu R)} \\
&= T \int_0^{\frac{F}{R}} \mathbb{Z}_x(t, f - \nu R) \mathbb{Z}_y(t, \nu R) d\nu \\
&= \frac{1}{F} \int_0^F \mathbb{Z}_x(t, f - \nu) \mathbb{Z}_y(t, \nu) d\nu.
\end{aligned}$$

x. We obtain by direct calculation

$$\begin{aligned}
\mathbb{Z}_{\tilde{x}}(t, f) &= \sum_{k=-\infty}^{\infty} \left[\int_{-\infty}^{\infty} x(t + kT - \tau) y(\tau) d\tau \right] e^{-i2\pi k \frac{f}{F}} \\
&= \sum_{k=-\infty}^{\infty} e^{-i2\pi k \frac{f}{F}} \sum_{l=-\infty}^{\infty} \int_{lT}^{(l+1)T} x(t + kT - \tau) y(\tau) d\tau \\
&= \sum_{k=-\infty}^{\infty} e^{-i2\pi k \frac{f}{F}} \sum_{l=-\infty}^{\infty} \int_0^T x(t + kT - lT - \tau) y(\tau + lT) d\tau \\
&= \int_0^T \underbrace{\sum_{k'=-\infty}^{\infty} x(t + k'T - \tau) e^{-i2\pi k' \frac{f}{F}}}_{\mathbb{Z}_x(t - \tau, f)} \underbrace{\sum_{l=-\infty}^{\infty} y(\tau + lT) e^{-i2\pi l \frac{f}{F}} d\tau}_{\mathbb{Z}_y(\tau, f)}.
\end{aligned}$$

xi. It follows from ii that $\mathbb{Z}_x(t, f) \overline{\mathbb{Z}_y(t, f)}$ is periodic in both variables t and f . Since $\mathbb{Z}_x(t, f) \overline{\mathbb{Z}_y(t, f)}$ is periodic, it can be represented by its Fourier series

$$\mathbb{Z}_x(t, f) \overline{\mathbb{Z}_y(t, f)} = \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} a_{m,n} e^{-i2\pi m \frac{f}{F}} e^{i2\pi n \frac{t}{T}}.$$

The Fourier coefficients $a_{m,n}$ are

$$\begin{aligned}
a_{m,n} &= \int_0^T \int_0^F \mathbb{Z}_x(t, f) \overline{\mathbb{Z}_y(t, f)} e^{-i2\pi n \frac{t}{T}} e^{i2\pi m \frac{f}{F}} dt df \\
&= \int_0^T \int_0^F \sum_{k=-\infty}^{\infty} x(t + kT) e^{-i2\pi k \frac{f}{F}} \sum_{l=-\infty}^{\infty} \overline{y(t + lT)} e^{i2\pi l \frac{f}{F}} e^{-i2\pi n \frac{t}{T}} e^{i2\pi m \frac{f}{F}} dt df \\
&= \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \int_0^T x(t + kT) \overline{y(t + lT)} e^{-i2\pi n \frac{t}{T}} dt \underbrace{\int_0^F e^{i2\pi(m-k+l)\frac{f}{F}} df}_{\delta(m-k+l)} \\
&= F \sum_{l=-\infty}^{\infty} \int_0^T x(t + (l+m)T) \overline{y(t + lT)} e^{-i2\pi n \frac{t}{T}} dt \\
&= F \sum_{l=-\infty}^{\infty} \int_{(l+m)T}^{(l+m+1)T} x(t) \overline{y(t - mT)} e^{-i2\pi n \frac{t}{T}} dt \\
&= F \int_{-\infty}^{\infty} x(t) \overline{y(t - mT)} e^{-i2\pi n \frac{t}{T}} dt \\
&= F \left\langle x, \tilde{y}^{(mT, \frac{n}{T})} \right\rangle
\end{aligned}$$

xii. Observe that

$$\begin{aligned}
(\mathbb{Z}W_{m,n}g)(t, f) &= \mathbb{Z}_{g_{m,n}}(t, f) \\
&= \sum_{k=-\infty}^{\infty} g\left(t + \overbrace{(k-m)T}^{k'}\right) e^{i2\pi n F(t+kT)} e^{-i2\pi k \frac{f}{F}} \\
&= \sum_{k'=-\infty}^{\infty} g(t + k'T) e^{i2\pi n F(t+(k'+m)T)} e^{-i2\pi(k'+m)\frac{f}{F}} \\
&= e^{i2\pi(nF(t+mT)-m\frac{f}{F})} \sum_{k'=-\infty}^{\infty} g(t + k'T) e^{-i2\pi k'(\frac{f}{F}-nFT)}
\end{aligned}$$

which becomes, for integer $N = TF$

$$\begin{aligned}
(\mathbb{Z}W_{m,n}g)(t, f) &= e^{i2\pi(nFt-m\frac{f}{F})} \sum_{k'=-\infty}^{\infty} g(t + k'T) e^{-i2\pi k' \frac{f}{F}} \\
&= e^{i2\pi(nFt-m\frac{f}{F})} \mathbb{Z}_g(t, f).
\end{aligned}$$

□

Proposition 2.2. $\sqrt{\frac{1}{F}} \mathbb{Z}^{T,F}$ is a unitary map from $\mathcal{L}^2(\mathbb{R})$ onto $\mathcal{L}^2([0, T] \times [0, F])$.

Proof. Consider again the ONB for $\mathcal{L}^2(\mathbb{R})$

$$\left\{ \left(W_{m,n}^{(T, \frac{1}{T})} \sqrt{\frac{1}{T}} \text{rect}_{[0, T]} \right) (t) \right\}_{m,n \in \mathbb{Z}}$$

and apply the Zak transform

$$\begin{aligned}
& \sqrt{\frac{1}{F}} \mathbb{Z}^{T,F} W_{m,n}^{(T, \frac{1}{T})} \sqrt{\frac{1}{T}} \text{rect}_{[0,T]}(t) \\
&= \sqrt{\frac{1}{F}} \mathbb{Z}^{T,F} \left(e^{i2\pi n \frac{t}{T}} \sqrt{\frac{1}{T}} \text{rect}_{[0,T]}(t - mT) \right) \\
&= \sqrt{\frac{1}{TF}} \sum_{k \in \mathbb{Z}} e^{i2\pi n \frac{t+kT}{T}} \text{rect}_{[0,T]}(t + kT - mT) e^{-i2\pi k \frac{f}{F}} \\
&\stackrel{k'=k-m}{=} \sqrt{\frac{1}{TF}} e^{i2\pi n \frac{t}{T}} \sum_{k' \in \mathbb{Z}} \underbrace{\text{rect}_{[0,T]}(t + k'T)}_{\neq 0 \Leftrightarrow k'=0} e^{-i2\pi k' \frac{f}{F}} e^{-i2\pi m \frac{f}{F}} \\
&= \sqrt{\frac{1}{TF}} e^{i2\pi n \frac{t}{T}} e^{-i2\pi m \frac{f}{F}}.
\end{aligned}$$

This set of functions is an ONB for $\mathcal{L}^2([0, T] \times [0, F])$. Hence, $\sqrt{\frac{1}{F}} \mathbb{Z}^{T,F}$ maps an ONB for $\mathcal{L}^2(\mathbb{R})$ into an ONB for $\mathcal{L}^2([0, T] \times [0, F])$ and is consequently a surjective, unitary map. \square

3 When is a Weyl-Heisenberg System a Frame?

We now answer the question for which T and F the family $\{g_{m,n}(t)\}$ is a frame. In doing so, we discern three different cases, namely

- i. $TF = 1$, the critical case
- ii. $TF < 1$, the oversampled case
- iii. $TF > 1$, the undersampled case.

3.1 Undersampled Case

In the undersampled case $TF > 1$, the TF -grid defined by T and F is 'too loose', i.e., the $g_{m,n}(t)$ cannot span $\mathcal{L}^2(\mathbb{R})$.

Theorem 3.1. *If $TF > 1$ and $g \in \mathcal{L}^2(\mathbb{R})$, then $\{g_{m,n}(t)\}$ is incomplete in $\mathcal{L}^2(\mathbb{R})$.*

Proof. We omit the proof. \square

3.2 Critical Sampling

It is natural to ask under what conditions a Weyl-Heisenberg frame can be a ONB. It can be shown that this is only possible in the critical case, i.e., when $TF = 1$.

In this section, we first show that in the critical case, a Weyl-Heisenberg frame and its dual must be biorthogonal.

Next we next check whether there exists "useful" windows such that the corresponding Weyl-Heisenberg frame is an ONB.

Theorem 3.2. $(\mathbb{Z}Sx)(t, f) = T\mathbb{Z}_x(t, f) |\mathbb{Z}_g(t, f)|^2$.

Proof. First note that using $TF = 1$, we obtain by application of Proposition 2.1 xii.

$$(\mathbb{Z}W_{m,n}g)(t, f) = e^{i2\pi(n\frac{t}{T} - m\frac{f}{F})} \mathbb{Z}_g(t, f).$$

It follows from direct calculation that

$$\begin{aligned}
(\mathbb{Z}\mathbb{S}x)(t, f) &= \sum_{m,n} \langle x, g_{m,n} \rangle \mathbb{Z}_{g_{m,n}}(t, f) \\
&= \sum_{m,n} \langle x, g_{m,n} \rangle e^{i2\pi(n\frac{t}{T} - m\frac{f}{F})} \mathbb{Z}_g(t, f) \\
&= \frac{1}{F} \mathbb{Z}_x(t, f) \overline{\mathbb{Z}_g(t, f)} \mathbb{Z}_g(t, f) \\
&= T \mathbb{Z}_x(t, f) |\mathbb{Z}_g(t, f)|^2
\end{aligned}$$

where we used Proposition 2.1 xi. to come from the second to the third equality. \square

Theorem 3.3. *In the critical case, the set $\{g_{m,n}(t)\}$ is a frame for $\mathcal{L}^2(\mathbb{R})$ with bounds A, B if and only if*

$$A \leq T |\mathbb{Z}_g(t, f)|^2 \leq B \quad (3.2)$$

with $A > 0, B < \infty$.

Proof. We shall first show that (3.2) implies that $\{g_{m,n}(t)\}$ is a frame with frame bounds A and B . Starting from (3.2)

$$\begin{aligned}
A |\mathbb{Z}_x(t, f)|^2 &\leq T |\mathbb{Z}_x(t, f)|^2 |\mathbb{Z}_g(t, f)|^2 \leq B |\mathbb{Z}_x(t, f)|^2 \\
A \underbrace{\int_0^T \int_0^{\frac{1}{T}} |\mathbb{Z}_x(t, f)|^2 dt df}_{F \|x\|^2} &\leq T \underbrace{\int_0^T \int_0^{\frac{1}{T}} |\mathbb{Z}_x(t, f)|^2 |\mathbb{Z}_g(t, f)|^2 dt df}_{F \langle \mathbb{S}x, x \rangle} \\
&\leq B \underbrace{\int_0^T \int_0^{\frac{1}{T}} |\mathbb{Z}_x(t, f)|^2 dt df}_{F \|x\|^2}
\end{aligned}$$

where the expressions under the braces follow from Theorem 3.2 and Proposition 2.1 vii. and viii.

To show the other direction, we assume that $\{g_{m,n}(t)\}$ is a frame. Hence, it holds that

$$A \|x\|^2 = AT \int_0^T \int_0^{\frac{1}{T}} |\mathbb{Z}_x(t, f)|^2 dt df \leq T^2 \int_0^T \int_0^{\frac{1}{T}} |\mathbb{Z}_x(t, f)|^2 |\mathbb{Z}_g(t, f)|^2 dt df.$$

Reformulating the above expression yields

$$T \int_0^T \int_0^{\frac{1}{T}} |\mathbb{Z}_x(t, f)|^2 \left(T |\mathbb{Z}_g(t, f)|^2 - A \right) dt df \geq 0$$

and since $\mathbb{Z}_x(t, f)$ is arbitrary, this implies that $T |\mathbb{Z}_g(t, f)|^2 - A \geq 0$. Hence, it follows that

$$\begin{aligned}
T |\mathbb{Z}_x(t, f)|^2 &\geq A \\
T |\mathbb{Z}_x(t, f)|^2 &\leq B \quad \text{g, nicht x}
\end{aligned}$$

where the lower bound for B follows analogously. \square

Corollary 3.1. *In the critical case, $\{g_{m,n}(t)\}$ is a tight frame with $A = B$ if and only if $T |\mathbb{Z}_g(t, f)|^2 = A$.*

Theorem 3.4. Let $\{g_{m,n}(t)\}$ be a Weyl-Heisenberg frame and $TF = 1$. Then the Zak transform of the canonical dual function $\tilde{g}(t)$ is given by

$$\mathbb{Z}_{\tilde{g}}(t, f) = \frac{1}{T\mathbb{Z}_g(t, f)}.$$

Proof. Application of Theorem 3.2 yields

$$\begin{aligned}\mathbb{S}\tilde{g} = g &\Rightarrow \mathbb{Z}\mathbb{S}\tilde{g} = \mathbb{Z}g \\ &\Rightarrow T\mathbb{Z}_{\tilde{g}}(t, f) |\mathbb{Z}_g(t, f)|^2 = \mathbb{Z}_g(t, f).\end{aligned}$$

Since $\{g_{m,n}(t)\}$ is a frame, $|\mathbb{Z}_g(t, f)|^2$ is bounded by the frame bounds and hence we can divide both sides by $\mathbb{Z}_g(t, f)$ to obtain

$$\mathbb{Z}_{\tilde{g}}(t, f) = \frac{1}{T\mathbb{Z}_g(t, f)}.$$

□

Theorem 3.5. Let $\{g_{m,n}(t)\}$ be a Weyl-Heisenberg frame in the critical case $TF = 1$. Then $\{g_{m,n}(t)\}$ is exact, i.e., $\{g_{m,n}(t)\}$ and $\{\tilde{g}_{m,n}(t)\}$ are biorthonormal

$$\langle g_{m,n}, \tilde{g}_{m',n'} \rangle = \delta_{m-m'} \delta_{n-n'}.$$

Proof. We have

$$\begin{aligned}\langle \tilde{g}, g_{m,n} \rangle &= T \langle \mathbb{Z}\tilde{g}, \mathbb{Z}g_{m,n} \rangle \\ &= T \int_0^T \int_0^F \mathbb{Z}_{\tilde{g}}(t, f) e^{-i2\pi n \frac{t}{T}} e^{i2\pi m \frac{f}{F}} \overline{\mathbb{Z}_g(t, f)} dt df \\ &= \int_0^T \int_0^F e^{-i2\pi n \frac{t}{T}} e^{i2\pi m \frac{f}{F}} dt df \\ &= \delta_m \delta_n,\end{aligned}$$

where we applied Theorem 3.4 to obtain the last line. The claim now follows from

$$\langle \tilde{g}_{m',n'}, g_{m,n} \rangle = \langle W_{m',n'} \tilde{g}, W_{m,n} g \rangle \quad (3.3)$$

$$= \langle \tilde{g}, W_{m',n'}^* W_{m,n} g \rangle \quad (3.4)$$

$$= \langle \tilde{g}, g_{m-m', n-n'} \rangle \quad (3.5)$$

$$= \delta_{m-m'} \delta_{n-n'}. \quad (3.6)$$

□

Theorem 3.6 (Balian-Low). If $\{g_{m,n}(t)\}$ is a Weyl-Heisenberg frame for $\mathcal{L}^2(\mathbb{R})$ in the critical case $TF = 1$, then either $tg(t) \notin \mathcal{L}^2(\mathbb{R})$ or $f\hat{g}(f) \notin \mathcal{L}^2(\mathbb{R})$, i.e.,

$$\int_{-\infty}^{\infty} t^2 g(t)^2 dt = \infty \text{ or } \int_{-\infty}^{\infty} f^2 \hat{g}(f)^2 df = \infty.$$

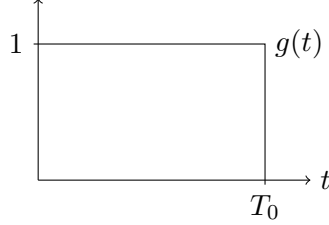
Proof. We omit the proof. □

Remember that we motivated Weyl-Heisenberg frames saying that they are a useful tool to represent functions that are concentrated in time and frequency provided that the prototype function g is concentrated in time and frequency. The above theorem basically says that this is impossible in the critical case, i.e., to achieve our aim, we have to choose $TF < 1$. Thus we have to resort to frames.

3.3 Oversampled Case

Even for $TF < 1$, a given window $g(t)$ gives rise to a frame only if T and F are properly chosen.

Example 3.1: Consider the prototype function $g(t)$ depicted in the figure below. If $T > T_0$, $g(t)$ does not give rise to a frame independently of how small F is.



Under certain restrictions on $g(t)$ and T , one can always find a frequency shift parameter F_0 , i.e.,

$$\begin{aligned} \forall F, 0 < F < F_0 : (g, T, F) \text{ is a frame.} \\ \forall F, F > F_0 : (g, T, F) \text{ is not a frame.} \end{aligned}$$

Theorem 3.7. *Let*

$$\begin{aligned} m(g(t); T) &= \min_{t \in [0, T)} \sum_m |g(t - mT)|^2 > 0 \\ M(g(t); T) &= \max_{t \in [0, T)} \sum_m |g(t - mT)|^2 < \infty \end{aligned}$$

be the minimum and the maximum of the T -periodic function $\sum_m |g(t - mT)|^2$, respectively, and assume $m(g(t); T) > 0$ and $M(g(t); T) < \infty$. Furthermore, assume that for some $\epsilon > 0$

$$\max_{\tau \in \mathbb{R}} (1 + \tau^2)^{1+\frac{\epsilon}{2}} \beta(\tau) = C_\epsilon < \infty$$

with

$$\beta(\tau) = \max_{t \in [0, T)} \sum_m |g(t - mT)| |g(t + \tau - mT)|.$$

Then, there exists an $F_0 > 0$ s.t.

i. $\forall F \in (0, F_0)$ $\{g_{m,n}(t)\}$ is a frame with frame bounds

$$\begin{aligned} A &\geq \frac{1}{F} \left[m(g(t); T) - \sum_{n \neq 0} \sqrt{\beta\left(\frac{n}{F}\right) \beta\left(-\frac{n}{F}\right)} \right] \\ B &\leq \frac{1}{F} \left[M(g(t); T) + \sum_{n \neq 0} \sqrt{\beta\left(\frac{n}{F}\right) \beta\left(-\frac{n}{F}\right)} \right]. \end{aligned}$$

ii. $\forall \delta > 0$, there exists an $F \in [F_0, F_0 + \delta]$ s.t. $\{g_{m,n}(t)\}$ associated with (g, T, F) is not a frame.

Proof. See 'The wavelet transform, T - F localization and signal analysis' by I. Daubechies. \square

Remark:

i. The condition $m(g(t); T) > 0$ means that there may not be gaps between translates $g(t - mT)$ of $g(t)$.

- ii. The condition $M(g(t); T) < \infty$ is satisfied if $g(t)$ decays sufficiently at $t \rightarrow \infty$.
 For $|g(t)| \leq C(t + t^2)^{-3/2}$, the condition $M(g(t); T) < \infty$ is always satisfied.

Theorem 3.8. *Let g be a Gaussian function, i.e., $g(t) = 2^{1/4}e^{-\pi t^2}$ for all $t \in \mathbb{R}$. Then $\{g_{m,n}\}_{m,n \in \mathbb{Z}}$ is a frame for $\mathcal{L}^2(\mathbb{R})$ if and only if $TF < 1$.*

3.3.1 Zak Transform Methods

In the following, we assume $TF = \frac{p}{q}$. First, we need an alternative expression for the frame operator.

Theorem 3.9. *The frame operator for a Weyl-Heisenberg frame $\{g_{m,n}(t)\}$ can be written as*

$$(\mathbb{S}x)(t) = \frac{1}{F} \sum_{n=-\infty}^{\infty} x\left(t - \frac{n}{F}\right) \sum_{m=-\infty}^{\infty} g(t - mT) \overline{g\left(t - mT - \frac{n}{F}\right)}.$$

Proof. Left as an exercise. □

We next restrict ourself to the case $TF = \frac{1}{N}$, slightly more involved results also hold for rational TF . The analogy of Theorem 3.2 is

$$(\mathbb{Z}\mathbb{S}x)(t, f) = \underbrace{\frac{1}{NF}}_{=T} \mathbb{Z}_x(t, f) \sum_{k=0}^{N-1} \left| \mathbb{Z}_g\left(t, f - \frac{k}{NT}\right) \right|^2.$$

In the case of oversampling by integer factors, the application of the frame operator to an arbitrary signal $x(t)$ corresponds to multiplication of $\mathbb{Z}_x(t, f)$ by $\sum_{k=0}^{N-1} |\mathbb{Z}_g(t, f - kF)|^2$ in the Zak transform domain.

Now, we can generalize Theorem 3.3.

Theorem 3.10. *The set $\{g_{m,n}\}$ is a frame for $\mathcal{L}^2(\mathbb{R})$ with bounds A, B in the oversampled case $TF = \frac{1}{N}$ if and only if*

$$A \leq T \sum_{i=0}^{N-1} |\mathbb{Z}_g(t, f - iF)|^2 \leq B.$$

Proof. The proof is analogous to the proof of Theorem 3.3. □

Corollary 3.2. *$\{g_{m,n}\}$ is a tight frame if and only if*

$$T \sum_{i=0}^{N-1} |\mathbb{Z}_g(t, f - iF)|^2 = A$$

Theorem 3.11. *Assume that $TF = \frac{1}{N}$. Then, the Zak transform of the canonical dual function $\tilde{g}(t)$ is given by*

$$\mathbb{Z}_{\tilde{g}}(t, f) = \frac{\mathbb{Z}_g(t, f)}{T \sum_{i=0}^{N-1} |\mathbb{Z}_g(t, f - iF)|^2}.$$

Proof. Start from

$$(\mathbb{Z}\mathbb{S}\tilde{g})(t, f) = T \mathbb{Z}_{\tilde{g}}(t, f) \sum_{i=0}^{N-1} |\mathbb{Z}_g(t, f - iF)|^2$$

and use $\mathbb{Z}\mathbb{S}\tilde{g} = \mathbb{Z}g$. □