



A Framework for static allocation of parallel OpenMP code on multi-core platforms

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Context and motivations

Real-time systems are moving towards multicore architectures. The majority of multithread/core libraries target high performance systems.

Real-time applications need strict timing guarantees and predictability.

Vs

▶ High performance systems try to achive a lower computation time in a best efford manner.

There is no actual automatic tool which has the advantages of HPC with timing contrains.





Objectives

The aim of this work is to create:

- ► An easy way to specify the concurrency between real-time tasks and scheduling parameters.
- ► A way to visualize task concurrency and code structure as graphs.
- ► A scheduling algorithm which supports multicore architectures, adapting to the specific platform.
- ► A run time support for the program execution which guarantees the scheduling order of tasks and their timing contrains.





Design Choices: OpenMP and Clang

OpenMP

- Minimal code overhead.
- ► Well spread standard.
- ► Opensource and supported by several vendors like Intel and IBM.

Clang

- ► Provides code analysis and source to source translation capabilities.
- Modularity and great efficency.
- ► Opensource and supported by several vendors like Google and Apple.

In July 2013 Intel released a patched version of Clang which fully supports the OpenMP 3.3 standard.



Ompss





General Design

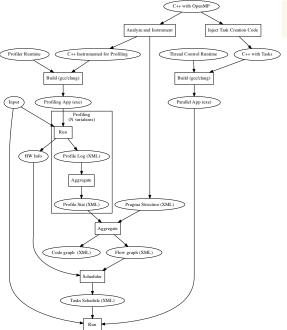
The framework takes as input a C++ code annotated with OpenMP.

- ► The pragmas are extracted with all relevant informations using Clang and saved as XML .
- ► The input code is rewritten to perform profiling .
- ► The scheduler tool uses these informations to create a possible schedule.
- ► The input code is rewritten to allow execution according to the generated schedule.
- ▶ The code is then executed with a custom run-time support.





Introduction Framework Test Future Directions







Graphs

The framework creates three types of graphs to visualize and work on the extracted data

- ► Code Graph: represents the nested structure of the pragmas in the source code.
- ► Flow Graph: represents the parallel execution flow and the synchronization barriers.
- Agumented Flow Graph: enhances the Flow Graph with the profiling information and the function calls.
- ► Schedule Graph: enhances the Agumented Flow Graph with scheduling informations.

The graphs are stored using XML and visualized using Graphviz.





OpenMP

Multiple threads of execution perform tasks defined by directives.

- ► Each directive applies to a block of C++ code embedded in a scope.
- Allows nested parallelism though nested directives.
- Clauses allow variables management.

```
#pragma omp directive-name [clause[ [,] clause]...] new-line
```

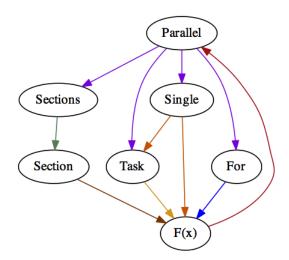
Choosen subset for the framwork:

- Control directives : parallel, sections, single.
- ▶ Working directives : task, section, for.





${\sf OpenMP}$

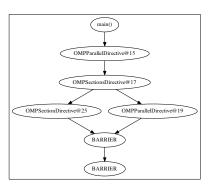






Simple Example

```
void work(int bar){
       #pragma omp parallel for
       for (int i = 0: i < bar: ++i)
          //do stuff
   };
   int main(int argc, char* argv[]) {
       int bar:
       #pragma omp parallel private(bar)
           #pragma omp sections
14
               #pragma omp section
                    //do stuff (bar)
17
                    work(bar);
18
19
               #pragma omp section
                    //do stuff (bar)
                    work(bar);
24
26 }
```









Clang

The strength of Clang lies in its implementation of the Abstract Syntax Tree (AST).

- ► Closely resembles both the written C++ code and the C++ standard.
- Clang's AST nodes are modeled on a class hierarchy that does not have a common ancestor.
- ► Hundreds of classes for a total of more than one hundred thousand lines of code.





Clang - AST

To traverse the AST, Clang provides the RecursiveASTVisitor class.

- Very powerful and easy to learn interface
- Possibility to create a custom visitor that triggers only on specific nodes.

Clang supports the insertion of custom code through the Rewriter class.

- ▶ Allows insertion, deletion and replacement of code.
- Operations are performed during the AST visit.
- ▶ A new source file with all the modifications is generated at the end of the visit.





Clang - AST

```
class A {
public:
    int x;
    void set_x(int val) {
        x = val * 2;
    }
    int get_x() {
        return x;
    }
};
int main() {
        A a;
    int val = 5;
    a.set_x(val);
}
```

```
Translation Unit Decl
-CXXRecordDecl < clang_ast_test.cpp:2:1, line:13:1>
     class A
 I-CXXRecordDecl < line: 2:1. col:7> class A
  -AccessSpecDecl <line:3:1, col:7> public
  -FieldDecl line:4:2, col:6> x 'int'
  -CXXMethodDecl < line:5:2. line:7:2> set_x 'void_(
   I-ParmVarDecl < line:5:13, col:17> val 'int'
   '-CompoundStmt <col:22, line:7:2>
      '-BinaryOperator < line:6:3. col:13> 'int' lyalue
        |-MemberExpr <col:3> 'int' lvalue ->x
         '-CXXThisExpr <col:3> 'class_A_*' this
       '-BinaryOperator <col:7, col:13> 'int' '*'
          |-ImplicitCastExpr <col:7> 'int' <
     LValueToRValue>
          | '-DeclRefExpr <col:7> 'int' Ivalue ParmVar
      'val' 'int'
         '-IntegerLiteral <col:13> 'int' 2
```





Instrumentation for Profile

Creation of a custom profiler to time OpenMP pragma code blocks and functions. No existing profiling tool allows this operation.

- ► Code is instrumented with calls to a custom run-time support.
- Extracted information: execution time, children execution time, caller identifier, for loop counter.
- Output is saved in an XML file.
- ▶ Allows to create the Agumented Flow Graph containing all the call information.

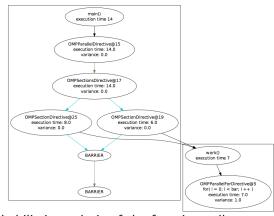
```
/#pragma omp_parallel_for
   if ( ProfileTracker profile\_tracker = ProfileTrackParams(3, 5, bar - 0))
   for (int i = 0; i < bar; ++i)
        //do stuff
    /#pragma omp section
   if( ProfileTracker profile_tracker = ProfileTrackParams(12, 25))
       //do stuff (bar)
13
       work (bar);
14
```





Profile

- ► The profiled code is executed *N* times and statistics are obtained.
- ► IProfile statistics can be associated to different input arguments.
- An edge is added for each function call that contains pragmas.



Possible improvement: probabilistic analysis of the function calls and execution times.



Scheduler

The scheduler takes as input the Agumented Flow Graph and the program's deadline.

- ► Since the problem is *NP*-complete, all possible schedules have to be checked.
- ▶ It is possible to set a fixed amount of computation time.
- ► A parallel version of the scheduler has been developed which achieves better results in a fixed amount of time.

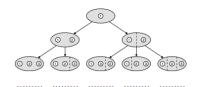
The final schedule is saved as XML file which specifies for each pragma the thread identifier.





Scheduler - Algorithm

The scheduler assigns each task to a flow using a search tree. Each flow will be allocated to a different thread.



- All tasks are stored in an unordered list.
- The scheduler extracts one task at a time adding it to the current flows and to a new flow.
- ▶ The algorithm splits each pragma for node.
- ► The scheduler recurs on each flow pruning it as soon as possible.
- ► When a leaf is reached, the algorithm checks if the current solution is better then the previous one.



Scheduler - Feasibility

The produced schedule does not account for precedence relations. A modified version of Chetto&Chetto (1990) has been used to check the feasibility.

- ▶ All deadlines are set for each task starting from the last one.
- ▶ All arrival times are set for each task starting from the first and accounting for precedence relations.
- ▶ If all deadline are positive and each arrival time is less then the corresponding deadline the schedule is produced.





Final Execution - Instrumentation

Each pragma block is transformed in a custom task.

- ▶ Each pragma code block is embedded in a function call.
- The function is member of a class defined inside the scope of the pragma block.
- ▶ All the variables used in the pragma block, but declared outside are passed to the class's constructor.
- ▶ The nested pragma structure is not changed.
- ▶ Each for is rewritten in order to allow it to be splitted.





Final Execution - Instrumentation Example

```
//#pragma omp section
2
3
4
       class Nested : public NestedBase {
       public:
5
            virtual shared_ptr<NestedBase> clone() const {
              return make_shared < Nested > (*this);
7
8
            Nested(int pragma_id, int & bar) :
9
                NestedBase(pragma_id), bar_(bar) {}
10
            int & bar_:
11
           void fx(int & bar){
               //do stuff (bar)
14
                work (bar);
15
                launch_todo_job();
16
17
            void callme() {
18
                fx(bar_);
19
20
       shared_ptr<NestedBase> nested_b = make_shared<Nested>(19, bar);
22
       if (ThreadPool::getInstance()->call(nested_b))
            todo_job_.push(nested_b);
24
```





Final Execution - Run-time

The run-time parses the generated XML schedule.

- Instantiates all the requested threads using the standard thread library.
- Creates a work queue for each thread.
- When invoked it receives a task and extracts from the schedule the designated execution thread.
- ▶ The task is enhanced with synchronization variables.
- ▶ The task is pushed in the corresponding working thread queue.

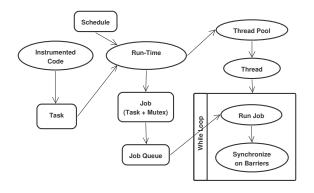




Final Execution - Run-time

Each thread behaves as follows

- ▶ An infinite loop is executed polling the its work queue.
- After work completion all the necessary synchronizations are perfored before continuing with the next task.







General structure

Face recognition algorithm in OpenCV.

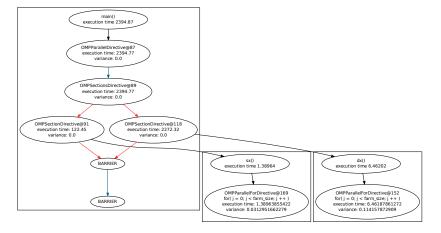
- ► Takes as input two videos to simulate a stereo camera system.
- Frames are dispatched in blocks of *N* frames.
- ► All faces are detected, using a Cascade Detector Multiscale, and circled in each frame.
- All frames are saved on disk.

Three different qualities of the same videos have been used to test the algorithm (480p, 720p, 1080p).





Agumented Flow Graph for Evaluation







Results

- ► Test on a Intel i7@3.2 GHz with 6 cores and HT running Linux 3.8.0.
- Statistics are calculated over 5 executions.
- ► Tested with three different scheduler configurations: 4,6 and 12 cores
- Video properties:
 - 2 people in each.
 - 1 minute length.
 - ▶ 34 FPS.
 - ► Resolutions: 640×360 (230400px), 1280×720 (921600px), 1920×1080 (2073600px)





Results

	Sequential	OpenMP		Soma	
	$T_{seq}[s]$	$T_c(n)[s]$	$\epsilon(n) = \frac{T_{seq}}{nT_c(n)}$	$T_c(n)[s]$	$\epsilon(n) = \frac{T_{seq}}{nT_c(n)}$
480p(4)	750	195	0.96	195	0.96
720p(4)	3525	921	0.96	921	0.96
1080p(4)	8645	2271	0.95	2270	0.95
480p(6)	-	133	0.94	134	0.93
720p(6)	-	627	0.94	629	0.93
1080p(6)	-	1536	0.94	1539	0.94
480p(12)	-	98	0.64	92	0.68
720p(12)	-	427	0.69	426	0.69
1080p(12)	-	1043	0.69	1035	0.70





Results - Service Time

Service time in second of each thread (gap between the delivery of a parsed image).

- ► Soma variance < OpenMP variance
- ▶ Video quality 720p, 6 cores.

Thread	Sequential		OpenMP		Soma	
	T_s	variance	T_s	variance	T_s	variance
0	1.3263	0.1968	1.4226	0.0092	1.4987	0.0065
1	-	-	1.4225	0.0090	1.4297	0.0065
2	-	-	1.4225	0.0098	1.4298	0.0065
3	-	-	1.4257	0.0125	1.4117	0.0067
4	-	-	1.4256	0.0129	1.4111	0.0060
5	-	-	1.4256	0.0129	1.4117	0.0060

Performances remain consistent changing the video quality.





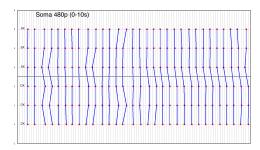
Results - Mean Service Time

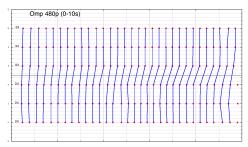
Mean service time between cores for each video quality, changing the core number.

	Sequential	OpenMP		Soma	
	mean T _s	mean T _s	mean var	mean T _s	mean var
480p(4)	0.2823	0.2966	0.0014	0.2919	0.0004
720p(4)	1.3263	1.3955	0.0087	1.3884	0.0009
1080p(4)	3.2524	3.4399	0.0101	3.4369	0.0075
480p(6)	-	0.3038	0.0016	0.3023	0.0006
720p(6)	-	1.4241	0.0111	1.4206	0.0064
1080p(6)	-	3.4906	0.0238	3.4983	0.0197
480p(12)	-	0.4223	0.1421	0.4148	0.0044
720p(12)	-	1.9426	0.0862	1.9228	0.1334
1080p(12)	-	4.7394	0.3956	4.6915	0.6277



Results - Jitter





- ► Time between output of a frame for each thread.
- ► Soma self realigning.
- Omp increasing delay between sx and dx.





Results - Comments

All the results of the framework are comparable with the OpenMP results.

- Almost same performance.
- ► The framework achieves a lower service time variance → more predictable.
- Low overhead.

The framework achieved the two main requested properties to work with real-time applications.





Future Directions

Creation of custom pragmas and clauses.

- ► Too many pragmas
- No possibility to specify real-time constrains

Better scheduler heuristics.

Save time by early pruning.

Implement a probabilistic profiling step.

▶ Some functions could not be called.

Add the possibility to extend the concept to GPU and heterogeneous programming.



