Causal Inference - Part B

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Topics:

CausalGraphicalModels library

Application of CausalGraphicalModels to the Sprinkler example

Causal Inference with Causal Graphical Models

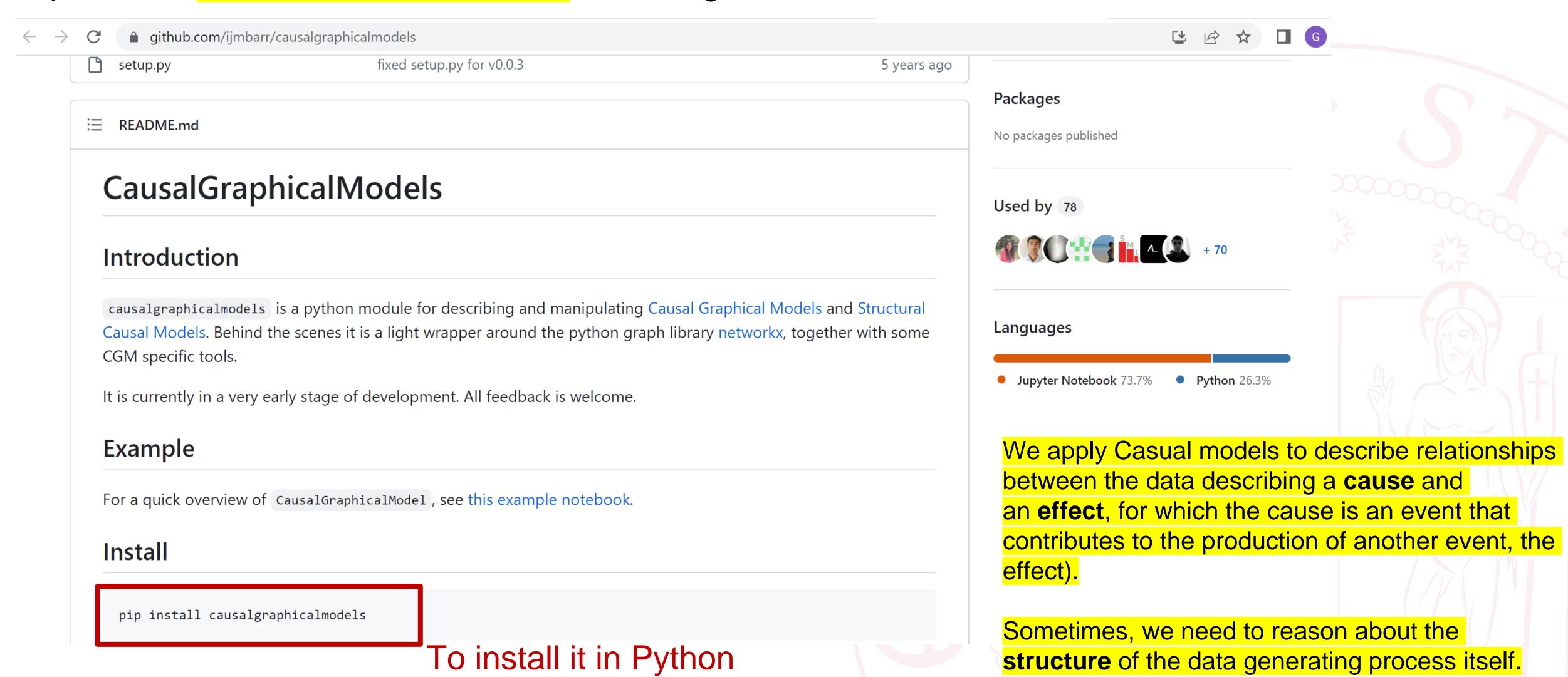
- Recap on adjustment formula
- Adjustment formula & Backdoor criterion
- Adjustment formula & Backdoor criterion: Example
- Recap on front-door adjustment
- Unobserved confounders: Smoking example





CausalGraphicalModels library

In this laboratory, we will use another easy-to-use library to implement Causal Graphical Models and in particular Structural Causal Models, including causal networks.

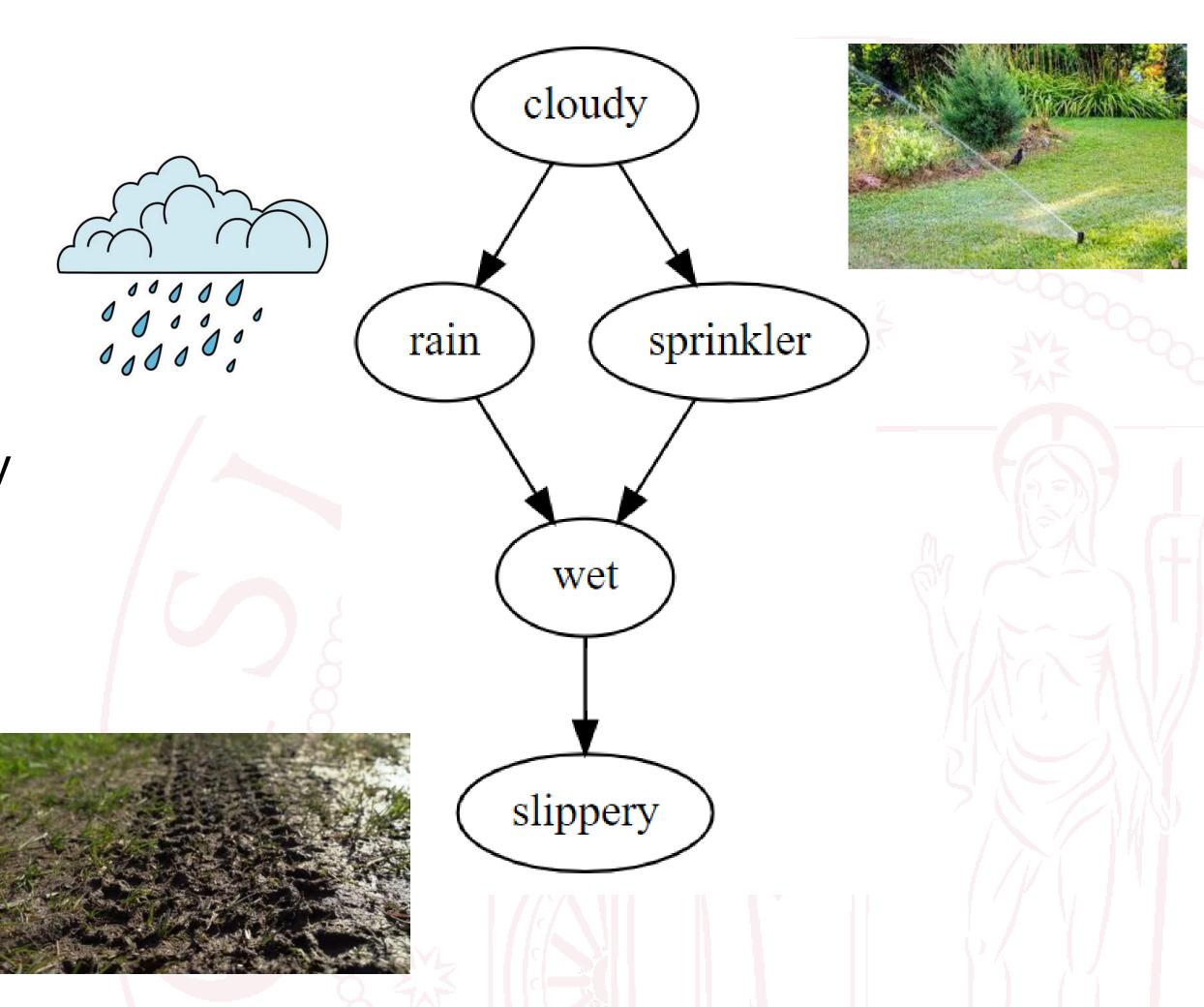


Let's start by introducing the Causal Graphical Models library by applying it to a variant of the Sprinkler example

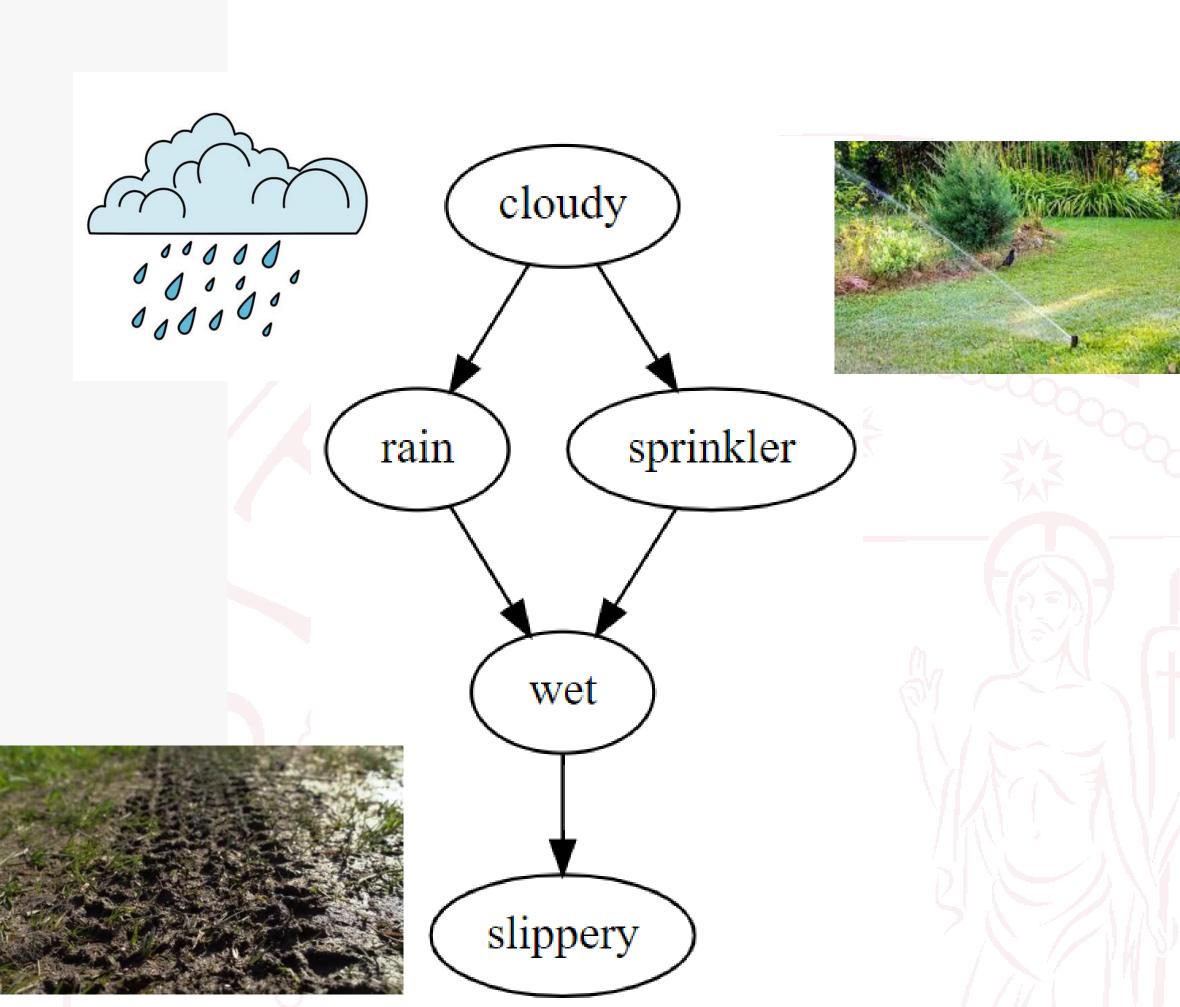
We consider the following five variables:

- Cloudy: indicates whether it is cloudy
- Rain: indicates whether it is raining
- Sprinkler: indicates whether our sprinkler is on
- Wet: indicates whether the grass is wet
- Slippery: indicates whether the ground is slippery

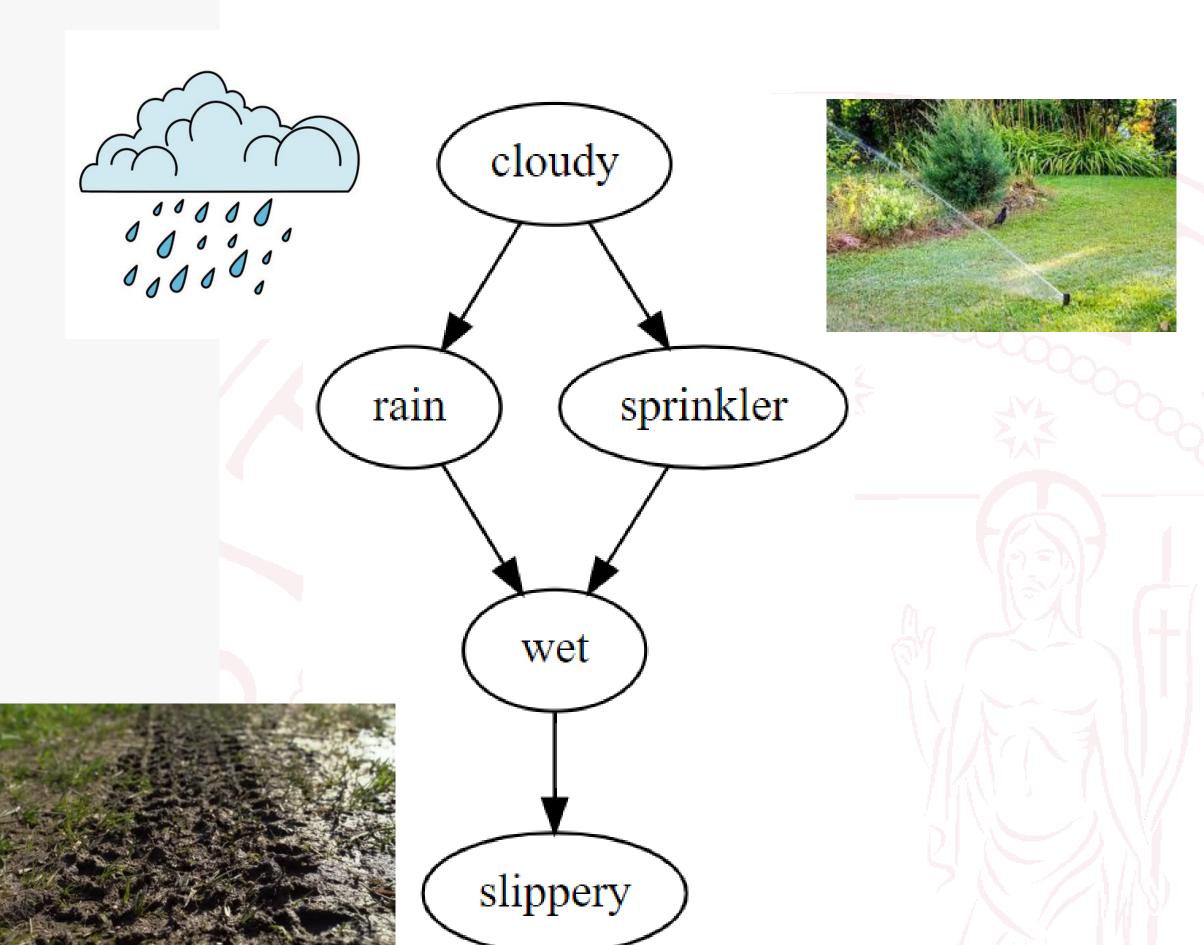
We know that when it rains, the ground will become wet, the making the ground wet doesn't cause it to rain.



```
!pip install causalgraphicalmodels
from causalgraphicalmodels import CausalGraphicalModel
sprinkler = CausalGraphicalModel(
    nodes=["cloudy", "rain", "sprinkler", "wet", "slippery"],
    edges=[
        ("cloudy", "rain"),
        ("cloudy", "sprinkler"),
        ("rain", "wet"),
        ("sprinkler", "wet"),
        ("wet", "slippery")
# draw return a graphviz `dot` object, which jupyter can render
sprinkler.draw()
```



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from causalgraphicalmodels import CausalGraphicalModel
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```



get the distribution implied by the graph
print(sprinkler.get_distribution())

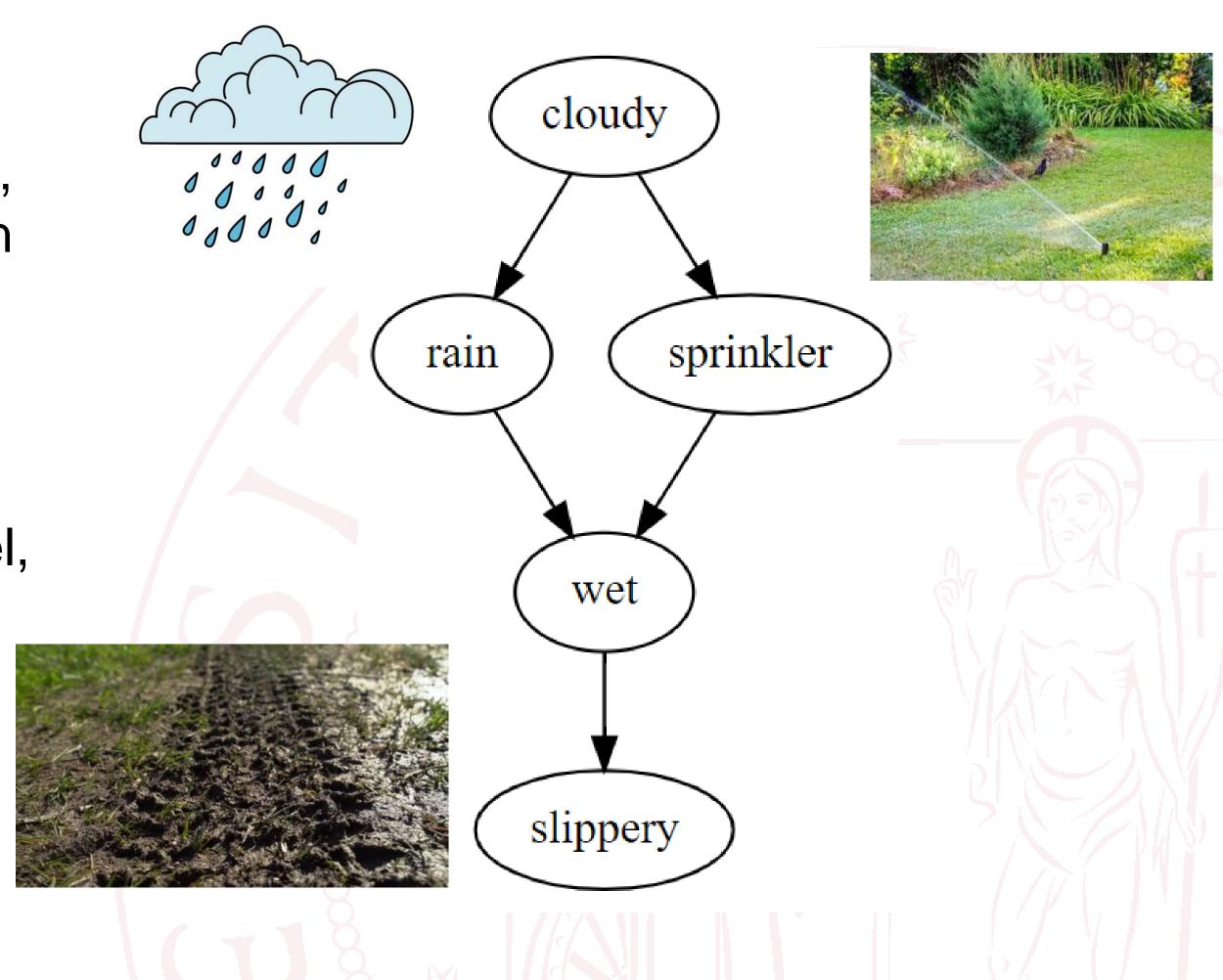
P(cloudy)P(rain|cloudy)P(sprinkler|cloudy)P(wet|rain,sprinkler)P(slippery|wet)

To get the join probability distribution as we saw in the previous lectures

This description of the causal graphical model has been the same as those of general Bayesian Networks.

To endow these structures with a notion of causality, we some assumptions about what happens when an **intervention** occurs.

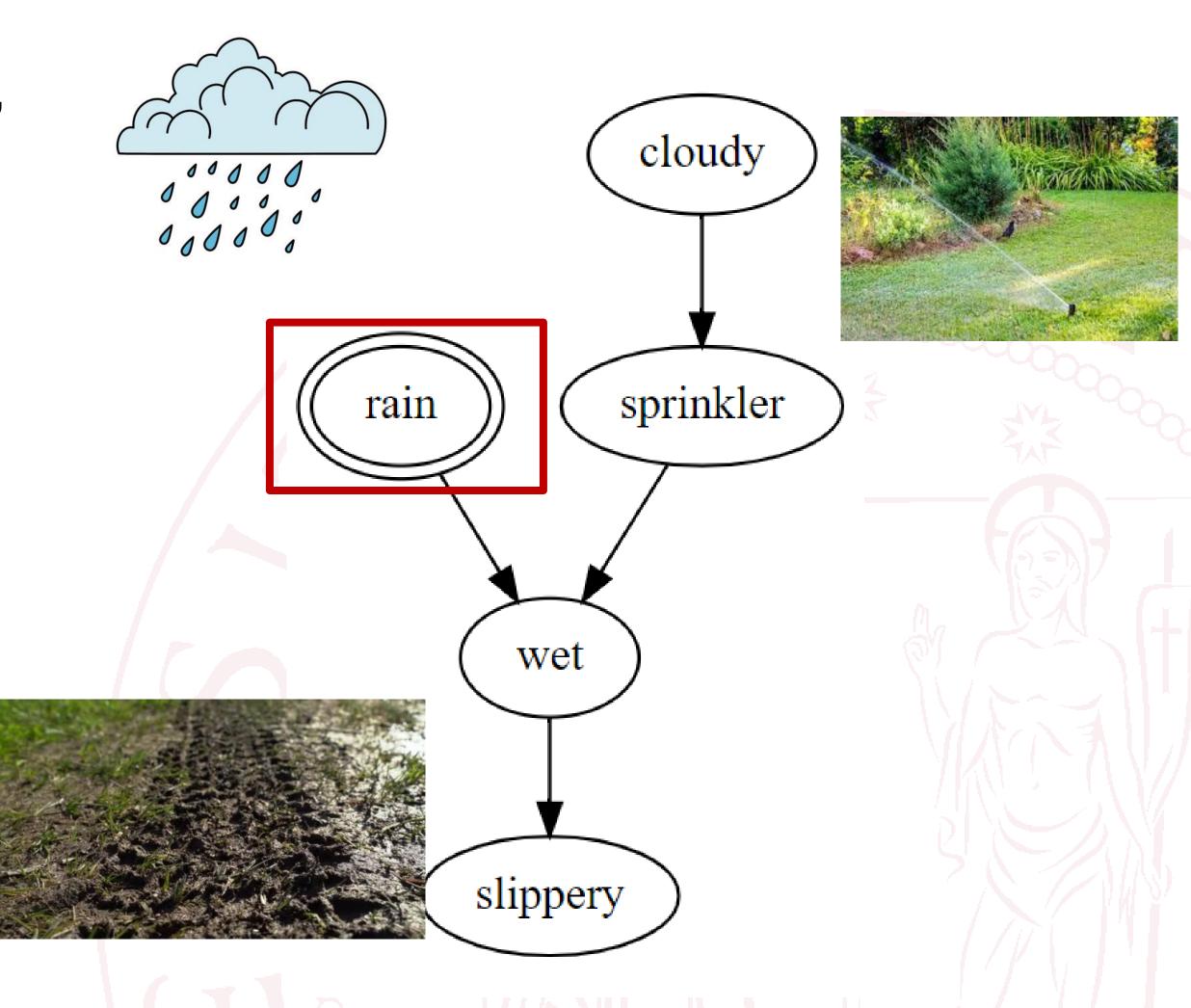
For instance, imagine that we had the **power the control the weather**. If use it to make an intervention on the "rain" node of our sprinkler model, we get the following system.



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```
sprinkler_do = sprinkler.do("rain")
sprinkler_do.draw()
```

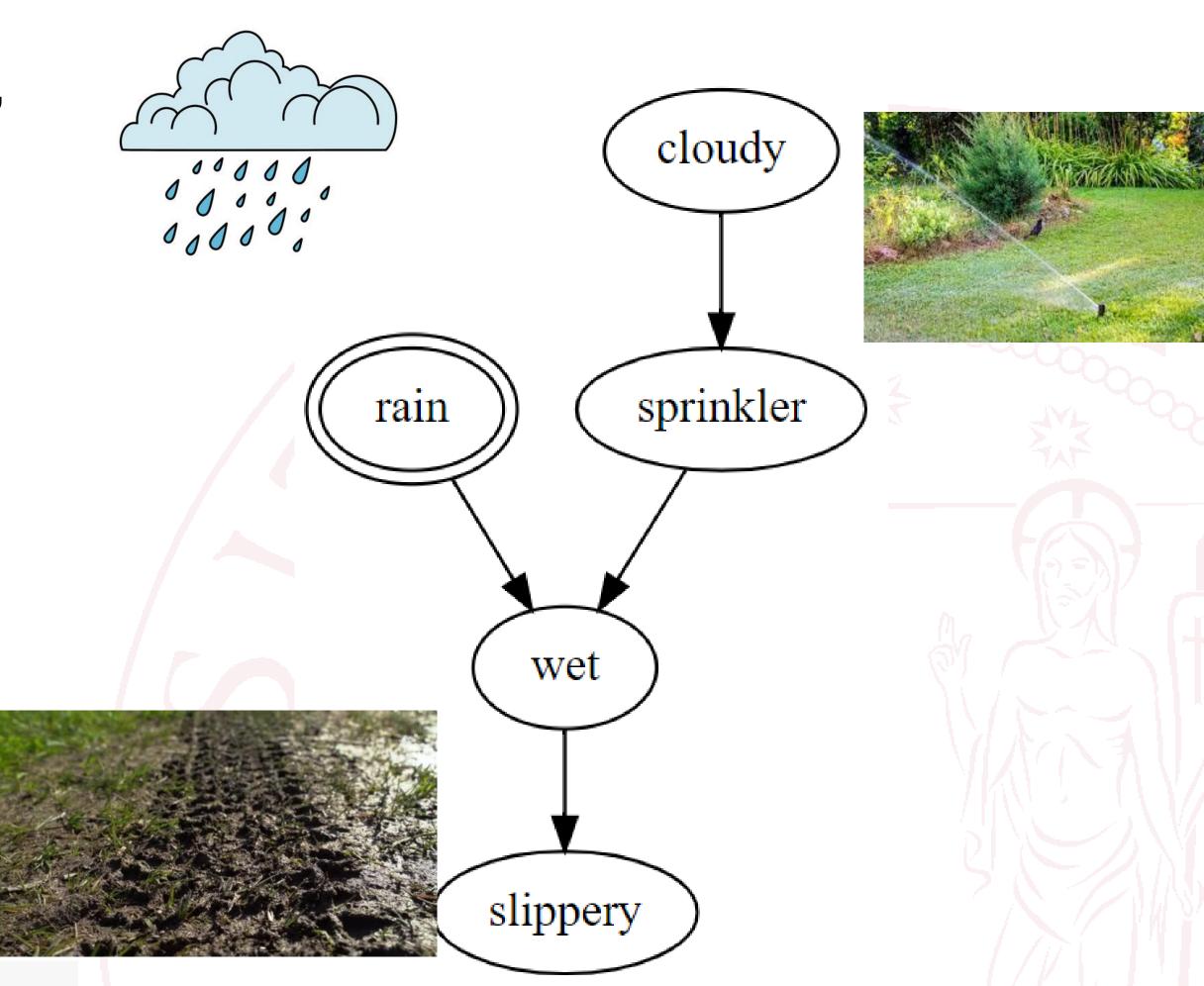
The visualization has been changed. A node with a **double outline** indicates a node with an intervention.



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sprinkler_do.draw()
```

The visualization has been changed. A node with a **double outline** indicates a node with an intervention.



Obviously, the joint probability distribution is changed too.

print(sprinkler_do.get_distribution())

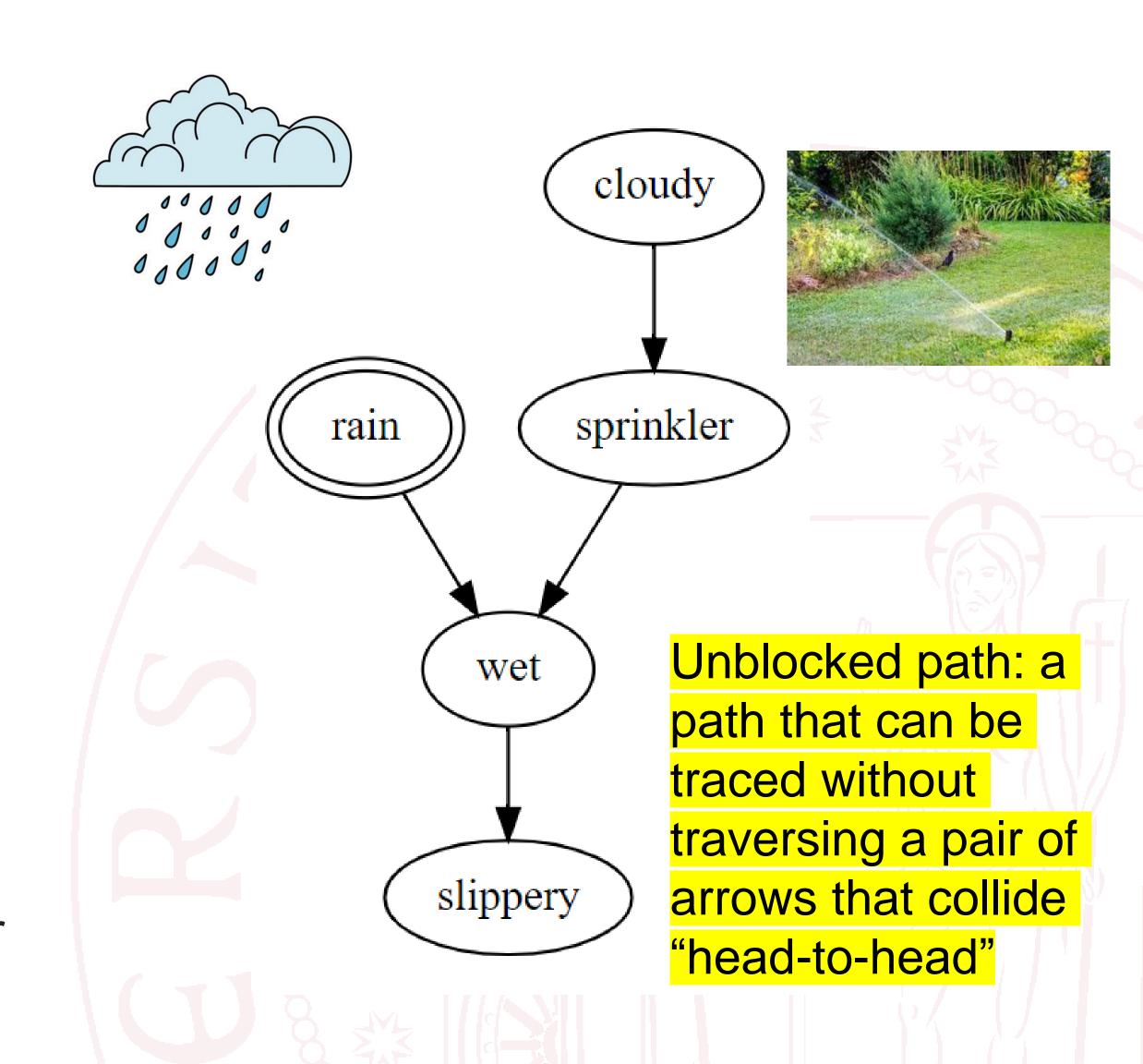
P(cloudy)P(sprinkler|cloudy)P(wet|do(rain),sprinkler)P(slippery|wet)

Causal graphical models are non-parametric, they cannot tell us what the relationship between two variables are.

They only give us an idea if there is a relationship between the two variables through the notion of conditional independence.

It does this using the idea of "paths" between variables: if there are no unblocked paths between two variables, they are independent. It also means that if two causal graphical models share the same paths between two variables, the conditional relationship between these two variables are the same.

For instance, P(slippery|wet) is the same whether or not we make the intervention on rain, but P(slippery|cloudy) is not.

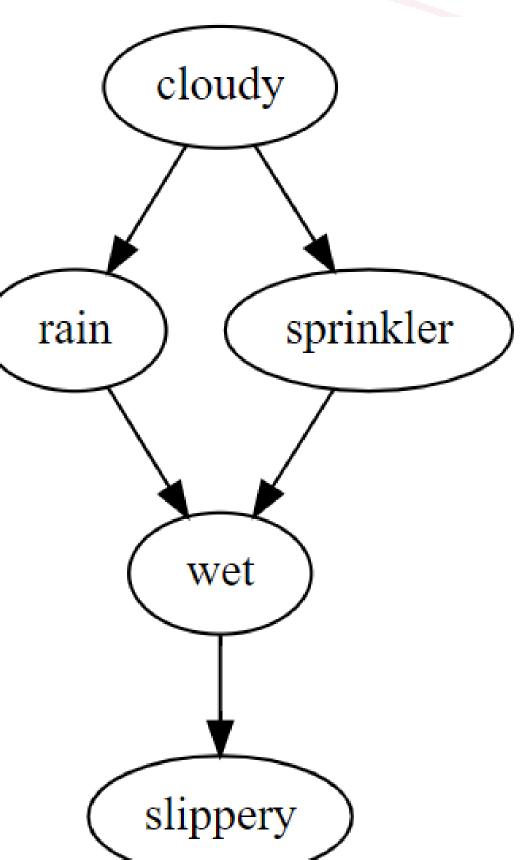


The consequences of interventions

• X can only have some causal inference on Y if there is at least one directed path between X and Y. This is because if there is no directed path, with respect to the intervention graph the parents of X have been removed, so X Y Y in the intervention graph.

• If there are only directed paths between X and Y, then the causal inference of X and Y is given by the simply conditional distribution P(Y|X). This is because the intervention graph has the same paths between X and Y as the observational distribution.

If there is a unblocked, but not completely directed path between X and Y, it
means that both X and Y share a common ancestor. This common ancestor is
what is called as a confounder and this means that if we try to estimate
P(Y|do(X)) from P(Y|X) of estimates will be biased.



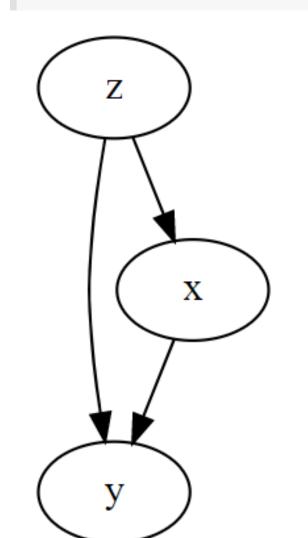
Is it possible to make causal inferences from a system we only have observational samples from?

This problem is often called "Identifiability".

Thus, what circumstances can we estimate P(Y|do(X)) from observational data, given some assumed causal graphical model?

Let's consider the following simple example:

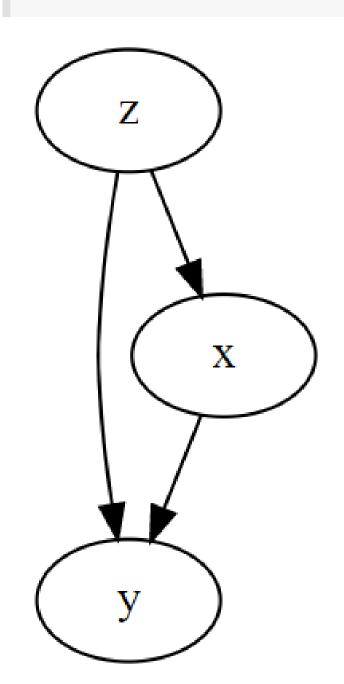
from causalgraphicalmodels.examples import simple_confounded
simple_confounded.draw()



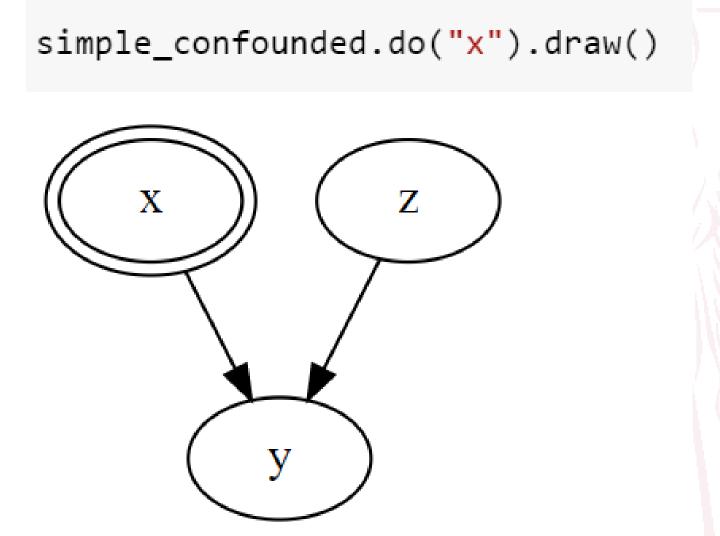


Let's consider the following simple example:

```
from causalgraphicalmodels.examples import simple_confounded
simple_confounded.draw()
```



Under intervention on X, the causal graphical model generating the data is



We are going to try and estimate the quantity P(Y|do(X))

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We have already seen how to estimate it



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Adjustment formula



$$\begin{split} P(y|do(x)) &= P_m(y|x) & \text{from definition of intervention} \\ &= \sum_z P_m(y|x,z) P_m(z|x) & \text{from Law of Total Probability} \\ &= \sum_z P_m(y|x,z) P_m(z) & \text{from independence of X and Z} \\ &= \sum_z P(y|x,z) P(z) & \text{from previous slide's equalities} \end{split}$$

More in general, we can write the adjustment formula, or causal effect rule:

$$P(y|do(x)) = \sum_{z \in \Lambda} P(y|x, z)P(z)$$

where Λ is the set of parents of X

Adjustment formula & Backdoor criterion

The adjustment formula states that under certain circumstances, for a set of variables Z, we can estimate the causal influence of X on Y with respect to a causal graphical model using the equation

$$P(Y|do(X)) = \sum_{Z} P(Y|X,Z) P(Z)$$

The criterion for Z to exist is sometimes called the **backdoor criterion**. Graphically it states that:

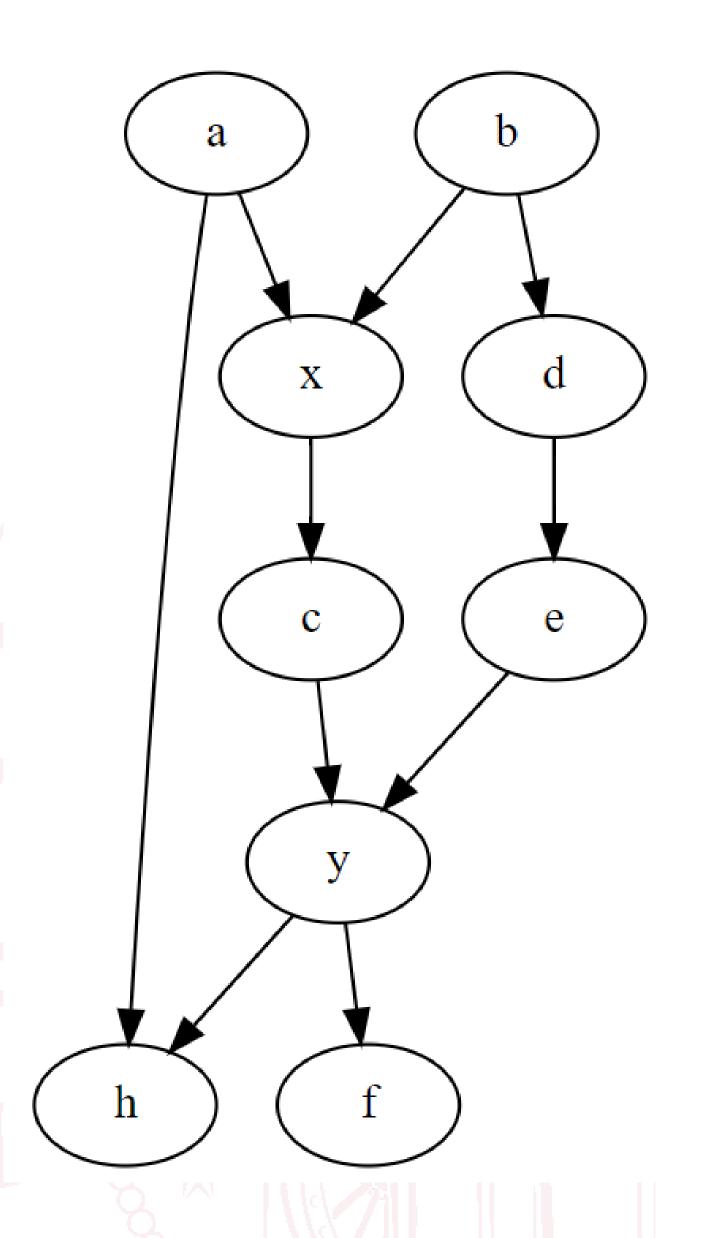
- Z blocks all backdoor paths between X and Y (all paths with arrows going into X)
- Z does not contain any descendant of X

These criteria are met when Z are the parents of X, but these aren't the only variables which can be used as an adjustment set.

Let's see an example

```
from causalgraphicalmodels.examples import big_csm
example_cgm = big_csm.cgm
example_cgm.draw()
```

How many backdoor paths are there between X and Y?

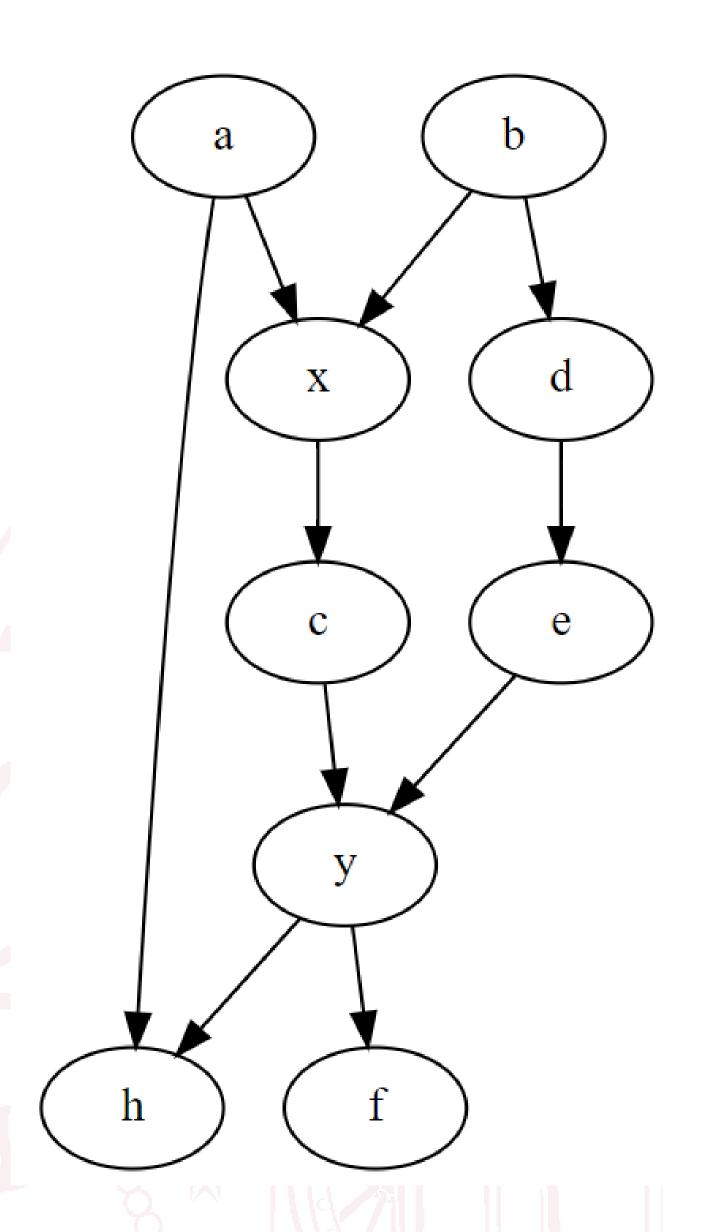


```
from causalgraphicalmodels.examples import big_csm
example_cgm = big_csm.cgm
example_cgm.draw()
```

How many backdoor paths are there between X and Y?

```
example_cgm.get_all_backdoor_paths("x", "y")
[['x', 'a', 'h', 'y'], ['x', 'b', 'd', 'e', 'y']]
```

There are **two** backdoor paths between X and Y



example_cgm.get_all_backdoor_paths("x", "y")

There are two backdoor paths between X and Y

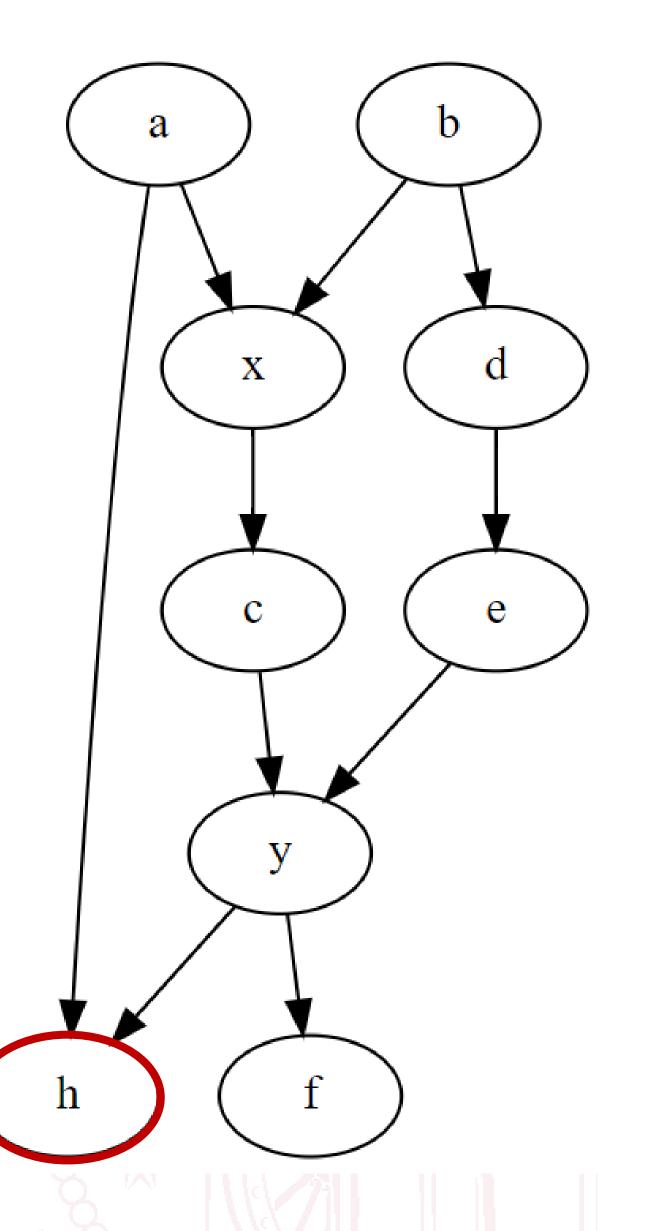
Note: But because *h* acts as a **collider** in the first path, it is blocked unless conditioned on.

To find a valid adjustment set, we need a set which blocks this path.

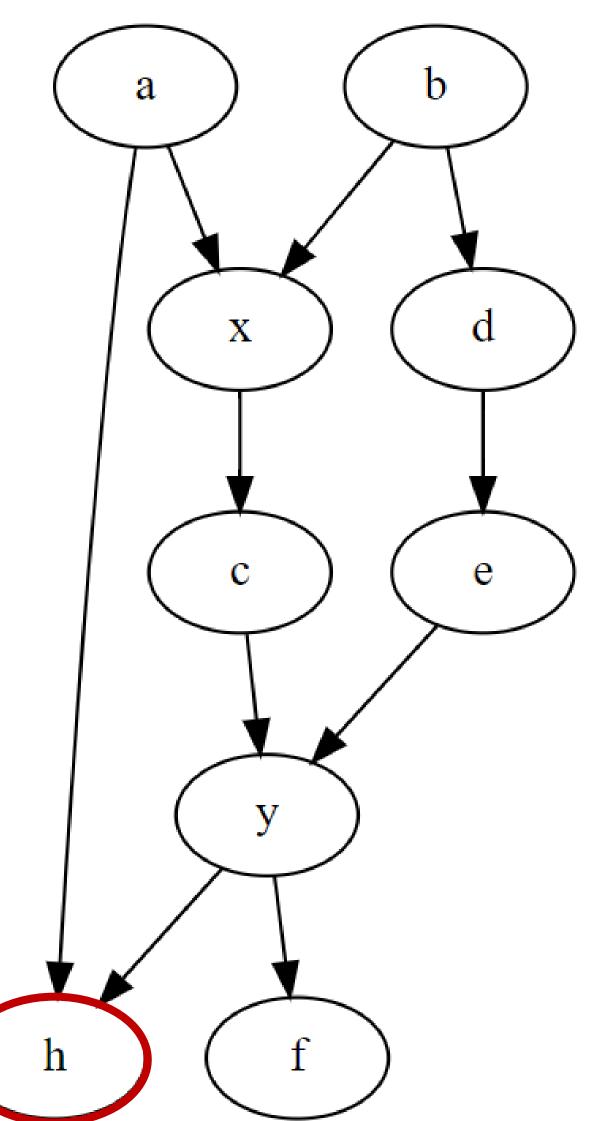
Any of the variables B, D, E would work, as well as any combination of the above.

We can also include any other variable in this set, as long as it doesn't create new paths.

Adding H, F or C to the adjustment set would create a new path, making the adjustment set invalid.

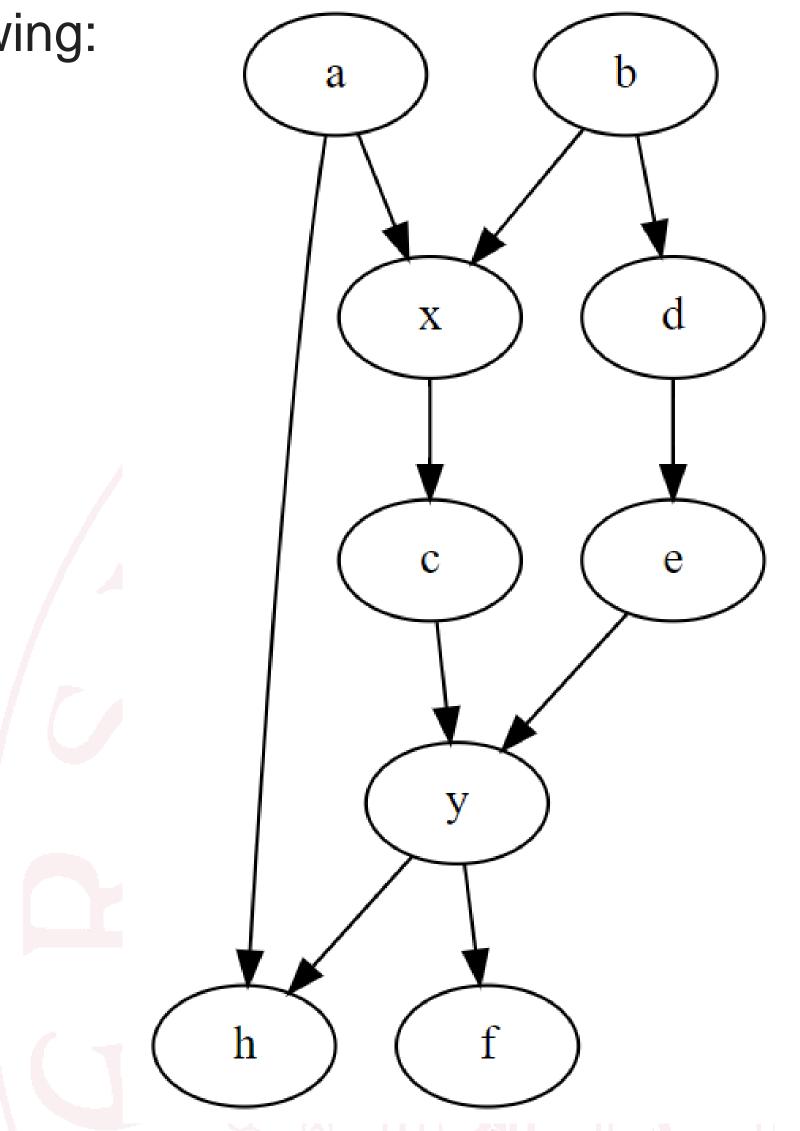


```
example_cgm.get_all_backdoor_paths("x", "y")
[['x', 'a', 'h', 'y'], ['x', 'b', 'd', 'e', 'y']]
example_cgm.is_valid_backdoor_adjustment_set("x", "y", {"a", "h"})
False
example_cgm.is_valid_backdoor_adjustment_set("x", "y", {"b", "d", "e"})
True
example_cgm.is_valid_backdoor_adjustment_set("x", "y", {"b", "d", "e", "h"})
False
example_cgm.is_valid_backdoor_adjustment_set("x", "y",
False
```



We can compute all valid adjustment sets using the following:

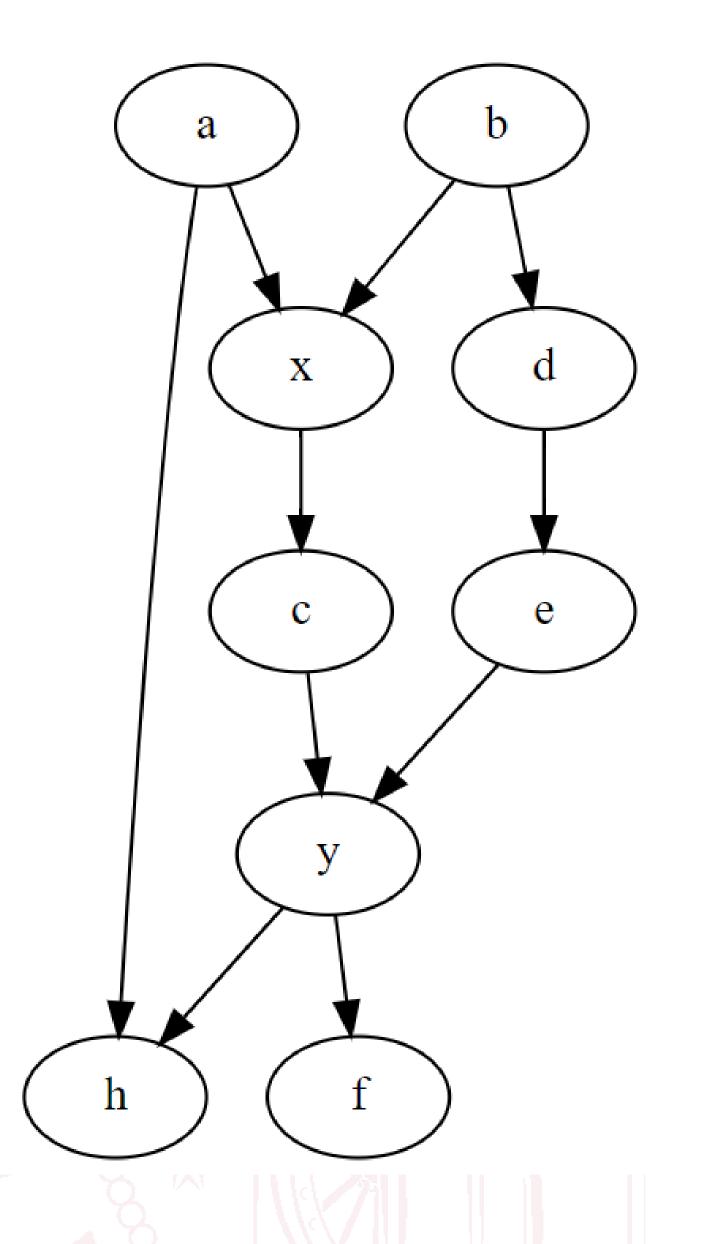
```
example_cgm.get_all_backdoor_adjustment_sets("x", "y")
frozenset({frozenset({'b'}),
           frozenset({'e'}),
           frozenset({'b', 'e'}),
           frozenset({'a', 'd'}),
           frozenset({'a', 'd', 'e'}),
           frozenset({'a', 'b'}),
           frozenset({'b', 'd'}),
           frozenset({'a', 'b', 'd'}),
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```

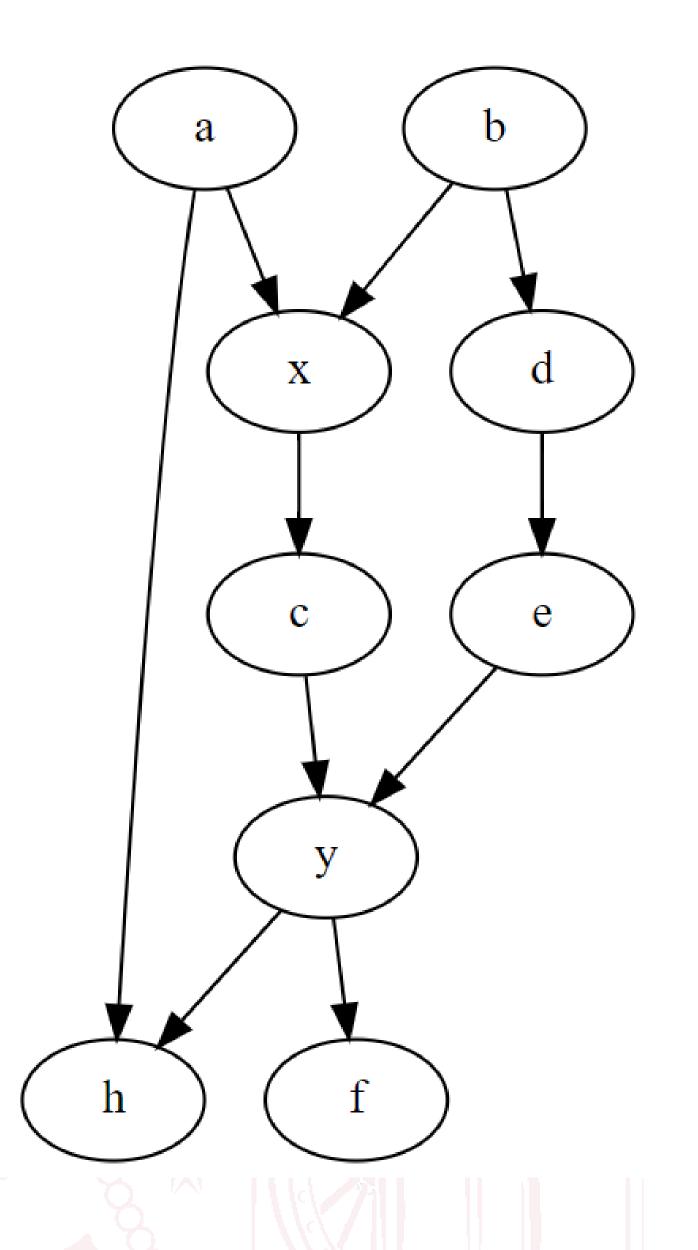
Note: blocking all backdoor paths accounts for any bias introduced by confounding variables, and the requirement that no descendants are conditioned on prevents any new paths from being created.



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```

Note: When all variables in a causal graphical model are observed, is always a set which can be used for adjustment. If not all variables are observed, there can be causal statements which cannot be estimated from the observed data.



We have seen how causal graphical models can be used as a way to make statements about *causal* inference (how data would be generated if there is an intervention on the system),

whereas potential outcomes describe *counterfactual inference* (what would have happened to a system which had already been observed, if a different treatment had been applied),

but it is possible to use CGMs/SCMs to reason about unobserved confounders.

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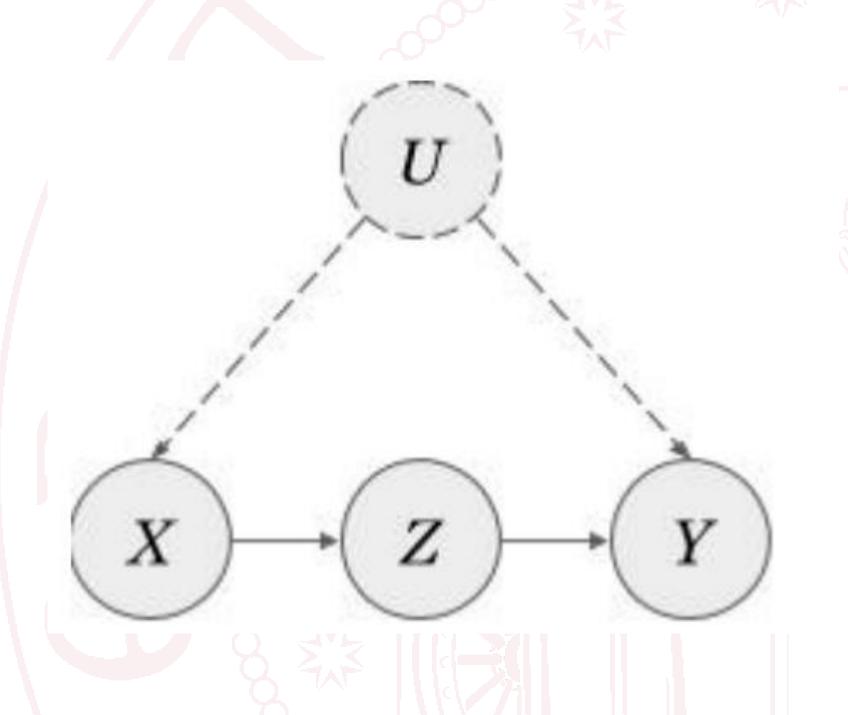
whereas potential outcomes describe *counterfactual inference* (what would have happened to a system which had already been observed, if a different treatment had been applied),

but it is possible to use CGMs/SCMs to reason about unobserved confounders.

Let's consider the following smoking example:

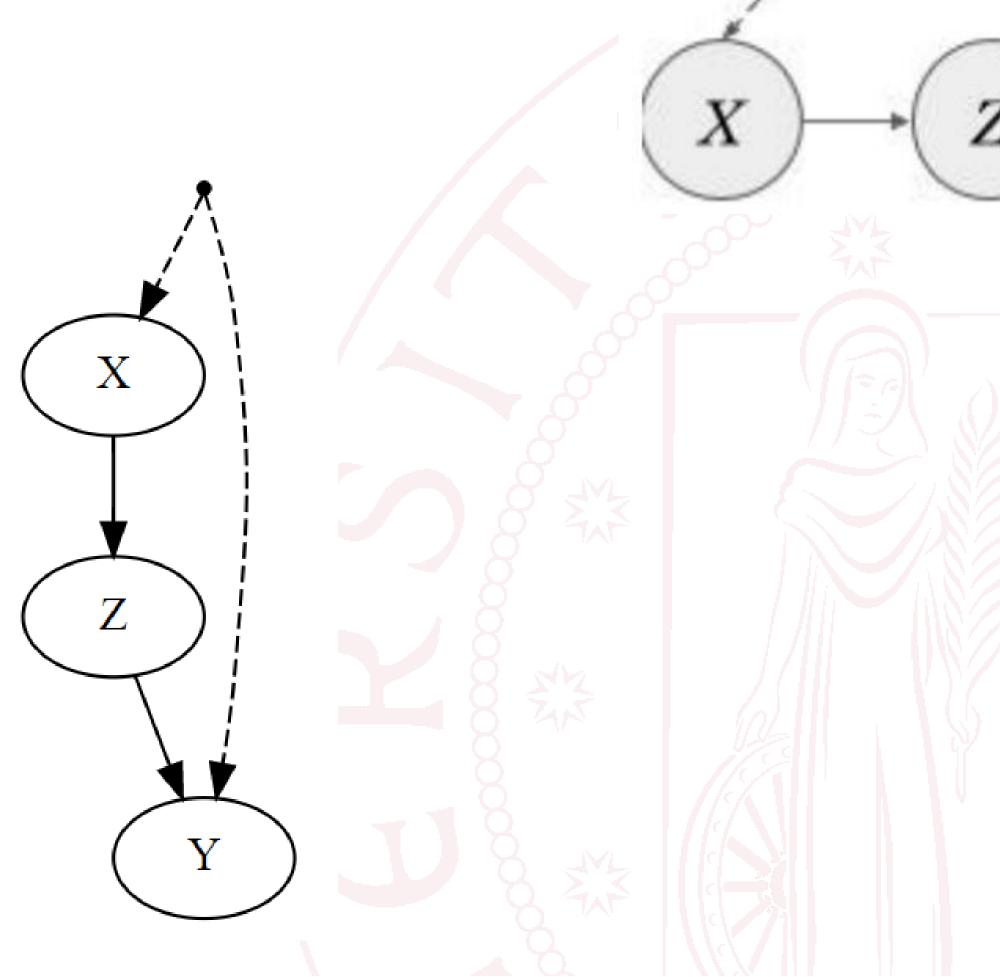
- U (smoking gene) → unobserved confounders
- Z (tar deposit) → observed variables,
- X (smoking) causes Z (tar deposit)
- Z (tar deposit) outcomes Y (lung cancer)





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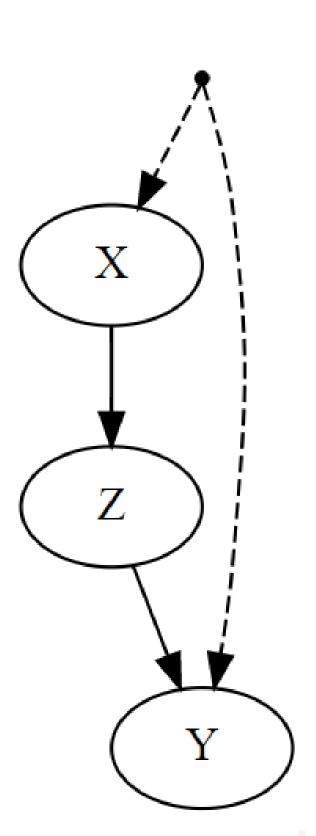
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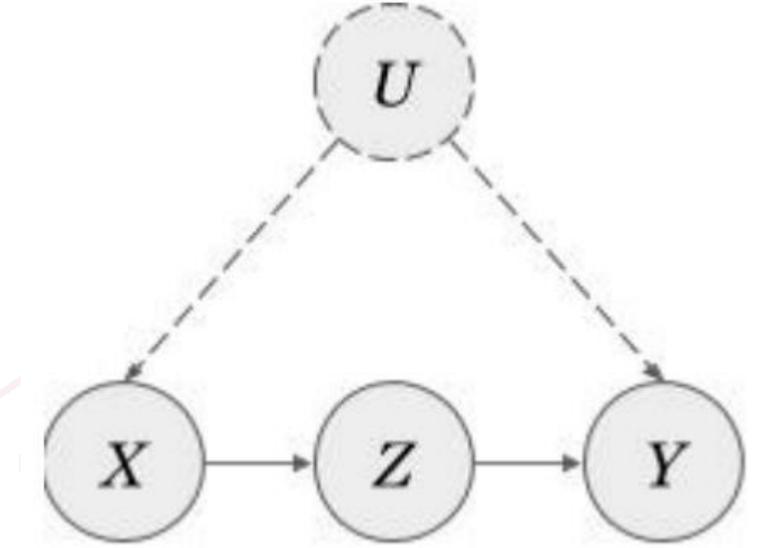


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where the variable U, since unobserved, is substituted by a generic confounder link (dashed arrows) between X and Y

Front-door adjustment

To calculate the causal effect of smoking (X) on lung cancer (Y) by observing the presence of tar deposit (Z), even without knowing if there are other confounders (i.e. smoking gene U)



Front-door adjustment

- A set S of variables satisfies the front-door criterion if 1) it blocks every directed path between X and Y, 2) there are no backdoor paths between X and S, and 3) all the backdoor paths from S to Y are blocked by X
- If S satisfies the front-door criterion, then the following formula can be used to compute the causal effect of X on Y (front-door adjustment)

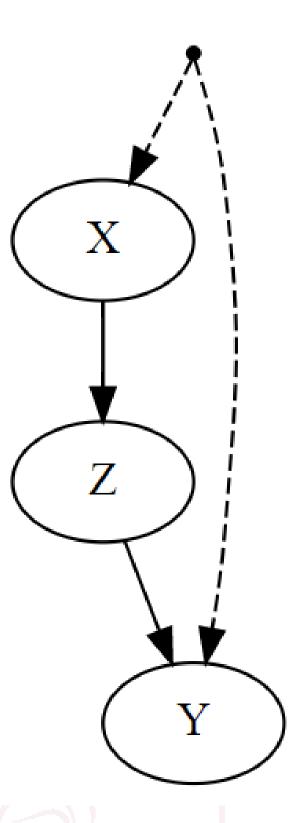
$$P(y|do(x)) = \sum_{s} P(s|x) \sum_{x'} P(y|x', s) P(x')$$

where s are all the possible values of the variables in S

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- U (smoking gene) → unobserved confounders
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The following method can be used to detect all the valid sets for applying the front-door criterion:



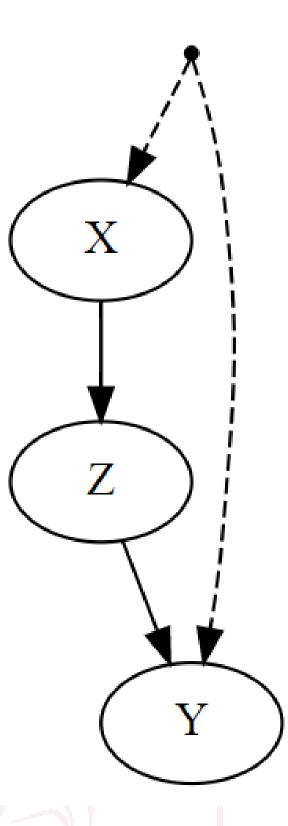
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The following method can be used to detect all the valid sets for applying the front-door criterion:

```
bdnet3.get_all_frontdoor_adjustment_sets('X', 'Y')
frozenset({frozenset({'Z'})})
```

The answer is the intermediate variable Z as expected



Questions

