

# Random time step probabilistic methods for uncertainty quantification in chaotic and geometric numerical integration

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## Abstract

**Keywords.**

**AMS classification subjects.**

## 1 Introduction

## 2 Prob. methods

*Assumption 1.* Assumption on the random variables.

## 3 Technical part

*Assumption 2.* Assumptions on  $f$  and on  $\Psi_h$ .

**Theorem 1.** *Error growth of deterministic RK [1].*

**Lemma 1.** *For the additive noise method*

$$\mathbb{E}(Y_n | Y_{n-j}) = \Psi_h^j(Y_{n-j}) + \mathcal{O}((j-1)h^{2p+1}) \quad (1)$$

*Proof.* We prove the result by induction on the index  $j$ . First, consider  $\mathbb{E}(Y_n | Y_{n-1})$ , which is trivially

$$\mathbb{E}(Y_n | Y_{n-1}) = \mathbb{E}(\Psi_h(Y_{n-1}) + \xi_{n-1} | Y_{n-1}) = \Psi_h(Y_{n-1}). \quad (2)$$

Iterating once and exploiting the properties of conditional expectations, we get

$$\begin{aligned} \mathbb{E}(Y_n | Y_{n-2}) &= \mathbb{E}(\mathbb{E}(Y_n | Y_{n-1}) | Y_{n-2}) \\ &= \mathbb{E}(\Psi_h(Y_{n-1}) | Y_{n-2}) \\ &= \mathbb{E}(\Psi_h(\Psi_h(Y_{n-2}) + \xi_{n-2}) | Y_{n-2}). \end{aligned} \quad (3)$$

A Taylor expansion, the properties of conditional expectations and Assumption 1 give

$$\begin{aligned} \mathbb{E}(Y_n | Y_{n-2}) &= \mathbb{E}(\Psi_h^2(Y_{n-2}) + D\Psi_h(Y_{n-2})\xi_{n-2} \\ &\quad + D^2\Psi_h(Y_{n-2})(\xi_{n-2}, \xi_{n-2}) + \dots | Y_{n-2}) \\ &= \Psi_h^2(Y_{n-2}) + \mathcal{O}(h^{2p+1}). \end{aligned} \quad (4)$$

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The induction step can then be written as

$$\begin{aligned}\mathbb{E}(Y_n | Y_{n-j}) &= \mathbb{E}(\mathbb{E}(Y_n | Y_{n-j+1}) | Y_{n-j}) \\ &= \mathbb{E}(\Psi_h^{j-1}(Y_{n-j+1}) | Y_{n-j}) + \mathcal{O}((j-2)h^{2p+1}) \\ &= \mathbb{E}(\Psi_h^{j-1}(\Psi_h(Y_{n-j}) + \xi_{n-j}) | Y_{n-j}) + \mathcal{O}((j-2)h^{2p+1}).\end{aligned}\tag{5}$$

Expanding  $\Psi_h^{n-j}$  in a Taylor series we get

$$\begin{aligned}\mathbb{E}(Y_n | Y_{n-j}) &= \mathbb{E}(\Psi_h^j(Y_{n-j}) + D\Psi_h^{j-1}(Y_{n-j})\xi_{n-j} | Y_{n-j}) + \mathcal{O}((j-1)h^{2p+1}) \\ &= \Psi_h^j(Y_{n-j}) + \mathcal{O}((j-1)h^{2p+1}),\end{aligned}\tag{6}$$

which proves the desired result.  $\square$

**Lemma 2.** *For the RTS-RK method*

$$\mathbb{E}(Y_n | Y_{n-j}) = \dots\tag{7}$$

*Proof.* Let us first consider the difference between a single step of a fixed time step method with respect to the RTS-RK method. Any Runge-Kutta method of order  $q \geq 1$  can be written for any  $y \in \mathbb{R}^d$  and  $z > 0$  as

$$\Psi_z(y) = y + zf(y) + z^2R(y),\tag{8}$$

where  $R(y)$  is a function depending on the coefficients of the method, on the function  $f$  as well as on  $z$ . Hence, for a generic random time step  $H$ , we have

$$\Psi_H(y) - \Psi_h(y) = (H - h)f(y) + (H^2 - h^2)R(y).\tag{9}$$

Let us now proceed by induction. For the first step we have thanks to the properties of conditional expectations and (9)

$$\begin{aligned}\mathbb{E}(Y_n | Y_{n-1}) &= \mathbb{E}(\Psi_{H_{n-1}}(Y_{n-1}) | Y_{n-1}) \\ &= \mathbb{E}(\Psi_h(Y_{n-1}) + \Psi_{H_{n-1}}(Y_{n-1}) - \Psi_h(Y_{n-1}) | Y_{n-1}) \\ &= \Psi_h(Y_{n-1}) + \mathcal{O}(\mathbb{E}(H_{n-1}^2 - h^2)).\end{aligned}\tag{10}$$

Conditioning with respect to the previous step therefore gives

$$\begin{aligned}\mathbb{E}(Y_n | Y_{n-2}) &= \mathbb{E}(\mathbb{E}(Y_n | Y_{n-1}) | Y_{n-2}) \\ &= \mathbb{E}(\Psi_h(Y_{n-1}) | Y_{n-2}) + \mathcal{O}(\mathbb{E}(H_{n-1}^2 - h^2)).\end{aligned}\tag{11}$$

Goes on like before...  $\square$

**Theorem 2.** *For the additive noise method*

$$\|\text{Var } Y_n\|_F \leq C_1 t_n h^{2p} + C_2 t_n^4 h^{4p-2},\tag{12}$$

where  $C_1, C_2$  are positive constants independent of  $h$  and  $n$ .

*Proof.* Let us first remark that since  $\text{Var } Y_n$  is symmetric positive definite we have

$$\|\text{Var } Y_n\|_F \leq \text{tr}(\text{Var } Y_n) = \mathbb{E}\|Y_n - \mathbb{E} Y_n\|^2.\tag{13}$$

Let us therefore work with the right hand side of the inequality above. By a telescopic sum, we obtain

$$\begin{aligned}\mathbb{E}\|Y_n - \mathbb{E} Y_n\|^2 &= \mathbb{E}\|\mathbb{E}(Y_n | Y_n) - \mathbb{E}(Y_n | y_0)\|^2 \\ &= \mathbb{E}\left\|\sum_{j=0}^{n-1} \mathbb{E}(Y_n | Y_{n-j}) - \mathbb{E}(Y_n | Y_{n-j-1})\right\|^2 \\ &= \sum_{j=0}^{n-1} \mathbb{E}\|\mathbb{E}(Y_n | Y_{n-j}) - \mathbb{E}(Y_n | Y_{n-j-1})\|^2 \\ &\quad + 2 \sum_{j=0}^{n-1} \sum_{k < j} \mathbb{E}\left(\mathbb{E}(Y_n | Y_{n-j}) - \mathbb{E}(Y_n | Y_{n-j-1}), \mathbb{E}(Y_n | Y_{n-k}) - \mathbb{E}(Y_n | Y_{n-k-1})\right)\end{aligned}\tag{14}$$

Let us consider the first term. Thanks to Lemma 1, we have

$$\begin{aligned}
\mathbb{E}(Y_n | Y_{n-j}) - \mathbb{E}(Y_n | Y_{n-j-1}) &= \Psi_h^j(Y_{n-j}) - \Psi_h^{j+1}(Y_{n-j-1}) + \mathcal{O}(jh^{2p+1}) \\
&= \Psi_h^j(\Psi_h(Y_{n-j-1}) + \xi_{n-j-1}) - \Psi_h^{j+1}(Y_{n-j-1}) \\
&\quad + \mathcal{O}(jh^{2p+1}) \\
&= D\Psi_h^j(\Psi_h(Y_{n-j-1}))\xi_{n-j-1} \\
&\quad + D^2\Psi_h^j(\Psi_h(Y_{n-j-1}))(\xi_{n-j-1}, \xi_{n-j-1}) + \mathcal{O}(jh^{2p+1}).
\end{aligned} \tag{15}$$

Hence, we get for a constant  $C > 0$

$$\begin{aligned}
\sum_{j=0}^{n-1} \mathbb{E} \|\mathbb{E}(Y_n | Y_{n-j}) - \mathbb{E}(Y_n | Y_{n-j-1})\|^2 &\leq C \sum_{j=0}^n (h^{2p+1} + j^2 h^{4p+2}) \\
&\leq C(t_n h^{2p} + t_n^3 h^{4p-1}).
\end{aligned} \tag{16}$$

Introducing the notation

$$P_{j,k} = \mathbb{E} \left( \mathbb{E}(Y_n | Y_{n-j}) - \mathbb{E}(Y_n | Y_{n-j-1}), \mathbb{E}(Y_n | Y_{n-k}) - \mathbb{E}(Y_n | Y_{n-k-1}) \right), \tag{17}$$

we have for  $k < j$  thanks to (15) and Assumption 1

$$\begin{aligned}
P_{j,k} &= \mathbb{E} \left( D\Psi_h^j(\Psi_h(Y_{n-j-1}))\xi_{n-j-1}, D\Psi_h^k(\Psi_h(Y_{n-k-1}))\xi_{n-k-1} \right) + \mathcal{O}(jkh^{4p+2}) \\
&= \mathcal{O}(jkh^{4p+2}).
\end{aligned} \tag{18}$$

Therefore, we obtain for a constant  $C > 0$

$$\sum_{j=0}^{n-1} \sum_{k < j} P_{j,k} \leq C t_n^4 h^{4p-2}, \tag{19}$$

which concludes the proof.  $\square$

**Theorem 3.** *Assumption on local variance mimicking local error  $\implies$  global error captured by variance.*

## 4 Calibration of the probabilistic integrator

- Constant in the error term, need for calibration
- Explanation of the procedure in [2]
- Proposal of a new technique? Proving it works?

## 5 Adaptive time stepping probabilistic

Is it doable?

## 6 Inverse problems

Is it possible to have an estimation of variance under posterior measure  $\implies$  well-calibrated UQ on the parameter.

## 7 Numerical experiments

### References

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